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[10] // Author information:
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%model model1.xml
// -- Begin Antimony block converted from model1.xml
// Created by libAntimony v2.9.3
model *BorisEJB()
    // Compartments and Species:
    compartment compartment_;
    species MKKK in compartment_, MKKK_P in compartment_, MKK in compartment_;
    species MKK_P in compartment_, MKK_PP in compartment_, MAPK in compartment_;
    species MAPK_P in compartment_, MAPK_PP in compartment_;
    // Reactions:
    \label{eq:control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_control_co
    J1: MKKK_P => MKKK; J1_V2*MKKK_P/(J1_KK2 + MKKK_P);
    J2: MKK => MKK_P; J2_k3*MKKK_P*MKK/(J2_KK3 + MKK);
    J3: MKK_P => MKK_PP; J3_k4*MKKK_P*MKK_P/(J3_KK4 + MKK_P);
    J4: MKK_PP => MKK_P; J4_V5*MKK_PP/(J4_KK5 + MKK_PP);
    J5: MKK_P \Rightarrow MKK; J5_V6*MKK_P/(J5_KK6 + MKK_P);
    J6: MAPK => MAPK_P; J6_k7*MKK_PP*MAPK/(J6_KK7 + MAPK);
    J7: MAPK_P => MAPK_PP; J7_k8*MKK_PP*MAPK_P/(J7_KK8 + MAPK_P);
    J8: MAPK_PP => MAPK_P; J8_V9*MAPK_PP/(J8_KK9 + MAPK_PP);
    // Species initializations:
    MKKK = 90;
    MKKK_P = 10;
    MKK = 100;
    MKK_P = 10;
    MKK_PP = 10;
    MAPK = 100;
    MAPK_P = 10;
    MAPK_PP = 10;
    // Compartment initializations:
    compartment_ = 1;
    // Variable initializations:
    J0_V1 = 2.5;
    J0_{Ki} = 9;
    J0_n = 1;
    J0_K1 = 10;
    J1_V2 = 0.25;
    J1_KK2 = 8;
    J2_k3 = 0.025;
    J2_KK3 = 15;
    J3_k4 = 0.025;
    J3_KK4 = 15;
    J4_V5 = 0.75;
    J4_KK5 = 15;
    J5_V6 = 0.75;
    J5_KK6 = 15;
    J6_k7 = 0.025;
    J6_KK7 = 15;
    J7_k8 = 0.025;
    J7_KK8 = 15;
    J8_V9 = 0.5;
    J8_KK9 = 15;
    J9_V10 = 0.5;
    J9_KK10 = 15;
    // Other declarations:
    const compartment_, J0_V1, J0_Ki, J0_n, J0_K1, J1_V2, J1_KK2, J2_k3, J2_KK3;
    const J3_k4, J3_KK4, J4_V5, J4_KK5, J5_V6, J5_KK6, J6_k7, J6_KK7, J7_k8;
    const J7_KK8, J8_V9, J8_KK9, J9_V10, J9_KK10;
end
// -- End Antimony block
%tasks simresults.xml --master=True
// -- Begin PhraSEDML block converted from simresults.xml
// Created by libphrasedml v1.0.7
// Models
model1 = model "model1"
// Simulations
steady1 = simulate steadyState
steady1.algorithm = kisao.282
// Tasks
task0 = run steady1 on model1
// Repeated Tasks
task1 = repeat task2 for model1.J1_KK2 in [1, 5, 10, 50, 60, 70, 80, 90, 100]
task2 = repeat task0 for model1.J4_KK5 in uniform(1, 40, 100)
report "Steady State Values (Boris2D)" task1.J4_KK5, task1.J1_KK2, task1.MKK, task1.MKK_P
plot "Steady State Scan (Boris 2D)" task1.J4_KK5 vs task1.MKK, task1.MKK_P
// -- End PhraSEDML block
      task1.J4_KK5 task1.J1_KK2 task1.MKK task1.MKK_P
                   1.00
0
                                            1.0 33.465751
                                                                         64.942807
                                            1.0 34.607356
1
                   1.39
                                                                         63.784046
                                           1.0 35.750748 62.624230
2
                   1.78
                                           1.0 36.892899 61.466340
3
                   2.17
                                            1.0 38.030822
                   2.56
                                                                          60.313320
                                                   Steady State Scan (Boris 2D)
              80
                                                                                                                             task1.MKK
                                                                                                                              task1.MKK_P
              60
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