

Linear System & Linear Transformation

Linear Equation

1. Linear equation is written as below:

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$

- coefficients: a_1, \dots, a_n

2. By using vector:

$$a^T x = b$$

Linear System

1. Linear system is a set of linear equations

- a. 주어진 여러 feature를 이용하여 최종 값 b 를 잘 예측하는 것이 목표 (= regression)

- b. solution

- i. use vector or matrix

- matrix A is a collection of the coefficients

- ii. use inverse matrix

- the solution is uniquely obtained

- iii. use non-invertible matrix

- the solution is infinite or not exist

2. Identity Matrix

- a. written as I_n

3. Inverse Matrix

- a. written as A^{-1}

- b. not all of the matrices have inverse matrix

- i. i.e., need a special condition to have an inverse matrix

$$AA^{-1} = A^{-1}A = I_n$$

- use determinant of A (= det A) such as $ad - bc$

ii. defined only for **square matrix**

Linear Combinations

1. Linear combination is written as below:

$$c_1v_1 + \dots + c_pv_p$$

- called a linear combination of v_1, \dots, v_p with weights or coefficients c_1, \dots, c_p

2. Solution of linear system

a. by matrix

$$Ax = b$$

b. by vector

$$a_1x_1 + a_2x_2 + a_3x_3 = b$$

- called a vector equation
- the solution exists only when b is contained in the span $\{a_1, a_2, a_3\}$

3. Span

a. Span $\{v_1, \dots, v_p\}$ is the set of all linear combinations of v_1, \dots, v_p

b. Span with different number of vectors

i. 2개의 벡터를 이용해서 span 되는 3차원 공간은 전체가 될 수 있음

ii. 3개의 벡터를 이용해서 span 되는 4차원 공간은 전체가 되기에는 살짝 무리가 있음

Linear Transformation

1. Definition

a. domain (정의역): X

b. co-domain (공역): Y

c. image (상): $y = f(x)$

i. preimage (원상): $x = f^{-1}(y)$

- d. range (치역): set of all images
- e. 화살표는 하나의 x 에 대하여 **한번만** 가능

2. Linear transformation

- a. Transformation (or mapping) T is linear if:

$$T(cu + dv) = cT(u) + dT(v)$$

- e.g., $y = 3x + 2$
- $(1, 2) \rightarrow 3 * 1 + 4 * 2 = 11 \rightarrow 3 * 11 + 2 = 35$
- $(1, 2) \rightarrow (5, 8) \rightarrow 3 * 5 + 4 * 8 = 47$
- 위 두 값이 다르기 때문에 선형변환이 아님

- b. Vector of linear transformation

- i. transform n-dimensional vector to m-dimensional vector

- c. Matrix of linear transformation

- i. written as a matrix-vector multiplication

$$T(x) = Ax, A = [T(e_1), \dots, T(e_n)]$$

- matrix A는 가장 단순한 기저벡터를 넣었을 때 나온 결과물의 집합

3. Neural networks [\[link\]](#)

- a. Affine layer (or frequent layer)

- i. fc layer usually involve a bias term
- ii. use linear transformation to deal with bias term

ONTO and ONE-TO-ONE

1. ONTO (전사)

- a. co-domain (공역) = range (치역)
- b. 어떠한 y 값에 대해서도 최소한 한 개 이상의 화살표를 받아야함
- c. NOT able to be ONTO
 - i. input dimension < output dimension
 - e.g., GAN, decoder

2. ONE-TO-ONE (일대일)

- a. 어떠한 y 값에 대해서도 화살표를 한 개만 받아야함
 - b. NOT able to be ONE-TO-ONE
 - i. input dimension > output dimension
 - c. ONE-TO-ONE = linearly independent
3. Neural networks
- a. ONE-TO-ONE
 - i. unique people mapped to the same (over weighted, tall and smoking)
 - ii. may have information loss
 - b. ONTO
 - i. (over weighted, tall and smoking) always exist