

# C2SIM

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1 | Overview

2 | SMAX

3 | Behaviour trees

4 | Language model

# 1 | Overview

The project<sup>1</sup> uses JAX<sup>2</sup> throughout, with JaxMARL's<sup>3</sup> SMAX as the main environment. The agents are modelled using behaviour trees (BT) stored in a sqlite3 database (we call it BTBank). The ollama<sup>4</sup> library is used for the language modelling to map game states to human language and BTs, and vice versa.

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<sup>1</sup><https://github.com/syrkis/c2sim/>

<sup>2</sup><https://github.com/google/jax/>

<sup>3</sup><https://blog.foersterlab.com/jaxmarl/>

<sup>4</sup><https://ollama.com/>

## 1 | Overview (cont.)

- ☒ SMAX visual playback (`src/{plot,smax}.py`).
- ☒ BT function constructor (`src/{bt,atomics}.py`).
- ☐ BT based trajectory (`src/smax.py`).
- ☐ Implement the BTBank (`src/bank.py`).
- ☐ Language out (`src/llm.py`).
- ☐ Language in (`src/llm.py`).
- ☐ Smart way to generate atomics (genetic programming)?

## 2 | SMAX

- ▶ Extensive work on visual playback of trajectory fig. 1.
  - ⊗ Costum SMAX [1] vizualization.
  - ⊗ Show unit type, team, health, attacks, and reward.
  - ⊗ Successfully runnning 10K+ parallel environments.

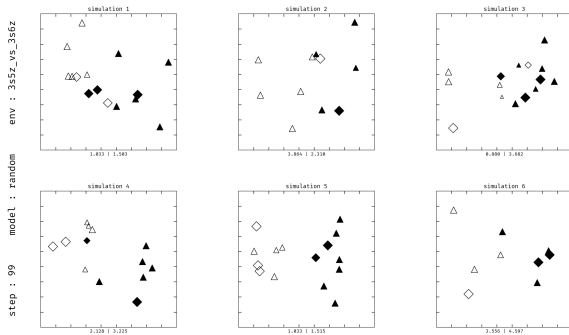


Figure 1: SMAX in parallel

## 2 | SMAX (cont.)

```
1 key = random.PRNGKey(0).split(num_envs)
2 env = make('SMAX', num_allies=n, num_enemies=m)
3 obs, state = vmap(env.reset)(key)
4 for _ in range(num_steps):
5     act = vmap(act_fn)(rng, env, obs, state)
6     obs, state, (_) = vmap(env.step)(act, state)
```

### 3 | Behaviour trees

- ▶ Behaviour trees (BT) are a way to model the behaviour of agents.
- ▶ They are used in games and robotics.

## 3 | Atomics

- ▶ Atomics are the leaves of the tree.
- ▶ They are the actions that the agent can take.



### 3 | BTBank

- ▶ BTBank is a library for creating and running BTs.
- ▶ It is written in Python.
- ▶ sqlite3 is used to store the trees.

## 4 | Language model

- ▶ The language model is a transformer model.
- ▶ I/O architecture.
- ▶ The output is a sequence of tokens.

## References

- [1] Alexander Rutherford et al. *JaxMARL: Multi-Agent RL Environments in JAX*. Dec. 2023. DOI: **10.48550/arXiv.2311.10090**. arXiv: 2311.10090 [cs].