cse327hw8 Q3

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```
% Set 10 sample points
pts = [17 23 35 37 45 57 61 70 80 84;
        81 72 73 58 50 56 36 32 32 19];
% Extract x and y values
x = pts(1, :);
y = pts(2, :);
% Get N sample points
N = length(x);
% Calculate matrix entry values
x_square = x.^2;
y_square = y.^2;
xy = x.*y;
A = [sum(x_square), sum(xy), sum(x);
     sum(xy), sum(y_square), sum(y);
     sum(x), sum(y), N];
[U, D, V] = svd(A);
% Extract eigenvalues from the diagonal of D
lambda = diag(D);
% Get eigenvalue indices
[~, index] = min(abs(lambda));
% Extract corresponding eigenvector
h = V(:, index);
% Normalize eigenvector
h = h / norm(h);
% Extract a, b, and c from the eigenvector
a = h(1);
b = h(2);
c = h(3);
% Generate predicted values
x values = linspace(0, 90, 10);
y_values = (-a*x_values - c) / b;
% Plot points and the fitted line
figure;
scatter(x, y, 'DisplayName', 'Sample Points');
```

```
hold on;

plot(x_values, y_values, '-r', 'LineWidth', 1, 'DisplayName', 'Fitted Line');
  title('Linear Model for Sample Points');
  xlabel('x');
  ylabel('y');
  legend('show');
  grid on;

hold off;
```

