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# Inferring social networks from physical interactions: a feasibility study

Social networks

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## Abstract

**Purpose** – The purpose of this paper is to present a prototype system that can be used to capture longitudinal socialising processes by recording people's encounters in space.

**Design/methodology/approach** – The paper presents the results of a longitudinal study, carried out with members of the public, which demonstrates the capabilities of the system.

**Findings** – The findings show that community structure can be inferred from physical interactions, and that different locations exhibit varying community structures.

**Originality/value** – The paper argues that such a system can usefully be deployed in environments where people interact and socialise, as a mechanism for inferring the underlying network structure of those people's relationships.

**Keywords** Social networks, Social interaction

**Paper type** Research paper

## 1. Introduction

Our society regenerates through people's movement and encounter (Hillier and Hanson, 1984). A vibrant and sustainable environment gives us the opportunity to meet new people and make new friends. Walking down the street and visiting a pub are opportunities for such encounters. Architecture theory maintains that people's movement, and subsequently encounter with others, is affected by the structure of space (Hillier and Hanson, 1984; Hillier *et al.*, 1987). Demonstrating a relationship between structure and movement has been achieved with some success (Hillier *et al.*, 1993). Although movement, at the aggregate level, is relatively easy to measure, the same is not true of encounters. Before the advent of mobile technology, it was extremely difficult, if not impossible, to measure and record a large number of individuals' encounters with others in the course of everyday life. In this paper, we describe how we made use of the Bluetooth technology, typically found in mobile devices, to record people's visiting patterns and encounters in space. We then show how these data can be analysed to give us an insight into the nature of people's encounter and their emergent social interactions.

In this paper, we argue that the deployment of pervasive technology in places where people interact can provide an insight in relation to these people's emerging relationships. Here we argue that the systematic capturing and analysis of the social processes within such environments can provide an improved understanding of the underlying nature of those interactions.

To demonstrate the type of data that can be obtained from public spaces, we present the results of a longitudinal study we carried out in the City of Bath, UK, involving



people who socialised in various locations across the city. Here we discuss how we were able to automatically capture and analyse data on people's encounters, and we present the results of our analysis. While the study has a number of limitations, nevertheless, it did take place in a real-world setting and, as such, provides useful insights into how pervasive technologies may be utilised in this context.

2. Pervasive technology for capturing social interactions

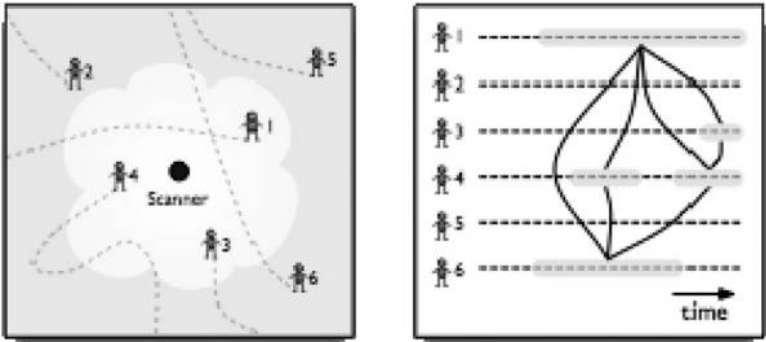
As part of our research, we prototyped a pervasive system that captures longitudinal socialising processes by recording and analysing people's encounters in space. To achieve this, we utilised the Bluetooth technology, typically found in mobile devices. Bluetooth technology has a characteristic that renders it appropriate for studying people's encounters. In contrast to the wireless signals emitted by typically static WiFi access points, the signals emitted by Bluetooth devices map very closely to the movements of people around the city, which in turn are a unique indicator of encounter and socialising. In a previous work, we found that approximately 7.5 percent of the observed pedestrians had discoverable Bluetooth devices (O'Neill *et al.*, 2006). This number most certainly varies between different cities, but still it shows that a considerable portion of the public was recorded using our method.

Our basic setup, replicated across four sites, involved installing a computer that constantly recorded the presence of nearby Bluetooth devices within a 10-m range (Figure 1). These data enable us to correlate pedestrian movements with Bluetooth device movements, providing baseline data about the penetration of Bluetooth into city life. On the right side of Figure 1, we see that for each unique device (i.e. person) we are able to capture sessions, defined as the points in time when each person was in close range of the scanner (indicated as yellow horizontal bars). Subsequently, we are able to detect encounters (indicated as links between the sessions), which we define as overlapping sessions. In other words, an encounter takes place when two people are in the same place at the same time.

In our study we considered four locations, which we shall refer to as:

- (1) campus;
- (2) street;
- (3) pub; and
- (4) office.

**Figure 1.**  
Left: At each scanning location, our computer uses Bluetooth to monitor the presence of mobile devices within an approximately 10-m radius. Right: Each recorded device is allocated its own timeline (dotted horizontal lines). Using the data from our scanners, we can plot each device's visit sessions (yellow bars). Overlapping sessions are identified and linked (solid lines), thus indicating encounters



The first two locations are outdoor pedestrian streets, one on our campus and the other in the city of Bath, both of which connect open spaces and can be thought of as pedestrian gateways. The latter two are indoor locations where visitors typically spend some time. The pub is open to anyone over the age of 18, while the office is a secure location to which only employees and their visitors have access.

We should point out that the nature of Bluetooth technology mitigates against extreme accuracy of location. The 10-m range of our Bluetooth scanner reached beyond walls, and adjacent offices. Effectively, if our scanner picks up a Bluetooth device, there is no way of knowing if that device was on the street, or in any of the offices. Despite this, on aggregate level we still get quite distinctive patterns of data between the first two and last two locations, as we describe in the following sections. This is because the great majority of devices our scanners picked up was indeed on the street (for the first two locations). During a six-month study of our prototype, we captured approximately 10,000 unique devices. In the following sections we describe in detail the data we captured and the analyses we carried out.

### 3. Data and analysis

The method we used to scan for Bluetooth devices generates discrete data about the presence of devices in the environment. To study the patterns of co-presence in our data, we first need to identify instances where two or more devices were present at the same place and at the same time. We developed filters that analysed our data and gave us instances of devices encountering each other at each of the four locations in our study. These initial results took the form of records: `<device1_id, device2_id, location>`.

At this stage in our analysis we had a long list of such records, describing which devices encountered each other and at which location. This list of encounters is a textual representation of the patterns of encounter across our four locations. To further study the patterns and structure hidden within this list, we transformed it into four social network graphs, one for each location. Assuming that each device from our data set represents a node in the social graph, the list of encounters indicates which nodes are connected. Proceeding in this manner, we generated four social network graphs, one for each location.

We found that most devices are linked to the main core, whilst some devices are islands. The latter indicates cases where a device was seen only by itself and never in the presence of others. One of our initial observations was that due to the sheer number of nodes in the graphs, the visualisations themselves helped little in analysing our data, due to visual clutter. However, by transforming our data into graph form, we were able to run a number of well-established analysis algorithms using existing software (e.g. Pajek, Ucinet). Specifically, we analysed each of our four graphs in terms of:

- degree centrality, calculated as the number of neighbours of each node;
- closeness centrality (access), calculated for any given node as the number of nodes (minus 1) divided by the sum of all distances between the node and every other node;
- betweenness centrality (control), calculated for any given node as the proportion of shortest paths between all pairs of nodes that include this node; and
- distance, calculated as the probability that the shortest path between a random pair of nodes will be 1, 2, 3, etc.

The degree and closeness centrality are measures of the reachability of a node within a network, and describe how easily information can reach a node. Betweenness centrality indicates the importance of a node, and the extent to which it is needed as a link in the chains of contacts that facilitate the spread of information within the network. Effectively, the centrality measures we focused on can indicate each individual's role, or potential, within the observed social structure.

#### 4. Results: capturing social processes

To gain an overview of the structural properties of the graphs representing encounter, we calculated the metrics shown in Table I. For each of our locations we calculated the number of unique devices that were recorded by our Bluetooth scanner, the size of the largest core in the encounter graphs, the number of edges in the largest core, the density of the largest core, as well as the size of the second largest core. We also calculated some generic centrality measures for each of the largest cores: network degree, closeness, and betweenness centralisation. Finally, we measured the maximum and average degree of each graph, the longest shortest-path distance in each of the graphs, as well as the average shortest-path distance.

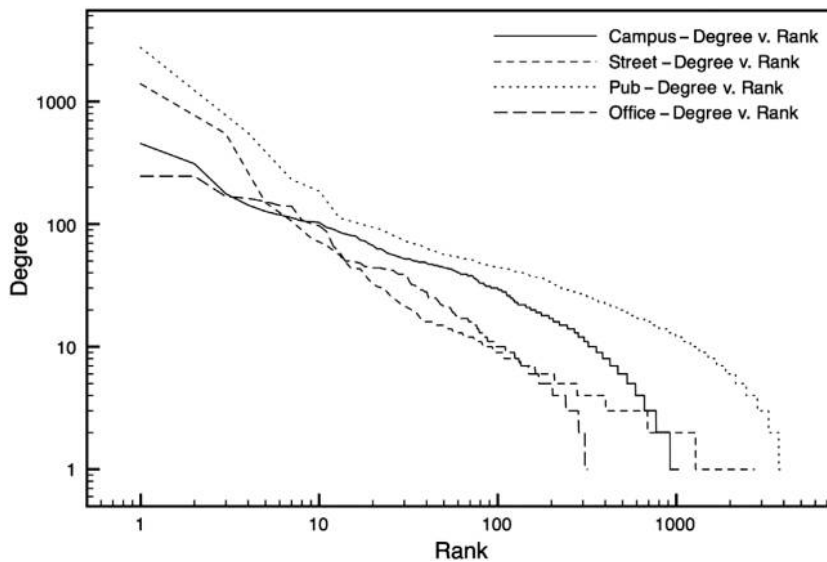
In addition to the above metrics, for each of the degree, closeness, and betweenness centrality measures, we generated ranked log-log plots. To do this, we attached a value (degree, closeness, or betweenness) to each node in the graphs (only the core) and then sorted this list in descending order. We then plotted the sorted lists, resulting in three sets of graphs (degree, closeness, betweenness) for each of our four gates. Additionally, we generated a fourth set of graphs, based on the probable distance between any randomly selected pair of nodes. These graphs are shown in Figures 2-5.

##### 4.1 Structural measures

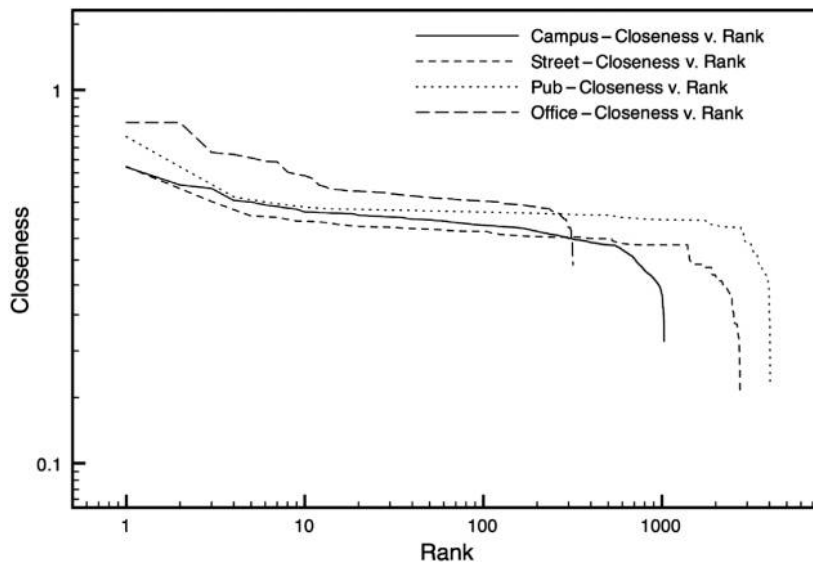
Our results indicate that the data captured by our prototype are far from random. On the contrary, across the four locations of our study we identified homogeneous patterns and comparable underlying temporal behaviour. To demonstrate this, here we focus our discussion on the various properties of the social graphs that we listed in Table I. The way in which we captured and analysed our data prohibits us from directly

	Campus	Street	Pub	Office
Unique devices	1,162	8,450	4,175	329
Largest core	1,028	2,738	4,036	318
Second largest core size	2	4	2	1
Edges in largest core	6,434	5,060	23,919	2,419
Density (%)	0.5	0.007	1.4	2.2
Network degree centralisation	0.43	0.51	0.68	0.73
Network closeness centralisation	0.49	0.55	0.66	0.65
Network betweenness centralisation	0.36	0.65	0.57	0.27
Maximum degree	454	1,394	2,758	246
Average degree	12.26	3.70	11.85	15.21
Maximum distance (diameter)	6	10	9	4
Average distance	2.72	2.96	2.44	2.04
Average clustering coefficient	0.50	0.32	0.68	0.82

**Table I.**  
Metrics for each of our  
four graphs



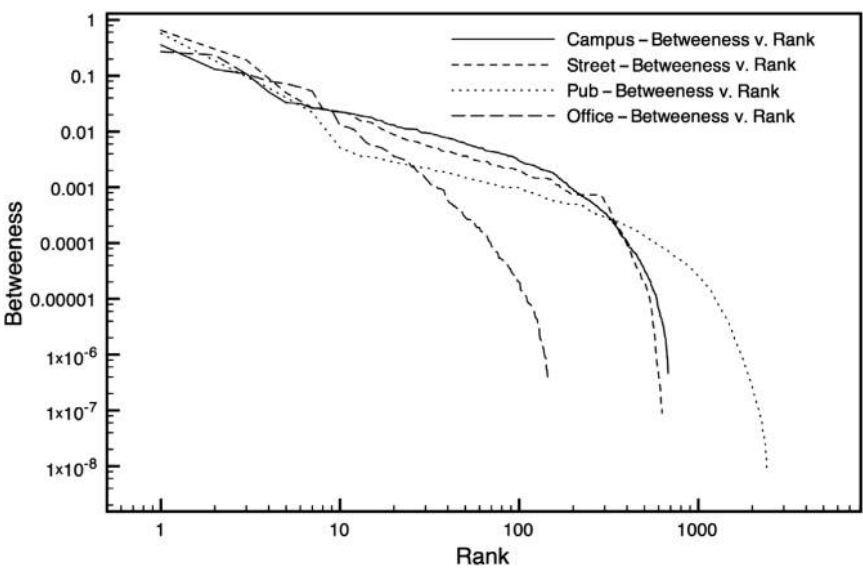
**Figure 2.**  
Ranked log-log plots  
of degree for each of our  
four locations



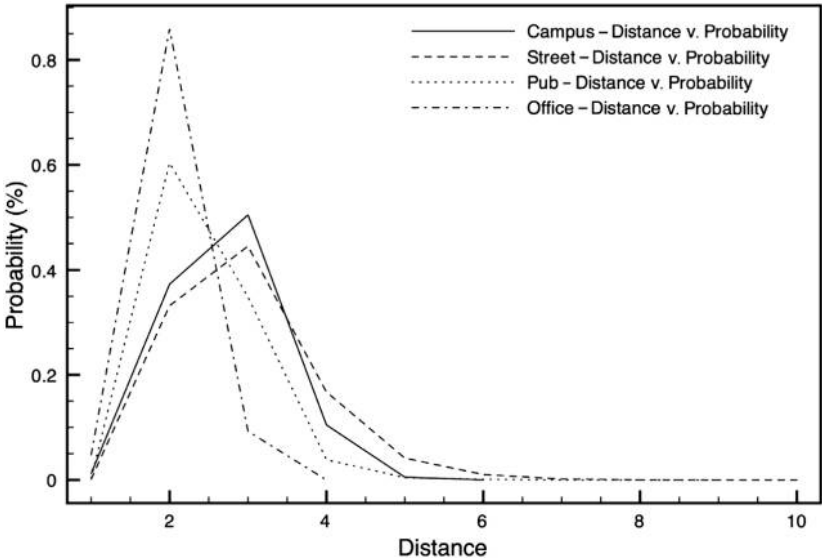
**Figure 3.**  
Ranked log-log plots  
of closeness for each of our  
four locations

inferring intelligence for each of the social networks. However, by comparing the properties of the social graphs across our four locations, we can begin to draw a picture of the communities that inhabit those locations. Also, it is important to keep in mind that in our observations of the four locations the only parameter we changed was the location itself: the hardware, software, and algorithms we used to derive our results are identical for all locations. Although it can be argued that our data are affected by a number of further variables, we consider those as part of the location and the environment.

**Figure 4.**  
Ranked log-log plots of  
betweenness for each of  
our four locations



**Figure 5.**  
Probability plots of the  
shortest path distance for  
each of our four locations



A notable feature of the graphs is their size. As we expected, the city street had the most “visitors”, followed by the pub, the campus, and the office. This is quite representative of the populations inhabiting each of the locations, since the street is open to everyone, thus being likely to get lots of distinct visitors. The pub is also open to everyone (over 18) and again has a large population of potential visitors. The campus, on the other hand, is mostly visited by students and staff, which amount to about 15,000 students and staff (while the population of Bath is about 86,000). Finally,



the office is a secure area where only employees have access, thus having a small population of potential visitors.

It is interesting to note, however, that the social network of the street consists of about two-thirds of islands, with the core consisting of about one-third of the devices. Looking at Table I, we see that the campus has a much higher density than the street. This indicates that there are more static devices on the campus, such as computers or employees' phones, which are likely to act as hubs that connect to the core those single devices that go past in the environment. This is something we can verify from Figure 2, where we see the street graph has a few well-connected hubs but then falls quite sharply, as opposed to the campus, where there are many more nodes with degree between 100 and 5.

It is interesting to note that both locations where the public can go, the street and the pub, have quite large max-degree (1,394 and 2,758), yet average degree is much smaller on the street than in the pub (3.70 and 11.85). In fact, in Figure 2 we see that the pub completely outperforms the street in terms of degree. This is due to the fact that most people in the pub are co-present; thus they get linked together. In other words, a visit to the pub can give someone much more opportunity for co-presence than a visit to the street. This is something we expect, as it is the primary purpose of a pub. Also, we should note that in the pub there are certain devices with extremely high degrees, which we believe are attributed to members of staff or regular customers. These act as central hubs that bring together all the customers of the pub into the central core of the social graph. The same is true in the office, where a number of devices have a relatively high degree, indicating that these people come in frequent contact with others.

#### 4.2 Network centrality measures

In general, the "tightness" of the communities varies across the four locations. Specifically, the office and the pub have shorter average distances between their members (2.04 and 2.44 in Table I, respectively), we also see in Figure 5 that the probability curves of these two locations are shifted to the left. This is further enhanced by the relatively high density of the pub and the office, which indicates more interactions between the members of the community.

Another interesting point to note is that although the pub has quite a tight and dense population, it has a large diameter (9), which is also true of the street (10). Yet, the pub has a smaller average distance (2.44) as opposed to the street (2.96). Coupled with the density measures, we can describe the pub's network as a large central core, while the street's network more closely resembles a small core with a number of branches and, additionally, a large number of islands.

Considering the network centralisation measures, we can make more inferences about the overall structure of the social networks. These measures range from 0 to 1 and indicate similarity to a perfect linear-shaped network (0) or to a perfect star-shaped network (1). This is calculated for each of degree (DC), closeness (CC), and betweenness (BC). The office scores high on DC and CC, indicating that some nodes can be reached more easily than others; yet BC is low, indicating that all nodes are more or less equally important in terms of control and communication. The opposite is true of the pub, where high DC and CC are coupled with high BC. This indicates that there are certain nodes in the pub that act as hubs of communication and control (most likely the members of staff or regular customers). Comparing the campus and street in terms of centralisation measures also yields interesting insights. Both have similar levels of DC and CC, but the



campus has low BC while the street has high BC. This indicates that on the street there are a few important nodes, while on the campus the nodes are more equal.

#### 4.3 Cumulative distribution measures

We now consider the graphs shown in Figures 2-5, which we found to be much more useful than a visualisation of the social networks themselves. A really interesting observation is that although in each of the four graphs the lines have similar shape, the subtle differences are crucial pointers to the effect of space on encounter. For instance, the variation in how sharply the values fall is a useful indicator, along with the overall steepness of the graphs.

When considering the whole range of values, degree graphs are overall more close to a power law distribution. Closeness graphs have short sharp tails, with a body that approximates a power law extremely well. Similarly, betweenness graphs have long sharp tails, while their body approximates a power law. The distance probability graphs can be approximated by a Poisson distribution.

The graphs we derived by analysing our Bluetooth data point to power-law distributions ( $\gamma \approx 0.6$ -1.1 for degree,  $\gamma \approx 1.2$ -1.4 for betweenness,  $\gamma \approx 0.1$  for closeness) that are characteristic of scale-free or self-similar networks. Such networks imply infinite variance, and usually in such networks there are a few nodes with an extremely large number of links. Barabási and Albert (1999) have dubbed such networks “scale-free”, by analogy with fractals, phase transitions and other situations where power laws arise and no single characteristic scale can be defined. These characteristics can be found in kinship networks, physical and biological systems, and economic systems.

Scale-free networks have stimulated a great deal of theorising. The earliest work is due to Simon (1955), independently rediscovered by Barabási and Albert (1999) and Barabási *et al.* (1999). They show that scale-free networks emerge automatically from a stochastic growth model in which new nodes are added continuously and attach themselves preferentially to existing nodes, with a probability proportional to the degree of the target node. Effectively, the richly connected nodes get richer. The stronger the continuity of a node within a given turf, the higher its visibility, and the greater the chances that this node will get more connected via new encounters.

We believe that our scanners recorded a phenomenon and process which is quite similar to the “rich getting richer” model, which explains the presence of power laws in our data. In terms of encounters, those people who have more links and encounters are the ones who are present more in the environment. When a new person comes along, chances are that they are going to encounter the regular customers or the employees. Thus, they share an encounter with an already well-connected person in the graph. It is this exact process that has been shown to result in power-law distributions.

## 5. Conclusion

Our analysis suggests that intricate social processes were captured by our prototype, given adequate time and a large-enough sample of people to be observed. Additionally, the underlying properties of our data suggest that our prototype did not capture noise, but somewhat of a “slice of reality”. Interpreting the numbers generated by our algorithms can yield insight, but doing so requires knowledge of the scanning locations and the people being observed in them. There are, however, a number of issues that need to be resolved before such a system can be utilised further.

To begin with, Bluetooth is only one possible technology that may be used for our purposes. Other proximity technologies such as RFID, NFC, and possibly ZigBee are

all potential candidates for such a system. In fact, RFID would be the preferred mechanism, as RFID tags can easily be embedded in clothes or any other items that people may carry. Key to the success of this scheme is the ability to relate each user to an individual or a set of RFID/Bluetooth identifiers. Ideally, these identifiers would persist for each individual across different locations.

In addition to establishing the technological components required to deploy our system, an appropriate infrastructure is necessary so that data generated by our system can be readily accessed and analysed by interested parties. This is most efficiently achieved by establishing a centralised data server, which will be used to store data arriving from various locations. Subsequently, queries can be issued to the data server to retrieve the necessary information.

In this paper, we describe our attempts to measure and quantify longitudinal socialising processes in four different locations. We present a study where four distinct locations were chosen for installing Bluetooth scanners which monitor the presence, and thus encounter, of people in those spaces. Our scanners generated a very rich data set that we used to derive social graphs for each of the four locations.

In our analysis, we focused on the derived social graphs, and were able to compare various well-established properties and measurements of social graphs across the four locations. We found that the graphs exhibit power-law distributions when plotting their properties in rank-ordered graphs. These are characteristic of scale-free networks that can be found in kinship networks, physical and biological systems, and economic systems.

As part of our ongoing work we are interested in exploring further our data sets. For example, we are interested in experimenting with different rules for generating the social graphs from the Bluetooth data. Also, we are in the process of running emulations of our data to explore ways in which information is diffused and spreads across the social networks.

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