Shape Interrogation for CAD/CAM

All of the generic processing routines, those that are not necessarily specific to hyperbook codes, are put into the one of the libraries, e.g. B-spline routines in the ../lib/bspl library, etc.

Codes for the hyperbook-related executables are under this directory: e.g. ./Ch_1 contains the routines for some executables related to Chapter 1 of the hyperbook.

The file formats used in the hyperbook-related codes are described as follows:

1. ParCurv, NURBS Curve

```
n
                            m
                            k_2
\mathbf{k}_1
                                                                                    k_{m+p}
                                                                                    \mathbf{w}_1
\mathbf{x}_1
                            \mathbf{y}_1
                                                       \mathbf{z}_1
\mathbf{x}_2
                            y_2
                                                       \mathbf{z}_2
                                                                                    W_2
\mathbf{x}_{\mathbf{m}}
                            y_{\rm m}
                                                        \mathbf{z}_{\mathbf{m}}
                                                                                    \mathbf{w}_{\mathrm{m}}
```

where n is the order of the curve (order = degree + 1) and m is the number of control points. These are followed by the m+p knots where p equals n for non-periodic NURBS curves, and the m control points in homogeneous coordinates where w is the homogeneous coordinate and must be non-zero. The 3D coordinates x', y', z' of a control point are defined by x'=x/w, y'=y/w, z'=z/w.

2. ParSurf, NURBS Surface

```
n_{\rm u}
                n_{v}
                               m_{\rm n}
                                                m_{\rm v}
k_{u,1}
                k_{u,2}
                                                k_{u,mu+nu}
k_{v,1}
                k_{v,2}
                                                k_{v,mv+nv}
X_{1,1}
                                                W_{1,1}
                y_{1,1}
                               z_{1,1}
X_{1.2}
                y_{1,2}
                               z_{1,2}
                                                W_{1,2}
X_{1,mv}
                y_{1,mv}
                               z_{1.mv}
                                                \mathbf{w}_{1,\mathbf{m}\mathbf{v}}
                y_{2,1}
                               z_{2,1}
                                                W_{2,1}
X_{2,1}
x_{mu,mv} \quad y_{mu,mv} \quad z_{mu,mv} \quad w_{mu,mv}
```

where n_u , n_v are the orders of the surface (order = degree + 1) in the u and v directions and m_u , m_v are the numbers of control points in the u and v directions. These are followed by the m_u+n_u knots in the u direction, the m_v+n_v knots in the v direction, and the m_uxm_v control points in homogeneous coordinates, stored as a series of control polygons in the v direction. The homogeneous coordinate w must be non-zero. The 3D coordinates x', y', z' of a control point are defined by x'=x/w, y'=y/w, z'=z/w.

3. Vector Graphics Results

where op is either M, indicating a move operation, or D, indicating a draw operation. The file is read until the final E is found.