New $C = a + MPC(Y-T_x+T_r)$

New $C = a + MPCY - MPCT_x + MPCT_r$

New $C = a - MPCT_x + MPCT_r + MPCY$

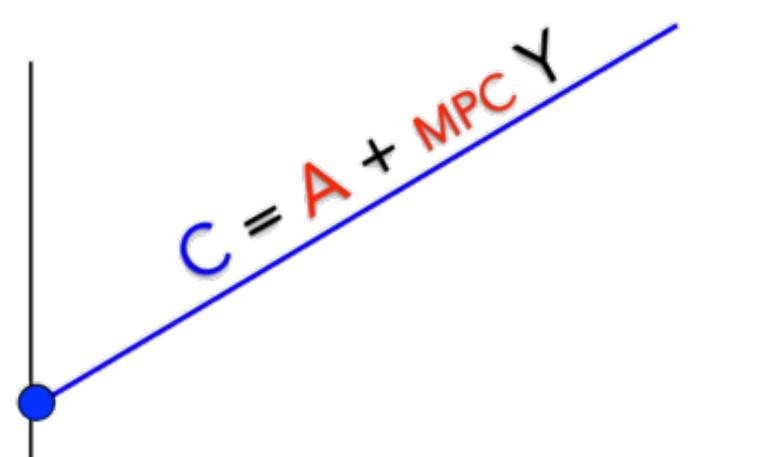
New Intercept

$A = a - MPCT_x + MPCT_r$

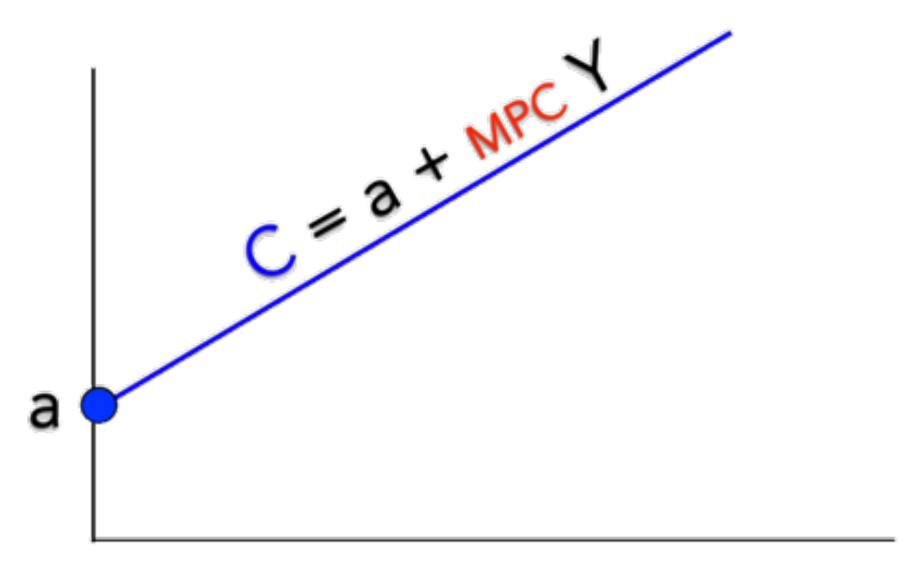


With Government

$$A = a - MPCTx + MPCTr$$



Without Government



With Government



























Rearrage terms:

New C =
$$a + MPC(Y-T_x+T_r)$$

With Government New $C = a + MPCY - MPCT_x + MPCT_r$

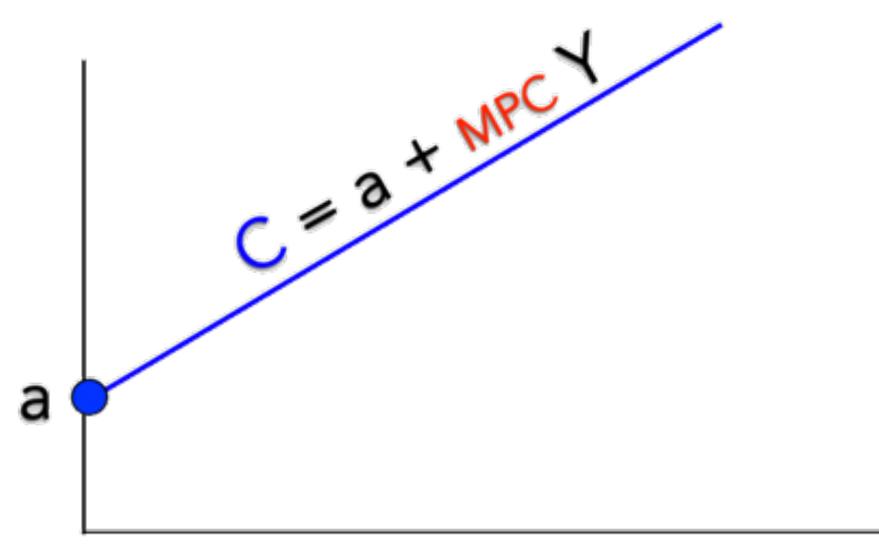
Rearrage terms:

New
$$C = a - MPCT_x + MPCT_r + MPCY$$
Same Slope

New

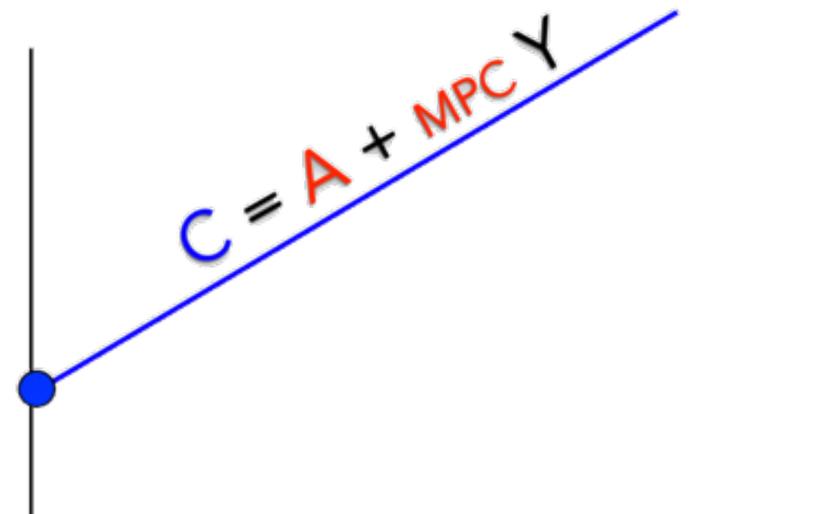
Intercept
$$A = a - MPCT_x + MPCT_r$$

Without Government



With Government

$$A = a - MPCTx + MPCTr$$



Without Government

