

# **M451 Series Board Supporting Package Directory Introduction**

Rev.3.00.003

**Directory Information**

<b>Document</b>	Driver reference manual and revision history.
<b>Library</b>	Driver header and source files.
<b>SampleCode</b>	Driver sample code.
<b>ThirdParty</b>	Library from third party

## Document Information

<b>BSP Revision History</b>	Show all the revision history about specific BSP.
<b>Driver Reference Guide</b>	Describe the definition, input and output of each API.

## Library Information

<b>CMSIS</b>	CMSIS definitions by ARM® Corp.
<b>Device</b>	CMSIS compliant device header file.
<b>StdDriver</b>	All peripheral driver header and source files.
<b>SmartcardLib</b>	Library for CCID smart card reader.
<b>UsbHostLib</b>	Library for USB Host.

## Sample Code Information

<b>\SampleCode\CardReader</b>	CCID <sup>[1]</sup> smart card reader sample code.
<b>\SampleCode\FreeRTOS</b>	Simple FreeRTOS™ demo code.
<b>\SampleCode\Hard_Fault_Sample</b>	Show hard fault information when hard fault happened.
<b>\SampleCode\NuTiny-SDK-M453</b>	Sample code for M453 Tiny Board.
<b>\SampleCode\Template</b>	Software Development Template.
<b>\SampleCode\Semihost</b>	The sample code to show how to debug with semihost message print.
<b>\SampleCode\RegBased</b>	The sample code able to access control registers directly.
<b>\SampleCode\StdDriver</b>	M451 Series Driver Samples

1. Circuit card interface device (CCID) is USB device that interface with integrated circuit cards.

## \SampleCode\NuTiny-SDK-M453

LED	Toggle PC.9 to turn on / off the board LED.
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## \SampleCode\RegBased

ACMP	Demonstrate how ACMP <sup>[1]</sup> works with internal band-gap voltage.
ACMP_Wakeup	Demonstrate how to wake up from Power-down mode by ACMP wake-up function.
CAN_Set_MaskFilter	Demonstrate how to use MaskFilter to receive message in Normal mode. This sample code needs to work with CAN_Test_MaskFilter.
CAN_Test_MaskFilter	Demonstrate how to use message object No.1 to send message objects (ID=0x700~0x70F). This sample code needs to work with CAN_Set_MaskFilter.
CLK_ClockDetector	Demonstrate how to use clock fail detector and clock frequency monitor function.
CRC_CCITT	Perform CRC-CCITT operation and get the CRC checksum result.
CRC_CRC8	Perform CRC-8 operation and get the CRC checksum result.
DAC_PWMTrigger	Demonstrate how to trigger DAC by PWM.
DAC_TimerTrigger	Demonstrate how to trigger DAC by timer.
DAC_WriteDataTrigger	Demonstrate how to trigger DAC by writing DAC_DAT register.
EADC_ADINT_Trigger	Demonstrate how to use ADINT interrupt to do the ADC continuous scan conversion.
EADC_PWM_Trigger	Demonstrate how to trigger ADC by PWM.
EADC_ResultMonitor	Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.

<b>EADC_SWTRG_Trigger</b>	Demonstrate how to trigger ADC by writing EADC_SWTRG register.
<b>EADC_Timer_Trigger</b>	Demonstrate how to trigger ADC by timer.
<b>EBI_NOR</b>	Demonstrate how to access MX29LV320T (NOR Flash) through EBI bus.
<b>EBI_SRAM</b>	Demonstrate how to access BS616LV4017 (SRAM) through EBI bus.
<b>FMC_ExecInSRAM</b>	Demonstrate how to execute code in SRAM and program embedded Flash. (Support KEIL® MDK Only)
<b>FMC_IAP</b>	Demonstrate how to call LDROM functions from APROM. The code in APROM will look up the table at 0x100E00 to get the address of function of LDROM and call the function.
<b>FMC_MultiBoot</b>	Demonstrate how to implement multi-boot system to boot from different applications in APROM. A LDROM code and 4 APROM code are implemented in this sample code.
<b>FMC_RW</b>	Demonstrate how to read/program embedded flash by ISP function.
<b>GPIO_EINTAndDebounce</b>	Demonstrate how to use GPIO external interrupt function and de-bounce function.
<b>GPIO_INT</b>	Demonstrate how to use GPIO interrupt function.
<b>GPIO_OutputInput</b>	Demonstrate how to set GPIO pin mode and use pin data input/output control.
<b>GPIO_PowerDown</b>	Demonstrate how to wake up system form Power-down mode by GPIO interrupt.
<b>I2C_EEPROM</b>	Demonstrate how to access EEPROM by I2C interface.
<b>I2C_GCMode_Master</b>	Demonstrate how a Master uses I2C address 0x0 to write data to I2C Slave. This sample code needs to work with I2C_GCMode_SLAVE.
<b>I2C_GCMode_Slave</b>	Demonstrate how to receive Master data in GC (General

	Call) mode. This sample code needs to work with I2C_GCMode_MASTER.
<b>I2C_Master</b>	Demonstrate how a Master access Slave. This sample code needs to work with I2C_SLAVE.
<b>I2C_Slave</b>	Demonstrate how to set I2C in Slave mode to receive the data of a Master. This sample code needs to work with I2C_MASTER.
<b>I2C_SMBus</b>	Demonstrate how to control I2C SMBus and use SMBus protocol between Host and Slave.
<b>I2C_Wakeup_Master</b>	Demonstrate how to wake up MCU from power-down. This sample code needs to work with I2C_Wakeup_Slave.
<b>I2C_Wakeup_Slave</b>	Demonstrate how to set I2C to wake up MCU from Power-down mode. This sample code needs to work with I2C_Wakeup_Master.
<b>I2S_Master</b>	Demonstrate how I2S works in Master mode. This sample code needs to work with I2S_Slave.
<b>I2S_Slave</b>	Demonstrate how I2S works in Slave mode. This sample code needs to work with I2S_Master.
<b>PDMA</b>	Demonstrate how to use PDMA channel 2 to transfer data from memory to memory.
<b>PDMA_Scatter_Gather</b>	Demonstrate how to use PDMA channel 5 to transfer data from memory to memory by scatter-gather mode.
<b>PWM_Capture</b>	Demonstrate how to use PWM1 Channel 2 to capture the PWM1 Channel 0 waveform.
<b>PWM_DeadZone</b>	Demonstrate how to use PWM Dead Zone function.
<b>PWM_DoubleBuffer</b>	Demonstrate how to use PWM Double Buffer function to change duty cycle and period of output waveform.
<b>RTC_AlarmWakeup</b>	Demonstrate how to use RTC alarm interrupt event to wake up system.

<b>RTC_SpareRegisterRW</b>	Demonstrate how to access RTC spare registers.
<b>RTC_TimeAndTick</b>	Demonstrate how to get the current RTC data/time per tick.
<b>SC_ReadATR</b>	Demonstrate how to get smart card ATR data.
<b>SCUART_TxRx</b>	Demonstrate how to use smartcard interface UART mode to print "Hello World!"
<b>SPI_Loopback</b>	Demonstrate SPI master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSIO pin together. It will compare the received data with transmitted data.
<b>SPI_MasterMode</b>	Demonstrate how to communicate with an off-chip SPI slave device. This sample code needs to work with SPI_SlaveMode.
<b>SPI_PDMA_LoopTest</b>	Demonstrate SPI data transfer with PDMA. SPI0 will be configured as Master mode and SPI1 will be configured as Slave mode. Both TX PDMA function and RX PDMA function will be enabled.
<b>SPI_SlaveMode</b>	Demonstrate how to communicate with an off-chip SPI master device. This sample code needs to work with SPI_MasterMode.
<b>SYS_BODWakeup</b>	Demonstrate how to wake up system form Power-down mode by brown-out detector interrupt.
<b>SYS_PLLClockOutput</b>	Demonstrate how to change system clock to different PLL frequency and output system clock from CLKO pin.
<b>TIMER_CaptureCounter</b>	Demonstrate how to use the timer2 capture event to capture timer2 counter value.
<b>TIMER_EventCounter</b>	Demonstrate how to use timer2 counter input function to count the input event.
<b>TIMER_PeriodicINT</b>	Demonstrate how to perform timer counting in Periodic mode.
<b>TIMER_TimeoutWakeup</b>	Demonstrate how to use timer0 periodic timeout interrupt

	event to wake up system.
<b>UART_AutoBaudRate_Master</b>	Demonstrate how to use auto baud rate detection function. This sample code needs to work with UART_AutoBaudRate_Slave.
<b>UART_AutoBaudRate_Slave</b>	Demonstrate how to use auto baud rate detection function. This sample code needs to work with UART_AutoBaudRate_Master.
<b>UART_Autoflow_Master</b>	Demonstrate how to transmit and receive data with auto flow control. This sample code needs to work with UART_Autoflow_Slave.
<b>UART_Autoflow_Slave</b>	Demonstrate how to transmit and receive data with auto flow control. This sample code needs to work with UART_Autoflow_Master.
<b>UART_IrDA_Master</b>	Demonstrate how to transmit and receive data in UART IrDA mode. This sample code needs to work with UART_IrDA_Slave.
<b>UART_IrDA_Slave</b>	Demonstrate how to transmit and receive data in UART IrDA mode. This sample code needs to work with UART_IrDA_Master.
<b>UART_LIN</b>	Demonstrate how to transmit LIN header and response.
<b>UART_RS485_Master</b>	Demonstrate how to transmit and receive data in UART RS485 mode. This sample code needs to work with UART_RS485_Slave.
<b>UART_RS485_Slave</b>	Demonstrate how to transmit and receive data in UART RS485 mode. This sample code needs to work with UART_RS485_Master.
<b>UART_TxRxFunction</b>	Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.
<b>UART_Wakeup</b>	Demonstrate how to wake up system from Power-down mode by UART interrupt.
<b>WDT_TimeoutWakeupAndReset</b>	Demonstrate how to use WDT time-out interrupt event to



	wake up system and generate time-out reset system event while WDT time-out reset delay period expired.
<b>WWDT_CompareINT</b>	Select one WWDT window compare value to generate window compare match interrupt event.

1. Analog Comparator (ACMP).

### **\SampleCode\StdDriver**

<b>ACMP</b>	Demonstrate how ACMP works with internal band-gap voltage.
<b>ACMP_Wakeup</b>	Demonstrate how to wake up from Power-down mode by ACMP wake-up function.
<b>CAN_BasicMode_Receive</b>	Demonstrate how to receive message in Basic mode. This sample code needs to work with CAN_BasicMode_Transmit.
<b>CAN_BasicMode_Transmit</b>	Demonstrate how to transmit message in Basic mode. This sample code needs to work with CAN_BasicMode_Receive.
<b>CAN_NormalMode_Receive</b>	Demonstrate how to receive message in Normal mode. This sample code needs to work with CAN_NormalMode_Transmit.
<b>CAN_NormalMode_Transmit</b>	Demonstrate how to transmit message in Normal mode. This sample code needs to work with CAN_NormalMode_Receive.
<b>CAN_Wakeup</b>	Demonstrate how to wake up system form Power-down mode by detecting a transition.
<b>CLK_ClockDetector</b>	Demonstrate how to use clock fail detector and clock frequency monitor function.
<b>CRC_CCITT</b>	Perform CRC-CCITT operation and get the CRC checksum result.
<b>CRC_CRC8</b>	Perform CRC-8 operation and get the CRC checksum result.
<b>DAC_PWMTrigger</b>	Demonstrate how to trigger DAC by PWM.

<b>DAC_SoftwareTrigger</b>	Demonstrate how to trigger DAC conversion by software method.
<b>DAC_TimerTrigger</b>	Demonstrate how to trigger DAC by timer.
<b>DSP_FFT</b>	Demonstrate how to call ARM CMSIS DSP library to calculate FFT.
<b>EADC_ADINT_Trigger</b>	Demonstrate how to use ADINT interrupt to do the ADC continuous scan conversion.
<b>EADC_PWM_Trigger</b>	Demonstrate how to trigger ADC by PWM.
<b>EADC_ResultMonitor</b>	Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.
<b>EADC_SWTRG_Trigger</b>	Demonstrate how to trigger ADC by writing EADC_SWTRG register.
<b>EADC_Timer_Trigger</b>	Demonstrate how to trigger ADC by timer.
<b>EBI_NOR</b>	Demonstrate how to access MX29LV320T (NOR Flash) through EBI bus.
<b>EBI_SRAM</b>	Demonstrate how to access BS616LV4017 (SRAM) through EBI bus.
<b>FMC_ExecInSRAM</b>	Demonstrate how to execute code in SRAM and program embedded Flash. (Support KEIL® MDK Only)
<b>FMC_IAP</b>	Demonstrate how to reboot to LDROM functions from APROM. This sample code set VECMAP to LDROM and reset to re-boot to LDROM.
<b>FMC_RW</b>	Demonstrate how to read/program embedded flash by ISP function.
<b>GPIO_EINTAndDebounce</b>	Demonstrate how to use GPIO external interrupt function and de-bounce function.
<b>GPIO_INT</b>	Demonstrate how to use GPIO interrupt function.
<b>GPIO_OutputInput</b>	Demonstrate how to set GPIO pin mode and use pin data

	input/output control.
<b>GPIO_PowerDown</b>	Demonstrate how to wake up system form Power-down mode by GPIO interrupt.
<b>I2C_EEPROM</b>	Demonstrate how to access EEPROM by I2C interface.
<b>I2C_GCMode_Master</b>	Demonstrate how a Master uses I2C address 0x0 to write data to I2C Slave. This sample code needs to work with I2C_GCMode_SLAVE.
<b>I2C_GCMode_Slave</b>	Demonstrate how to receive Master data in GC (General Call) mode. This sample code needs to work with I2C_GCMode_MASTER.
<b>I2C_Master</b>	Demonstrate how a Master access Slave. This sample code needs to work with I2C_SLAVE.
<b>I2C_Slave</b>	Demonstrate how to set I2C in Slave mode to receive the data of a Master. This sample code needs to work with I2C_MASTER.
<b>I2C_SMBus</b>	Demonstrate how to control I2C SMBus and use SMBus protocol between Host and Slave.
<b>I2C_Wakeup_Master</b>	Demonstrate how to wake up MCU from power-down. This sample code needs to work with I2C_Wakeup_Slave.
<b>I2C_Wakeup_Slave</b>	Demonstrate how to set I2C to wake up MCU from power-down mode. This sample code needs to work with I2C_Wakeup_Master.
<b>I2S_Master</b>	Demonstrate how I2S works in Master mode. This sample code needs to work with I2S_Slave.
<b>I2S_Slave</b>	Demonstrate how I2S works in Slave mode. This sample code needs to work with I2S_Master.
<b>PDMA</b>	Demonstrate how to use PDMA channel 2 to transfer data from memory to memory.
<b>PDMA_Scatter_Gather</b>	Demonstrate how to use PDMA channel 5 to transfer data from memory to memory by scatter-gather mode.

<b>PWM_Capture</b>	Demonstrate how to use PWM1 Channel 2 to capture the PWM1 Channel 0 waveform.
<b>PWM_DeadZone</b>	Demonstrate how to use PWM Dead Zone function.
<b>PWM_DoubleBuffer</b>	Demonstrate how to use PWM Double Buffer function to change duty cycle and period of output waveform.
<b>RTC_AlarmWakeup</b>	Demonstrate how to use RTC alarm interrupt event to wake up system.
<b>RTC_SpareRegisterRW</b>	Demonstrate how to access RTC spare registers.
<b>RTC_TimeAndTick</b>	Demonstrate how to get the current RTC data/time per tick.
<b>SC_ReadATR</b>	Demonstrate how to get smart card ATR data.
<b>SCUART_TxRx</b>	Demonstrate how to use smartcard interface UART mode to print "Hello World!"
<b>SPI_Loopback</b>	Demonstrate SPI master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSI0 pin together. It will compare the received data with transmitted data.
<b>SPI_MasterMode</b>	Demonstrate how to communicate with an off-chip SPI slave device. Needs to work with SPI_SlaveMode sample code.
<b>SPI_PDMA_LoopTest</b>	Demonstrate SPI data transfer with PDMA. SPI0 will be configured as Master mode and SPI1 will be configured as Slave mode. Both TX PDMA function and RX PDMA function will be enabled.
<b>SPI_SlaveMode</b>	Demonstrate how to communicate with an off-chip SPI master device. This sample code needs to work with SPI_MasterMode.
<b>SYS_BODWakeup</b>	Demonstrate how to wake up system from Power-down mode by brown-out detector interrupt.
<b>SYS_PLLClockOutput</b>	Demonstrate how to change system clock to different PLL frequency and output system clock from CLK0 pin.

<b>TIMER_EventCounter</b>	Demonstrate how to use timer1 counter input function to count the input event.
<b>TIMER_CaptureCounter</b>	Demonstrate how to use the timer2 capture event to capture timer2 counter value.
<b>TIMER_Delay</b>	Demonstrate how to use timer0 to create a precise delay loop.
<b>TIMER_PeriodicINT</b>	Demonstrate how to perform timer counting in periodic mode.
<b>TIMER_TimeoutWakeup</b>	Demonstrate how to use timer0 periodic time-out interrupt event to wake up system.
<b>UART_AutoBaudRate_Master</b>	Demonstrate how to use auto baud rate detection function. This sample code needs to work with UART_AutoBaudRate_Slave.
<b>UART_AutoBaudRate_Slave</b>	Demonstrate how to use auto baud rate detection function. This sample code needs to work with UART_AutoBaudRate_Master.
<b>UART_Autoflow_Master</b>	Demonstrate how to transmit and receive data with auto flow control. This sample code needs to work with UART_Autoflow_Slave.
<b>UART_Autoflow_Slave</b>	Demonstrate how to transmit and receive data with auto flow control. This sample code needs to work with UART_Autoflow_Master.
<b>UART_IrDA_Master</b>	Demonstrate how to transmit and receive data in UART IrDA mode. This sample code needs to work with UART_IrDA_Slave.
<b>UART_IrDA_Slave</b>	Demonstrate how to transmit and receive data in UART IrDA mode. This sample code needs to work with UART_IrDA_Master.
<b>UART_LIN</b>	Demonstrate how to transmit LIN header and response.
<b>UART_RS485_Master</b>	Demonstrate how to transmit and receive data in UART RS485 mode. This sample code needs to work with

	UART_RS485_Slave.
<b>UART_RS485_Slave</b>	Demonstrate how to transmit and receive data in UART RS485 mode. This sample code needs to work with UART_RS485_Master.
<b>UART_TxRxFunction</b>	Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.
<b>UART_Wakeup</b>	Demonstrate how to wake up system form Power-down mode by UART interrupt.
<b>USBD_Audio_HID_NAU8822</b>	Demonstrate how to implement a USB audio class device with HID key. NAU8822 is used in this sample code to play the audio data from Host. It also supports to record data from NAU8822 to Host.
<b>USBD_Audio_NAU8822</b>	Demonstrate how to implement a USB audio class device. NAU8822 is used in this sample code to play the audio data from Host. It also supports to record data from NAU8822 to Host.
<b>USBD_HID_Keyboard</b>	Demonstrate how to implement a USB keyboard device. This sample code supports to use GPIO to simulate key input.
<b>USBD_HID_Mouse</b>	Demonstrate how to implement a USB mouse device. The mouse cursor will move automatically when this mouse device connecting to PC by USB.
<b>USBD_HID_Transfer</b>	Demonstrate how to transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with USB device.
<b>USBD_MassStorage_DataFlash</b>	Demonstrate how to implement a USB Mass-Storage. It uses embedded data flash as storage.
<b>USBD_VCOM</b>	Demonstrate how to implement a USB virtual com port device. It supports one virtual comport.
<b>USBH_HID</b>	Demonstrate how to implement a USB Host and recognize a HID device when device plug-in.

<b>USBH_UMAS</b>	Demonstrate how to implement a USB Host with a file system to read/write a file on USB Mass Storage.
<b>USBOTG_Dual_Role_UMAS</b>	Demonstrate how USB works as a dual role device. If it works as USB Host, it can access a mass storage device. If it works as USB Device, It acts as a mass storage device.
<b>WDT_TimeoutWakeupAndReset</b>	Demonstrate how to use WDT time-out interrupt event to wake up system and generate time-out reset system event while WDT time-out reset delay period expired.
<b>WWDT_CompareINT</b>	Select one WWDT window compare value to generate the window compare match interrupt event.

### Important Notice

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