# Sistema de semaforización inteligente para el control de flujo vehicular mediante el Procesamiento Digital de Imágenes

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Index Terms—component, formatting, style, styling, insert

### I. Introduction

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### II. ANTECEDENTES

El enfoque en la implementación de señalización vehicular inteligentes toma fuerza con el avance de la inteligencia artificial y las diversas aplicaciones que se desarrollan para optimizar y facilitar el estudio de esta área. El artículo redactado de Hoang et al. [1] desarrolla un sistema de control de señales de tráfico mediante un algoritmo Max Weight y SUMO como herramienta de simulación, con ello determinó una reducción promedio del tiempo de espera de hasta el 32%, reducción del viaje promedio en un 26% y una reducción del 22% en emisiones. Asimismo, SUMO, al ser una plataforma de simulación ampliamente utilizada en modelamiento, se pudo investigar que Esra'a y Taqwa [2] publicaron un artículo el cual implementan esta plataforma con un sistema de aprendizaje profundo por refuerzo (DRL) para el control adaptativo de las señales de tráfico, propuso un modelo basado en redes de duelo, aprendizaje doble Q y entrenamiento mediante PyTorch para mejorar la eficiencia, con ello demostró una reducción en las emisiones de CO del 56%, una reducción en el retraso de la intersección del 60%, una reducción en la longitud máxima de la cola del 52% y una reducción en el consumo de combustible de más del 60%. Otro caso es el de Victor et al. [3] en su articulo estudia el impacto ambiental debido al trafico vehicular mediante simulación en SUMO para simulación macroscópica y microscópica que permite modelar escenarios

selección de componentes de software y hardware basados en criterios de fiabilidad, costo y velocidad de respuesta. Para el procesamiento de imágenes, se evaluaron plataformas de inteligencia artificial como OpenCV, Amazon Rekognition, Microsoft Computer Vision API, Google Cloud Vision API, entre otras. Amazon Rekognition fue seleccionada debido a su alta fiabilidad, detectando el 100% de los vehículos en las pruebas (11 de 11), frente a IBM Watson con un 54.54% (6 de 11) y Google Cloud y Microsoft con un 36.36% (4 de 11). Además, AWS destacó por ofrecer 5000 imágenes gratuitas al mes y un costo adicional de \$1.30 USD por cada

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con alto nivel de detalle, ademas de usar la base de datos de la Municipalidad de la ciudad, hizo uso de Open Street Map para la construcción del mapa de la zona de estudio, con ello determino que al reducir reducción media en la contaminación por ruido de 1,46%; CO2 de 13,72%, CO de 16,09%; y el número de vehículos en 11,75; mientras que, con la macrosimulación la situación no varía.

En el trabajo de grado de Manzo y Arzate [4] estudiaron un sistema de semáforos inteligentes que controle el cambio de luces en los semáforos utilizando algoritmos de visión artificial y procesamiento de imágenes donde empleó una arquitectura donde a partir de la captura de imágenes se ejecutan procesos en tiempo real mediante algoritmos de visión artificial, haciedo uso de Pycharm Jetbrains y OPENCV para la integración de sensores, la comunicación con el hardware y el reconocimiento de patrones, con ello contribuyó a disminuir la congestión especialmente en el caso de intersecciones que presentan una diferencia contrastante en los niveles de afluencia vehicular.

En la implementación de un sistema de semaforización

inteligente de Monterrey y Sosa [5], se llevó a cabo la

1000 imágenes adicionales, junto con un tiempo promedio

de respuesta de 2.219 segundos, siendo el más rápido entre

las opciones analizadas. En cuanto al sistema embebido, se

optó por la Raspberry Pi 3 modelo B, ya que cumple con los

requisitos de conexión a internet, almacenamiento de hasta 256GB por MicroSD y compatibilidad con cámaras, todo a

un costo de COP \$310,000. Para la captura de imágenes, se seleccionó la cámara ELP 1MP USB debido a su resolución óptima de 720p y su capacidad para operar en exteriores, con un costo de COP \$160,000. Asimismo, el sistema incluye el sensor de luz TSL2561, con un rango de medición de 0.1 a 40,000 lux y un consumo de energía de 15 mA, junto con el sensor de humedad DHT22, que ofrece un rango de humedad de 0 a 100% y un rango de temperatura de -40 a 80°C, siendo crítico para la detección de condiciones climáticas adversas.

Otro aporte es el de Álvarez y Olaya [6] utilizando la red neuronal YOLOv3 para la detección en tiempo real de vehículos y peatones. El sistema fue entrenado con un dataset de 2,100 imágenes extraídas de 20 videos simulados con diversas condiciones de luz. Cada video fue procesado a una tasa de 20 cuadros por minuto. La simulación del tráfico se llevó a cabo en un entorno creado en Unity 3D, que incluyó 3 carreras y 4 calles, generando 8 intersecciones semaforizadas, de las cuales una fue utilizada para pruebas. La red YOLOv3 se entrenó durante 100 épocas utilizando PyTorch, logrando los niveles de precisión requeridos. El proceso de entrenamiento fue optimizado en Google Colaboratory, aprovechando una GPU Nvidia Tesla K80 con 12.7 GB de memoria y 360 GB de almacenamiento, lo que permitió una aceleración significativa.

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#### B. Units

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Use a zero before decimal points: "0.25", not ".25". Use "cm<sup>3</sup>", not "cc".)

## C. Equations

Number equations consecutively. To make your equations more compact, you may use the solidus ( / ), the exp function, or appropriate exponents. Italicize Roman symbols for quantities and variables, but not Greek symbols. Use a long dash rather than a hyphen for a minus sign. Punctuate equations with commas or periods when they are part of a sentence, as in:

$$a + b = \gamma \tag{1}$$

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Please use "soft" (e.g., \eqref{Eq}) cross references instead of "hard" references (e.g., (1)). That will make it possible to combine sections, add equations, or change the order of figures or citations without having to go through the file line by line.

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# E. Some Common Mistakes

- The word "data" is plural, not singular.
- The subscript for the permeability of vacuum  $\mu_0$ , and other common scientific constants, is zero with subscript formatting, not a lowercase letter "o".

- In American English, commas, semicolons, periods, question and exclamation marks are located within quotation marks only when a complete thought or name is cited, such as a title or full quotation. When quotation marks are used, instead of a bold or italic typeface, to highlight a word or phrase, punctuation should appear outside of the quotation marks. A parenthetical phrase or statement at the end of a sentence is punctuated outside of the closing parenthesis (like this). (A parenthetical sentence is punctuated within the parentheses.)
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- There is no period after the "et" in the Latin abbreviation "et al.".
- The abbreviation "i.e." means "that is", and the abbreviation "e.g." means "for example".

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# G. Identify the Headings

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Component heads identify the different components of your paper and are not topically subordinate to each other. Examples include Acknowledgments and References and, for these, the correct style to use is "Heading 5". Use "figure caption" for your Figure captions, and "table head" for your table title. Run-in heads, such as "Abstract", will require you to apply a style (in this case, italic) in addition to the style provided by the drop down menu to differentiate the head from the text.

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TABLE I TABLE TYPE STYLES

Table	Table Column Head		
Head	Table column subhead	Subhead	Subhead
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<sup>a</sup>Sample of a Table footnote.

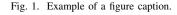


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## ACKNOWLEDGMENT

The preferred spelling of the word "acknowledgment" in America is without an "e" after the "g". Avoid the stilted expression "one of us (R. B. G.) thanks ...". Instead, try "R. B. G. thanks...". Put sponsor acknowledgments in the unnumbered footnote on the first page.

# IV. REFERENCES

## REFERENCES

- T. A. Hoang, N. Walton, and H. L. Vu, "Optimal decentralized signal control for platooning in connected vehicle networks," *Transportation Research Part C: Emerging Technologies*, vol. 167, 10 2024.
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