

arrives at $t = 0$

P_2 requirements

Bi	t/e	Core 1	Core 2
B1	t	7	3
	e	3	5
B2	t	3	2
	e	3	5

Thesis Research
Presentation for Huawei Technologies

Prog. P_2
arrives at $t = 1$

Application of State-Transition Graphs for Optimized Heterogeneous Scheduling

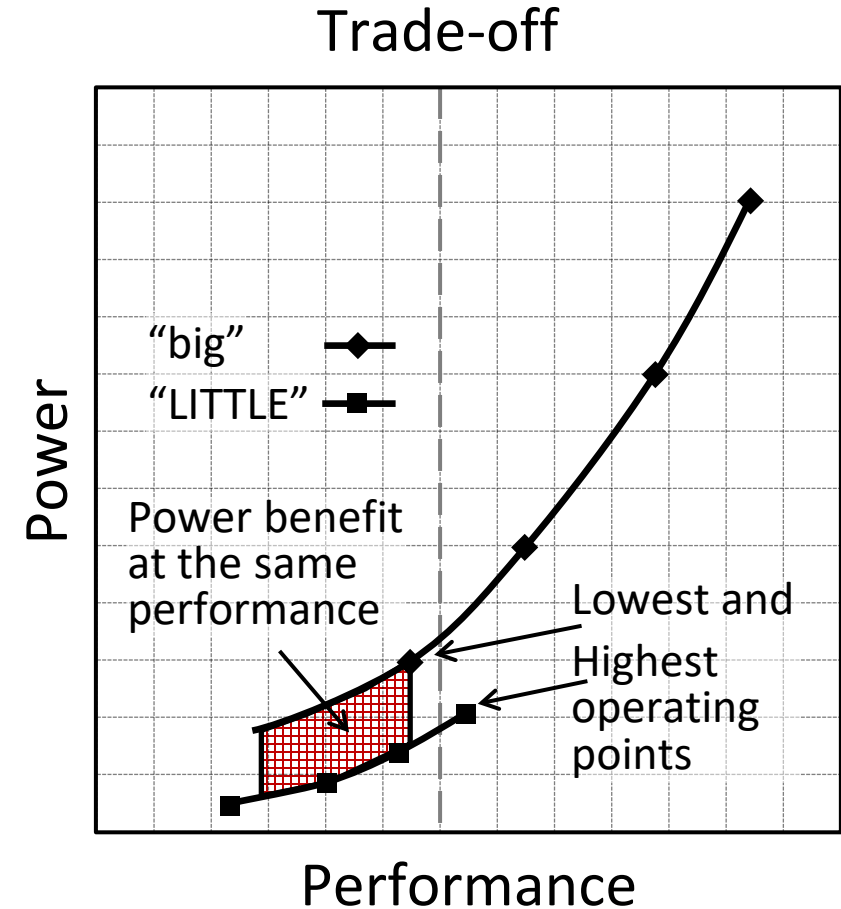
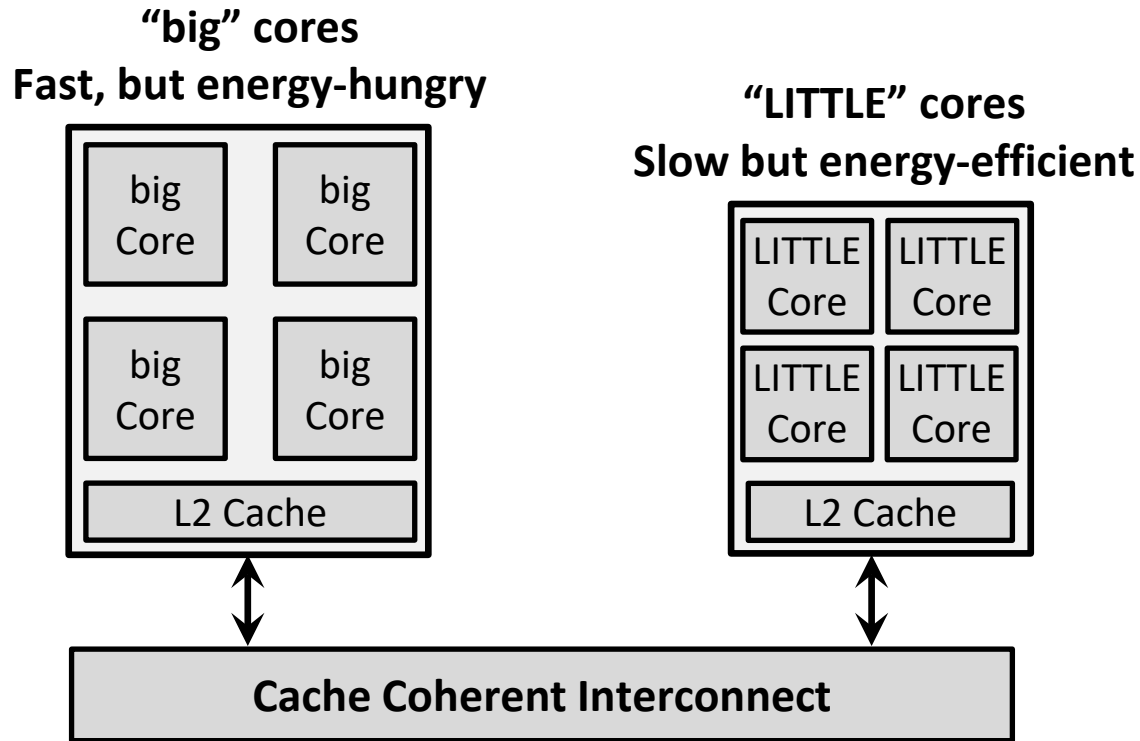
Arsen Mutalapov

Supervised by Artem Burmyakov

May 22, 2025



Heterogeneous Platform Example: ARM big.LITTLE

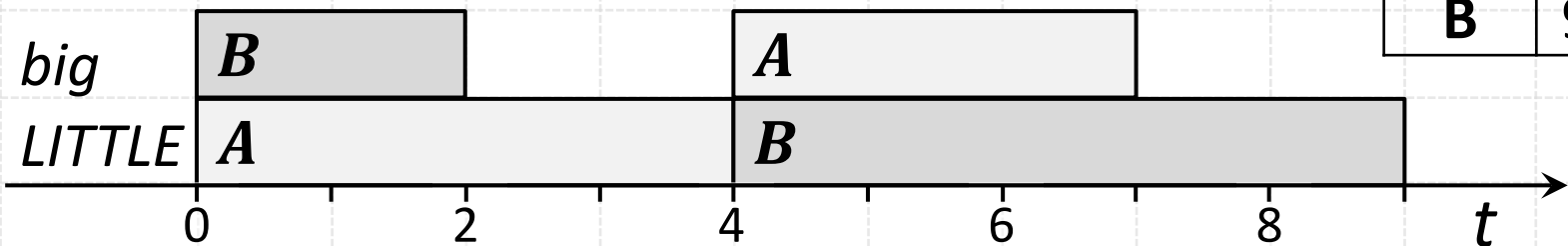


- A chosen scheduling policy significantly affects the runtime and energy efficiency;
- Essential for mobile devices with autonomous power supply.

Examples of Heterogeneous Schedules for Programs A, B

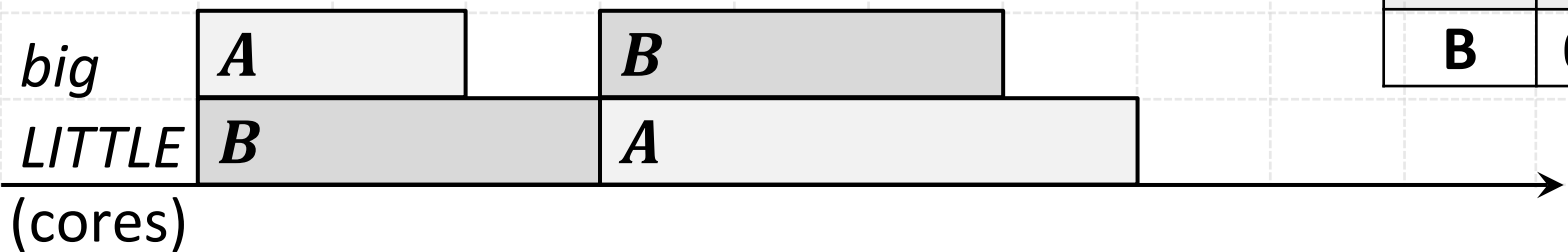
Objective: optimize trade-off between **Response Time** and **Energy**

Case 1: Worse Average RT

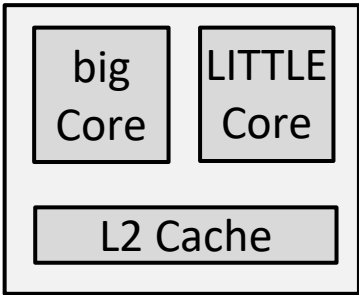


Prog.	RT	E
A	7	4
B	9	4

Case 2: Better Average RT



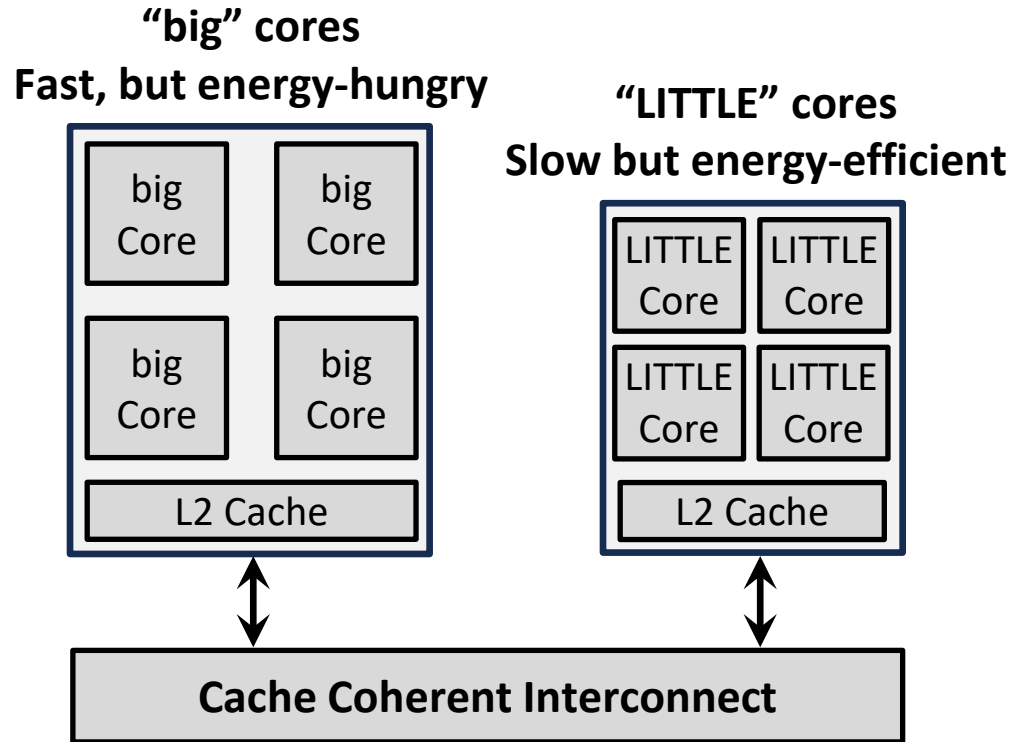
Prog.	RT	E
A	7	4
B	6	5



Oversimplified ARM big.LITTLE

Schedulers affect the efficiency of hardware utilization

Existing Heterogeneous Schedulers

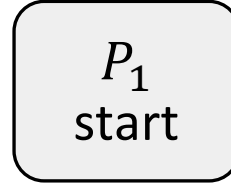


Schedulers:

- HEFT: Heterogeneous Earliest Finish Time;
- HASS: Heterogeneity-Aware Signature-Supported.

Property	Description
Objective	to minimize programs response times;
Principle	heuristic and greedy based
Key limitations	suboptimal scheduling decisions; no optimization of energy consumption.

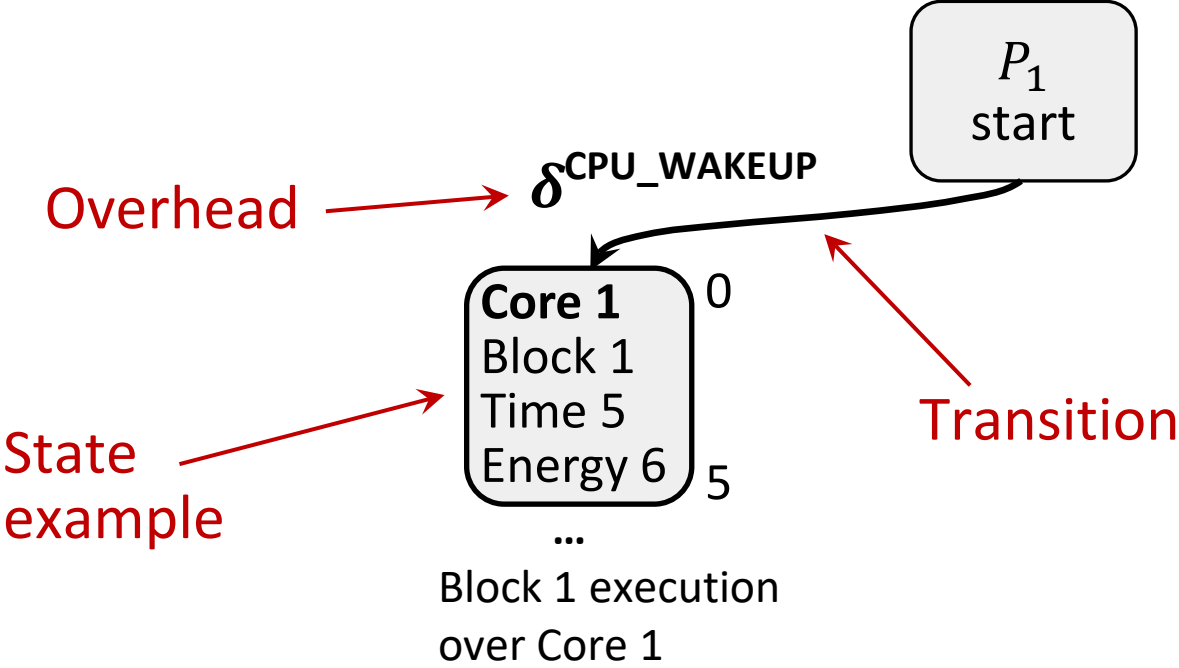
State-Transition Graph for a Solo Program P_1



P_1 requirements

Block	Param	Core 1	Core 2
Block 1	Time	5	4
	Energy	6	10
Block 2	Time	3	2
	Energy	3	7
Block 3	Time	2	2
	Energy	3	6

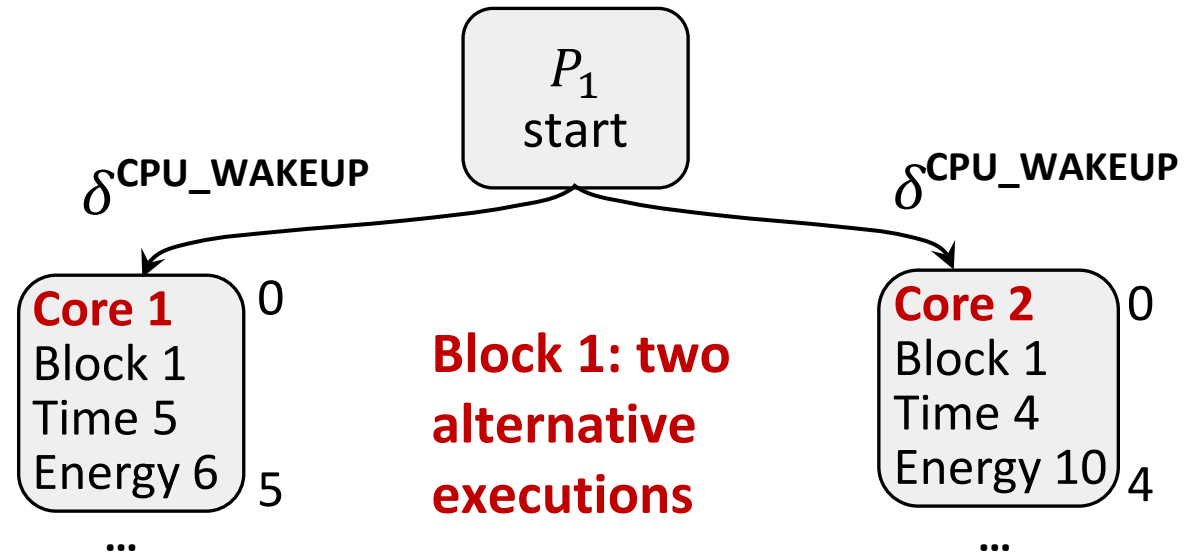
State-Transition Graph for a Solo Program P_1



P_1 requirements

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Block 1	Time	5	4
	Energy	6	10
Block 2	Time	3	2
	Energy	3	7
Block 3	Time	2	2
	Energy	3	6

State-Transition Graph for a Solo Program P_1



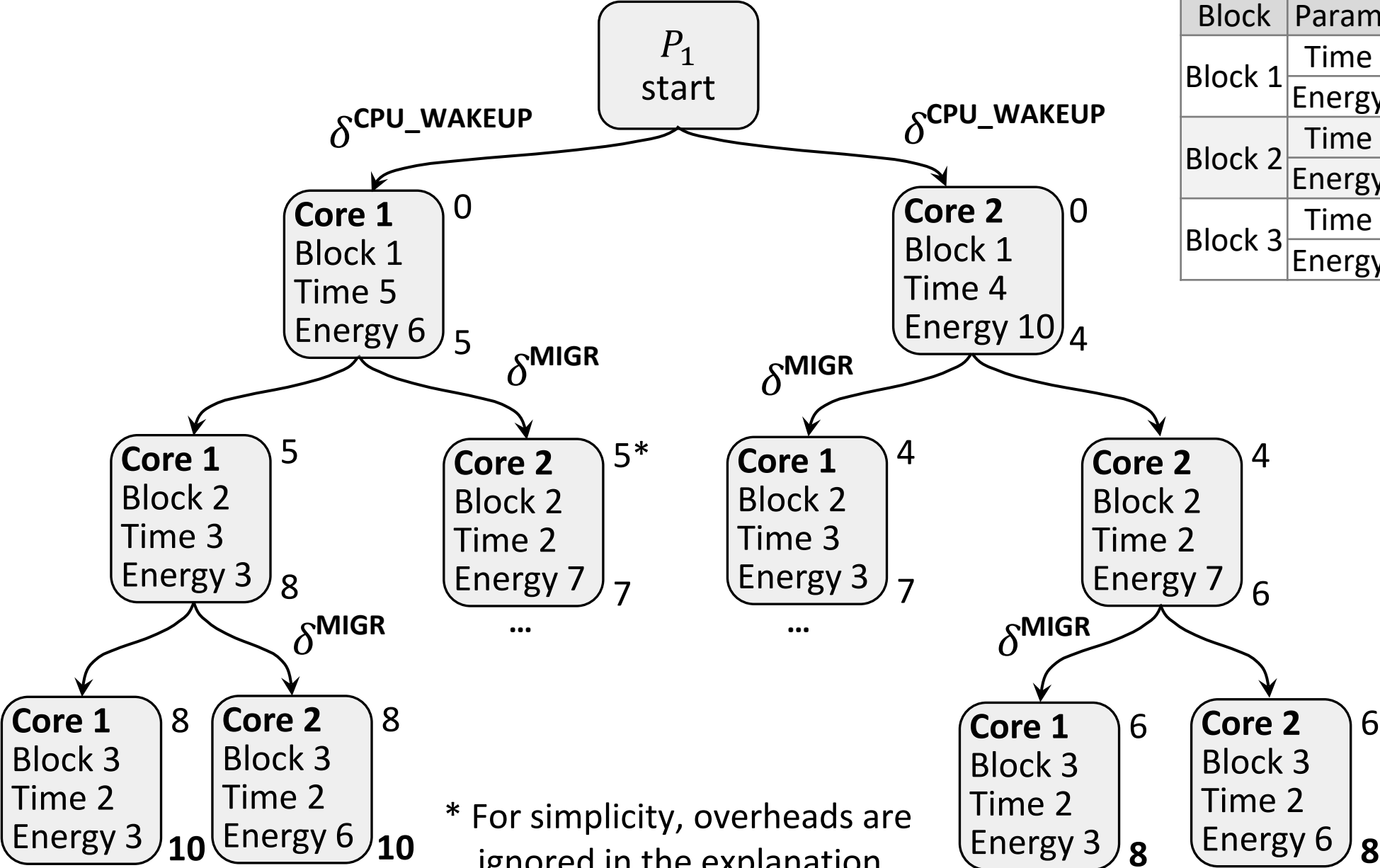
P_1 requirements

Block	Param	Core 1	Core 2
Block 1	Time	5	4
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Block 2	Time	3	2
	Energy	3	7
Block 3	Time	2	2
	Energy	3	6

State-Transition Graph for a Solo Program P_1

P_1 requirements

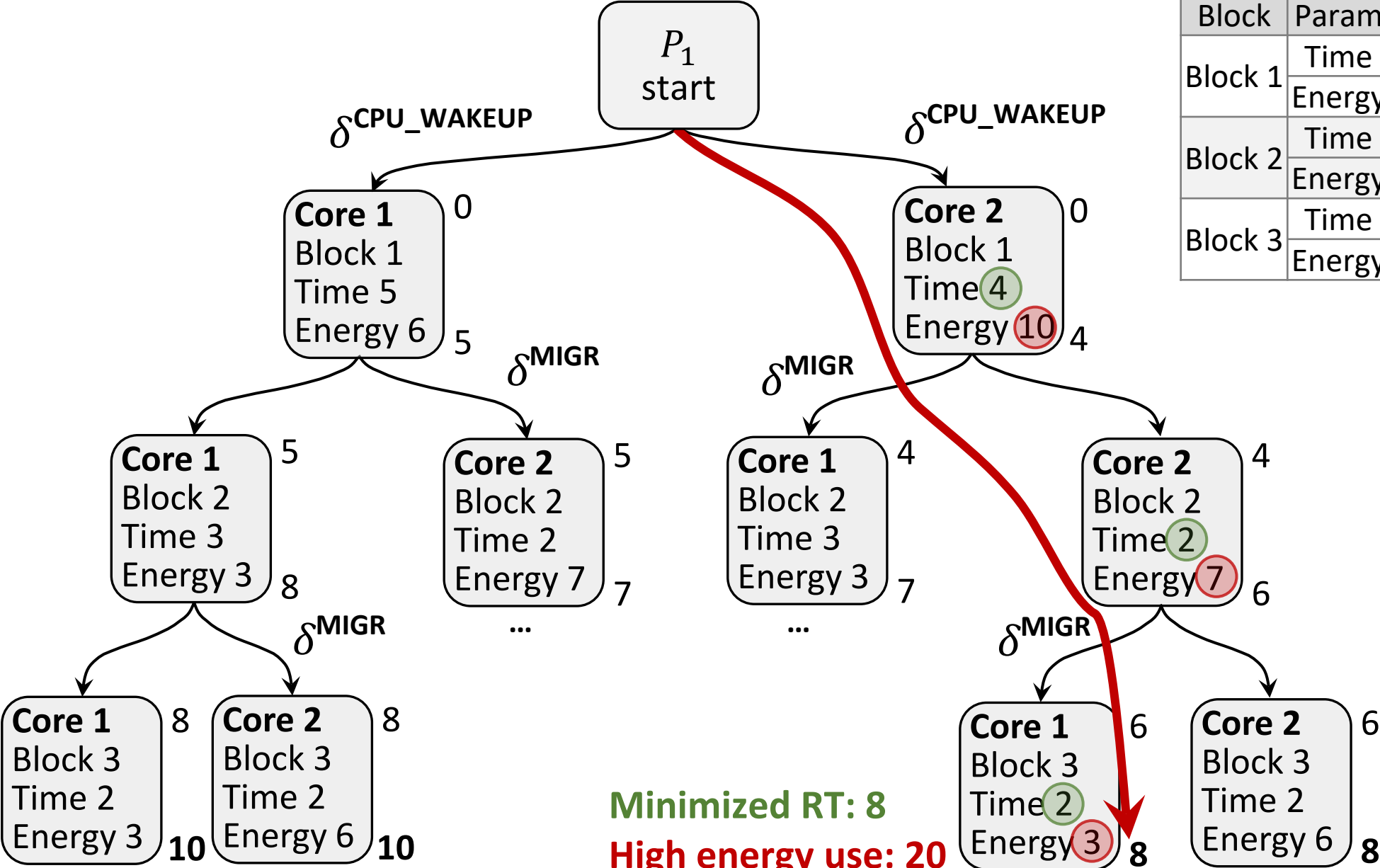
Block	Param	Core 1	Core 2
Block 1	Time	5	4
	Energy	6	10
Block 2	Time	3	2
	Energy	3	7
Block 3	Time	2	2
	Energy	3	6



State-Transition Graph for a Solo Program P_1

P_1 requirements

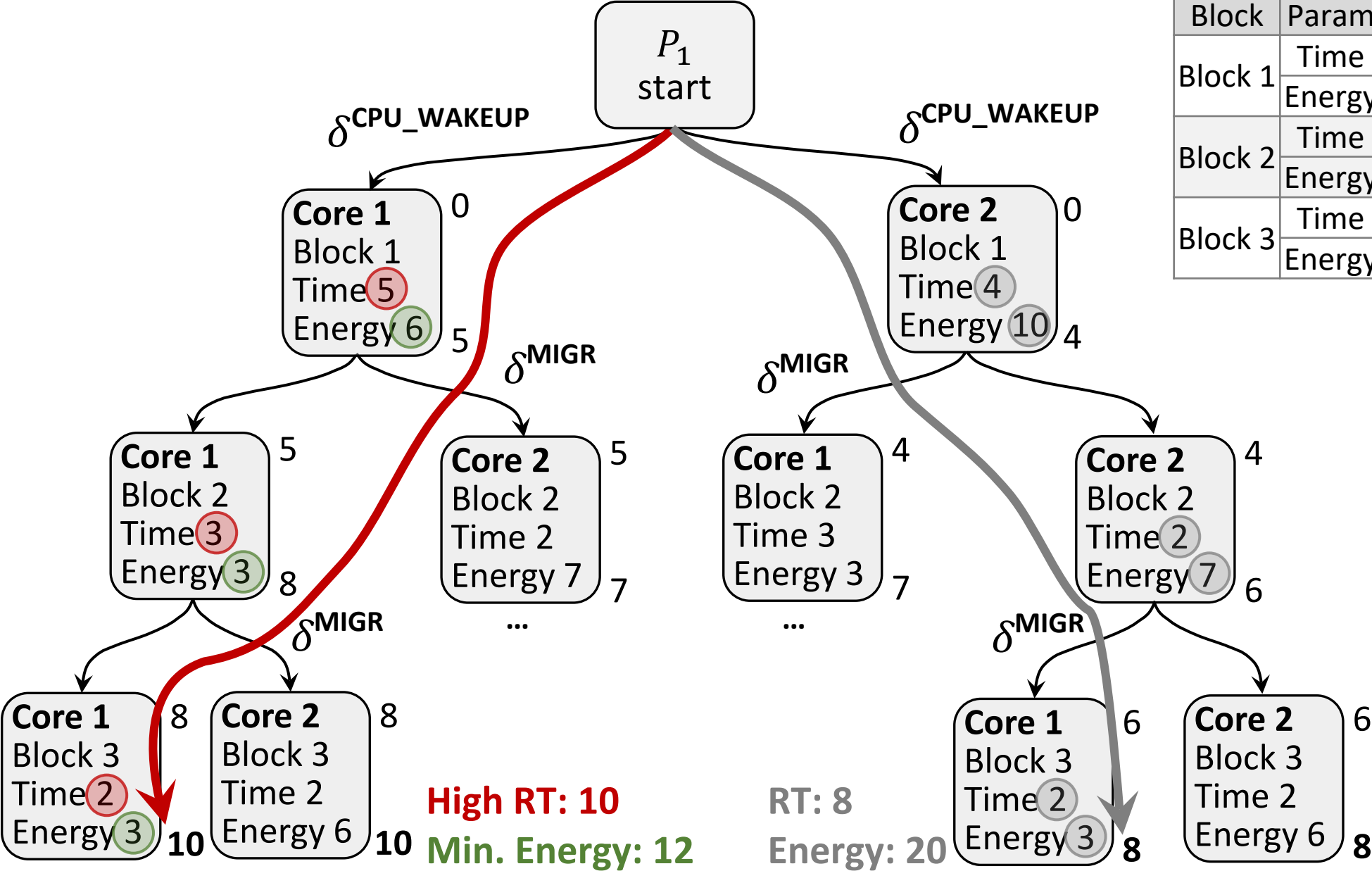
Block	Param	Core 1	Core 2
Block 1	Time	5	4
	Energy	6	10
Block 2	Time	3	2
	Energy	3	7
Block 3	Time	2	2
	Energy	3	6



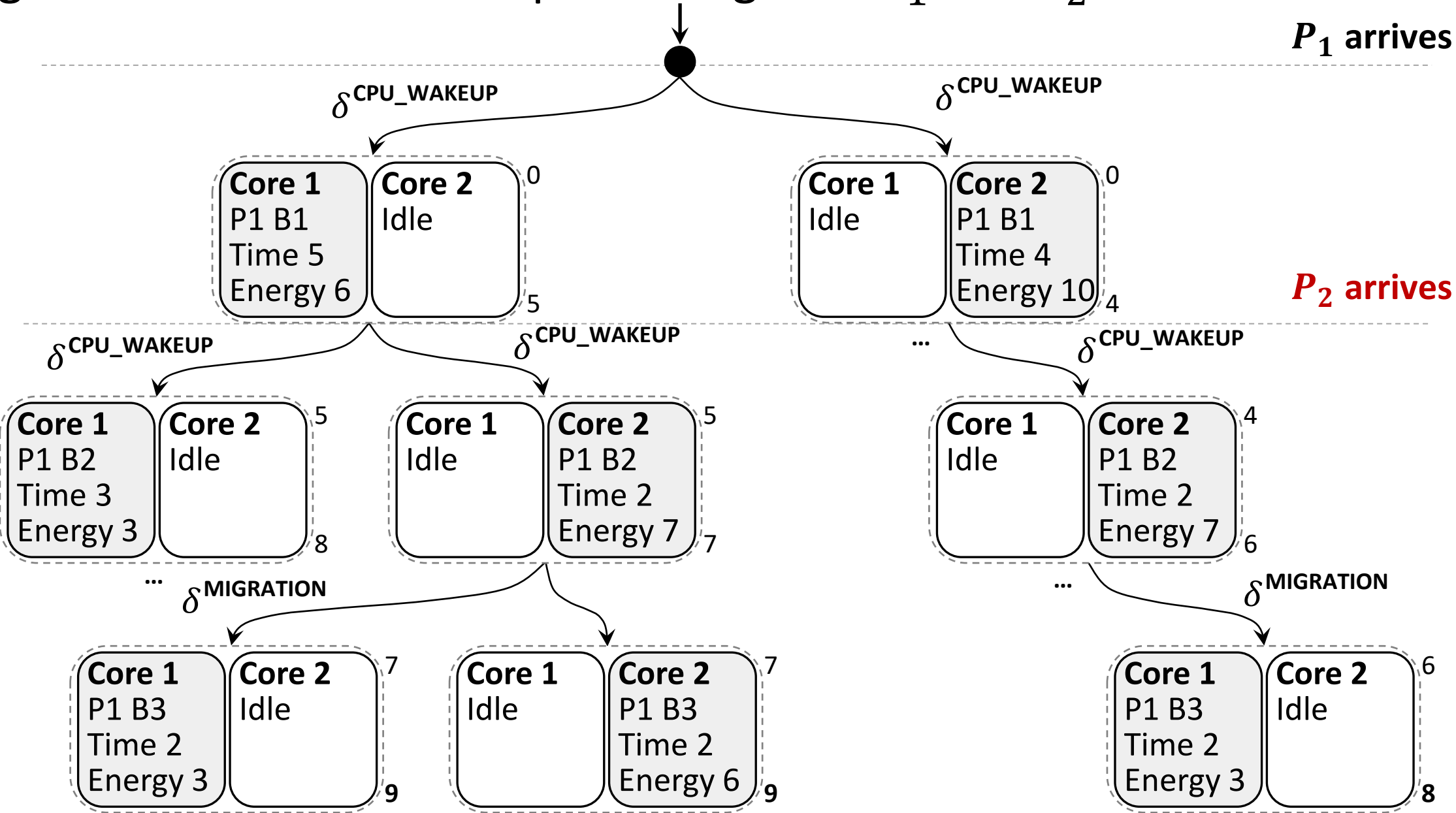
State-Transition Graph for a Solo Program P_1

P_1 requirements

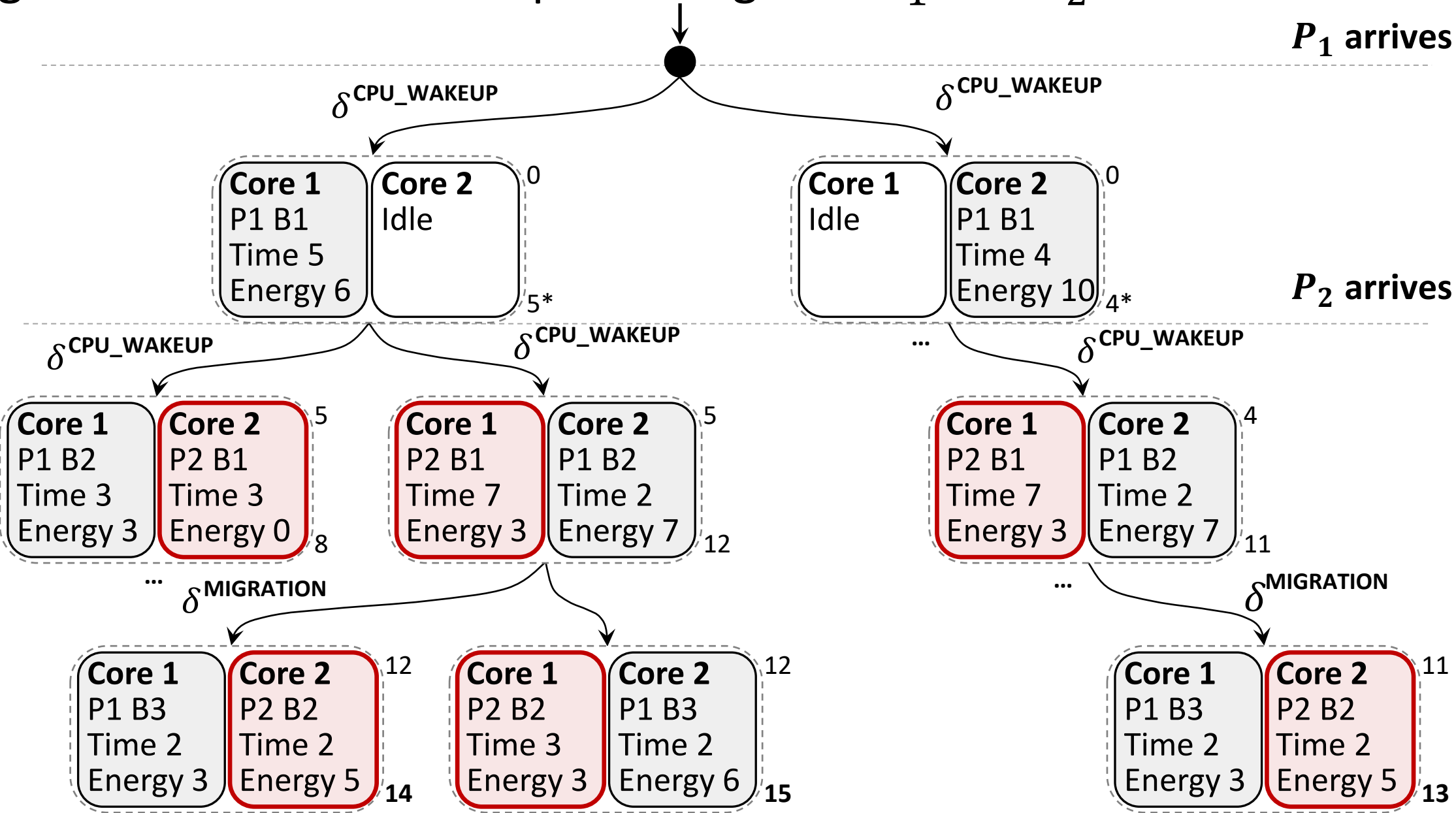
Block	Param	Core 1	Core 2
Block 1	Time	5	4
	Energy	6	10
Block 2	Time	3	2
	Energy	3	7
Block 3	Time	2	2
	Energy	3	6



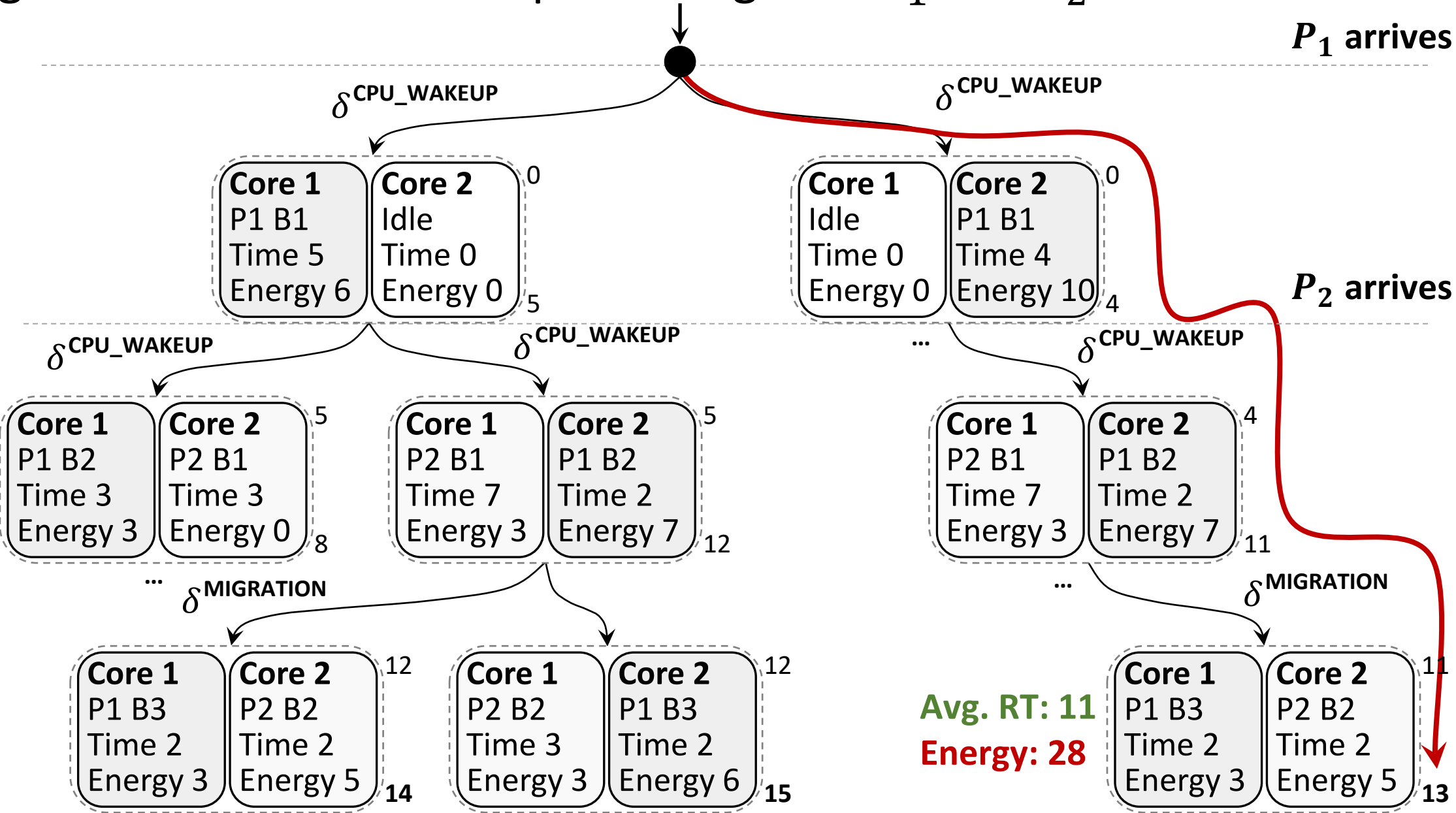
Merged State-Transition Graph of Programs P_1 and P_2



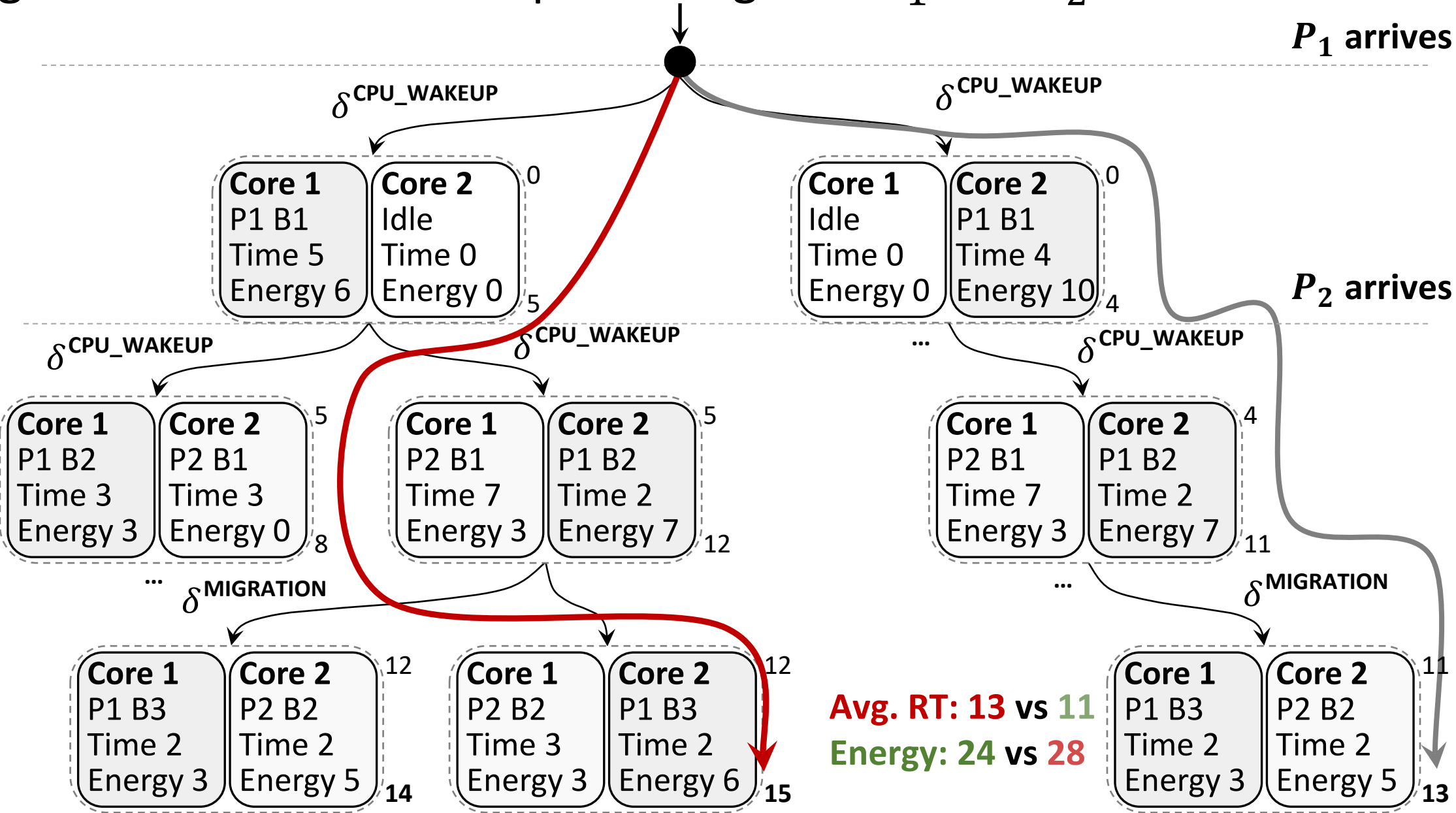
Merged State-Transition Graph of Programs P_1 and P_2



Merged State-Transition Graph of Programs P_1 and P_2



Merged State-Transition Graph of Programs P_1 and P_2



Status: Ongoing Thesis Work

- State-Transition Graph is an appropriate starting point for deriving optimal and suboptimal scheduling techniques;
- Potential pruning rules allow to control the analysis runtime making it more tractable for large systems;
- This methodology triggered a potential collaboration with Huawei but for now the submitted research proposal to the CSTT grant committee was not approved.

