Survival Analysis with Functional Covariates

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25 April 2023

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1/12

Survival Analysis

- Outcome variable of interest = time until an event occurs
- Examples: time until patient dies after surgery, time until patient recovers from illness etc.
- Outcome variable is referred to as survival time
- I will continue to use the example of time until death.

What is different about time to event data?

- Interested in: whether the event occurred AND when the event occurred
- Traditional methods not equipped to handle censoring a special kind of missingness observed in time-to-event data analysis.
- Other reasons for censoring: lost to follow up, withdraws from study

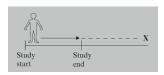


Figure: Censored patient

T Padma Ragaleena 25 April 2023 2 / 12

Cox Proportional Hazards (PH) model

■ Cox PH model given real valued predictors $\mathbf{X} = (X_1, \dots, X_p)$

$$h(t,\mathbf{X}) = h_0(t) \exp\{\sum_{i=1}^p \beta_i X_i\}$$

- $h(t, \mathbf{X}) = \text{hazard at time t for individual with predictors } \mathbf{X}$
- \blacksquare $h_0(t)$ represents baseline hazard unspecified function.
- Assumes the Proportional hazards assumption
- **Semi-parametric model** one of the reasons why the model is so popular. Can estimate all β_i and the hazard function without knowing the form of $h_0(t)$.
- Observe: no distributional assumption for the outcome variable.

T Padma Ragaleena 25 April 2023

3/12

Cox likelihood/ Partial likelihood

- We want to ensure we include the *partial* information until censorship as well.
- Here, we do not model the joint distribution of the outcomes.
- Likelihood depends on **order of events** and independent of baseline hazard.

ID	TIME	STATUS	SMOKE
Barry	2	1	1
Gary	3	1	0
Harry	5	0	0
Larry	8	1	1

SURVT = Survival time (in years) STATUS = 1 for event, 0 for censorship

SMOKE = 1 for a smoker, 0 for a nonsmoker

Cox PH model

$$h(t) = h_0(t)e^{\beta_1 SMOKE}$$

Likelihood is product of 3 terms

$$\begin{split} L &= L_1 \times L_2 \times L_3 \\ L_1 &= \left[\frac{h_0(t)e^{\beta_1}}{h_0(t)e^{\beta_1} + h_0(t)e^0 + h_0(t)e^0 + h_0(t)e^{\beta_1}} \right] \\ L_2 &= \left[\frac{h_0(t)e^0}{h_0(t)e^0 + h_0(t)e^0 + h_0(t)e^{\beta_1}} \right] \\ L_3 &= \left[\frac{h_0(t)e^{\beta_1}}{h_0(t)e^{\beta_1}} \right] \end{split}$$

Incorporating functional covariates

■ First paper to incorporate a functional predictor to model time-to-even data is Generalized linear models with functional predictors (2002) by G.M.James

$$E[Y] = g(\mu) = 0 + \gamma z + \int w_1(t)X(t)dt$$

- Assume each predictor can be modelled as a smooth curve using cubic splines.
- Similar idea has been used to incorporate functional predictors into the Cox-PH model.

$$\log[h_i(t, Z_i; \gamma, \beta(.))] = \log h_0(t) + \gamma^T Z_i + \int X_i(s)\beta(s)ds$$

- I will give an over-view of two approaches that I came across:
 - First approach is similar to Ridge regression.
 - The second approach is similar to dimension reduction using PCA.

T Padma Ragaleena 25 April 2023

5/12

Approach 1: Penalized partial likelihood

■ Approximating $\beta(s)$ using B-spline basis $\{\phi_i(s)\}_{i=1}^{k_b}$ gives

$$\beta(s) = \sum_{i=1}^{k_b} b_i \phi_i(s)$$

Using this approximation in the functional Cox PH model gives:

$$\log[h_i(t, Z_i; \gamma, \beta(.))] = \log h_0(t) + \gamma^T Z_i + \mathbf{b}^T \mathbf{c}_i \text{ where } c_{ij} = \int X_i(s) \phi_j(s) \mathrm{d}s$$

■ Penalized partial likelihood with penalty function $p(\theta)$ for $\theta^T = (\gamma^T b^T)$, $\lambda \ge 0$ and symmetric, positive semi-definite matrix.

$$I^{\lambda}(\theta) = I(\theta) - \frac{1}{2}\lambda p(\theta)$$
 where $p(\theta) = \theta^{T}D\theta$

■ Given λ , estimate θ by maximizing partial log-likelihood using **Newton-Raphson** procedure.

Approach 1: Penalized partial likelihood

- Cross-validated log likelihood (CVL) is used to find the "optimal" smoothing parameter.
- Define the following:

$$\widehat{\theta}_{(-i)}^{\lambda} = \operatorname{argmax}_{\theta} l_{\lambda,(-i)}^{(p)}(\theta) \text{ and } l_{\lambda,i}^{(p)}(\cdot) = l_{\lambda}^{(p)}(\cdot) - l_{\lambda,(-i)}^{(p)}(\cdot)$$

Then we define:

$$CVL(\lambda) = \sum_{i=1}^{n} I_{\lambda,i}^{(p)}(\widehat{\theta}_{(-i)}^{\lambda})$$

■ Since the above equation is computationally expensive, authors define a different AIC based approximation of CVL that can be used to compute λ .

T Padma Ragaleena 25 April 2023 7 / 12

■ The model is still the same:

$$\log[h_i(t, Z_i; \gamma, \beta(.))] = \log h_0(t) + \gamma^T Z_i + \int X_i(s) \beta(s) \mathrm{d}s$$

- Here, we model $\{X(t)\}_{t \in \mathcal{T}}$ as a stochastic process with mean $\mu(t)$ and covariance matrix G(s,t) = cov(X(s),X(t)).
- Think of the operator \widehat{A} as a map between function spaces. Eg. Differential operator

$$\widehat{A}f = k \cdot f$$
 then f is the eigen function and k is eigen value

■ Let $\lambda_1 \ge \lambda_2 \ge \cdots$ and ϕ_1, ϕ_2, \cdots be the eigen values and eigen functions of covariance function.

T Padma Ragaleena 25 April 2023 8 / 12

Assume the following result: Centered Stochastic process can be spanned by the eigen function basis.

$$X(t) - \mu(t) = \sum_{k=1}^{\infty} \xi_k \phi_k(t)$$
 where ξ_k is k-th PC associated with ϕ_k

Common approximation used (just like in PCA):

$$X(t) - \mu(t) \approx \sum_{k=1}^{r_n} \xi_k \phi_k(t)$$

- The above approximation has theoretical convergence gurantee.
- Authors describe how to choose "m".

Functional Cox PH model:

$$\log[h_i(t, Z_i; \gamma, \beta(.))] = \log h_0(t) + \gamma^T Z_i + \int X_i(s)\beta(s) ds$$

Substitute following two expressions in the main equation:

$$\beta(\mathbf{s}) = \sum_{i=1}^{k_b} b_i \phi_i(\mathbf{s}) \text{ and } X(t) = \mu(t) + \sum_{k=1}^{m} \xi_k \phi_k(t)$$

Using the fact that the eigen basis form an orthonormal set, we can simplify the main equation as follows:

$$\log[h_i(t, Z_i; \gamma, \beta(.))] = \log h_0(t) + \gamma^T Z_i + \sum_{i=1}^{r_n} \xi_{ij} \beta_j$$

Functional Cox PH model

$$\log[h_i(t, Z_i; \gamma, \beta(.))] = \log h_0(t) + \gamma^T Z_i + \sum_{j=1}^{r_n} \xi_{ij} \beta_j$$

■ Authors then describe how to estimate $h_0(t)$, (γ^T, β^T) after getting smoothed estimates for $X_i(s)$ for each i.

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T Padma Ragaleena 25 April 2023 12 / 12