Lest square estimation method

S estimator for the linear mode constraint LS lartial LS

LS method - assumptions

Lets consider a linear regression

$$y_i = G(x_i; \theta) + u_i$$

Models:

- linear model: $G(x_i; \theta) = x_i \theta$
- nonlinear model: $G(x_i; \theta) = x_i\beta_1 + x_i\beta_2\Phi(z_i; \mu, \sigma^2)$ with $\Phi(z_i; \mu, \sigma^2)$ being a probit function,
- factor model: $G = \lambda' F_i$ with both λ and F_i unknown.

Linear regression - LS estimator

Lets consider a linear regression

$$y_i = x_i \theta + u_i$$

then

$$y = x\theta + u$$

Notation:

- $y = [y_1, ..., y_N]'$ a $(N \times 1)$ vector of endogenous variables,
- $x = [x'_1, ..., x'_N]'$ a $(N \times K)$ matrix of exogenous variables,
- $u = [u_1, ..., u_N]'$ a $(N \times 1)$ vector of random noise,
- θ is a $(K \times 1)$ vector of parameters.



LS method

Least square estimation method aims at minimizing a sum of squares of residuals

$$\hat{\theta} = argmin_{\theta \in \Theta} \sum_{i=1}^{N} u_i^2 = argmin_{\theta \in \Theta} u'u$$

Remark: The LS estimation method is an optimization problem. It can be applied for linear and nonlinear functions, even when not all assumptions of CLS are valid (then the estimator may not have all desired properties).

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LS estimator

In a linear model

$$y = x\theta + u$$

hence

$$\hat{\theta} = \operatorname{argmin}_{\theta \in \Theta} (y - x\theta)'(y - x\theta)$$

In a nonlinear model

$$y = G(x, \theta) + u$$

$$\hat{\theta} = argmin_{\theta \in \Theta}(y - G(x, \theta))'(y - G(x, \theta))$$

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We want to minimize the loss function

$$L = u'u$$

What are the F.O.C. for

• linear model with $u = y - x\theta$?

$$-2(y-x\theta)'x=0$$

$$-2(y-G(\theta;x))'\frac{\partial G(\theta;x)}{\partial \theta'}=0$$



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Examples

Examples of models

2
$$y_i = \mu + \beta_1 x_{1i} + ... + \beta_{K-1} x_{K-1i} + u_i$$

In the Model 1 $y_i = \mu + u_i$ Model residuals are

$$U_i = y_i - \mu = y_i - x_i \mu$$

with
$$x_i = 1$$

$$u = y - x\mu$$

$$\hat{\mu} = (x'x)^{-1}x'y = \frac{1}{N}\sum_{i=1}^{N} y_i$$

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In the Model 2

$$y_i = x_i'\theta + u_i$$

with $\theta = [\mu, \beta_1, ..., \beta_{K-1}]'$ and $x_i = [1, x_{i1}, ..., x_{iK-1}]$ the model is

$$y - x\theta$$

$$\hat{\theta} = (x'x)^{-1}x'y$$

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$$y - x\theta$$

$$\hat{\theta} = (x'x)^{-1}x'y$$

The parameter vector is

$$\theta = [\alpha, \beta, \gamma]'$$

The function $G(\theta; x_i) = \alpha x_{1i}^{\beta} x_{2i}^{\gamma}$ and the residuals are

$$u_i = y_i - G(\theta; x_i)$$

Hence F.O.C. are

$$u'\frac{\partial G(\theta;x)}{\partial \theta'}=0$$

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The derivative is

$$\frac{\partial G(\theta, x_i)}{\partial \theta'} = x_{1i}^{\beta} x_{2i}^{\gamma} \begin{bmatrix} 1, & \alpha \ln x_{1i}, & \alpha \ln x_{2i} \end{bmatrix}$$

F.O.C. don't have a closed form solution and...

... needs to be approximated numerically (NEWTON algorithm...) or estimated with a nonlinear LS algorithm

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LS estimation

To sum up

 For a linear model, the LS estimator has a closed form solution

$$\hat{\theta} = \left(X'X \right)^{-1} X'Y$$

 For a nonlinear model, there may not be a closed form solution for the LS problem. The minimum can be approximated numerically or with a nonlinear LS algorithm.

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 For a linear model, the LS estimator has a closed form solution

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CLS estimation

Sometimes, we need to estimate the constraint model, for example:

• identity constraint: $\theta_i = r$

• linear constraint: $R\theta = r$

• nonlinear constraint: $R(\theta) = 0$

CLS - identity constraint

Suppose, we work with a linear regression model

$$y = x\theta + u_i$$

and want to estimate the model with a constraint $\theta_1 = 1$. In the constraint model

$$y = x_1 + \tilde{x}\tilde{\theta} + u_i$$
$$\tilde{y} = \tilde{x}\tilde{\theta} + u_i$$

with

$$\tilde{y} = y - x_1$$

•
$$\tilde{x} = [x_2, ..., x_K]$$

•
$$\tilde{\theta} = [\theta_2, ..., \theta_K]'$$

CLS - identity constraint

The model

$$\tilde{y} = \tilde{x}\tilde{\theta} + u$$

can be simple estimated with LS

$$\hat{\tilde{\theta}} = (\tilde{x}'\tilde{x})\tilde{x}'\tilde{y}$$

and

$$\hat{ heta} = [1, \hat{ ilde{ heta}}']'$$

CLS - linear restriction

Lets consider a linear model with restriction:

$$\theta_1 - \theta_2 = 1$$

then

$$\theta_1 = \theta_2 + 1$$

and the model becomes

$$y = x_1(\theta_2 + 1) + x_2\theta_2 + ... x_K\theta_K + u = x_1 + (x_1 + x_2)\theta_2 + ... + u$$

CLS - linear restriction

We can rewrite the model

$$\tilde{y} = \tilde{x}\tilde{\theta} + u$$

with

$$\tilde{y} = y - x_1$$

$$\tilde{x} = [x_1 + x_2, x_3, ..., x_K]$$

$$\bullet \ \tilde{\theta} = [\theta_2, ..., \theta_K]'$$

The estimator

$$\hat{\tilde{\theta}} = (\tilde{x}'\tilde{x})\tilde{x}'\tilde{y}$$

and

$$\hat{\theta} = [\hat{\hat{\theta_2}} + 1, \hat{\hat{\theta}'}]'$$



CLS - linear restriction

Suppose, we want to estimate the model with *M* restrictions

$$R\theta = r$$

Lets assume that rk(R) = M. Then the parameters can be ordered in such a way that there exist a $(M \times K - M)$ matrix \tilde{R} and a $(M \times 1)$ vector \tilde{r} such that

$$\theta_{1:M} = \tilde{R}\theta_{M+1:K} + \tilde{r}$$

Question: how to use the restriction to reformulate the model and estimate the model parameters with LS?



Partial LS

Lets consider a linear regression model with two groups of regressors

$$y=x_1\theta_1+x_2\theta_2+u.$$

Suppose, we are interested only in the first vector of parameters: θ_1 .

Question: do we need to estimate the whole model?

Partial LS

Suppose, we regress *y* on *x* then the estimator is

$$\hat{\theta} = (x'x)^{-1}x'y$$

and residuals are

$$\hat{u} = y - x(x'x)^{-1}x'y = (I - x(x'x)^{-1}x')y = My$$

Notice: M is a symmetric, idempotent matrix and M = MM.

Lets look at $(x'x)^{-1}$:

$$(x'x)^{-1} = \begin{pmatrix} x'_1x_1 & x'_1x_2 \\ x'_2x_1 & x'_2x_2 \end{pmatrix}^{-1} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}$$

Then

$$\hat{\theta_1} = A_{11} x_1' y + A_{12} x_2' y$$

What is the inverse of a partition matrix $(x'x)^{-1}$:

$$(x'x)^{-1} = \begin{pmatrix} x'_1x_1 & x'_1x_2 \\ x'_2x_1 & x'_2x_2 \end{pmatrix}^{-1} = \begin{pmatrix} D & -D(x'_1x_2)(x'_2x_2)^{-1} \\ * & * \end{pmatrix}$$

with

$$D = \left((x_1'x_1) - (x_1'x_2)(x_2'x_2)^{-1}(x_2'x_1) \right)^{-1}$$

The partial estimator is

$$\hat{\theta}_1 = Dx_1'y - D(x_1'x_2)(x_2'x_2)^{-1}x_2'y$$

$$\hat{\theta}_1 = Dx_1'(I - x_2(x_2'x_2)^{-1}x_2')y$$

Lets denote by $M_2 = I - x_2(x_2'x_2)^{-1}x_2'$. It is similar to M a symmetric, idempotent matrix. Hence

$$\hat{\theta_1} = Dx_1'M_2'y$$

It can be shown that

$$D = (x_1' M_2' M_2 x_1)^{-1}$$

Hence

$$\hat{\theta_1} = (\tilde{x_1}'\tilde{x_1})\tilde{x_1}'y$$

where:

• $\tilde{x_1} = M_2 x_1$ are the residuals from regressing x_1 on x_2 !

Remark: when x_1 and x_2 are orthogonal then:

$$\tilde{x_1} = x_1$$

and

$$\hat{\theta_1} = (x_1'x_1)x_1'y$$

In all other cases:

$$\hat{\theta_1} \neq (x_1'x_1)x_1'y$$

Assumptions and properties of LS estimation method

LS estimator

We know, that for a linear regression model, the LS estimator is

$$\hat{\theta} = \left(x'x \right)^{-1} x'y$$

- What are the necessary conditions needed to estimate the model?
- What are the properties of the estimator?



- The model is linear
- ② Full rank: the $N \times K$ matrix X, has a full column rank
- **Solution Exogeneity of the independent variables**: $E(\varepsilon_i|x_j) = 0$ for any i and j. There is no correlation between the disturbances and the independent variables
- **1 Homoscedasticity and nonautocorrelation**: each disturbance ε_i has the same variance σ^2 and is uncorrelated with any other disturbance ε_i
- X are non stochastic
- Normal distribution: residuals are normally distributed



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Questions

- Which of these assumptions are necessary?
- Why are these assumptions imposed?

Lets go back to the parameter estimator

$$\hat{\theta} = (x'x)^{-1} x'y$$

It can be computed, only when $(x'x)^{-1}$ exists.

A1: The columns of X are linearly independent (the a2 in CLS)

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A1: The columns of X are linearly independent (the a2 in CLS)

When is the A1 assumption a problem?

- When we use some artificial indicators, which can be a linear function of variables
- When dummy variables are added in the model

Consistency

What conditions are necessary to ensure consistency?

$$\hat{\theta} = \theta + (x'x)^{-1} x'u$$

Hence

$$\hat{\theta} - \theta = \left(\frac{x'x}{N}\right)^{-1} \frac{x'u}{N}$$

We want

$$\hat{\theta} - \theta \rightarrow_{p} 0_{K \times 1}$$

Consistency

$$\hat{\theta} - \theta = \left(\frac{x'x}{N}\right)^{-1} \frac{x'u}{N}$$

A2: there exists a second, noncentral moment of X

$$\frac{x'x}{N} \to \Omega$$

A3: there is no correlation between the disturbances and the independent variables

$$\frac{x'u}{N} \to 0_{K \times 1}$$

Then

$$\hat{\theta} - \theta \rightarrow_{p} 0_{K \times 1}$$



Unbiasedness

Under conditions A1-A3, the LS estimator is unbiased

$$E(\hat{\theta} - \theta | X) = \left(\frac{X'X}{N}\right)^{-1} \frac{X'U}{N} | X) = 0$$

Hence the conditions A2-A3 are crucial for consistency and unbiasedness.

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When the assumptions are not valid:

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- Omitted variables IV estimation method

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Suppose, we want to estimate the model

$$Income_i = \mu + \beta_1 Age_i + \beta_2 Edu_i + \beta_3 Exp_i + \beta_4 Sex_i + \varepsilon_i$$

What variables are not included in the model (left in residuals)?

- Social skills
- Intelligence
- Personal feature



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Remember: there is a third feature of an estimator - efficiency.

Question: what is the variance of the estimator?

It can be shown that

$$\Sigma(\hat{\theta} - \theta | x) = (x'x)^{-1} x' E (uu'|x) x (x'x)^{-1}$$

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Under the assumption

A4: each disturbance u_i has the same variance σ^2 and is uncorrelated with any other disturbance u_j (homoscedasticity and no autocorrelation)

$$E\left(uu'\right) = \sigma^2 I_N$$

Then

$$\Sigma(\hat{\theta} - \theta | x) = \sigma^2 (x'x)^{-1}$$

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The assumption A4 is needed to compute the variance of the estimator

...but is not needed to ensure consistency and unbiasedness.

Efficiency

I order to estimate the variance of the residuals σ^2 , two type of estimators are typically used

Unbiased, consistent

$$\hat{\sigma}^2 = \frac{e'e}{N - K}$$

Biased, consistent

$$\hat{\sigma}^2 = \frac{e'e}{N}$$

Where e is a vector of residuals computed for $\hat{\theta}$.



Efficiency

Then the variance-covariance matrix of parameters is

$$\Sigma_{\hat{\theta}} = \hat{\sigma}^2 \left(x' x \right)^{-1}$$

Parameter variances are

$$Var(\hat{ heta}) = diag\left(\Sigma_{\hat{ heta}}\right)$$

Standard deviation

$$\mathit{St.Dev}(\hat{ heta}) = \sqrt{\mathit{diag}\left(\Sigma_{\hat{ heta}}
ight)}$$



What is the asymptotic distribution of the LS estimator?

Under assumptions A1-A3 we have shown that

$$\hat{\theta} - \theta = \left(\frac{x'x}{N}\right)^{-1} \frac{x'u}{N} \to_{\rho} 0$$

Hence, $\hat{\theta}$ has a degenerated distribution

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In order to use the CLT, we need to multiply $\hat{\theta}$ by \sqrt{N} . Then

$$\sqrt{N}(\hat{\theta} - \theta) = \left(\frac{x'x}{N}\right)^{-1} \frac{x'u}{\sqrt{N}}$$

From A2, it follows

$$\left(\frac{X'X}{N}\right)^{-1} \to_{p} \Omega^{-1}$$

Under Grenader conditions (weak conditions, which ensure that *X* is well behaved)

$$\frac{x'u}{\sqrt{N}} \to N(0,\Phi)$$



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What is Φ?

$$\Phi_N = E(\frac{1}{N}x'uu'x)$$

Under A4, it converges to Ф

$$\Phi = \sigma^2 \Omega$$

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$$\Phi = \sigma^2 \Omega$$

Finally

$$\sqrt{N}(\hat{\theta} - \theta) \rightarrow \Omega^{-1}N\left(0, \sigma^{2}\Omega\right) = N\left(0, \sigma^{2}\Omega^{-1}\right)$$

Remark: We obtain asymptotic normality, without assuming the normality of disturbances.

Finally

$$\sqrt{\textit{N}}(\hat{\theta} - \theta) \rightarrow \Omega^{-1}\textit{N}\left(0, \sigma^2\Omega\right) = \textit{N}\left(0, \sigma^2\Omega^{-1}\right)$$

Remark: We obtain asymptotic normality, without assuming the normality of disturbances.

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