

Lecture 10 Outline

Thursday, September 26, 2019 3:29 PM

Linear Transformations

Rank - Nullity

Orthogonality

Numerical Solutions

Matrix & Vector norms

Condition number

LU decomposition

Gaussian elimination

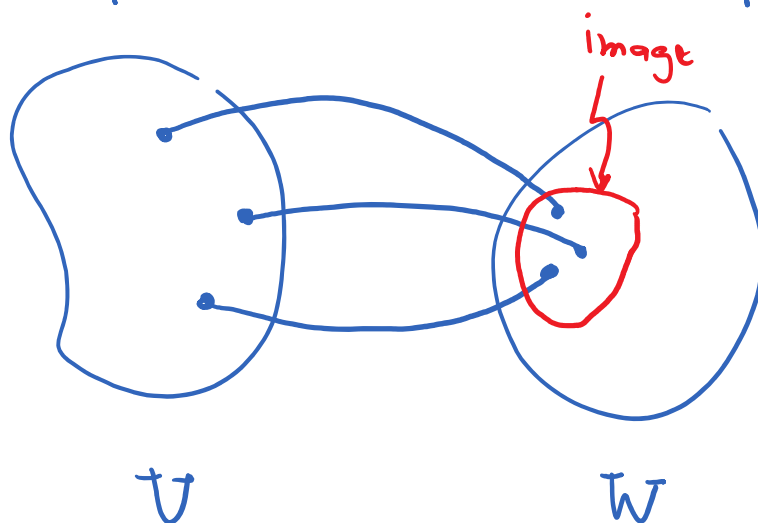
Let V & W be vector spaces with a linear transformation $L: V \rightarrow W$

Kernel of L : The $\ker(L)$ is the subspace of V , such that $\ker(L) = \{ \underline{v} \in V : L\underline{v} = \underline{0}_W \}$

The size of the $\ker(L)$ is called the nullity of L : $\text{nullity}(L)$

Rank of L : The rank of a linear operator, $\text{rank}(L)$, is the dimension of its image.

Recall that the image of a vector space is the portion of W that it maps into



Rank-Nullity or Dimension Theorem

Let V & W be vector spaces with a
linear transformation $L: V \rightarrow W$

Then

$$\text{rank}(L) + \text{nullity}(L) = \underbrace{|L|}_{\substack{\text{dimension (or size)} \\ \text{of } V}}$$

Apply to matrices: $\underline{A} \in M_{mn}$

$$\underline{A} \underline{x} = \underline{b} \quad \begin{array}{l} \underline{x} \in V \in \mathbb{R}^n \\ \underline{b} \in W \in \mathbb{R}^m \end{array}$$

\underline{b} is the image of \underline{x} under the
linear transformation of \underline{A}

Linear combinations of $C(\underline{A})$ give all vectors
in the image

$$\Rightarrow \text{rank}(\underline{A}) = |\mathcal{C}(\underline{A})|$$

↳ dimension (or size)
of the column space of \underline{A}

Note: Each vector in $\mathcal{C}(\underline{A})$ must be an independent vector (i.e., $\mathcal{C}(\underline{A})$ contains the minimum # of vectors to span the columns of \underline{A})

Example:

$$\underline{A} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

Do not say

$$\mathcal{C}(\underline{A}) \neq \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \right\}$$

but rather

$$\mathcal{C}(\underline{A}) = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\Rightarrow \text{rank}(\underline{A}) = 3$$

All linear combinations of $N(\underline{A})$ give

vectors $\underline{b} = \underline{0} = \underline{0}_w$

$$\underline{A}\underline{x} = \underline{0}$$

$$\Rightarrow \text{nullity}(\underline{A}) = |N(\underline{A})|$$

\downarrow
dimension (or size)
of the null space of \underline{A}

Since for $\underline{A}\underline{x} = \underline{b}$, $\underline{x} \in \mathbb{R}^n$

$$\begin{aligned} \text{Then } \text{rank}(\underline{A}) + \text{nullity}(\underline{A}) &= n \\ &= \# \text{ of columns} \end{aligned}$$

Theorem: Let $\underline{A} \in M_{mn}$, $C(\underline{A})$ be the column space, $N(\underline{A})$ be the nullspace, $C(\underline{A}^T)$ be the row space and $N(\underline{A}^T)$ be the left nullspace.

$$1) \text{rank}(\underline{A}) = |C(\underline{A})| = |C(\underline{A}^T)|$$

$$2) |N(\underline{A})| = n - \text{rank}(\underline{A})$$

$$3) |N(\underline{A}^T)| = m - \text{rank}(\underline{A})$$

Example: Let

$$\underline{A} = \begin{bmatrix} 8 & 2 & 1 & 23 \\ 4 & 2 & 9 & 19 \\ 10 & 1 & 6 & 35 \end{bmatrix}$$

3×4 $4 \times p$ $3 \times p$

$$\underline{A}\underline{x} = \underline{b}$$

$$\underline{x} \in \mathbb{R}^4$$

$$\underline{b} \in \mathbb{R}^3$$

rref reduced
row echelon
form

$$\begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

Independent

variable
free

$$\text{rref}(\underline{A}^T) =$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Independent
columns

no
free
variables

$$\Rightarrow \text{rank}(\underline{A}) = |C(\underline{A})| = 3 = |C(\underline{A}^T)|$$

$$\Rightarrow |N(\underline{A})| = n - \text{rank}(\underline{A}) = 4 - 3 = 1$$

$$\Rightarrow |N(\underline{A}^T)| = m - \text{rank}(\underline{A}) = 3 - 3 = 0$$

Find all subspaces (Matlab check: rref)

$$C(\underline{A}) = \left\{ \begin{bmatrix} 8 \\ 4 \\ 10 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 9 \\ 6 \end{bmatrix} \right\}$$

$$N(\underline{A}): \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Let $x_4 = 1$ (free variable)

$$\text{Then } x_1 + 3 = 0 \quad x_1 = -3$$

$$x_2 - 1 = 0 \Rightarrow x_2 = 1$$

$$x_3 + 1 = 0 \quad x_3 = -1$$

$$\therefore N(\underline{A}) = \left\{ \begin{bmatrix} -3 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

Also, $N(\underline{A})$

contains the

zero vector $\underline{0}_4$

Check

$$\begin{bmatrix} -3 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

Check

$$\begin{bmatrix} 8 & 2 & 1 & 23 \\ 4 & 2 & 9 & 19 \\ 10 & 1 & 6 & 35 \end{bmatrix} \begin{bmatrix} -3 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -24 + 2 - 1 + 23 \\ -12 + 2 - 9 + 19 \\ -30 + 1 - 6 + 35 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\zeta(\underline{A}^T) = \left\{ \begin{bmatrix} 8 \\ 2 \\ 1 \\ 23 \end{bmatrix}, \begin{bmatrix} 4 \\ 2 \\ 9 \\ 19 \end{bmatrix}, \begin{bmatrix} 10 \\ 1 \\ 6 \\ 35 \end{bmatrix} \right\}$$

$$N(\underline{A}^T) = \{ \} \quad \text{Contains } \underline{0}_3 \text{ vector}$$

Let $\underline{A} \in M_{mn}$

(i) The matrix \underline{A} has full column rank if

$\text{rank}(\underline{A}) = n$. If \underline{A} has full column rank, then the following holds

a) All columns of \underline{A} are independent

.. .. .

b) Only vector in $N(\underline{A})$ is $\underline{0}$

c) If \underline{A}^{-1} exists, then the solution to $\underline{A}\underline{x} = \underline{b}$ is unique (i.e., only an \underline{x} such that $\underline{A}\underline{x} = \underline{b}$)

(2) The matrix \underline{A} has **full row rank** if $\text{rank}(\underline{A}) = m$. Furthermore,

a) All rows of \underline{A} are independent

b) $C(\underline{A})$ spans all of \mathbb{R}^m ($\underline{b} \in \mathbb{R}^m$)

c) $\underline{A}\underline{x} = \underline{b}$ has at least one solution for any \underline{b}

$C(\underline{A})$ spans all of \mathbb{R}^m

⇒ Any vector in \mathbb{R}^m can be written as a linear combination of the columns of \underline{A}

⇒ Any \underline{b} must be in \mathbb{R}^m (for $\underline{A}\underline{x} = \underline{b}$)

$\Rightarrow \underline{x}$ is that linear combination of the columns of \underline{A} that gives \underline{b}

$$\begin{aligned}\underline{A}\underline{x} &= [\underline{a}_1 \ \underline{a}_2 \ \dots \ \underline{a}_n] \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \\ &= x_1 \underline{a}_1 + x_2 \underline{a}_2 + \dots + x_n \underline{a}_n\end{aligned}$$

(3) Now let $\underline{A} \in M_{nn}$ (square matrix)

The matrix \underline{A} has **full rank** if

$\text{rank}(\underline{A}) = n$ (i.e., both full row + column rank)

If \underline{A} is full rank, then

a) $\underline{A}\underline{x} = \underline{b}$ has a solution for any \underline{b}

b) $C(\underline{A})$ span all of \mathbb{R}^n

c) $N(\underline{A})$ is only the $\underline{0}$

d) $\underline{A}\underline{x} = \underline{b}$ only has one solution

for any \underline{b}

In other words, if \underline{A} is full rank,
then \underline{A}^{-1} exists

Only one solution: $\underline{A}\underline{x} = \underline{b} \Rightarrow \underline{x} = \underline{A}^{-1}\underline{b}$

Now, all of the following are equivalent
statements:

- ① \underline{A} is invertible
- ② The columns of \underline{A} are independent
- ③ The rows of \underline{A} are independent
- ④ $\det(\underline{A}) \neq 0$
- ⑤ $\underline{A}\underline{x} = \underline{0}$ only has $\underline{x} = \underline{0}$ as a solution
- ⑥ \underline{A} has n pivots for $\underline{A} \in M_{nn}$
- ⑦ \underline{A} is full rank (i.e. $\text{rank}(\underline{A}) = n$)
- ⑧ $\text{rref}(\underline{A}) = \underline{I}$
- ⑨ $C(\underline{A})$ spans all of \mathbb{R}^n

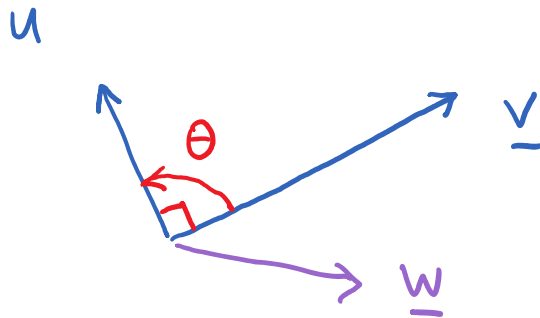
⑩ $\text{Col}(A^T)$ spans all of \mathbb{R}^n

If any one of these is true, then
all are true for square matrix A

Orthogonality

Recall: Two vectors are orthogonal (perpendicular)
to each other iff

$$\underline{u} \cdot \underline{v} = \underline{u}^T \underline{v} = 0$$



Here, u and v are orthogonal

$$\underline{u} \cdot \underline{v} = \|\underline{u}\| \|\underline{v}\| \cos \theta = 0$$

while u and w are not orthogonal

Two subspaces are orthogonal to each other if any vector in one subspace is orthogonal to all vectors in the other subspace.

If \underline{u} is in subspace S and \underline{v} is in subspace T , then if for any $\underline{u} \in S$ & $\underline{v} \in T$, we have $\underline{u} \cdot \underline{v} = 0$, then S and T are orthogonal.

For a matrix $\underline{A} \in M_{mn}$

(1) The row space $C(\underline{A}^T)$ is an orthogonal subspace in \mathbb{R}^n of the nullspace $N(\underline{A})$

(a) To show this, consider

$$\underline{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & & a_{2n} \\ \vdots & & & \vdots \\ a_{m1} & a_{m2} & & a_{mn} \end{bmatrix}$$

$$\text{Let } \underline{x} \in N(\underline{A}) \Rightarrow \underline{A}\underline{x} = \underline{0}$$

$$\begin{aligned} \underline{A}\underline{x} &= \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & & a_{2n} \\ \vdots & & & \vdots \\ a_{m1} & a_{m2} & & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \\ &= \begin{bmatrix} \underline{\text{row 1}} \cdot \underline{x} \\ \underline{\text{row 2}} \cdot \underline{x} \\ \vdots \\ \underline{\text{row m}} \cdot \underline{x} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \end{aligned}$$

The row space is the linear combination of the rows of \underline{A}

Since any \underline{x} in $N(\underline{A})$ gives $\underline{A}\underline{x} = \underline{0}$ and since $\underline{A}\underline{x}$ is simply a dot product between rows of \underline{A} and \underline{x}

$\Rightarrow C(\underline{A}^T) + N(\underline{A})$ are orthogonal to each other

(b) Another way to show this:

Let \underline{y} be any vector compatible with \underline{A}^T . Then

$\underline{A}^T \underline{y}$ is a linear combination of the rows of \underline{A}

Let \underline{x} be in $N(\underline{A})$. Then

$$\underline{x} \cdot (\underline{A}^T \underline{y}) = \underline{x}^T \underline{A}^T \underline{y} = (\underline{A} \underline{x})^T \underline{y} = \underline{0}^T \underline{y} = 0$$

(2) The column space $C(\underline{A})$ is an orthogonal subspace in \mathbb{R}^m of the left nullspace $N(\underline{A}^T)$

Let $\underline{A} \underline{y}$ represent any vector in $C(\underline{A})$

and let $\underline{x} \in N(\underline{A}^T) : \underline{x}^T \underline{A} = \underline{0} = \underline{A}^T \underline{x}$

Then,

$$\underline{x} \cdot (\underline{A} \underline{y}) = \underline{x}^T \underline{A} \underline{y} = (\underline{x}^T \underline{A}) \underline{y} = \underline{0}^T \underline{y} = 0$$

$$\begin{matrix} m \times 1 & & \\ \underbrace{m \times n} & \underbrace{n \times 1} & \\ m \times 1 & & \end{matrix}$$

$$\vec{u} \cdot \vec{v} = \vec{u}^T \vec{v}$$

Now, one step further

(1) $N(\underline{A})$ is the orthogonal complement of $C(\underline{A}^T)$ in \mathbb{R}^n

(2) $N(\underline{A}^T)$ is the orthogonal complement of $C(\underline{A})$ in \mathbb{R}^m

The orthogonal complement to a subspace contains every possible vector that is perpendicular (orthogonal) to that subspace.

Example: continued from above

$$\underline{A} = \begin{bmatrix} 8 & 2 & 1 & 23 \\ 4 & 2 & 9 & 19 \\ 10 & 1 & 6 & 35 \end{bmatrix}$$

Recall

$$([8] \ [4] \ [10])$$

Recall

$$C(\underline{A}^T) = \left\{ \begin{bmatrix} 8 \\ 2 \\ 1 \\ 23 \end{bmatrix}, \begin{bmatrix} 4 \\ 2 \\ 9 \\ 19 \end{bmatrix}, \begin{bmatrix} 10 \\ 1 \\ 6 \\ 35 \end{bmatrix} \right\}$$

↙
row space

$$N(\underline{A}) = \left\{ \begin{bmatrix} -3 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

$$\begin{bmatrix} -3 \\ 1 \\ -1 \\ 1 \end{bmatrix}^T \begin{bmatrix} 8 \\ 2 \\ 1 \\ 23 \end{bmatrix} = -24 + 2 - 1 + 23 = 0 \quad \checkmark$$

$$\begin{bmatrix} -3 \\ 1 \\ -1 \\ 1 \end{bmatrix}^T \begin{bmatrix} 4 \\ 2 \\ 9 \\ 19 \end{bmatrix} = -12 + 2 - 9 + 19 = 0 \quad \checkmark$$

$$\begin{bmatrix} -3 \\ 1 \\ -1 \\ 1 \end{bmatrix}^T \begin{bmatrix} 10 \\ 1 \\ 6 \\ 35 \end{bmatrix} = -30 + 1 - 6 + 35 = 0 \quad \checkmark$$

$\therefore N(\underline{A})$ is the orthogonal complement

to $C(\underline{A}^T)$

On the other hand,

$$C(\underline{A}) = \left\{ \begin{bmatrix} 8 \\ 4 \\ 10 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 9 \\ 6 \end{bmatrix} \right\}$$

which spans all of \mathbb{R}^3 . Consequently,

there is no other vector orthogonal to

$C(\underline{A})$ in \mathbb{R}^3 and the left nullspace

$N(\underline{A}^T)$ consists of only the zero vector,

that is,

$$N(\underline{A}^T) = \{ \} \text{ or } N(\underline{A}^T) = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

Pictorial View of the Four Subspaces of \underline{A}
(Strang, 2019)

$C(\underline{A}^T)$

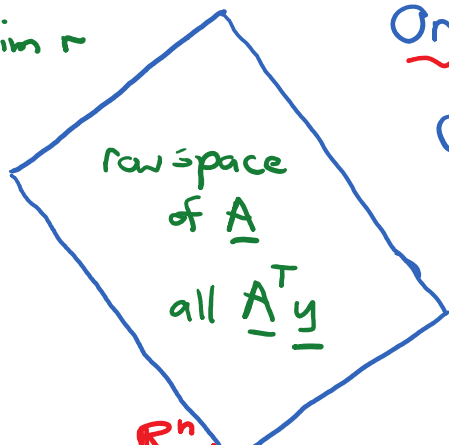
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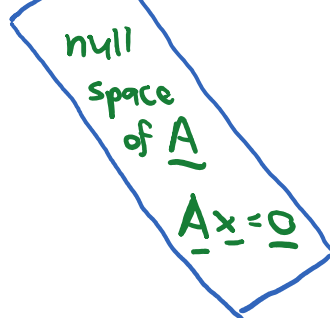
Orthogonal

$C(\underline{A}^T)$

dim r

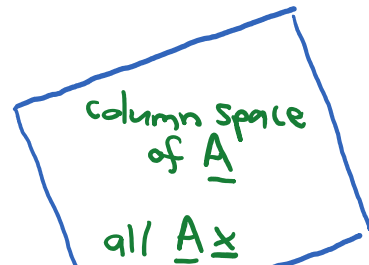


\mathbb{R}^n



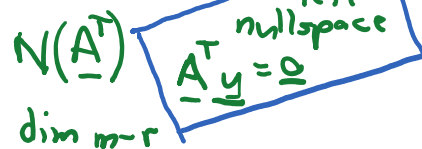
Orthogonal

Complements



$C(\underline{A})$
dim r

\mathbb{R}^m



$N(\underline{A}^T)$

dim $m-r$

$r = \text{rank}(\underline{A})$

$N(\underline{A})$

dim $n-r$