

Overview of NoSQL in Big Data Management with a closer look on graph databases *

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ABSTRACT

This paper gives an introduction to Big Data Management and NoSQL. A special look is taken on Graph-Storage systems and an example comparison of three popular systems.

1. INTRODUCTION

The data growth in the last years was intense. Social Systems like Facebook, LinkedIn and Twitter produce more and more data each day. Also the widespread use of mobile devices and the Internet of Things contribute the extreme data growth. In 2012 over 2.8 zettabytes of data existed[4]. This new amount of data and the rate at which it is generated leads to new challenges for companies and their storage models. The challenges include how to store the data and how to analyze it. This trend is broadly described as Big Data. We will have a closer look on the it and the new data-storage systems that developed in the last years known as NoSQL systems. Because graphs are a natural structure for social media, we will introduce some of the most used graph databases and evaluate them. As the topic of big data is huge, we will not cover analyzation techniques like Map-Reduce and Bulk-Synchronous-Processing, although we recommend reading them up.

2. BIG DATA

The term Big Data was first used in 2001 by the consulting company McKinsey[2]. There is no general definition about the term Big Data, but there is a common agreement on some characteristics

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of Big Data. In general, the amount of data in Big Data scenarios is too much, as that it could be managed by traditional IT systems. In 2010, Apache Hadoop defined big data as "datasets which could not be captured, managed, and processed by general computers within an acceptable scope"[2]. This means that traditional relational database management systems have reached their limits.

There are different characterizations for Big Data. The most common ones are the "3-Vs"[3].

- Variety - describing the different data and data structures
- Velocity - the speed of data creation
- Volume - the amount of data

Often, Value is added as a fourth V.

The picture in Figure 1 illustrates very well the Velocity, Volume and Value of Big Data.

Traditionally, most of the data was stored in relational database management systems (RDBMS). They usually store structured data and are therefore not good in handling the point of variety. Because of the structured way and the integrity constraints in RDBMS, they do not scale very well horizontally, which makes them not good for storing large amounts of data. Because of this shortcomings, the NoSQL ("Not only SQL") family of databases developed, which tackle those challenges.

3. NOSQL OVERVIEW

"NoSQL" stands for "Not only SQL" and describes a broad family of database management systems. They tackle a variety of problems that were introduced by Big Data - mainly variety and volume. The aspect of volume is covered by enabling the databases to scale horizontally and reducing constraints by different approach to the CAP Theorem compared to RDBMS. The aspect of variety is covered by the wide range of different NoSQL systems. We will look at the CAP Theorem first as it can explain the horizontal scalability of NoSQL systems.

3.1 CAP-Theorem

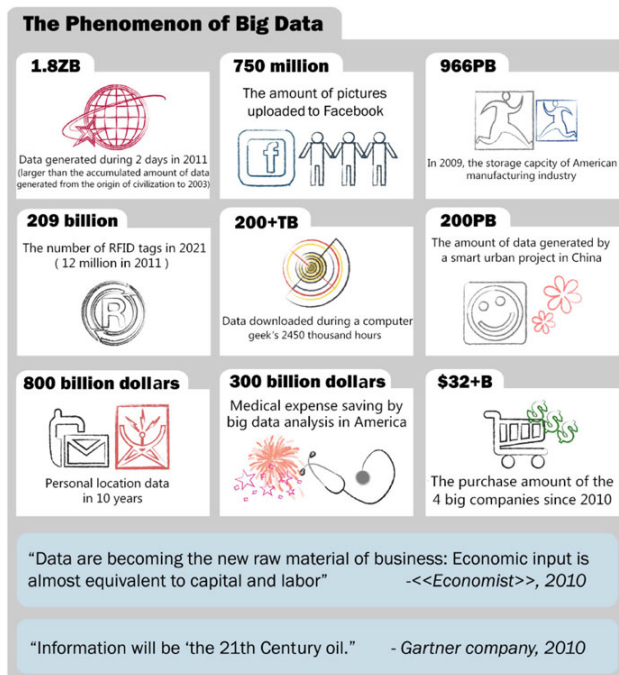


Figure 1: Phenomenon of Big Data, Source: Big Data - Related Technologies, Challenges and Future Prospects[2]

The CAP or Brewer Theorem[5] was formulated in 2000. The theorem states, that it is impossible for any data sharing system, to guarantee the following three properties all the time:

- Consistency**
 This means that all clients see the same data. In an environment with a huge amount of data, this is hard to achieve as it might be stored in different parts of the cluster.
- Availability**
 This means that the service responds to requests and is usable. To achieve this, the system must have some kind of fault tolerance to handle situations like servers going down. In our case with the amounts of data that Big Data is concerned with, multiple machines will be used for the system, even under heavy load and queries, the system should stay available.
- Partition tolerance**
 This means that the system can be partitioned and works good with this partitioning. The consequence of this is, that it can also partition the data.

Big Data is too big to be handled on a single machine or a small cluster. Therefore, partition tolerance is needed. Traditional RDBMS focus on the properties C and A, NoSQL systems vary if they focus on CP or on AP, but basically they are horizontally scalable. We will now see what kind of NoSQL databases exist.

3.2 Types of NoSQL systems

There are several different classifications of "NoSQL" databases. Most of them contain the following classes: Key-Value stores, Column-Stores, Document-Stores and Graph Databases. Other types like

Object-Oriented Databases and XML-Databases exist, but they will not be covered here. Also some databases do not fit very well in one category, as they take on aspects of other types as well. We have a short look on the basic characteristics of those types.

3.2.1 Key-Value Stores

The data model is simple. Each key is unique and it has an associated value. The storage has no knowledge about the value that is stored. Ad-Hoc query features and joins are usually omitted. They have very good scaling due to their easy lookup and storage model. A popular example is Amazon Dynamo DB, another ones are Apache Cassandra and BerkeleyDB[11].

3.2.2 Column-Stores

In RDBMS, the important unit is a row. Column-Stores, as the name implies, lay their focus on columns instead of rows. The columns are grouped together to a column-family. A row consists out of column-families which need to be predefined. Which columns are in a column-family is open, but they should relate to the family. For example, Address would be a column family containing the columns that represent the whole address. Columns of a column family are stored together, which makes it easier to retrieve those columns and process them together.

To achieve the performance needed, those databases normally allow temporary inconsistency. They usually store updates to data as a new version instead of updating the old one.

Popular examples of this type of storage are Google BigTable and Apache HBase. Apache Cassandra also is in this section as it is a hybrid system having prominent features of key-value and column-stores[11][7];

3.2.3 Document Stores

This kind of NoSQL Databases consider documents as their unit of information. A document can be seen like a record in a RDBMS, but they are schemaless. This gives them more flexibility and they do not include null values. Therefore those systems are very well suited systems that have unstructured data, so they tackle the issue of variety in Big Data. The documents are normally stored in JSON or XML. Usually, document stores are fully searchable. A typical element of a document store looks like this:

```

1 {
2   FirstName: "Jonathan",
3   Address: "15 Wanamassa Point Road",
4   Children: [
5     {Name: "Michael", Age: 10},
6     {Name: "Jennifer", Age: 8},
7     {Name: "Samantha", Age: 5},
8     {Name: "Elena", Age: 2}
9   ]
10 }
```

Prominent members for document stores are MongoDB and CouchDB. MongoDB also offers support for Hadoop, therefore suiting good for Map/Reduce applications. They both also provide good horizontal scaling. An example of a document store in the Big Data scenario was done in "Crime Analysis and Prediction Using Data Mining"[12]. They have utilized MongoDB to capture unstructured data from various resources like blogs, social media and RSS feed. Afterwards, they classified and analyzed the data to predict areas which have high crime rate.

3.3 Graph Databases

The dominant feature of graph databases is, that they represent their data in an actual graph. The importance here is on the relationship between the data. The nodes and edges can have properties, describing the node or the relationship between the nodes. Since the data is stored internally, they perform much better than relational databases on graphs. From all the data-models in the NoSQL family, the data model of graph-databases is the most complex and expressive one. When thinking of social media platforms like Facebook, Xing and LinkedIn, one can see very easily how it would feel natural to model the data as graphs. User in those systems represent nodes and the edges between them represent, if they are friends, for example.

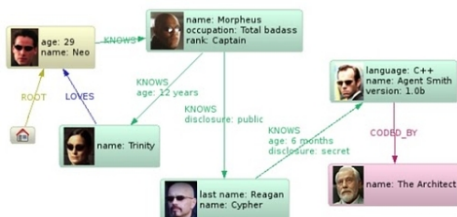


Figure 2: a social graph, Source: www.infoq.com/articles/graph-nosql-neo4j

Besides representing social-graphs, graph databases also have use in scientific computing. A request for databases optimized for graphs dates back to 1995 as they can represent genomes easier [6]. Another nice example for the use of graph databases is in the support of cloud management.

Yubin, Shanka, Byung-Hoon and Gosh used Neo4J, a popular graph database, to implement a large-scale healthcare system[13]. They compared its performance to the implementation with a MySQL version of the system. An interesting finding of theirs was, that the performance of Neo4J degrades with respect to the degree of a node, while in the MySQL case it degrades with respect to the overall size (see figure 3).

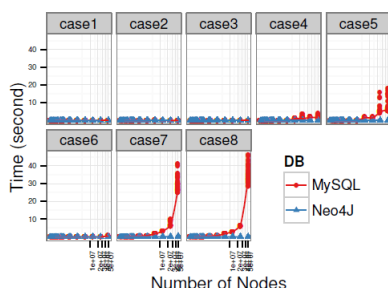


Figure 3: Data Size vs. Query Processing Time [add ref]

As those databases have the most expressive data-system, we will have a closer look on some of the available graph databases and compare them.

4. GRAPH DATABASE COMPARISON

We will now look at three graph databases, Neo4J, HyperGraphDB and Dex. A comparison between them was done by De Abreu et. al[1].

4.1 Neo4J

Neo4J is written in Java and was released in 2007. It is fully ACID compliant. The nodes and edges in the graph can have properties. Edges also have a type. A deep dive to the Neo4J architecture was done by Hongcheng Huang[8]. To access data, one has a wide variety of access methods. It is possible to query data via its native Java API, or to use SPARQL, which is normally used for RDF systems, Gremlin or Cypher. Below is an example for a cypher query finding all connections between node a and node b with three hops or less;

```
1 START a=node:indexName (name="A")
2 MATCH (a)-[*1..3]-(b)
3 WHERE b.node_type = "B"
4 RETURN distinct b;
```

4.2 HypergraphDB

HypergraphDB uses hypergraphs as a storage model. In hypergraphs, more edges correspond to a single hyperedge. Those hyperedges connect ordered sets of nodes. The HypergraphDB is built on top of the BerkeleyDB, a Key-Value Store. For accessing the data, a simple, but efficient querying API where data is loaded on demand with lazy join, bi-directional (whenever possible) cursors exists. Borislav Iordanov wrote a very detailed paper about HypergraphDB[9].

4.3 DEX / Sparksee

The name of DEX was changed in February 2014 to Sparksee. The storage model is a labeled and attributed multigraph. The edges between the nodes can be directed or undirected. In this kind of graph, every edge and node has a label representing the type. Each node and edge can also contain various attributes. Because of the multigraph structure, multiple edges are allowed between two nodes. The core engine of DEX was written in C++. A Java library with complete API access was also created. DEX does not offer a specific query language but instead relies on basic graph operations. The result of those operations are again graphs. Dex is described very well in "Dex: A high-performance graph database management system. Data Engineering Workshops"[10];

4.4 Performance

For comparison, De Abreu et. al used datasets representing road-networks that were used for the 9th DIMACS Implementation Challenge - Shortest Paths[1]. Interestingly, when initially loading the data, the HyperGraphDB timed out after 24-hours on one of the test-instances. They compared the performance on two basic graph search-operations: Depth-First-Search and Breadth-First-Search, running internally and externally. For external algorithms, they relied on adjacency functions of the APIs.

They also compared the performance for the following two use-cases: Densest-Subgraph and Graph-Summarization. Densest-Subgraph tries to look for a subgraph with the highest density. Graph-Summarization produces an aggregated graph of the initial graph where each node corresponds to a set of nodes and a single edge represent the set of edges between two node sets.

The core output is that Neo4J and DEX both outperform HyperGraphDB. Also Neo4J seems to have better performance on sparse graphs and DEX works better on dense graphs. This correlates with the finding of [13] where Neo4Js performance drops with the degree of nodes.

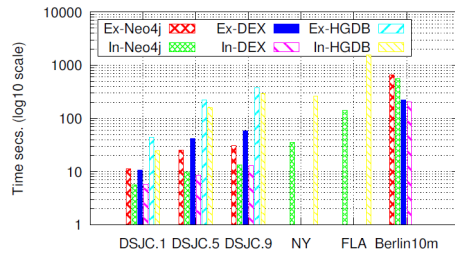


Figure 4: BFS performance, non-shown bars indicate that the corresponding engine timed out after 1 hour[1]

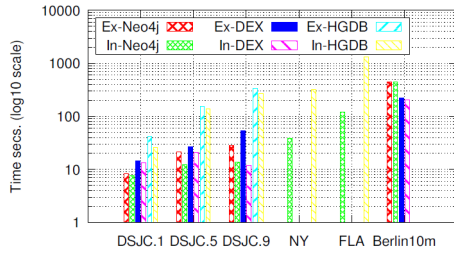


Figure 5: dfs performance, non-shown bars indicate that the corresponding engine timed out after 1 hour[1]

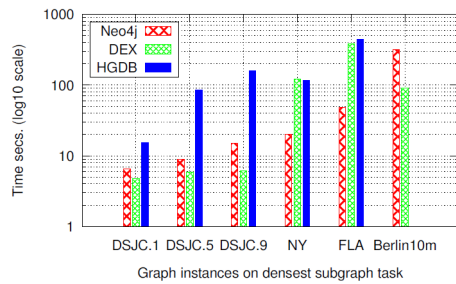


Figure 6: Denses Subgraph, non-shown bars indicate that the corresponding engine timed out after 1 hour[1]

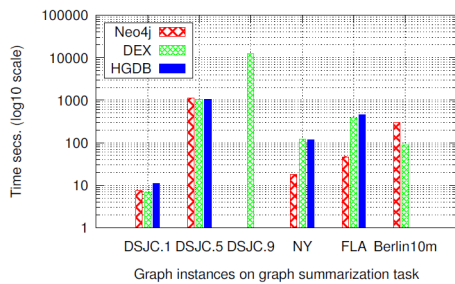


Figure 7: Graph Summarization performance, non-shown bars indicate that the corresponding engine timed out after 1 hour[1]

5. CONCLUSION

We have seen how Big Data changed the landscape for data-storage systems and how it gave birth to a whole new family of storage systems, broadly described as "NoSQL"-Systems. We have seen which properties they have in general and how they can be classified. At last, we took a closer look on Graph Database Management systems as graphs have widespread use. A closer comparison between Neo4J, DEX and Hypergraph showed us, that in this specialized field the performances can vary and one has to adapt to the given situation. We hope to see the spread of Graph Databases and the emerge of standardized bench-marks for comparing them.

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