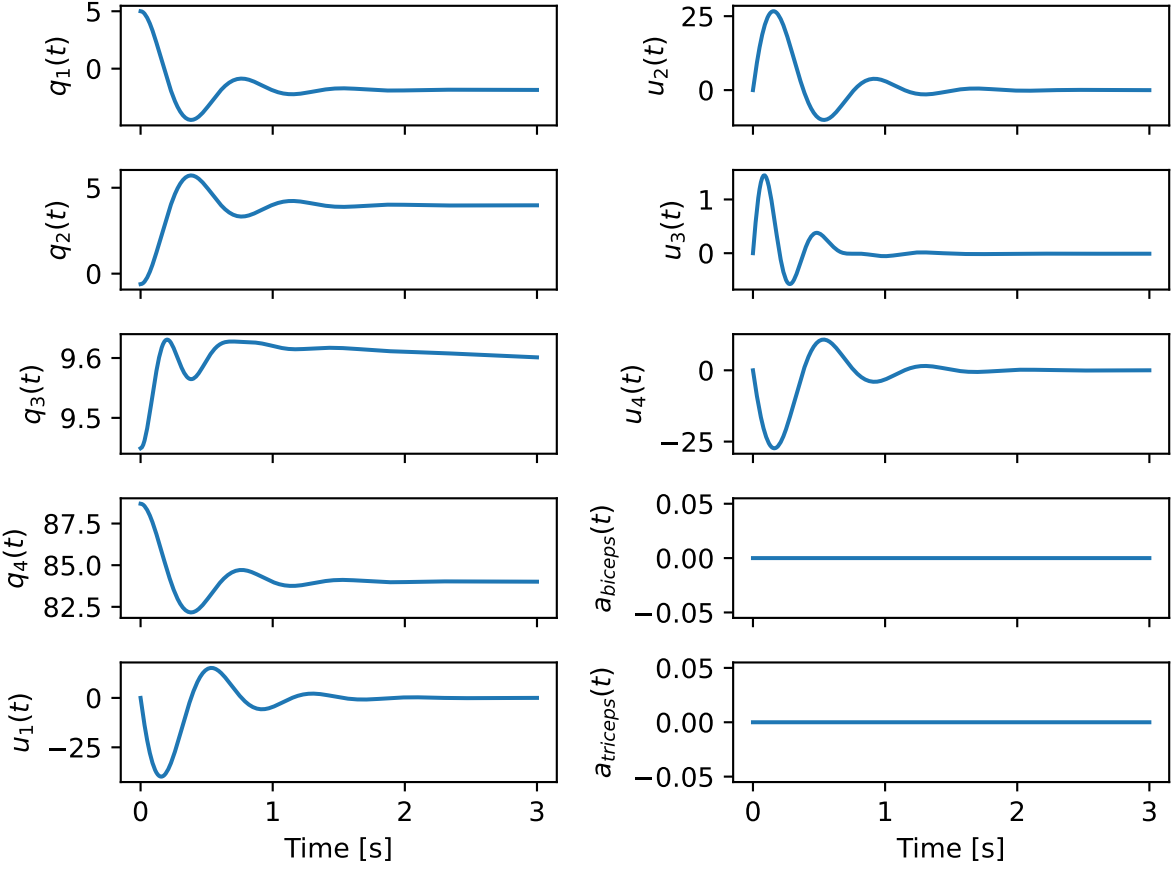
$q_1(t)$
$q_2(t)$
$q_3(t)$
$q_4(t)$
$u_1(t)$
$u_2(t)$
$u_3(t)$
$u_4(t)$
$a_{biceps}(t)$
$a_{triceps}(t)$
Time [s]
Time [s]