Tactical Autonomous	1 Overview
Language-Operated	2 SMAX
Network	,
	3 Behavior trees
Noah Syrkis	4 Atomic functions

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IT University of Copenhagen
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- ▶ User interacts with system through the LLM...
- ... or directly while being advised by the LLM.

2 | SMAX

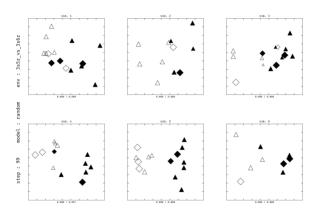


Figure 1: Running parallel SMAX environments

2 | SMAX (cont.)

- ► Trying to get SMAX [2] to work.
- ► SMAX is something something something
- Focus on unitcontrol (no buildings, resources, etc).

3 | Behavior trees

- ► Currently trying to get BT to work.
- ► LLM should make structured output.
- ► This output must be BT, following a grammar.

- ► Tools:
 - ▶ Overview by Lin [1]
 - ightharpoonup Grammar maker ^a.
 - ightharpoonup Pydantic b .

 $[^]a {\it https://grammar.intrinsiclabs.ai/} \\ ^b {\it https://github.com/pydantic/pydantic} \\ {\it dantic}$

3 | Behavior trees (cont.)

- ▶ BT output should follow a grammar.
- ► Military people like formal systems.
- ▶ BT should be formalized and validated.
- ▶ BT should be used for unit control and command issuing.
- ▶ Current approach is to represent behaviors trees as

4 | Atomic functions

- ► Manually written.
- ► Should written with genetic programming?

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|- LLM should output (or select) BT.

- BT should be used for unit control.

References

- Timothy Lin. Generating Structured Output from LLMs. https://www.timlrx.com/blog/generating-structured-outputfrom-llms, Nov. 2023.
- [2]Alexander Rutherford et al. JaxMARL: Multi-Agent RL Environments in JAX. Dec. 2023. DOI: 10.48550/arXiv.2311.10090. arXiv: 2311.10090 [cs].