Linear Transformation

Example (revisited)

Four Subspaces of a Matrix

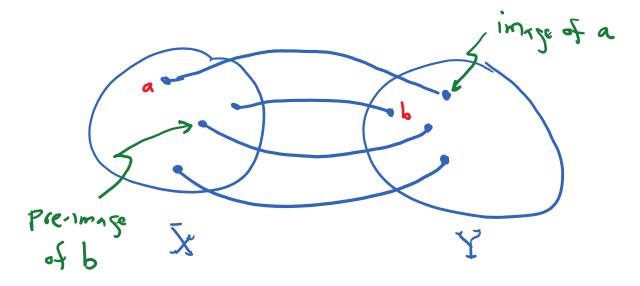
Column Space

Mull space

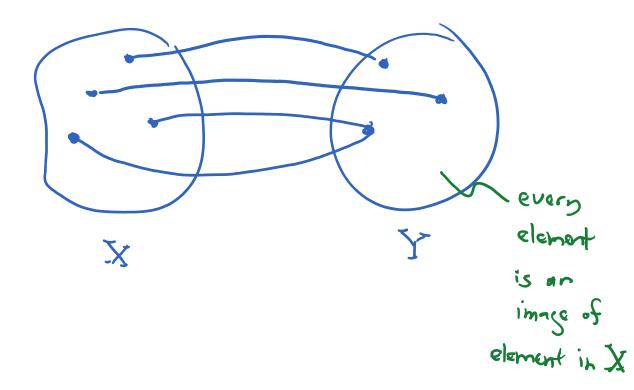
Raw Space

Left Nullspace

Functions are one-to-one iff every element in X goes to a distinct element in Y



Functions are onto iff every element of Y is an image of some element of X and thus range (f) = (odomain (f))



Linear Transformation Example

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Let
$$M = K_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + K_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + K_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + K_4 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Use B_{11} , B_{12} , B_{21} + B_{22} as basis

 $M = K_1 B_{11} + K_2 B_{12} + K_3 B_{21} + K_4 B_{22}$
 $K_1 B_{11} + K_2 B_{12} + K_3 B_{21} + K_4 B_{22} = \begin{bmatrix} q & b \\ c & d \end{bmatrix}$

$$R_{1} + R_{4} = a, R_{2} = b, R_{3} = c, R_{4} = d$$

$$+ R_{1} = a - d$$

$$L(\underline{B}_{11}) = [1 \circ o], L(\underline{B}_{12}) = [0 \circ o]$$

$$L(\underline{B}_{21}) = [0 \circ i], L(\underline{B}_{22}) = [1 \circ o]$$

$$\underline{A} = [L(\underline{B}_{11})^{T}, L(\underline{B}_{12})^{T}, L(\underline{B}_{22})^{T}, L(\underline{B}_{22})^{T}]$$

$$\underline{A} = [L(\underline{M})]$$

$$(\underline{A} + \underline{R}) = ([1 \circ o] + [1 \circ o]$$

Review Example:

Row reduce

Pivots

$$\begin{bmatrix}
0 & 1 & 0 & 0 \\
0 & 1 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$x_1 + x_3 = 0$$

$$x_1 + x_3 = 0$$

This exists because:

- a) det (A) = 0 -> A does not exist
- D) A has a non-trivial nullspace, where the nullspace of A is all vectors \underline{V} , such that $\underline{A}\underline{V} = \underline{0}$

Here, one finds

$$\lambda = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$A \vee = \begin{bmatrix} 1 & 0 & 1 \\ 2 & 1 & 3 \\ 1 & 1 & 7 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1-1 \\ 2+1-3 \\ 1+1-7 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

and the columns of A are not independent!

In addition to nullspace, it is useful to identify the column space of A.

Altogether, there are four subspaces of a matrix:

- (1) Column space
- (2) Null space
- (3) Row space
- (4) Laft nullspace

Column Space

Recall that a matrix-vector product is simply a linear combination of the matrix columns:

nx) vector

$$A = \begin{bmatrix} q_1 & q_2 & \dots & q_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = b$$

mxn matrix

mxl vectors

mxl vectors

b = x191 + x292 + ... + xn9n

All possible vectors \underline{b} exist in the column space C(A) of the matrix.

The column space is a subspace of R^m .

The column space is very important when solving $A \times = \underline{b}$

Theorem: The system Ax = b has at least one solution iff b is in the column space of A

Note: At least one solution!

Case 1: A' exists $A \times = b \quad \text{with } b \quad \text{in } C(A)$

then $x = A^{-1}b \Rightarrow a$ solution \Rightarrow any b is a valid right-hand side (rhs)

With A E Mnn (square matrix)

Tf A exists, then A has
n independent columns, which means
it spans all of Rn

Example:

A = [0 | 0 |

- 0 | 0 |

- 0 | 0 |

Al exists; all 3 columns are linearly independent; columns span all of IR3

Case 2: A does not exist then b must be in the column space G(A) to have a solution

Example:
$$A \times = b$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ \overline{z} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

only two
independent
columns;

A does not
exist

Can one write

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \times \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + z \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Try x=1, y=1, 2= 9

$$(1) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + (1) \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + a \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

b is in the column space C(A) and has at least one solution, actually an infinity of solutions

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ \overline{z} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{Changed anly this element}$$

Can one write

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} = x \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + \overline{z} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Is c in C(A)? No!

No x, y, z to satisfy above equation

. No solution

Nullspace

Another important subspace is the nullspace, given by N(A)

The nullspace is all vectors V, such that

Is this a vector space?

Let v + w be in N (A)

(Av=0 and Aw=0)

Yes, the nullspace is a vector space

The nullspace is always non-empty;

Q is always in the nullspace

$$A_0 = 0$$

If A exists, then

$$A y = 0 \Rightarrow y = A 0 = 0$$

=> If A exists, then the only vector

If the null space has any vector in addition to 0, then A does not exist.

Example: To obtain N(A)

$$A = \begin{bmatrix} 1 & -1 & 1 \\ 2 & -1 & 0 \\ 0 & -1 & 2 \end{bmatrix}$$
 Solve $A \times = 0$

Two possibilities:

A ref
$$\rightarrow$$
 $0 \quad 0 \quad 0$
 $0 \quad 0 \quad 0$

Something similar

Example:

 $1 \quad -1 \quad 1$
 $A = \begin{bmatrix} 1 & -1 & 1 \\ 2 & -1 & 0 \\ 0 & -1 & 2 \end{bmatrix}$
 $1 \quad \text{rref}$
 $1 \quad 0 \quad -1 \quad 1 \quad 0$
 $2 \quad 1 \quad -2 \quad 0$
 $3 \quad \text{rref}$
 $4 \quad 1 \quad -2 \quad 0$
 $4 \quad 1 \quad -2 \quad 0$
 $5 \quad 1 \quad 0$
 $6 \quad 1 \quad -2 \quad 0$
 $6 \quad 1 \quad 0$
 $7 \quad 1 \quad 0$

$$x_{1}-1=0 \implies x_{1}=1$$

$$x_{2}-2=0 \implies x_{2}=2$$

$$\therefore x = \begin{bmatrix} 1 \\ z \end{bmatrix} \text{ is in null space}$$
of A

such that Ax=0

But so is
$$2x = \begin{bmatrix} 2 \\ 4 \\ 7 \end{bmatrix}, -3x = \begin{bmatrix} -3 \\ -6 \\ -3 \end{bmatrix}, ...$$

Nullspace is not limited to square matrice.

Example:
$$A = \begin{bmatrix} 1 & 3 & 2 & 3 \\ 7 & 6 & 8 & 10 \\ 3 & 9 & 10 & 13 \end{bmatrix}$$

To determine the nullspace, set one free Uariable to I, the others to zero + find fixed variables (x, x, here)

$$|A| = 5pan \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ -1 \\ 1 \end{bmatrix} \right\}$$

Recall, with span, any linear combination of these ucctors is in N(A)

Matrix Subspaces: Recap

Let A ∈ Mmn

#rans

columns

(1) Column Space ((A) is the subspace of Rm that is spanned by the columns of A. (Also called the Range Space)

 $\frac{A}{5} = \frac{b}{h}$

b is a linear

er" ER"

combination of the

Nullspace N(A) is the subspace of \mathbb{R}^n that is spanned by all vectors, which are solutions of $A \times = 0$. (Also called the Kernel Space)

All matrices have a nullspace, because O is always in N(A)

A 0 = 0

- (3) Row Space C(AT) is the subspace of Rn that is spanned by the rows of A.
- 4) Lest Nullspace N(AT) is the subspace of

 R^m that is spanned by all vectors, which are solutions of $A^T x = 0$

Note that

Summary

Let A E Mmn

Matrix Subspace	Notation	Subspace of
Column Space	$C(\overline{V})$	Rm
Nullspace	N(A)	Rh
Row Space	$C(\underline{A}^T)$	Rh
Lest Nullspace	$N(A^T)$	Rm