

Real-Time Web Scale Event Summarization Using Sequential Decision Making

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Abstract

We present a system based on sequential decision making for the online summarization of massive document streams, such as those found on the web. Given an event of interest (e.g. “Boston marathon bombing”), our system is able to filter the stream for relevance and produce a series of short text updates describing the event as it unfolds over time. Unlike previous work, our approach is able to jointly model the relevance, comprehensiveness, novelty, and timeliness required by time-sensitive queries. We demonstrate a 28.3% improvement in summary F_1 and a 43.8% improvement in time-sensitive F_1 metrics.

1 Introduction

Tracking unfolding news at web-scale continues to be a challenging task. Crisis informatics, monitoring of breaking news, and intelligence tracking all have difficulty in identifying new, relevant information within the massive quantities of text that appear online each second. One broad need that has emerged is the ability to provide realtime event-specific updates of streaming text data which are timely, relevant, and comprehensive while avoiding redundancy.

Unfortunately, many approaches have adapted standard automatic multi-document summarization techniques that are inadequate for web scale applications. Typically, such systems assume full retrospective access to the documents to be summarized, or that at most a handful of updates to the summary will be made [Dang and Owczarzak, 2008]. Furthermore, evaluation of these systems has assumed reliable and relevant input, something missing in an inconsistent, dynamic, noisy stream of web or social media data. As a result, these systems are poor fits for most real world applications.

In this paper, we present a novel streaming-document summarization system based on sequential decision making. Specifically, we adopt the “learning to search” approach, a technique which adapts methods from reinforcement learning for structured prediction problems [Daumé III *et al.*, 2009; Ross *et al.*, 2011]. In this framework, we cast streaming summarization as a form of greedy search and train our system to imitate the behavior of an oracle summarization system.

4:19 p.m. – Two explosions shattered the euphoria of the Boston Marathon finish line on Monday, sending authorities out on the course to carry off the injured while the stragglers were rerouted away...

4:31 p.m. – Police in New York City and London are stepping up security following explosions at the Boston Marathon.

4:31 p.m. – A senior U.S. intelligence official says two more explosive devices have been found near the scene of the Boston marathon where two bombs detonated earlier.

5:10 p.m. – Several candidates for Massachusetts Senate special election have suspended campaign activity in response to the explosions...

Figure 1: Excerpt of summary for the query ‘Boston marathon bombing’ generated from an input stream.

Given a stream of sentence-segmented news webpages and an event query (e.g. “Boston marathon bombing”), our system monitors the stream to detect relevant, comprehensive, novel, and timely content. In response, our summarizer produces a series of short text updates describing the event as it unfolds over time. We present an example of our realtime update stream in Figure 1. We evaluate our system in a crisis informatics setting on a diverse set of event queries, covering severe storms, social unrest, terrorism, and large accidents. We demonstrate a 28.3% improvement in summary F_1 and a 43.8% improvement in time-sensitive F_1 metrics against several state-of-the-art baselines.

2 Related Work

Multi-document summarization (MDS) has long been studied by the natural language processing community. We focus specifically on extractive summarization, where the task is to take a collection of text and select some subset of sentences from it that adequately describes the content subject to some budget constraint (e.g. the summary must not exceed k words). For a more in depth survey of the field, see [Nenkova and McKeown, 2012].

Because labeled training data is often scarce, unsupervised approaches to clustering and ranking predominate the field.

Popular approaches involve ranking sentences by various notions of input similarity or graph centrality [Radev *et al.*,

2000; Erkan and Radev, 2004].

Other ranking based methods use coverage of topic signatures [Lin and Hovy, 2000], or KL divergence between input/summary word distributions [Haghighi and Vanderwende, 2009] as the ranking, possibly adding some diversity penalty to ensure broader coverage.

Update summarization research has primarily focused on producing a 100 word summary from a set of 10 documents, assuming the reader is familiar with a different initial set of 10 documents [Dang and Owczarzak, 2008]. Generally the approaches to update summarization have adapted the above techniques. Top performers at the 2011 Text Analysis Conference (the last year update summarization was a task) made use of graph ranking algorithms, and topic model/topic-signature style importance estimates [Du *et al.*, 2011; Mason and Charniak, 2011; Conroy *et al.*, 2011].

Streaming or temporal summarization was first explored in the context of topic detection and tracking [Allan *et al.*, 2001] and more recently at the Text Retrieval Conference (TREC) [Aslam *et al.*, 2013]. Top performers at TREC included an affinity propagation clustering approach [Kedzie *et al.*, 2015] and a ranking/MDS system combination method [McCreadie *et al.*, 2014]. Both methods are unfortunately constrained to work in hourly batches, introducing potential latency. Perhaps most similar to our work is that of [Guo *et al.*, 2013] which iteratively fits a pair of regression models to predict ngram recall and precision of candidate updates to a model summary. However, their learning objective fails to account for errors made in subsequent prediction steps.

3 Problem Definition

A streaming summarization task is composed of a brief text query q , including a categorical event type (e.g. ‘earthquake’, ‘hurricane’), as well as a document stream $[X_0, X_1, \dots]$. In practice, we assume that each document is segmented into a sequence of sentences and we therefore consider a sentence stream $[x_0, x_1, \dots]$. A streaming summarization algorithm then selects or skips each sentence x as it is observed such that the end user is provided a filtered stream of sentences that are relevant, comprehensive, low redundancy, and timely (see Section 5.2). We refer to the selected sentences as *updates* and collectively they make up an *update summary*. We show a fragment of an update summary for the query ‘Boston marathon bombing’ in Figure 1.

4 Streaming Summarization as Sequential Decision Making

We could naively treat this problem as classification and predict which sentences to select or skip. However, this would make it difficult to take advantage of many features (e.g. sentence novelty w.r.t. previous updates). What is more concerning, however, is that the classification objective for this task is somewhat ill-defined: successfully predicting select on one sentence changes the true label (from select to skip) for sentences that contain the same information but occur later in the stream.

In this work, we pose streaming summarization as a greedy search over a binary branching tree where each level corre-

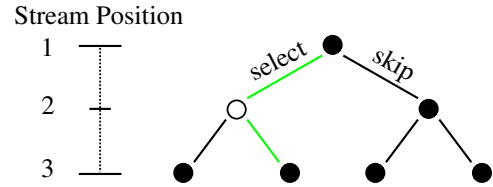


Figure 2: Search space for a stream of size two. The depth of the tree corresponds to the position in the stream. Left branches indicate selecting the current sentence as an update. Right branches skip the current sentence. The path in green corresponds to one trajectory through this space consisting of a select sentence one, then skip sentence 2. The state represented by the hollow dot corresponds to the stream at sentence position 2 with the update summary containing sentence 1.

sponds to a position in the stream (see Figure 2). The height of the tree corresponds to the length of stream. A path through the tree is determined by the system select and skip decisions.

When treated as a sequential decision making problem, our task reduces to defining a policy for selecting a sentence based on its properties as well as properties of its ancestors (i.e. all of the observed sentences and previous decisions). The union of properties—also known as the features—represents the current state in the decision making process.

The feature representation provides state abstraction both within a given query’s search tree as well as to states in other queries’ search trees, and also allows for complex interactions between the current update summary, candidate sentences, and stream dynamics unlike the classification approach.

In order to learn an effective policy for a query q , we can take one of several approaches. We could use a simulator to provide feedback to a reinforcement learning algorithm. Alternatively, if provided access to an evaluation algorithm at training time, we can simulate (approximately) optimal decisions. That is, using the training data, we can define an *oracle policy* that is able to omnisciently determine which sentences to select and which to skip. Moreover, it can make these determinations by starting at the root or at an arbitrary node in the tree, allowing us to observe optimal performance in states unlikely to be reached by the oracle. We adopt *locally optimal learning to search* to learn our model from the oracle policy [Chang *et al.*, 2015].

In this section, we will begin by describing the learning algorithm abstractly and then in detail for our task. We will conclude with details on how to train the model with an oracle policy.

4.1 Algorithm

In the induced search problem, each search state s_t corresponds to observing the first t sentences in the stream x_1, \dots, x_t and a sequence of $t - 1$ actions a_1, \dots, a_{t-1} . For all states $s \in \mathcal{S}$, the set of actions is $a \in \{0, 1\}$ with 1 indicating we add the t -th sentence to our update summary, and 0 indicating we ignore it. For simplicity, we assume a fixed length stream of size T but this is not strictly necessary. From each input stream, $\mathbf{x} = x_1, \dots, x_T$, we produce a corresponding output $\mathbf{a} \in \{0, 1\}^T$. We use $\mathbf{x}_{:t}$ to indicate the first t elements of \mathbf{x} .

Input: $\{\mathbf{x}_q, \pi_q^*\}_{q \in \mathcal{Q}}$, number of iterations N , and a mixture parameter $\beta \in (0, 1)$ for roll-out.

Output: $\tilde{\pi}$

```

1 Initialize  $\tilde{\pi}_0$ 
2  $i \leftarrow 0$ 
3 for  $n \in \{1, 2, \dots, N\}$  do
4   for  $q \in \mathcal{Q}$  do
5      $\Gamma \leftarrow \emptyset$ 
6     for  $t \in \{0, 1, \dots, T-1\}$  do
7       Roll-in by executing  $\tilde{\pi}_i$  for  $t$  rounds and reach  $s_t$ .
8       for  $a \in \mathcal{A}(s_t)$  do
9         Let  $\pi^0 = \pi_q^*$  with probability  $\beta$ , else  $\tilde{\pi}_i$ .
10        Compute  $c_t(a)$  by rolling out with  $\pi^0$ 
11         $\Gamma \leftarrow \Gamma \cup \{\langle \Phi(s_t), a, c_t(a) \rangle\}$ 
12       $\tilde{\pi}_{i+1} \leftarrow \text{Update Cost-Sensitive Classifier}(\tilde{\pi}_i, \Gamma)$ 
13       $i \leftarrow i + 1$ 
14 Return  $\tilde{\pi}_i$ .

```

Algorithm 1: Locally optimal learning to search.

For a training query q , a reference policy π_q^* can be constructed from the training data. Specifically, with access to the relevance and novelty of every x_i in the stream, we can omnisciently make a decision whether to select or skip based on a long term metric (see Section 5.2). The goal then is to learn a policy $\tilde{\pi}$ that imitates the reference well across a set of training queries \mathcal{Q} . We encode each state as a vector in \mathbb{R}^d with a feature function Φ and our learned policy is a mapping $\tilde{\pi} : \mathbb{R}^d \rightarrow \mathcal{A}$ of states to actions.

We train $\tilde{\pi}$ using locally optimal learning to search [Chang *et al.*, 2015], presented in Algorithm 1. The algorithm operates by iteratively updating a cost-sensitive classifier. For each training query, we construct a query-specific training set Γ by simulating the processing of the training input stream \mathbf{x}_q . The instances in Γ are triples comprised of a feature vector derived from the current state s , a candidate action a , and the cost $c(a)$ associated with taking action a in state s . Constructing Γ consists of (1) selecting states and actions, and (2) computing the cost for each state-action pair.

The number of states is exponential in T , so constructing Γ using the full set of states may be computationally prohibitive. Beyond this, the states in Γ would not be representative of those visited at test time. In order to address this, we sample from S by executing the current policy $\tilde{\pi}$ throughout the training simulation, resulting in T state samples for Γ , (lines 5-12).

Given a sampled state s , we need to compute the cost of taking actions $a \in \{0, 1\}$. With access to a query-specific oracle, π_q^* , we can observe its preferred decision at s and penalize choosing the other action. The magnitude of this penalty is proportional to the difference in expected performance between the oracle decision and the alternative decision. The performance of a decision is derived from a loss function ℓ , to be introduced in Section 4.3. Importantly, our loss function is defined over a complete update summary, incorporating the implications of selecting an action on future decisions. Therefore, our cost needs to incorporate a sequence of decisions af-

ter taking some action in state s . The algorithm accomplishes this by rolling out a policy after a until the stream has been exhausted (line 10). As a result, we have a prefix defined by $\tilde{\pi}$, an action, and then a suffix defined by the roll out policy. In our work, we use a mixture policy that combines both the current model $\tilde{\pi}$ and the oracle π^* (line 9). This mixture policy encourages learning from states that are likely to be visited by the current learned policy but not by the oracle.

After our algorithm has gathered Γ for a specific q using $\tilde{\pi}_i$, we train on the data to produce $\tilde{\pi}_{i+1}$. Here $\tilde{\pi}_i$ is implemented as a cost-sensitive classifier, i.e. a linear regression of the costs on features and actions; the natural policy is to select the action with lowest predicted cost. With each query, we update the regression with stochastic gradient descent on the newly sampled (state, action, cost) tuples (line 12). We repeat this process for N passes over all queries in the training set.

In the following sections, we specify the feature function Φ , the loss ℓ , and our reference policy π^* .

4.2 Features

As mentioned in the previous section, we represent each state as a feature vector. In general, at time t , these features are functions of the current sentence (i.e. x_t), the stream history (i.e. $\mathbf{x}_{:t}$), and/or the decision history ($\mathbf{a}_{:t-1}$). We refer to features only determined by x_t as static features and all others as dynamic features.¹

Static Features

Basic Features Our most basic features look at the length in words of a sentence, its position in the document, and the ratio of specific named entity tags to non-named entity tokens. We also compute the average number of sentence tokens that match the event query words and synonyms using WordNet.

Language Model Features Similar to [Kedzie *et al.*, 2015], we compute the average token log probability of the sentence on two language models: i) an event type specific language model and ii) a general newswire language model. The first language model is built from Wikipedia articles relevant to the event-type domain. The second model is built from the New York Times and Associate Press sections of the Gigaword-5 corpus [Graff and Cieri, 2003].

Single Document Summarization Features These features are computed using the current sentence’s document as a context and are also commonly used as ranking features in other document summarization systems. Where a similarity or distance is need, we use either a tf-idf bag-of-words or k -dimensional latent vector representation. The latter is derived by projecting the former onto a k -dimensional space using the weighted textual matrix factorization method [Guo and Diab, 2012].

We compute SUMBASIC features [Nenkova and Vanderwende, 2005]: the average and sum of unigram probabilities in a sentence. We compute the arithmetic and geometric means of the sentence’s cosine distance to the other sentences of the document [Guo *et al.*, 2013]. We refer to this quantity as novelty and compute it with both vector representations.

¹ We have attempted to use a comprehensive set of static features used in previous summarization systems. We omit details for space but source code is available at: <https://github.com/kedz/ijcai2016>

We also compute the centroid rank [Radev *et al.*, 2000] and LexRank of each sentence [Erkan and Radev, 2004], again using both vector representations.

Summary Content Probability For a subset of the stream sentences we have manual judgements as to whether they match to model summary content or not (see Sec. 5.1, Expanding Relevance Judgments). We use this data (restricted to sentences from the training query streams), to train a decision tree classifier, using the sentences’ term ngrams as classifier features. As this data is aggregated across the training queries, the purpose of this classifier is to capture the importance of general ngrams predictive of summary worthy content.

Using this classifier, we obtain the probability that the current sentence x_t contains summary content and use this as a model feature.

Dynamic Features

Stream Language Models We maintain several unigram language models that are updated with each new document in the stream. Using these counts, we compute the sum, average, and maximum token probability of the non-stop words in the sentence. We compute similar quantities restricted to the *person*, *location*, and *organization* named entities.

Update Similarity The average and maximum cosine similarity of the current sentence to all previous updates is computed under both the tf-idf bag-of-words and latent vector representation. We also include indicator features for when the set of updates is empty (i.e. at the beginning of a run) and when either similarity is 0.

Document Frequency We also compute the hour-to-hour percent change in document frequency of the stream. This feature helps gauge breaking developments in an unfolding event. As this feature is also heavily affected by the daily news cycle (larger average document frequencies in the morning and evening) we compute the 0-mean/unit-variance of this feature using the training streams to find the mean and variance for each hour of the day.

Feature Interactions Many of our features are helpful for determining the importance of a sentence with respect to its document. However, they are more ambiguous for determining importance to the event as a whole. For example, it is not clear how to compare the document level PageRank of sentences from different documents. To compensate for this, we leverage two features which we believe to be good global indicators of update selection: the summary content probability and the document frequency. These two features are proxies for detecting (1) a good summary sentences (regardless of novelty with respect to other previous decisions) and (2) when an event is likely to be producing novel content. We compute the conjunctions of all previously mentioned features with the summary content probability and document frequency separately and together.

4.3 Oracle Policy and Loss Function

Much of the multi-document summarization literature employs greedy selection methods. We adopt a greedy oracle that selects a sentence if it improves our evaluation metric (see Section 5.2).

We design our loss function to penalize policies that severely over- or under-generate. Given two sets of decisions, usually one from the oracle and another from the candidate model, we define the loss as the complement of the Dice coefficient between the decisions,

$$\ell(\mathbf{a}, \mathbf{a}') = 1 - 2 \times \frac{\sum_i a_i a'_i}{\sum_i a_i + a'_i}.$$

This encourages not only local agreement between policies (the numerator of the second term) but that the learned and oracle policy should generate roughly the same number of updates (the denominator in the second term).

5 Materials and Methods

5.1 Data

We evaluate our method on the publicly available TREC Temporal Summarization Track data.² This data is comprised of three parts.

The *corpus* consists of a 16.1 terabyte set of 1.2 billion timestamped documents crawled from the web between October, 2011 and February 2013 [Frank *et al.*, 2012]. The crawl includes news articles, forum data, weblogs, as well as a variety of other crawled web pages.³

The *queries* consist of a set of 44 events which occurred during the timespan of the corpus. Each query has an associated time range to limit the experiment to a timespan of interest, usually around two weeks. In addition, each query is associated with an ‘event category’ (e.g. ‘earthquake’, ‘hurricane’). Each query is also associated with an ideal summary, a set of short, timestamped textual descriptions of facts about the event. The items in this set, also known as *nuggets*, are considered the completed and irreducible sub-events associated with the query. For example, the phrases “multiple people have been injured” and “at least three people have been killed” are two of the nuggets extracted for the query ‘Boston marathon bombing’. On average, 73.35 nuggets were extracted for each event.

The *relevance judgments* consist of a sample of sentences pooled from participant systems, each of which has been manually assessed as related to one or more of a query’s nuggets or not. For example, the following sentence, “Two explosions near the finish line of the Boston Marathon on Monday killed three people and wounded scores,” matches the nuggets mentioned above. The relevance judgments can be used to compute evaluation metrics (Section 5.2) and, as a result, to also define our oracle policy (Section 4.3).

Expanding Relevance Judgments

Because of the large size of the corpus and the limited size of the sample, many good candidate sentences were not manually reviewed. After aggressive document filtering (see below), less than 1% of the sentences received manual review. In order to increase the amount of data for training and evaluation of our system, we augmented the manual judgements with automatic or “soft” matches. A separate gradient boosting classifier was trained for each nugget with more than

²<http://www.trec-ts.org/>

³<http://streamcorpus.org/>

10 manual sentence matches. Manually matched sentences were used as positive training data and an equal number of manually judged non-matching sentences were used as negative examples. Sentence ngrams (1-5), percentage of nugget terms covered by the sentence, semantic similarity of the sentence to nugget were used as features, along with an interaction term between the semantic similarity and coverage. When augmenting the relevance judgments with these nugget match soft labels, we only include those that have a probability greater than 90% under the classifier. Overall these additional labels increase the number of matched sentences by 1600%.

For evaluation, the summarization system only has access to the query and the document stream, without knowledge of any nugget matches (manual or automatic).

Document Filtering

For any given event query, most of the documents in the corpus are irrelevant. Because our queries all consist of news events, we restrict ourselves to the news section of the corpus, consisting of 7,592,062 documents.

These documents are raw web pages, mostly from local news outlets running stories from syndication services (e.g. Reuters), in a variety of layouts. In order to normalize these inputs we filtered the raw stream for relevancy and redundancy with the following three stage process.

We first preprocessed each document’s raw html using an article extraction library.⁴ Articles were truncated to the first 20 sentences. We then removed any articles that did not contain all of the query keywords in the article text, resulting in one document stream for each query. Finally, documents whose cosine similarity to any previous document was $> .8$ were removed from the stream.

5.2 Metrics

We are interested in measuring a summary’s relevance, comprehensiveness, redundancy, and latency (the delay in selecting nugget information). The Temporal Summarization Track adopts three principle metrics which we review here. Complete details can be found in the Track’s official metrics document.⁵ We use the official evaluation code to compute all metrics.

Given a system’s update summary a and our sentence-level relevance judgments, we can compute the number of matching nuggets found. Importantly, a summary only gets credit for the number of unique matching nuggets, *not* the number of matching sentences. This prevents a system from receiving credit for selecting several sentences which match the same nugget. We refer to the number of unique matching nuggets as the *gain*. We can also penalize a system which retrieves a sentence matching a nugget far after the timestamp of the nugget. The *latency-penalized gain* discounts each match’s contribution to the gain proportionally to the delay of the first matching sentence.

The gain value can be used to compute latency and redundancy-penalized analogs to precision and recall. Specifically, the *expected gain* divides the gain by the number of

system updates. This precision-oriented metric can be considered the expected number of new nuggets in a sentence selected by the system. The *comprehensiveness* divides the gain by the number of nuggets. This recall-oriented metric can be considered the completeness of a user’s information after the termination of the experiment. Finally, we also compute the harmonic mean of expected gain and comprehensiveness (i.e. F_1). We present results using either gain or latency-penalized gain in order to better understand system behavior.

To evaluate our model, we randomly select five events to use as a development set and then perform a leave-one-out style evaluation on the remaining 39 events.

5.3 Model Training

Even after filtering, each training query’s document stream is still too large to be used directly in our combinatorial search space. In order to make training time reasonable yet representative, we downsample each stream to a length of 100 sentences. The downsampling is done uniformly over the entire stream. This is repeated 10 times for each training event to create a total of 380 training streams. In the event that a downsample contains no nuggets (either human or automatically labeled) we resample until at least one exists in the sample.

In order to avoid over-fitting, we select the model iteration for each training fold based on its performance (in F_1 score of expected gain and comprehensiveness) on the development set.

5.4 Baselines and Model Variants

We refer to our “learning to search” model in the results as LS. We compare our proposed model against several baselines and extensions.

Cosine Similarity Threshold One of the top performing systems in temporal-summarization at TREC 2015 was a heuristic method that only examined article first sentences, selecting those that were below a cosine similarity threshold to any of the previously selected updates. We implemented a variant of that approach using the latent-vector representation used throughout this work. The development set was used to set the threshold. We refer to this model as COS (Team WATERLOOCLARKE at TREC 2015).

Affinity Propagation The next baseline was a top performer at the previous year’s TREC evaluations [Kedzie *et al.*, 2015]. This system processes the stream in non-overlapping windows of time, using affinity propagation (AP) clustering [Frey and Dueck, 2007] to identify update sentences (i.e. sentences that are cluster centers). As in the COS model, a similarity threshold is used to filter out updates that are too similar to previous updates (i.e. previous clustering outputs). We use the summary content probability feature as the preference or salience parameter. The time window size, similarity threshold, and an offset for the cluster preference are tuned on the development set. We use the authors’ publicly available implementation and refer to this method as APSAL.

Learning2Search+Cosine Similarity Threshold In this model, which we refer to as LSCOS, we run LS as before, but filter the resulting updates using the same cosine similar-

⁴<https://github.com/grangier/python-goose>

⁵<http://www.trec-ts.org/trec2015-ts-metrics.pdf>

	unpenalized			latency-penalized			num. updates
	exp. gain	comp.	F_1	exp. gain	comp.	F_1	
APSAL	0.119^c	0.09	0.094	0.105	0.088	0.088	8.333
Cos	0.075	0.176 ^s	0.099	0.095	0.236 ^s	0.128 ^s	145.615 ^{s,f}
LS	0.097	0.207^{s,f}	0.112	0.136 ^c	0.306^{s,c,f}	0.162 ^s	89.872 ^{s,f}
LSCos	0.115 ^{c,l}	0.189 ^s	0.127^{s,c,l}	0.162^{s,c,l}	0.276 ^s	0.184^{s,c,l}	29.231 ^{s,c}

Figure 3: Average system performance and average number of updates per event. Superscripts indicate significant improvements ($p < 0.05$) between the run and competing algorithms using the paired randomization test with the Bonferroni correction for multiple comparisons (*s*: APSAL, *c*: COS, *l*: LS, *f*: LSCos).

	latency-penalized		
	exp. gain	comp.	F_1
Cos	0.095	0.236	0.128
LSFs	0.164	0.220	0.157
LSCosFs	0.207	0.18	0.163

Figure 4: Average system performance. LSFs and LSCosFs runs are trained and evaluated on first sentences only (like the COS system). Unpenalized results are omitted for space but the rankings are consistent.

	Miss Lead	Miss Body	Empty	Dupl.	Total
APSAL	29.6%	68.7%	1.6%	0.1%	15,986
Cos	17.8%	39.4%	41.1%	1.7%	12,873
LSFs	25.4%	71.7%	2.0%	0.9%	13,088
LSCosFs	27.9%	70.8%	1.0%	0.2%	15,756
LS	19.6%	55.3%	19.9%	5.1%	13,380
LSCos	24.6%	66.7%	7.5%	1.2%	11,613

Figure 5: Percent of errors made and total errors on test set.

ity threshold method as in COS. The threshold was also tuned on the development set.

6 Results

Results for system runs are shown in Figure 3. On average, LS and LSCos achieve higher F_1 scores than the baseline systems in both latency penalized and unpenalized evaluations. For LSCos, the difference in mean F_1 score was significant compared to all other systems (for both latency settings).

APSAL achieved the overall highest expected gain, partially because it was the tersest system we evaluated. However, only COS was statistically significantly worse than it on this measure.

In comprehensiveness, LS recalls on average a fifth of the nuggets for each event. This is even more impressive when compared to the average number of updates produced by each system (Figure 3); while COS achieves similar comprehensiveness, it takes on average about 62% more updates than LS and almost 400% more updates than LSCos. The output size of COS stretches the limit of the term “summary,” which is typically shorter than 145 sentences in length. This is especially important if the intended application is negatively affected by verbosity (e.g. crisis monitoring).

7 Discussion

Since COS only considers the first sentence of each document, it may miss relevant sentences below the article’s lead. In order to confirm the importance of modeling the oracle, we also trained and evaluated the LS based approaches on first sentence only streams. Figure 4 shows the latency penalized results of the first sentence only runs. The LS approaches still dominate COS and receive larger positive effects from the latency penalty despite also being restricted to the first sentence. Clearly having a model (beyond similarity) of what to select is helpful. Ultimately we do much better when we can look at the whole document.

We also performed an error analysis to further understand how each system operates. Figure 5 shows the errors made by each system on the test streams. Errors were broken down into four categories. *Miss lead* and *miss body* errors occur when a system skips a sentence containing a novel nugget in the lead or article body respectively. An *empty* error indicates an update was selected that contained no nugget. *Duplicate* errors occur when an update contains nuggets but none are novel.

Overall, errors of the miss type are most common and suggest future development effort should focus on summary content identification. About a fifth to a third of all system error comes from missing content in the lead sentence alone.

After misses, empty errors (false positives) are the next largest source of error. COS was especially prone to empty errors (41% of its total errors). LS is also vulnerable to empties (19.9%) but after applying the similarity filter and restricting to first sentences, these errors can be reduced dramatically (to 1%).

Surprisingly, duplicate errors are a minor issue in our evaluation. This is not to suggest we should ignore this component, however, as efforts to increase recall (reduce miss errors) are likely to require more robust redundancy detection.

8 Conclusion

In this paper we presented a fully online streaming document summarization system capable of processing web-scale data efficiently. We also demonstrated the effectiveness of “learning to search” algorithms for this task. As shown in our error analysis, improving the summary content selection especially in article body should be the focus of future work. We would like to explore deeper linguistic analysis (e.g. coreference and discourse structures) to identify places likely to contain content rather than processing whole documents.

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