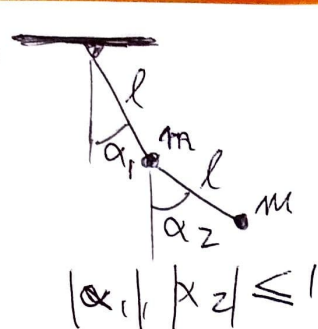


ESI Q4 (II)



USE SMALL ANGLES, IE

$$\cos(\alpha_1) \approx \cos(\alpha_2) \approx 1$$

$$\sin(\alpha_1) \approx \alpha_1$$

$$\sin(\alpha_2) \approx \alpha_2$$

$$T = \frac{1}{2} m (\ell \dot{\alpha}_1)^2 + \frac{1}{2} M (\ell \dot{\alpha}_1 + \ell \dot{\alpha}_2)^2$$

$$= \frac{1}{2} m \ell^2 (\dot{\alpha}_1^2 + \dot{\alpha}_1^2 + \dot{\alpha}_2^2 + 2\dot{\alpha}_1 \dot{\alpha}_2)$$

$$= \frac{1}{2} m \ell^2 (2\dot{\alpha}_1^2 + \dot{\alpha}_2^2 + 2\dot{\alpha}_1 \dot{\alpha}_2)$$

$$V = -mg\ell (\cos \alpha_1 + (\cos \alpha_1 + \cos \alpha_2))$$

$$= -mg\ell \left(\left(1 - \frac{\alpha_1^2}{2}\right) \cdot 2 + 1 - \frac{\alpha_2^2}{2} \right) = -mg\ell \left(2 - \alpha_1^2 - \frac{\alpha_2^2}{2} \right)$$

REDEFINE V FOR CONVENIENCE:

$$V = mg\ell \left(\alpha_1^2 + \frac{\alpha_2^2}{2} \right)$$

$$T = \frac{1}{2} \underline{\alpha}^T \underline{M} \underline{\alpha} \Rightarrow \underline{M} = m\ell^2 \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

$$V = \frac{1}{2} \underline{\alpha}^T \underline{K} \underline{\alpha} \Rightarrow \underline{K} = mg\ell \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\underline{M} \ddot{\underline{\alpha}} + \underline{K} \underline{\alpha} = 0 \quad \text{WHERE } \underline{\alpha} = \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} e^{i\omega t}$$

$$(-\omega^2 \underline{M} + \underline{K}) \underline{\alpha} = 0$$

$$\det(\underline{K} - \omega^2 \underline{M}) = 0$$

TO MAKE ALGEBRA SIMPLER, TEMPORARILY SET $m=\ell=g=1$

$$\left| \underline{K} - \omega^2 \underline{M} \right| = \begin{vmatrix} 2 - 2\omega^2 & -\omega^2 \\ -\omega^2 & 1 - \omega^2 \end{vmatrix} = 2(1 - \omega^2)^2 - \omega^4 = 0$$

$$= 2(1 - 2\omega^2 + \omega^4) - \omega^4 = 0$$

$$= \omega^4 - 4\omega^2 + 2 = 0$$

$$\omega_{1,2}^2 = \frac{4 \pm \sqrt{16 - 4 \cdot 1 \cdot 2}}{2} = 2 \pm \frac{\sqrt{8}}{2} = 2 \pm \sqrt{2}$$

ESIQ 4 (4)

IF $\omega^2 = 2 + \sqrt{2}$

$(-\omega^2 M + K) \underline{x} = 0$

$$\begin{pmatrix} 2 - 2(2 + \sqrt{2}) & -(2 + \sqrt{2}) \\ -(2 + \sqrt{2}) & 1 - (2 + \sqrt{2}) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -2 - 2\sqrt{2} & -(2 + \sqrt{2}) \\ -(2 + \sqrt{2}) & -1 - \sqrt{2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$(-2 - 2\sqrt{2})x_1 - (2 + \sqrt{2})x_2 = 0$

$(-2 - 2\sqrt{2})x_1 = (2 + \sqrt{2})x_2$

$\frac{x_2}{x_1} = \frac{-2 - 2\sqrt{2}}{2 + \sqrt{2}} = -\sqrt{2}$
↳ AFTER SOME ALGEBRA

IF $\omega^2 = 2 - \sqrt{2}$

$(-\omega^2 M + K) \underline{x} = 0$

$$\begin{pmatrix} 2 - 2(2 - \sqrt{2}) & -(2 - \sqrt{2}) \\ -(2 - \sqrt{2}) & 1 - (2 - \sqrt{2}) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -2 + 2\sqrt{2} & -(2 - \sqrt{2}) \\ -(2 - \sqrt{2}) & -1 + \sqrt{2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$(-2 + 2\sqrt{2})x_1 - (2 - \sqrt{2})x_2 = 0$

$\frac{x_2}{x_1} = \frac{-2 + 2\sqrt{2}}{-(2 - \sqrt{2})} = \sqrt{2}$

TWO NORMAL MODES
& THEIR FREQUENCIES:

$\underline{x}^{(1)} = \begin{pmatrix} 1 \\ -\sqrt{2} \end{pmatrix}$

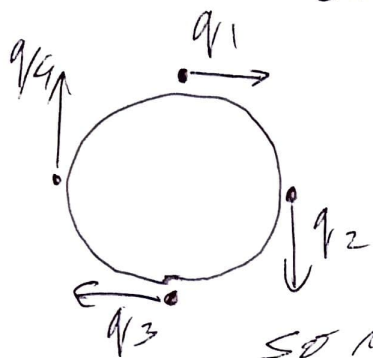
$\omega^{(1)} = \sqrt{2 + \sqrt{2}} \sqrt{\frac{g}{L}}$

$\underline{x}^{(2)} = \begin{pmatrix} 1 \\ \sqrt{2} \end{pmatrix}$

$\omega^{(2)} = \sqrt{2 - \sqrt{2}} \sqrt{\frac{g}{L}}$

ANSWER

ESIQS [LETS TRY DOING IT BY INTUITION, NOT LAGRANGIAN]



- we need:
- rotation
 - sth like this:
 - sth like this:
 - sth orthogonal to previous

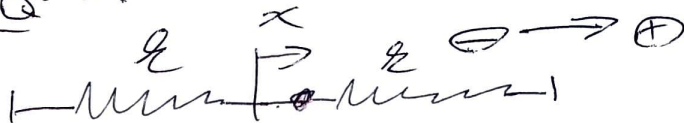
so we have:

$$\underline{Q}^{(1)} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \quad \underline{Q}^{(2)} = \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} \quad \underline{Q}^{(3)} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix} \quad \underline{Q}^{(4)} = \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\omega_1^2 = 0$$

(ROTATION)

SUSPECT $\underline{Q}^{(2)}$:



$$-2kx = m\ddot{x}$$

$$\ddot{x} + \frac{2k}{m}x = 0$$

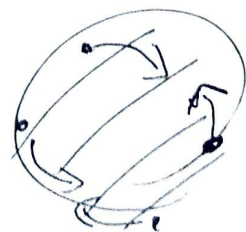
$$\omega^2 = \frac{2k}{m} \Rightarrow \omega^2 = \sqrt{\frac{2k}{m}}$$

& BY SYMMETRY: $\omega_3 = \sqrt{\frac{2k}{m}}$

$\omega_n^2 \propto \text{MAX KE STORED} = \text{MAX PE STORED} \propto \sum (\text{DISPLACEMENT OF EACH MASS})^2 \propto \underline{Q}^{(n)} \cdot \underline{Q}^{(n)} \Rightarrow \omega_n^2 \propto \underline{Q}^{(n)} \cdot \underline{Q}^{(n)}$

$$\omega_4^2 = \frac{\underline{Q}^{(4)} \cdot \underline{Q}^{(4)}}{\underline{Q}^{(2)} \cdot \underline{Q}^{(2)}} \omega^2 = \frac{4}{2} \sqrt{\frac{2k}{m}} \Rightarrow 2 \sqrt{\frac{2k}{m}} = \omega_4$$

The 4TH mode behaves like this:



[BAD DRAWING BUT I HOPE IT SHOWS THE POINT]

$$\left. \begin{aligned} T_{ij} \ddot{q}_j + V_{ij} \dot{q}_j = 0 \\ T_{ij} = T_{ji}, V_{ij} = V_{ji} \end{aligned} \right\} \Rightarrow (T_{ij} \ddot{q}_i + V_{ij} \dot{q}_i) \dot{q}_j + (T_{ij} \ddot{q}_j + V_{ij} \dot{q}_j) \dot{q}_i = 0$$

RE GROUP / MULTIPLY BY $\frac{1}{2}$:

$$\Rightarrow \frac{1}{2} T_{ij} (\ddot{q}_i \dot{q}_j + \dot{q}_i \ddot{q}_j) + \frac{1}{2} V_{ij} (\dot{q}_i \dot{q}_j + \dot{q}_i \dot{q}_j) = 0$$

RE EXPRESS:

$$\frac{\partial}{\partial t} \left(\frac{1}{2} T_{ij} \dot{q}_i \dot{q}_j + \frac{1}{2} V_{ij} \dot{q}_i \dot{q}_j \right) = 0$$

CONCLUDE:

$$\frac{1}{2} T_{ij} \dot{q}_i \dot{q}_j + \frac{1}{2} V_{ij} \dot{q}_i \dot{q}_j = C$$

ie

$$T + V = C$$

AS REQUIRED.

$$C = T + V \quad \left(\text{or } \frac{d}{dt} \right)$$

$$0 = \frac{d}{dt} (T + V) = \frac{1}{2} T_{ij} (\ddot{q}_i \dot{q}_j + \dot{q}_i \ddot{q}_j) + \frac{1}{2} V_{ij} (\dot{q}_i \dot{q}_j + \dot{q}_i \dot{q}_j) = 0$$

\Downarrow

~~$$\frac{1}{2} T_{ij} \dot{q}_i \dot{q}_j + \frac{1}{2} V_{ij} \dot{q}_i \dot{q}_j$$~~

REARRANGE:

$$\frac{1}{2} \dot{q}_j (T_{ij} \ddot{q}_i + V_{ij} \dot{q}_i) + \frac{1}{2} \dot{q}_i (T_{ij} \ddot{q}_j + V_{ij} \dot{q}_j) = 0$$

\dot{q}_i & \dot{q}_j ARE INDEPENDENT

$$\Rightarrow T_{ij} \ddot{q}_i + V_{ij} \dot{q}_i = 0 \quad \& \quad T_{ij} \ddot{q}_j + V_{ij} \dot{q}_j = 0$$

SO: YES, IT CAN.

ESIQ7 | I

CLOSURE: SATISFIED, SEE GROUP TABLE

IDENTITY: e_1

INVERSE: SATISFIED, SEE GROUP TABLE

ASSOCIATIVITY:

	e_1	e_2	e_3	e_4	e_5	e_6
e_1	e_1	e_2	e_3	e_4	e_5	e_6
e_2	e_2	e_3	e_1	e_6	e_4	e_5
e_3	e_3	e_1	e_2	e_5	e_6	e_4
e_4	e_4	e_5	e_6	e_1	e_2	e_3
e_5	e_5	e_6	e_4	e_3	e_1	e_2
e_6	e_6	e_4	e_5	e_2	e_3	e_1

SUBGROUPS: $\{e_1, e_4\}$, $\{e_1, e_5\}$, $\{e_1, e_6\}$,
 ~~$\{e_1, e_2, e_3\}$~~

~~$\{e_1, e_4\}$~~

\odot

$$N \triangleleft G \Leftrightarrow \forall n \in N, \forall g \in G: gng^{-1} \in N$$

USING GROUP TABLE

(FROM WIKIPEDIA)

$$e_5 e_4 e_5^{-1} = e_5 e_4 e_5 = e_3 e_5 = e_6 \notin \{e_1, e_4\}$$

$$e_6 e_5 e_6^{-1} = e_6 e_5 e_6 = e_6 e_2 = e_4 \notin \{e_1, e_5\}$$

$$e_4 e_6 e_4^{-1} = e_4 e_6 e_4 = e_4 e_2 = e_5 \notin \{e_1, e_5\}$$

THESE ARE
NOT NORMAL
 SUBGROUPS.

ESI Q7 II

$$f_i f_i f_i^{-1} = f_i f_i^{-1} = f_i$$

$$f_1 f_2 f_1^{-1} = f_1 f_2 f_1 = f_2$$

$$f_2 f_2 f_2^{-1} = f_2 f_1 = f_2$$

$$f_3 f_2 f_3^{-1} = f_3 f_2 f_2 = f_3 f_3 = f_2$$

$$f_4 f_2 f_4^{-1} = f_4 f_2 f_4 = f_4 f_6 = f_3$$

$$f_5 f_2 f_5^{-1} = f_5 f_2 f_5 = f_5 f_4 = f_3$$

$$f_6 f_2 f_6^{-1} = f_6 f_2 f_8 = f_6 f_5 = f_3$$

SAME PROCEDURE FOR f_3 TO SHOW $\{f_1, f_2, f_3\}$ IS NORMAL.

ANY NON-TEDIOUS WAY TO DO THIS?

LSIQ8 $C_4: \mathbb{Z}$

I	R	R ²	R ³
R	R ²	R ³	I
R ²	R ³	I	R
R ³	I	R	R ²

$K_4:$

I	x	y	z
x	I	z	y
y	z	I	x
z	y	x	I

They are both abelian because
both group tables are symmetric to main diagonal.

Isomorphic if:

$$g * h = j \Leftrightarrow f(g) \circ f(h) = f(j) \quad \forall g, h, j \in G$$

$$R^3 * R = I \text{ WHEREAS } f(R^3) \circ f(R) = z \circ x = y$$
$$f(I) = I \neq y \Rightarrow \text{THEY ARE NOT ISOMORPHIC}$$