

Geometric Buildup Methods for Protein Structure Determination

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Outline

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1 Problem Introduction

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- 2 Related Works

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- 4 Two New Models

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- 4 Two New Models
- 5 Conclusions and Future work

Distance Geometry(DG) Problem

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 - distance bounds

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► applications:

- graph realization
- **protein structure determination** (3D)
- sensor network localization (2D)
- ...

Related works

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Matrix Decomposition Method

DG problem with full set of exact distances

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► Set $x_n = (0, 0, 0)^T$, we have

$$\begin{aligned} d_{i,j}^2 &= \|x_i - x_j\|^2 \\ &= \|x_i\|^2 - 2x_i^T x_j + \|x_j\|^2 \\ &= d_{i,n}^2 - 2x_i^T x_j + d_{j,n}^2 \quad i, j = 1, 2, \dots, n-1 \end{aligned} \quad (1)$$

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► Define $X = (x_1, x_2, \dots, x_n)^T$ and

$$D = \{(d_{i,n}^2 - d_{i,j}^2 + d_{j,n}^2)/2 : i, j = 1, 2, \dots, n-1\}, (1) \Rightarrow \mathbf{X}\mathbf{X}^T = D.$$

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► Let $D = U\Sigma U^T$, and $V = U(:, 1:3)$, $\Lambda = \Sigma(1:3, 1:3)$. Then $X = V\Lambda^{1/2}$ solves the problem. [Eckart and Young 1936]

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 - determine their coordinates to remove the possible translation and rotation/reflection

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Zachary Voller, Zhijun Wu(2012), [Distance Geometry Methods for Protein Structure Determination](#).

Determine one unknown atom

Given four determined atoms x_1, x_2, x_3 and x_4 , which $x_i = (x_{i1}, x_{i2}, x_{i3})^T$ are known, and four **exact** distances.

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$$\blacktriangleright \Rightarrow Ax_j = b,$$

$$\text{where } A = 2 \begin{pmatrix} x_{11} - x_{21} & x_{12} - x_{22} & x_{13} - x_{23} \\ x_{21} - x_{31} & x_{22} - x_{32} & x_{23} - x_{33} \\ x_{31} - x_{41} & x_{32} - x_{42} & x_{33} - x_{43} \end{pmatrix}$$

$$\text{and } b = \begin{pmatrix} (\|x_1\|^2 - \|x_2\|^2) - (d_{1,j}^2 - d_{2,j}^2) \\ (\|x_2\|^2 - \|x_3\|^2) - (d_{2,j}^2 - d_{3,j}^2) \\ (\|x_3\|^2 - \|x_4\|^2) - (d_{3,j}^2 - d_{4,j}^2) \end{pmatrix}.$$

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\blacktriangleright **Inexact** distances?

Linear and Nonlinear Least-squares Approximation

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Linear and Nonlinear Least-squares Approximation

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Suppose l distances between the unknown atom to the determined atoms are known.

► linear least-squares

- use only the l distances
- $\min \|b - Ax_j\|$

► nonlinear least-squares

- use all the distances among the $l + 1$ atoms
- solve a matrix decomposition problem
- move the same points in two different reference system coincide

Atila Sit, Zhijun Wu and Ya-xiang Yuan(2009), [A geometric buildup algorithm for the solution of the distance geometry problem using least-squares approximation.](#)

Laplacian Matrix

Given a graph (V, E) , define its Laplacian matrix by L , whose entries $l_{i,j}$ are given by

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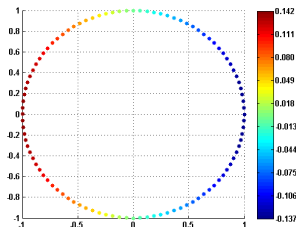
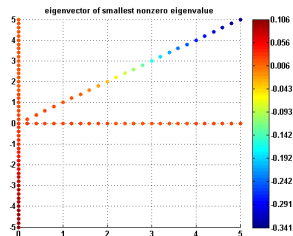
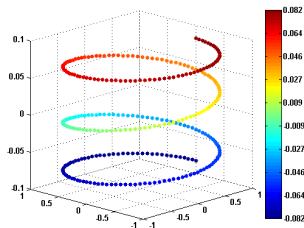
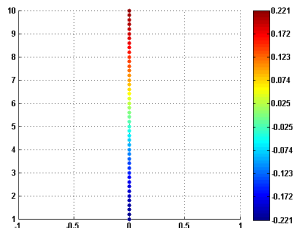
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► $L = D - A$, where D is degree matrix, and A is its adjacency matrix.

► Properties:

- L is always positive-semidefinite.
- 0 is always its eigenvalue and its corresponding eigenvector is $(1, 1, \dots, 1)^T$.
- The number of times 0 appears as an eigenvalue in the Laplacian is the number of connected components in the graph.

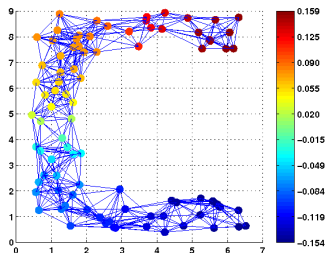
Eigenvector of smallest nonzero eigenvalue



a Conjecture

Conjecture

Given a graph (V, E) , its Laplacian matrix is defined as before, then the eigenvector of the smallest nonzero eigenvalue, which can be viewed as a function of the vertexes, monotonically decrease or increase along the main trend/direction of the graph.



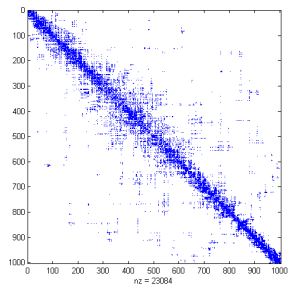
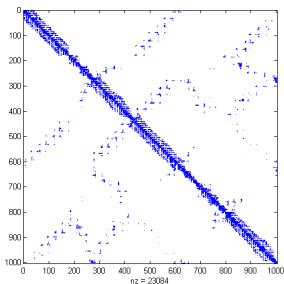


Figure : 1AX8

Implement Details

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► computational order:

IAX8, 1003 atoms, cutoff=5Å, 2.3% exact		
order	RmsdErr	CPU time (s)
original	7.395926e+000	1.258295
greedy	9.281000e-005	2.346640
Laplacian	9.281000e-005	1.999627
random	7.372537e-007	4.980335
	1.726266e-007	2.946320
	3.858138e-003	2.988656
	2.437341e-008	3.517570
	1.223379e-005	4.757714
	1.169260e-003	5.339559
	1.399711e-006	2.478225
	1.771925e-005	4.957635
	9.559394e-009	2.750663
	8.637780e-007	5.196890

► computational order:

1MQQ, 5681 atoms, cutoff=6 Å, 0.75%, exact		
order	RmsdErr	CPU time (s)
original	1.130061e+001	11.262673
greedy	4.310119e-003	53.904010
Laplacian	5.039401e-005	135.032459
random	5.315594e-003	23.218307
	1.612265e-002	67.657580
	2.928411e-004	142.834237
	2.262457e-007	29.632780
	3.823293e-006	70.646800
	3.165929e-003	140.470924
	8.535506e-001	254.812797
	6.665072e-005	214.758550
	4.334586e-001	141.894475
	2.888975e-001	23.932108

PDB ID	No.	greedy order				Laplacian order		
		RmsdErr	CPU time	NumDet		RmsdErr	CPU time	NumDet
1PTQ	402	1.15e-012	1.22e+000	402		8.97e-013	4.98e-001	402
1HOE	558	1.50e-012	8.09e-001	558		1.08e-011	2.17e+000	558
1LFB	641	7.59e-010	9.10e-001	641		1.75e-010	1.51e+000	641
1PHT	811	1.61e-011	1.23e+000	811		1.67e-013	8.41e+001	4
1POA	914	6.17e-010	1.43e+000	914		3.31e-011	1.59e+000	914
1AX8	1003	1.24e-011	1.68e+000	1003		4.87e-007	3.62e+000	1003
1F39	1534	2.32e-006	3.86e+000	1534		4.03e-014	2.93e+002	1534
1RGS	461	2.61e-014	2.11e-001	4		3.33e-014	2.14e+000	4
1KDH	2846	7.15e-004	8.56e+000	2846		1.58e-001	5.17e+000	2846
1BPM	3671	4.45e-005	9.03e+000	3671		9.45e-013	9.92e+002	4
1RHJ	3740	3.47e-008	1.07e+001	3740		1.00e-006	1.19e+001	3740
1HQQ	3944	4.77e-006	1.22e+001	3944		2.76e+000	7.43e+000	3944
1TOA	4292	2.35e+001	2.79e+001	4292		1.09e-001	8.93e+000	4292
1MQQ	5681	4.31e-003	4.98e+001	5681		1.55e-002	5.48e+001	5681

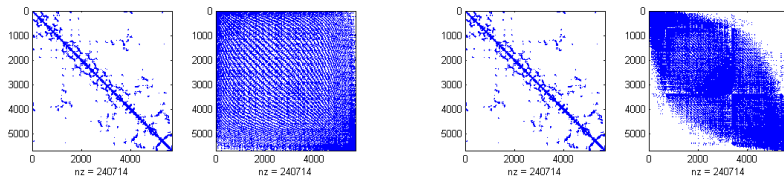


Figure : 1MQQ, greedy, theoretical VS. real order

Some other problems

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- ▶ \rightsquigarrow move to last

Motivation

1MQQ, 5681 atoms, cutoff=6Å, 0.75%, exact distances

ltr	RmsdErr	ltr	RmsdErr
300	1.020647e-012	3000	1.186818e-004
600	1.805403e-010	3300	3.477342e-004
900	2.059775e-007	3600	1.953754e-003
1200	6.691896e-007	3900	1.973875e-003
1500	3.358551e-006	4200	2.162615e-003
1800	4.677271e-006	4500	2.231129e-003
2100	7.869284e-006	4800	2.790680e-003
2400	2.062700e-005	5100	3.084867e-003
2700	6.988388e-005	5400	4.277911e-003

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► Error Accumulation!

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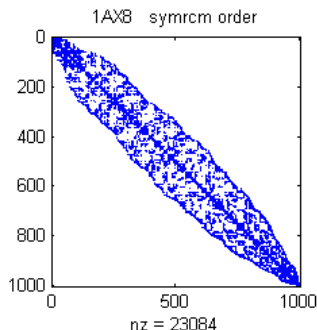
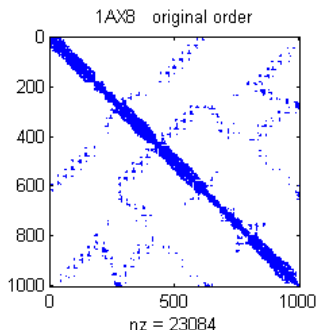
- ▶ Divide into small patches
- ▶ Geometric Buildup at each patch
- ▶ Stitch together

How to divide

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- **symrcm**: minimize the bandwidth

Pratik Biswas, Kim-Chuan Toh and Yinyu Ye(2007), [A Distributed SDP Approach for Large-scale Noisy Anchor-free Graph Realization with Application to Molecular Conformation](#).



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$$\begin{aligned} \min_{R, T} \quad & \sum_{i=1}^k \|p_i - (Rq_i + T)\|_2^2 \\ \text{s.t.} \quad & R^T R = I. \end{aligned} \tag{2}$$

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► R:

$$\begin{aligned} \min_R \quad & \|P - RQ\|_F^2 \\ \text{s.t.} \quad & R^T R = I. \end{aligned} \tag{3}$$

Let $C = PQ^T$, and $C = U\Sigma V^T$, then $R = VU^T$ solves (3). [[Matrix Computation, Golub](#)]

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► Remark: a fundamental problem in [Machine Intelligence](#) and [Optical Science](#).

Numerical experiments

Distributed Buildup:

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1AX8	1003	4.161234e-008	1.793236
1F39	1534	3.480137e-012	4.303442
1RGS	2015	1.804018e-009	4.713639
1KDH	2923	5.424939e+002	18.708290

A generalized DG problem

DG problem with distance bounds

Given the lower bounds $l_{i,j}$ and upper bounds $u_{i,j}$, the problem can be formulated as:

$$\begin{aligned} \max_{x_i, r_i} \quad & \sum_{i=1}^n r_i \\ \text{s.t.} \quad & \|x_i - x_j\| + r_i + r_j \leq u_{i,j} \\ & \|x_i - x_j\| - r_i - r_j \geq l_{i,j} \quad \forall (i,j) \in S \\ & r_i \geq 0, \quad i = 1, 2, \dots, n. \end{aligned}$$

Atila Sit, Zhijun Wu(2011), [Solving a Generalized Distances Geometry Problem for Protein Structure Determination](#).

Matrix Completion for DG

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- ▶ Given distance matrix D , we have

$$\begin{aligned} DD &= D.^2 = (d_{i,j}^2) \\ &= (\|x_i\|^2 - 2x_i^T x_j + \|x_j\|^2) \\ &= E + E^T - 2XX^T. \end{aligned}$$

where E is a rank one matrix.

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- ▶ FPCA, LMaFit

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► X is symmetric.

A new type of MC problem



$$\begin{aligned} \min_{X, x_i} \quad & \|X - \sum_{i=1}^r x_i x_i^T\|_F^2 \\ \text{s.t.} \quad & X_{i,j} = M_{i,j}, \quad \forall (i,j) \in S, \end{aligned}$$

- ▶ X is symmetric.
- ▶ M has some special structure (not randomly sampled).

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► Future work:

- theoretical analysis on eigenvector of Laplacian matrix
- make clear the advantage and limitation of our distributed method
- work on the new models

Thank you for your attention!