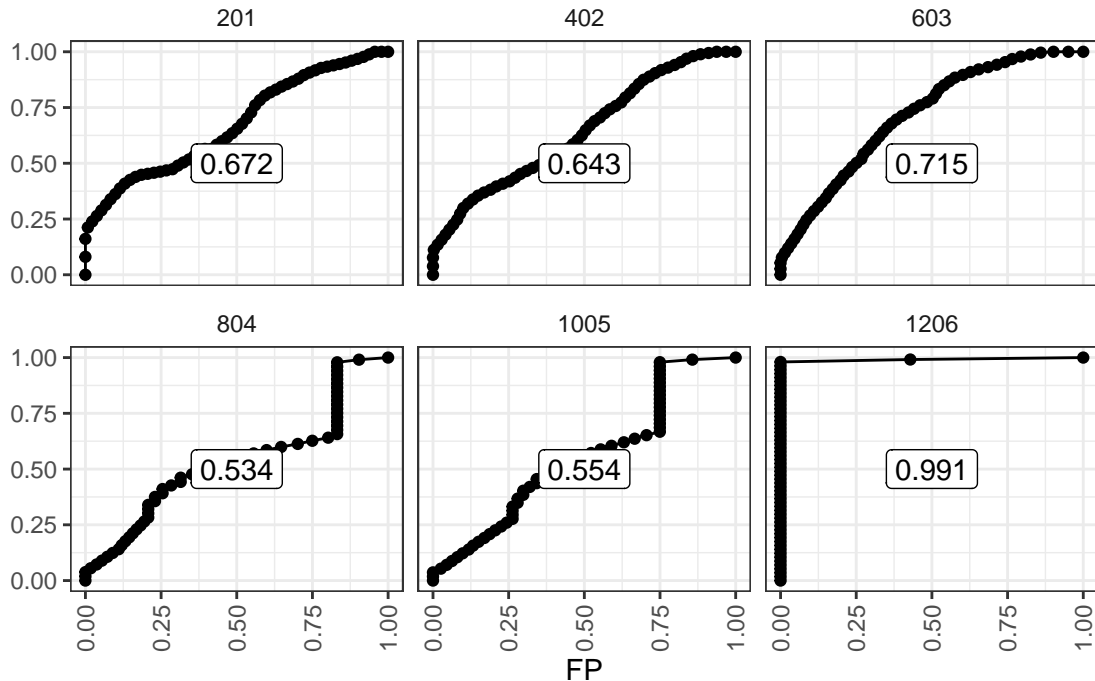


# Cumulative case/ Dynamic control ROC

TP



FP