

Mechanistic Interpretability on Irreducible Integer Identifiers

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1 | Mechanistic Interpretability (MI)

2 | Modular Arithmetic

3 | Grokking on $\mathcal{T}_{\text{miii}}$

4 | Embeddings

5 | Neurons

6 | The ω -Spike

“This disgusting pile of matrices is actually just an astoundingly poorly written, elegant and concise algorithm” – Neel Nanda¹

¹Not verbatim, but the gist of it

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- ▶ Sub-symbolic nature of deep learning obscures model mechanisms
- ▶ No obvious mapping from the weights of a trained model to math notation
- ▶ MI is about reverse engineering these models, and looking closely at them
- ▶ How does a given model work? How can we train it faster? Is it safe?

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$(0,0)$	$(1,0)$	$(2,0)$
$(0,1)$	$(1,1)$	$(2,1)$
$(0,2)$	$(1,2)$	$(2,2)$

Table 1: Table of (x_0, x_1) -tuples for $p = 3$

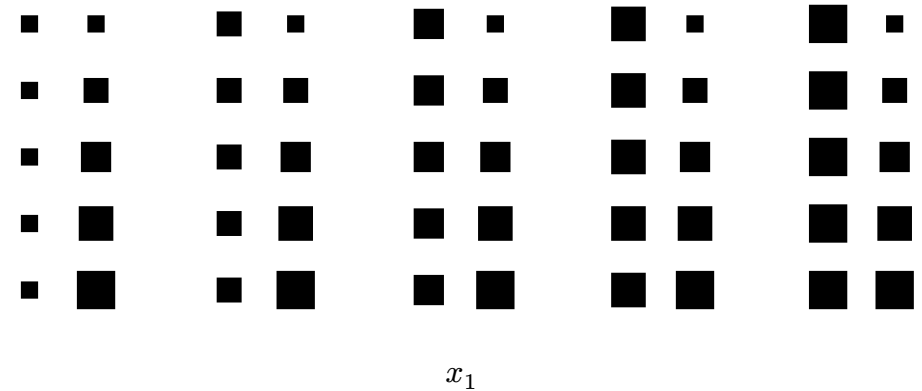


Figure 1: esch of (x_0, x_1) -tuples for $p = 5$

1 | Mechanistic Interpretability (MI)

► on y from $\mathcal{T}_{\text{nanda}}$

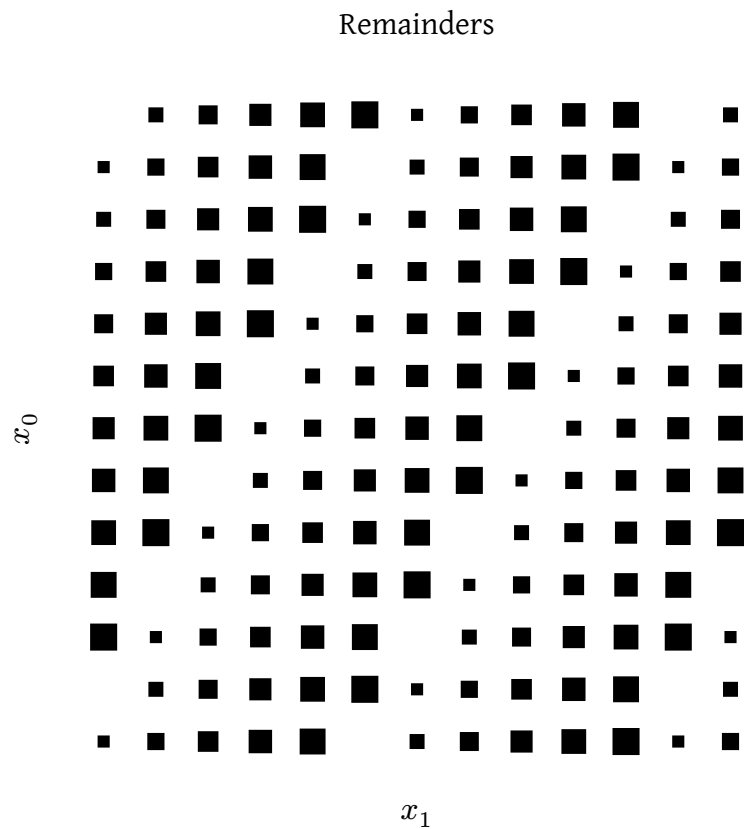


Figure 2: esch diagram of y from $\mathcal{T}_{\text{nanda}}$

1 | Mechanistic Interpretability (MI)

► Array

7	2	11	4	9	1	8	2	10	6	3	10	5
3	8	1	7	12	5	2	9	11	4	0	6	10
11	4	9	2	6	0	7	3	8	2	1	11	10
5	10	3	8	1	12	4	7	2	9	1	10	6
12	6	0	11	4	8	1	5	10	3	7	2	9
2	9	7	0	11	3	12	6	4	8	10	1	5
8	1	12	5	10	7	0	11	9	2	6	4	3
4	11	6	9	3	2	10	1	7	0	12	8	5
10	5	2	12	7	9	3	0	6	1	8	11	4
6	12	8	3	0	11	5	4	1	10	2	9	7
1	7	4	10	8	6	9	2	12	5	11	3	0
9	3	10	6	2	4	11	8	5	7	0	12	1
0	8	5	1	11	10	6	12	3	9	4	7	2

1 | Mechanistic Interpretability (MI)

- ▶ Are hard to see

1 | Mechanistic Interpretability (MI)

1. Make a task
2. Solve the task
3. Inspect the solution

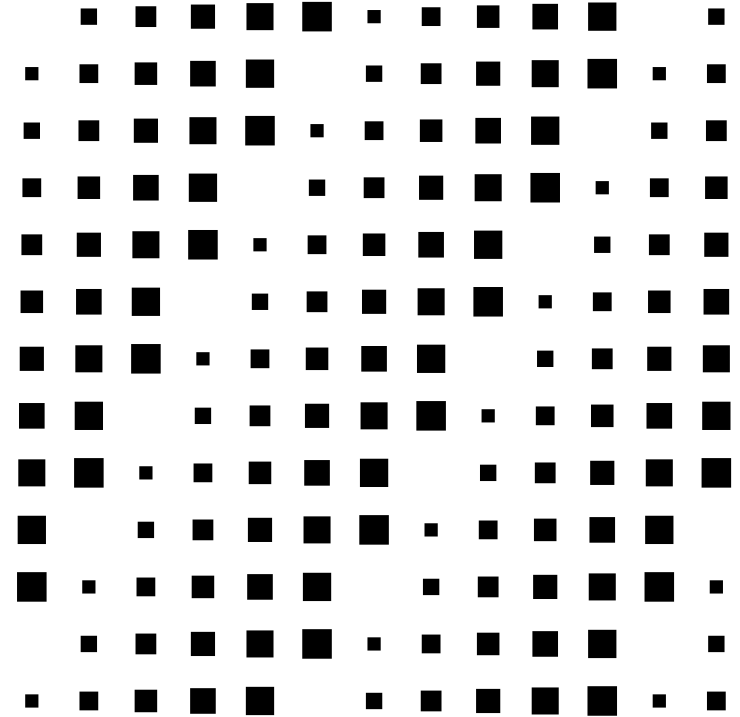


Figure 3: Target y for as x_0 and x_1 move from 0 to $p - 1$ for the task $x_0 + x_1 \bmod p = y$

1 | Mechanistic Interpretability (MI)

1. Make a task
 2. Solve the task
 3. Inspect the solution
- Think artificial neuroscience

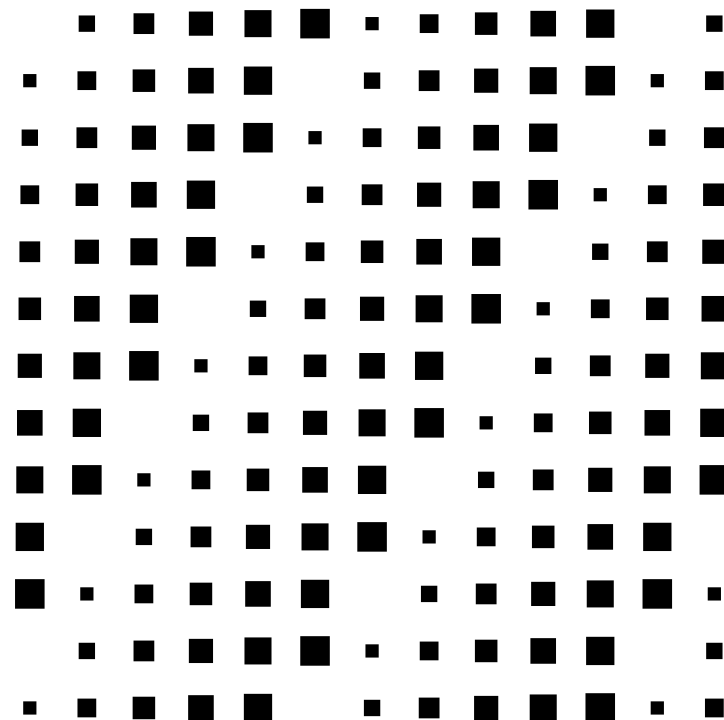


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$$p - 1 \text{ for the task } x_0 + x_1 \bmod p = y$$

1.1 | Grokking [1]

- Sudden generalization long after overfitting

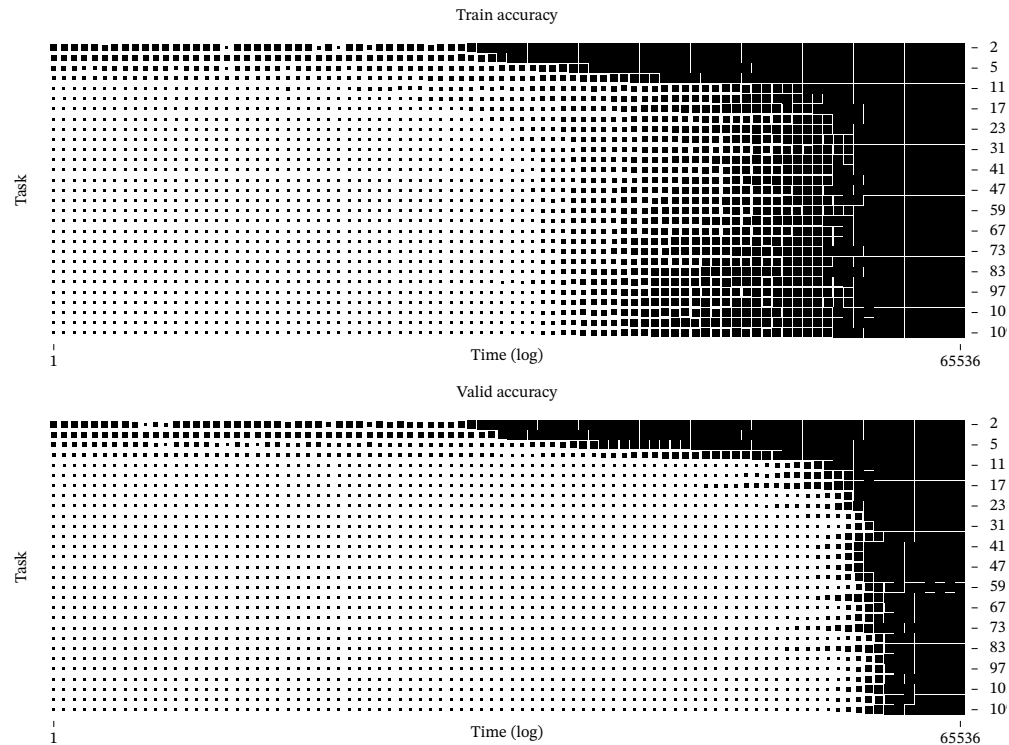


Figure 4: Example of the grokking

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- ▶ Sudden generalization long after overfitting
- ▶ MI (by definition) needs a mechanism

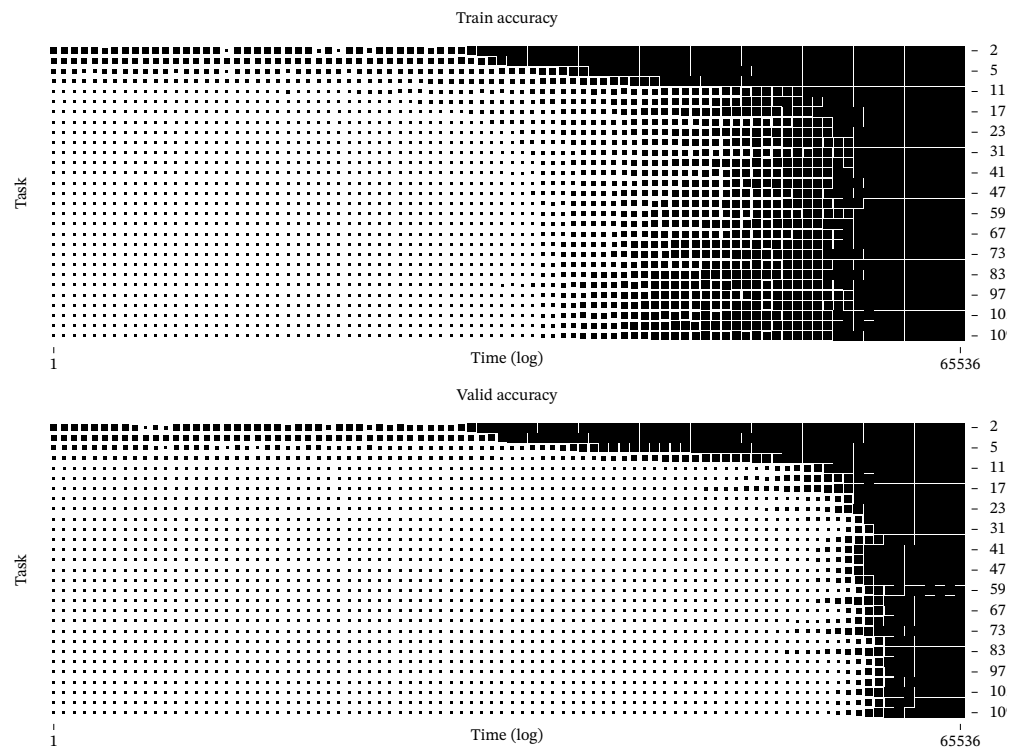


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1.1 | Grokking [1]

- ▶ Sudden generalization long after overfitting
- ▶ MI (by definition) needs a mechanism
- ▶ Grokking is thus convenient for MI

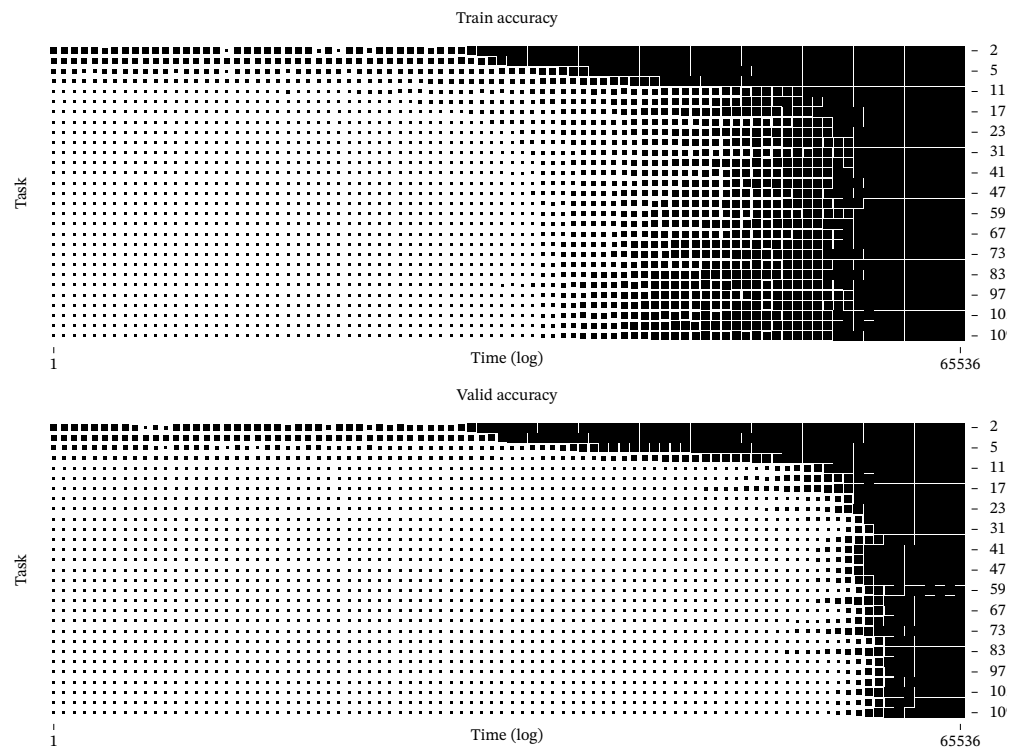


Figure 4: Example of the grokking

2 | Modular Arithmetic

- ▶ “Seminal” MI paper by Nanda et al. (2023)
focuses on modular addition ($\mathcal{T}_{\text{nanda}}$)
- ▶ Their final setup trains on $p = 113$
- ▶ They train a one-layer transformer
- ▶ We call their task $\mathcal{T}_{\text{nanda}}$

$$\mathcal{T}_{\text{nanda}} = (x_0 + x_1) \bmod p, \forall x_0, x_1 \quad (1.1)$$

$$\mathcal{T}_{\text{miii}} = (x_0 p^0 + x_1 p^1) \bmod q, \forall q < p \quad (1.2)$$

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2 | Modular Arithmetic

- ▶ $\mathcal{T}_{\text{miii}}$ is non-commutative ...
- ▶ ... and multi-task: q ranges from 2 to 109^1
- ▶ $\mathcal{T}_{\text{nanda}}$ use a single layer transformer
- ▶ Note that these tasks are synthetic and trivial to solve with conventional programming
- ▶ They are used in the MI literature to turn black boxes opaque

¹Largest prime less than $p = 113$

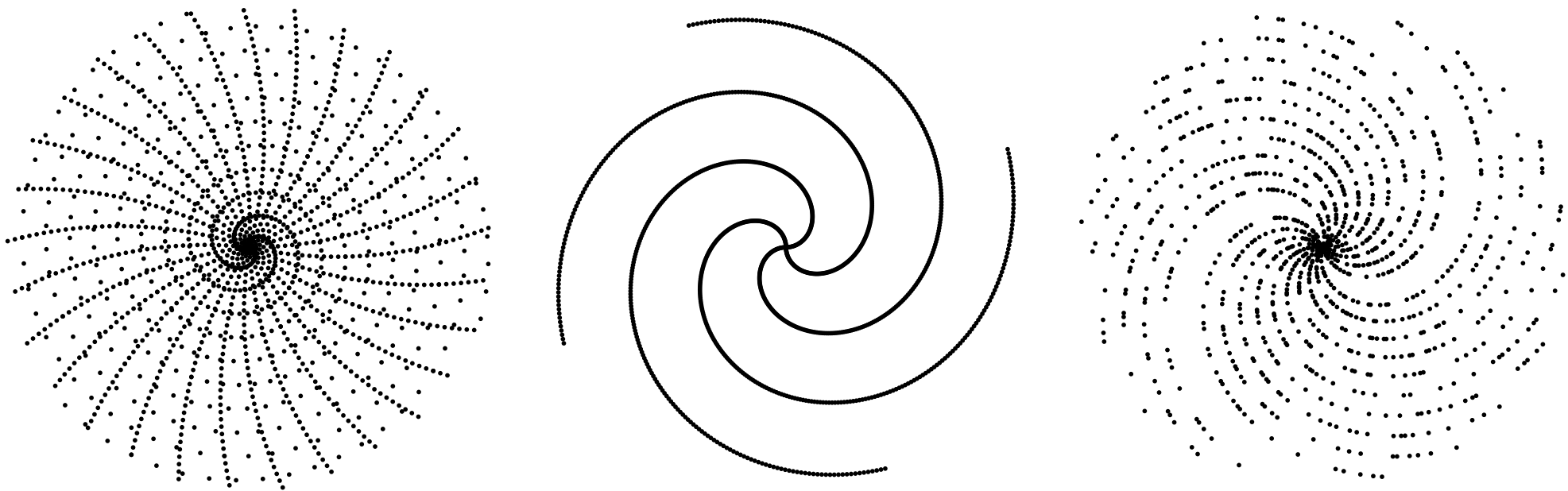


Figure 8: $\mathbb{N} < p^2$ multiples of 13 or 27 (left) 11 (mid.) or primes (right)

3 | Grokking on \mathcal{T}_{miii}

- ▶ For two-token samples, plot them varying one on each axis (Figure 9)
- ▶ When a matrix is periodic use Fourier
- ▶ Singular value decomposition

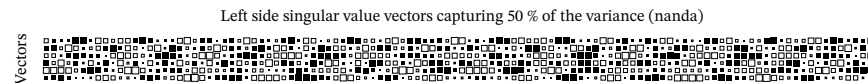


Figure 9: Top singular vectors of $\mathbf{U}_{W_{E_{\mathcal{T}_{nanda}}}}$ (top), varying x_0 and x_1 in sample (left) and freq. (right) space in $W_{\text{out}_{\mathcal{T}_{miii}}}$

3 | Grokking on \mathcal{T}_{miii}

- ▶ The model groks on \mathcal{T}_{miii} (Figure 10)
- ▶ Needed GrokFast [2] on compute budget
- ▶ Final hyperparams are seen in Table 6

rate	λ	wd	d	lr	heads
$\frac{1}{10}$	$\frac{1}{2}$	$\frac{1}{3}$	256	$\frac{3}{10^4}$	4

Table 6: Hyperparams for \mathcal{T}_{miii}

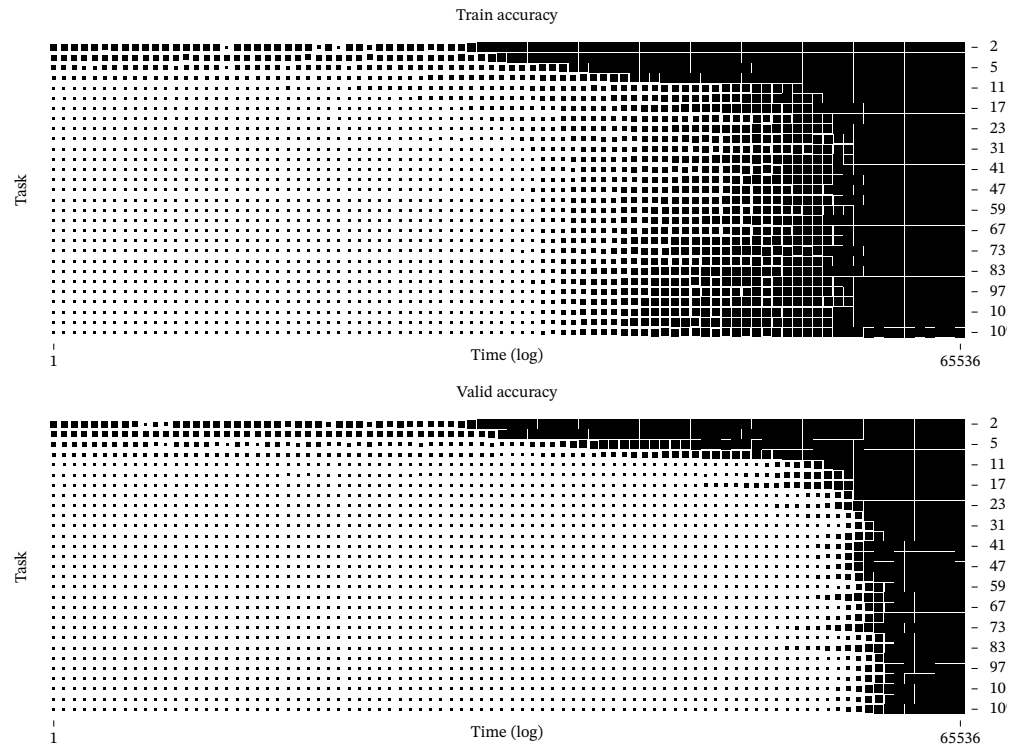


Figure 10: Training (top) and validation (bottom)
accuracy during training on \mathcal{T}_{miii}

4 | Embeddings

How the embedding layer deals with the difference between $\mathcal{T}_{\text{nanda}}$ and $\mathcal{T}_{\text{miii}}$

4.1 | Correcting for non-commutativity

- The position embs. of Figure 12 reflects that

$\mathcal{T}_{\text{nanda}}$ is commutative and $\mathcal{T}_{\text{miiii}}$ is not

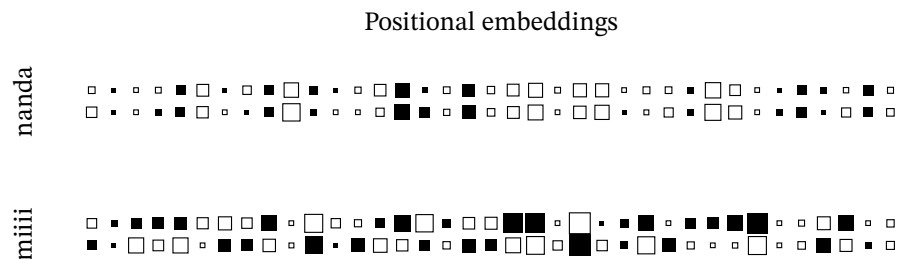


Figure 11: Positional embeddings for $\mathcal{T}_{\text{nanda}}$ (top) and $\mathcal{T}_{\text{miiii}}$ (bottom).

4.1 | Correcting for non-commutativity

- ▶ The position embs. of Figure 12 reflects that $\mathcal{T}_{\text{nanda}}$ is commutative and $\mathcal{T}_{\text{miiii}}$ is not
- ▶ Maybe: this corrects non-comm. of $\mathcal{T}_{\text{miiii}}$?
- ▶ Corr. is 0.95 for $\mathcal{T}_{\text{nanda}}$ and -0.64 for $\mathcal{T}_{\text{miiii}}$

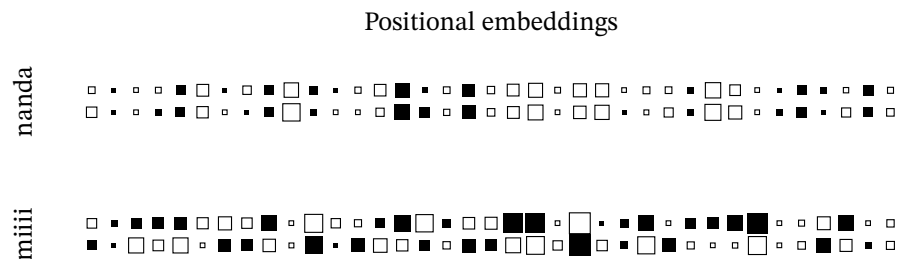


Figure 12: Positional embeddings for $\mathcal{T}_{\text{nanda}}$ (top) and $\mathcal{T}_{\text{miiii}}$ (bottom).

4.2 | Correcting for multi-tasking

- ▶ For $\mathcal{T}_{\text{nanda}}$ token embs. are essentially linear combinations of 5 frequencies (ω)
- ▶ For $\mathcal{T}_{\text{miii}}$ more frequencies are in play
- ▶ Each $\mathcal{T}_{\text{miii}}$ subtask targets unique prime
- ▶ Possibility: One basis per prime task

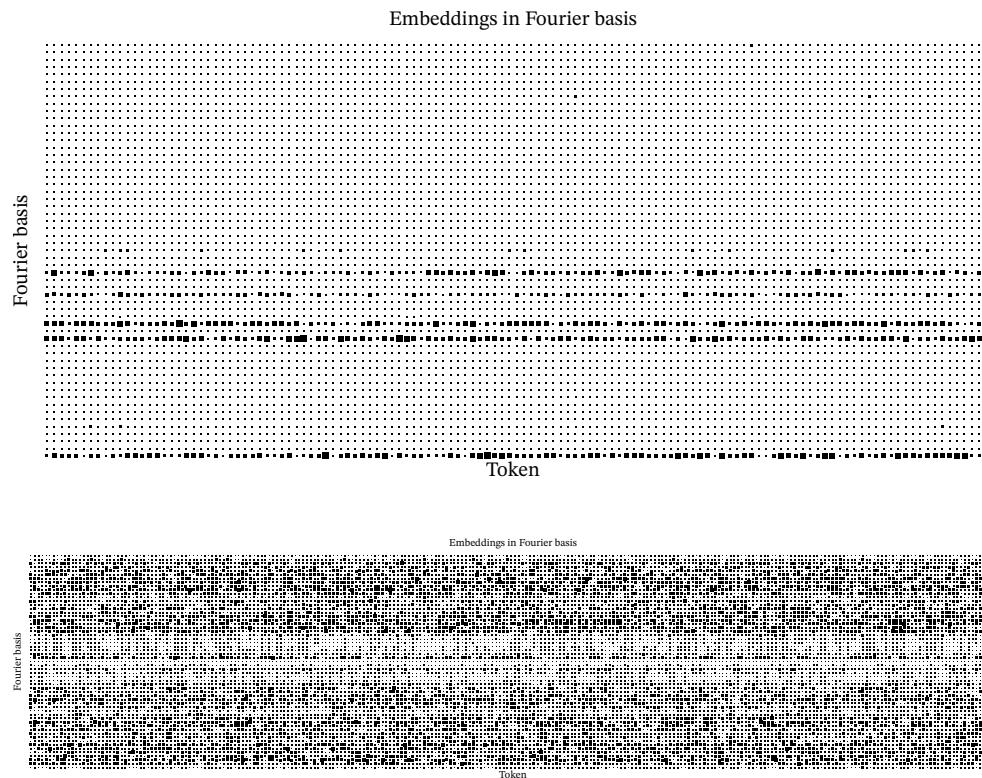


Figure 13: $\mathcal{T}_{\text{nanda}}$ (top) and $\mathcal{T}_{\text{miii}}$ (bottom) token embeddings in Fourier basis

4.3 | Sanity-check and task-mask

- ▶ Masking $q \in \{2, 3, 5, 7\}$ yields we see a slight decrease in token emb. freqs.
- ▶ Sanity check: $\mathcal{T}_{\text{baseline}}$ has no periodicity
- ▶ The tok. embs. encode a basis per subtask?



Figure 14: $\mathcal{T}_{\text{baseline}}$ (top), $\mathcal{T}_{\text{miii}}$ (middle) and $\mathcal{T}_{\text{masked}}$ (bottom) token embeddings in Fourier basis

5 | Neurons

- In spite of the dense Fourier basis of $W_{E_{\mathcal{T}_{miii}}}$ the periodicity is clear

figs/neurs_113_miii.svg
, caption: [Activations of first three neurons for $\mathcal{T}_{\text{nanda}}$ (top) and $\mathcal{T}_{\text{miii}}$ (bottom)],)

5 | Neurons

- ▶ (Probably redundant) sanity check: Figure 16 confirms neurons are periodic
- ▶ See some freqs. ω rise into significance
- ▶ Lets log $|\omega > \mu_\omega + 2\sigma_\omega|$ while training

Figure 16: FFT of Activations of first three neurons for $\mathcal{T}_{\text{nanda}}$ (top) and $\mathcal{T}_{\text{miii}}$ (bottom)

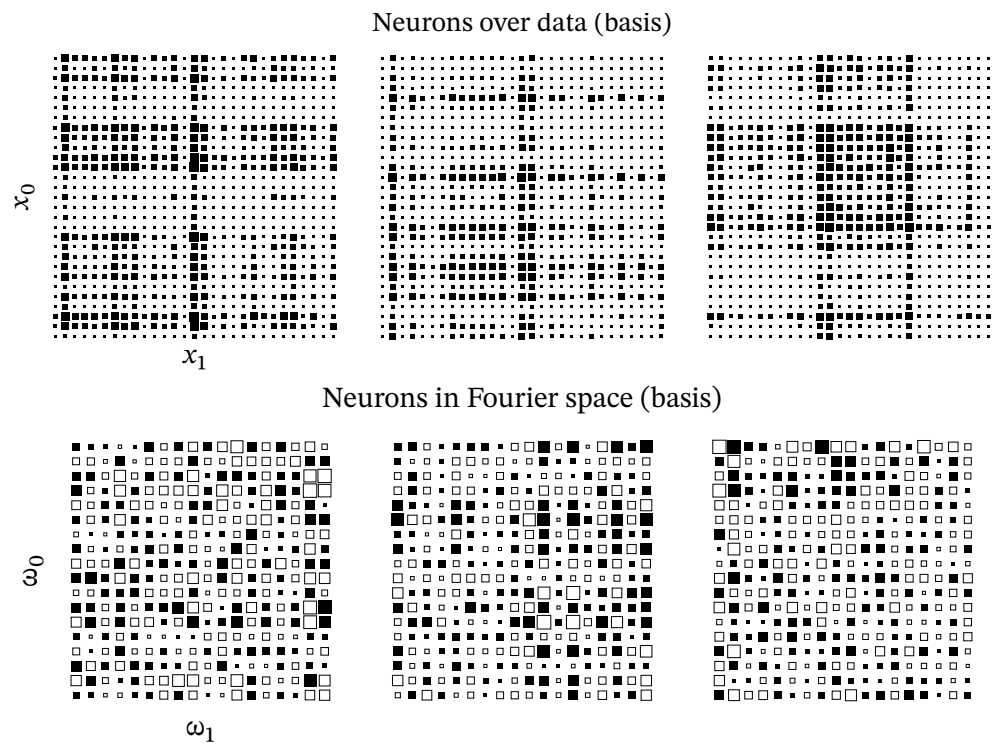


Figure 17: Neurons as archive for $\mathcal{T}_{\text{baseline}}$

Figure 18: Neurons as algorithm $\mathcal{T}_{\text{miii}}$

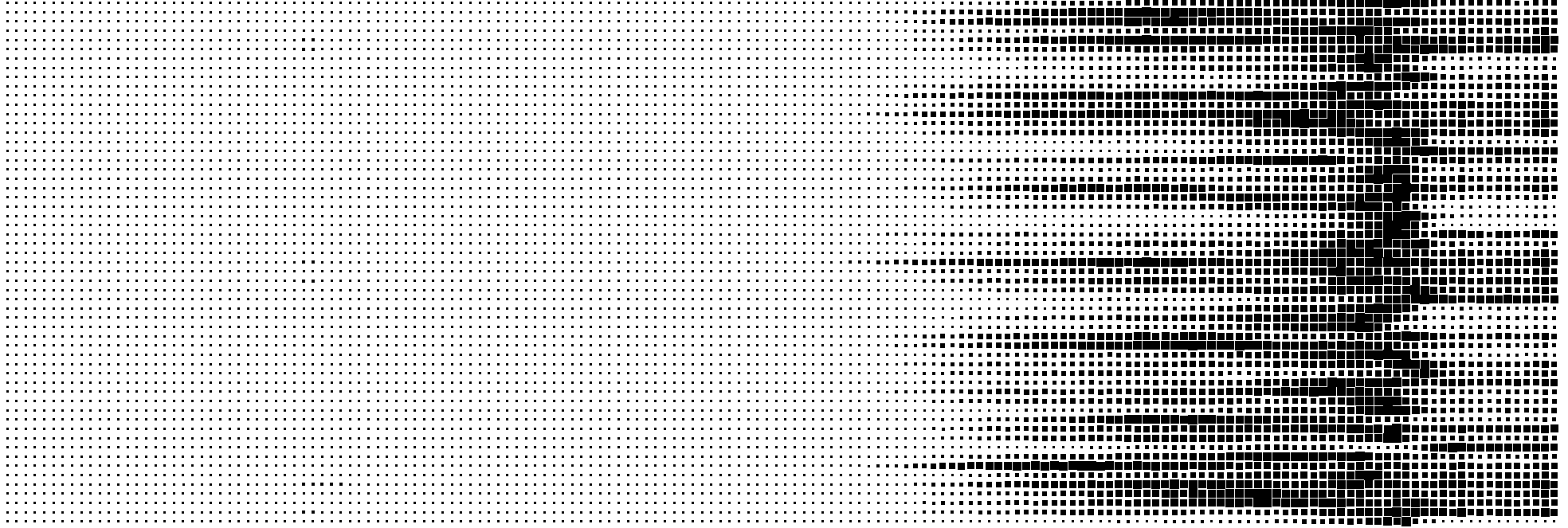


Figure 19: Number of neurons with frequency ω above the threshold $\mu_\omega + 2\sigma_\omega$

6 | The ω -Spike

- Neurs. periodic on solving $q \in \{2, 3, 5, 7\}$
- When we generalize to the remaining tasks, many frequencies activate (64-sample)
- Those ω 's are not useful for memory and not useful after generalization

time	256	1024	4096	16384	65536
$ \omega $	0	0	10	18	10

Table 7: active ω 's through training

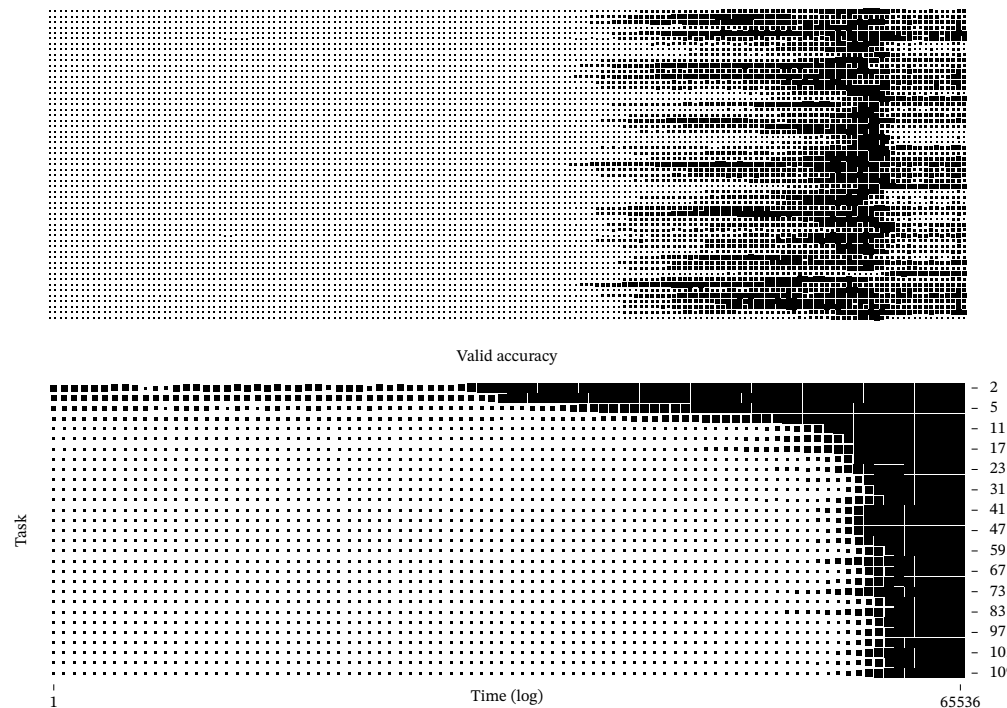


Figure 20: Figure 19 (top) and validation accuracy from Figure 10 (bottom)

6 | The ω -Spike

- ▶ GrokFast [2] shows time gradient sequences is (arguably) a stocastical signal with:
 - ▶ A fast varying overfitting component
 - ▶ A slow varying generealizing component
- ▶ My work confirms this to be true for $\mathcal{T}_{\text{miii}}$...
- ▶ ... and observes a strucutre that seems to fit neither of the two

6 | The ω -Spike

- ▶ Future work:
 - ▶ Modify GrokFast to assume a third stochastic component
 - ▶ Relate to signal processing literature
 - ▶ Can more depth make tok-embedding sparse?

References

- [1] N. Nanda, L. Chan, T. Lieberum, J. Smith, and J. Steinhardt, “Progress Measures for Grokking via Mechanistic Interpretability,” no. arXiv:2301.05217. arXiv, Oct. 2023.
- [2] J. Lee, B. G. Kang, K. Kim, and K. M. Lee, “Grokfast: Accelerated Grokking by Amplifying Slow Gradients,” no. arXiv:2405.20233. Jun. 2024.

A | Stochastic Signal Processing

We denote the weights of a model as θ . The gradient of θ with respect to our loss function at time t we denote $g(t)$. As we train the model, $g(t)$ varies, going up and down. This can be thought of as a stochastic signal. We can represent this signal with a Fourier basis. GrokFast posits that the slow varying frequencies contribute to grokking. Higher frequencies are then muted, and grokking is indeed accelerated.

B | Discrete Fourier Transform

Function can be expressed as a linear combination of cosine and sine waves. A similar thing can be done for data / vectors.

C | Singular Value Decomposition

An $n \times m$ matrix M can be represented as a $U\Sigma V^*$, where U is an $m \times m$ complex unitary matrix, Σ a rectangular $m \times n$ diagonal matrix (padded with zeros), and V an $n \times n$ complex unitary matrix. Multiplying by M can thus be viewed as first rotating in the m -space with U , then scaling by Σ and then rotating by V in the n -space.