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1 Basic

1.1 default code

```

1 #include <bits/stdc++.h>
2 #define PB push_back
3 #define MP make_pair
4 #define F first
5 #define S second
6 #define SZ(x) ((int)(x).size())
7 #define ALL(x) (x).begin(),(x).end()
8 #ifdef _DEBUG_
9     #define debug(...) printf(__VA_ARGS__)
10 #else
11     #define debug(...) (void)0
12 #endif
13 using namespace std;
14 typedef long long ll;
15 typedef pair<int,int> PII;
16 typedef vector<int> VI;
17
18 int main() {
19     return 0;
20 }
```

1.2 .vimrc

```

1 color torte
2 syn on
3 set guifont=Consolas:h16: nu sc ai si ts=4
4   sm sts=4 sw=4
5
6 map <F9> <ESC>:w<CR>:!g++ % -o %< -O2 -Wall
7   -Wno-unused-result -Wshadow -std=c++0x<
8   CR>
9 map <S-F9> <ESC>:w<CR>:!g++ % -o %< -O2 -
10  Wall -Wno-unused-result -Wshadow -
11  D_DEBUG_ -std=c++0x<CR>
12 map <S-F10> <ESC>:w<CR>:!g++ % -o %< -O2 -
13  Wall -Wno-unused-result -Wshadow -
14  D_DEBUG_ -std=c++0x -fsanitize=undefined
15  -fsanitize=address<CR>
16
17 map <F5> <ESC>:!./%<<CR>
18 map <F6> <ESC>:w<CR>ggVG"+y
19 map <S-F5> <ESC>:!./%< <%<.in<CR>
20
21 imap <Home> <ESC>^i
22
23 com INPUT sp %<.in
```

2 math

2.1 ext gcd

```

1 // find one solution (x,y) of ax+by=gcd(
2   a,b)
3 void ext_gcd(int a,int b,int &g,int &x,int
4   &y)
5 {
6     if(!b){ g=a; x=1; y=0; }
```

```

5 else{ ext_gcd(b, a%b, g, y, x); y -= x*(a
    /b); }
6 }

```

2.2 FFT

```

1 typedef complex<double> CD;
2
3 const double PI=acos(-1.0);
4 inline CD ang(double t) { return CD(cos(t),
    sin(t)); }
5
6 int rev_int(int x,int lgn) {
7     int re=0;
8     for(int i=0;i<lgn;i++) {
9         re=(re<<1)+(x&1);
10        x>>=1;
11    }
12    return re;
13 }
14 void fft(CD* A, int lgn, bool inv=false) {
15     int n=1<<lgn;
16     for(int i=0;i<n;i++)
17         if(i<rev_int(i, lgn)) swap(A[i], A[
            rev_int(i, lgn)]);
18     for(int i=1;i<n;i*=2) {
19         CD W(1.0, 0.0), Wn;
20         if(inv) Wn=ang(-PI/i);
21         else Wn=ang(PI/i);
22         for(int j=0;j<n;j++) {
23             if(j&i) {
24                 W=CD(1.0, 0.0);
25                 continue;
26             }
27             CD x=A[j], y=A[j+i]*Wn;
28             A[j]=x+y;
29             A[j+i]=x-y;
30             W*=Wn;
31         }
32     }
33     if(inv)
34         for(int i=0;i<n;i++)
35             A[i]/=n;
36 }

```

2.3 NTT

```

1 //      MOD      Wn_      LGN
2 //      5767169   177147 19
3 //      7340033   2187  20
4 //      2013265921 440564289 27
5 const int MOD=786433;
6 const int Wn_=5; // 25 625
7 const int LGN=18; // 17 16
8 inline int add(int x,int y) { return (x+y)%
    MOD; }
9 inline int mul(int x,int y) { return 111*x*
    y%MOD; }
10 inline int sub(int x,int y){ return (x-y+
    MOD)%MOD; }
11

```

```

12 int pw[MOD]; // power of Wn
13 int divN;
14 int inv(int a) {
15     int re=1, k=MOD-2, t=a;
16     while(k) {
17         if(k%2) re=mul(re, t);
18         k/=2;
19         t=mul(t, t);
20     }
21     return re;
22 }
23 void NTTinit(int lgn) { // call every time
    using new lgn !
24     int Wn=Wn_;
25     for(int i=lgn;i<LGN;i++) Wn=mul(Wn,Wn);
26     divN=inv(1<<lgn);
27     pw[0]=1;
28     for(int i=1;i<LGN;i++) {
29         pw[i]=mul(pw[i-1], Wn);
30         if(pw[i]==1) break;
31     }
32 }
33
34 int rev_int(int x,int lgn) {
35     int re=0;
36     for(int i=0;i<lgn;i++) {
37         re=(re<<1)+(x&1);
38         x>>=1;
39     }
40     return re;
41 }
42 void ntt(int *A,int lgn,bool inv=false) {
43     int n=1<<lgn;
44     for(int i=0;i<n;i++)
45         if(i<rev_int(i,lgn))
46             swap(A[i], A[rev_int(i,lgn)]);
47     for(int i=1;i<n;i*=2) {
48         int W=1, Wn;
49         if(inv) Wn=pw[n-(n/2/i)];
50         else Wn=pw[n/2/i];
51         for(int j=0;j<n;j++) {
52             if(j&i) {
53                 W=1;
54                 continue;
55             }
56             int x=A[j], y=mul(A[j+i],Wn);
57             A[j]=add(x,y);
58             A[j+i]=sub(x,y);
59             W=mul(W,Wn);
60         }
61     }
62     if(inv)
63         for(int i=0;i<n;i++)
64             A[i]=mul(A[i],divN);
65 }

```

2.4 MillerRabin other

```

1 /* Miller Rabin code from ioicamp */
2 ll mul(ll a, ll b, ll n) {
3     ll r = 0;
4     a %= n, b %= n;
5     while(b) {

```

```

6   if(b&1) r = (a+r>=n ? a+r-n : a+r);
7   a = (a+a>=n ? a+a-n : a+a);
8   b >>= 1;
9   }
10  return r;
11 }
12
13 ll bigmod(ll a, ll d, ll n) {
14   if(d==0) return 1LL;
15   if(d==1) return a % n;
16   return mul(bigmod(mul(a, a, n), d/2, n),
17              d%2?a:1, n);
18 }
19 const bool PRIME = 1, COMPOSITE = 0;
20 bool miller_rabin(ll n, ll a) {
21   if(__gcd(a, n) == n) return PRIME;
22   if(__gcd(a, n) != 1) return COMPOSITE;
23   ll d = n-1, r = 0, res;
24   while(d%2==0) { ++r; d/=2; }
25   res = bigmod(a, d, n);
26   if(res == 1 || res == n-1) return PRIME;
27   while(r-->0) {
28     res = mul(res, res, n);
29     if(res == n-1) return PRIME;
30   }
31   return COMPOSITE;
32 }
33
34 bool isprime(ll n) {
35   if(n==1)
36     return COMPOSITE;
37   ll as[7] = {2, 325, 9375, 28178, 450775,
38              9780504, 1795265022};
39   for(int i=0; i<7; i++)
40     if(miller_rabin(n, as[i]) == COMPOSITE)
41       return COMPOSITE;
42   return PRIME;
43 }

```

2.5 Guass

```

1 // be care of the magic number 7 & 8
2 void guass() {
3   for(int i = 0; i < 7; i++) {
4     Frac tmp = mat[i][i]; // Frac -> the
5                           // type of data
6     for(int j = 0; j < 8; j++)
7       mat[i][j] = mat[i][j] / tmp;
8     for(int j = 0; j < 7; j++) {
9       if(i == j)
10        continue;
11       Frac ratio = mat[j][i]; // Frac ->
12                               // the type of data
13       for(int k = 0; k < 8; k++)
14         mat[j][k] = mat[j][k] - ratio * mat
15         [i][k];
16     }
17   }
18 }

```

2.6 xorFFT

```

1 //      1   1
2 // H =  1  -1
3 //      /sqrt(2)
4 vector<ll> FWHT(vector<ll> P, bool inverse)
5 {
6   for(int len = 1; 2 * len <= SZ(P); len
7     <=< 1) {
8     for(int i = 0; i < SZ(P); i += 2 * len)
9       {
10        for(int j = 0; j < len; j++) {
11          ll u = P[i + j];
12          ll v = P[i + len + j];
13          P[i + j] = u + v;
14          P[i + len + j] = u - v;
15        }
16      }
17   }
18   if (inverse) {
19     for (int i = 0; i < SZ(P); i++)
20       P[i] = P[i] / SZ(P);
21   }
22   return P;
23 }

```

2.7 orFFT

```

1 //      1   1
2 // T =  1   0
3 //      0   1
4 //T-1=  1  -1
5 vector<ll> transform(vector<ll> P, bool
6   inverse) {
7   for(int len = 1; 2 * len <= SZ(P); len
8     <=< 1) {
9     for(int i = 0; i < SZ(P); i += 2 * len)
10      {
11        for(int j = 0; j < len; j++) {
12          ll u = P[i + j];
13          ll v = P[i + len + j];
14          if (!inverse) {
15            P[i + j] = u + v;
16            P[i + len + j] = u;
17          } else {
18            P[i + j] = v;
19            P[i + len + j] = u - v;
20          }
21        }
22      }
23   }
24   return P;
25 }

```

2.8 andFFT

```

1 //      0   1
2 // T =  1   1
3 //      -1  1
4 //T-1=  1   0

```

```

5 vector<ll> transform(vector<ll> P, bool
   inverse) {
6   for(int len = 1; 2 * len <= SZ(P); len
   <= 1) {
7     for(int i = 0; i < SZ(P); i += 2 * len)
       {
8       for(int j = 0; j < len; j++) {
9         ll u = P[i + j];
10        ll v = P[i + len + j];
11        if (!inverse) {
12          P[i + j] = v;
13          P[i + len + j] = u + v;
14        } else {
15          P[i + j] = -u + v;
16          P[i + len + j] = u;
17        }
18      }
19    }
20  }
21  return P;
22 }

```

2.9 Them.

Catalan number: $C_0 = 1$, $C_{n+1} = \frac{2(2n+1)}{n+2} C_n$

3 flow

3.1 dinic

```

1 const int MAXV=300;
2 const int MAXE=10000;
3 const int INF=(int)1e9+10;
4 // ^ config those things
5
6 struct E {
7   int to,co;//capacity
8   E(int t=0,int c=0):to(t),co(c) {}
9 }eg[2*MAXE];
10
11 // source:0 sink:n-1
12 struct Flow {
13   VI e[MAXV];
14   int ei,v;
15   void init(int n) {
16     v=n;
17     ei=0;
18     for(int i=0;i<n;i++)
19       e[i]=VI();
20   }
21   void add(int a,int b,int c) { //a to b ,
     maxflow=c
22     eg[ei]=E(b,c);
23     e[a].PB(ei);
24     ei++;
25     eg[ei]=E(a,0);
26     e[b].PB(ei);
27     ei++;
28   }
29
30   int d[MAXV],qu[MAXV],ql,qr;

```

```

31 bool BFS() {
32   memset(d,-1,v*sizeof(int));
33   ql=qr=0;
34   qu[qr++]=0;
35   d[0]=0;
36   while(ql<qr && d[v-1]==-1) {
37     int n=qu[ql++];
38     VI &v=e[n];
39     for(int i=SZ(v)-1;i>=0;i--) {
40       int u=v[i];
41       if(d[eg[u].to]==-1 && eg[u].co>0) {
42         d[eg[u].to]=d[n]+1;
43         qu[qr++]=eg[u].to;
44       }
45     }
46   }
47   return d[v-1]!=-1;
48 }
49 int ptr[MAXV];
50 int go(int n,int p) {
51   if(n==v-1)
52     return p;
53   VI &u=e[n];
54   int temp;
55   for(int i=ptr[n];i<SZ(u);i++) {
56     if(d[n]+1!=d[eg[u[i]].to] || eg[u[i]
57       ].co==0)
58       continue;
59     if((temp=go(eg[u[i]].to,min(p,eg[u[i]
60       ].co)))>0)
61       continue;
62     eg[u[i]].co-=temp;
63     eg[u[i]^1].co+=temp;
64     ptr[n]=i;
65     return temp;
66   }
67   ptr[n]=SZ(u);
68   return 0;
69 }
70 int max_flow() {
71   int ans=0,temp;
72   while(BFS()) {
73     for(int i=0;i<v;i++)
74       ptr[i]=0;
75     while((temp=go(0,INF))>0)
76       ans+=temp;
77   }
78   return ans;
79 }

```

3.2 min-cost-max-flow

```

1 typedef pair<int,ll> PIL;
2 const int MAXV=60;
3 const int MAXE=6000;
4 const int INF=(int)1e9+10;
5 const ll cINF=(ll)1e18+10;
6 // ^ config those things
7
8 struct E {
9   int to,ca,cost;//capacity, cost

```

```

10 E(int t=0,int c=0,int co=0):to(t),ca(c),
    cost(co) {}
11 }eg[2*MAXE];
12
13 // source:0 sink:n-1
14 struct Flow {
15     VI e[MAXV];
16     int ei,n;
17     void init(int n_) {
18         n=n_;
19         ei=0;
20         for(int i=0;i<n;i++)
21             e[i]=VI();
22     }
23     void add(int a,int b,int c,int d) {
24         //a to b ,maxflow=c, cost=d
25         eg[ei]=E(b,c,d);
26         e[a].PB(ei);
27         ei++;
28         eg[ei]=E(a,0,-d);
29         e[b].PB(ei);
30         ei++;
31     }
32
33     PII d[MAXV]={};
34     bool inq[MAXV]={};
35     queue<int> que;
36     VI pe;
37     bool SPFA() {
38         fill(d, d+n, MP(INF,INF));
39         d[0]=MP(0,0);
40         que.push(0);
41         inq[0]=1;
42         while(!que.empty()) {
43             int v=que.front(); que.pop();
44             inq[v]=0;
45             for(int id:e[v]) {
46                 if(eg[id].ca>0 && MP(d[v].F+eg[id].
                    cost,d[v].S+1)<d[eg[id].to]) {
47                     d[eg[id].to]=MP(d[v].F+eg[id].
                        cost,d[v].S+1);
48                     if(!inq[eg[id].to]) {
49                         que.push(eg[id].to);
50                         inq[eg[id].to]=1;
51                     }
52                 }
53             }
54         }
55         return d[n-1].F<INF;
56     }
57     PIL go(ll cb=cINF) {
58         // cost_bound
59         if(!SPFA()) return MP(0,0);
60         pe.clear();
61         int fl=INF;
62         for(int v=n-1;v!=0;) {
63             for(int id:e[v]) {
64                 int u=eg[id].to;
65                 const E& t=eg[id^1];
66                 if(t.ca>0 && MP(d[u].F+t.cost,d[u].
                    S+1)==d[v]) {
67                     fl=min(fl, t.ca);
68                     v=u;
69                     pe.PB(id^1);
70                     break;

```

```

71         }
72     }
73     }
74     if(d[n-1].F>0) fl=min(1ll*fl, cb/d[n
        -1].F);
75     for(int id:pe) {
76         eg[id].ca-=fl;
77         eg[id^1].ca+=fl;
78     }
79     return MP(fl, 1ll*fl*d[n-1].F);
80 }
81 PIL max_flow() {
82     PIL ans=MP(0,0),temp;
83     while((temp=go()).F>0) {
84         ans.F+=temp.F;
85         ans.S+=temp.S;
86     }
87     return ans;
88 }
89 } flow;

```

4 string

4.1 KMP

```

1 void KMP_build(const char *S,int *F) {
2     int p=F[0]=-1;
3     for(int i=1;S[i];i++) {
4         while(p!=-1 && S[p+1]!=S[i])
5             p=F[p];
6         if(S[p+1]==S[i])
7             p++;
8         F[i]=p;
9     }
10 }
11
12 VI KMP_match(const char *S,const int *F,
    const char *T) {
13     VI ans;
14     int p=-1;
15     for(int i=0;T[i];i++) {
16         while(p!=-1 && S[p+1]!=T[i])
17             p=F[p];
18         if(S[p+1]==T[i])
19             p++;
20         if(!S[p+1]) {
21             ans.PB(i-p);
22             p=F[p];
23         }
24     }
25     return ans;
26 }

```

4.2 Z-value

```

1 void Z_build(const char *S,int *Z) {
2     Z[0]=0;
3     int bst=0;
4     for(int i=1;S[i];i++) {
5         if(Z[bst]+bst<i) Z[i]=0;

```

```

6   else Z[i]=min(Z[bst]+bst-i,Z[i-bst]);
7   while(S[Z[i]]==S[i+Z[i]]) Z[i]++;
8   if(Z[i]+i>Z[bst]+bst) bst=i;
9   }
10 }

```

4.3 Z-value-palindrome

```

1 // AC code of NTUJ1871
2 char in[100100];
3 char s[200100];
4 int z[200100];
5
6 int main() {
7     while(gets(in)) {
8         int len=1;
9         for(int i=0;in[i];i++) {
10             s[len++]='*';
11             s[len++]=in[i];
12         }
13         s[len]=0;
14         z[0]=0;
15         z[1]=0;
16         int bst=1;
17         for(int i=1;i<len;i++) {
18             z[i]=min(bst+z[bst]-i,z[bst+bst-i]);
19             while(s[i+z[i]+1]==s[i-z[i]-1])
20                 z[i]++;
21             if(z[i]+i>bst+z[bst])
22                 bst=i;
23         }
24         bool yes=0;
25         for(int i=3;i<len;i+=2)
26             if(z[(i+1)/2]==i/2 && z[(i+len)/2]==(
27                 len-i-1)/2)
28                 yes=1;
29         if(yes)
30             puts("www");
31         else
32             puts("vvvvvv");
33     }
34     return 0;
35 }

```

4.4 Suffix Array($O(N\log N)$)

```

1 const int SASIZE=100020; // >= (max length
   of string + 20)
2 struct SA{
3     char S[SASIZE]; // put target string into
   S[0:(len-1)]
4     // you can change the type of S into int
   if required
5     // if the string is in int, please avoid
   number < 0
6     int R[SASIZE*2],SA[SASIZE];
7     int tR[SASIZE*2],tSA[SASIZE];
8     int cnt[SASIZE],len; // set len
   before calling build()
9     int H[SASIZE];
10 }

```

```

11 void build_SA() {
12     int maxR=0;
13     for(int i=0;i<len;i++)
14         R[i]=S[i];
15     for(int i=0;i<len;i++)
16         R[len+i]=-1;
17     memset(cnt,0,sizeof(cnt));
18     for(int i=0;i<len;i++)
19         maxR=max(maxR,R[i]);
20     for(int i=0;i<len;i++)
21         cnt[R[i]+1]++;
22     for(int i=1;i<=maxR;i++)
23         cnt[i]+=cnt[i-1];
24     for(int i=0;i<len;i++)
25         SA[cnt[R[i]]++]=i;
26     for(int i=1;i<len;i*=2)
27     {
28         memset(cnt,0,sizeof(int)*(maxR+10));
29         memcpy(tSA,SA,sizeof(int)*(len+10));
30         memcpy(tR,R,sizeof(int)*(len+i+10));
31         for(int j=0;j<len;j++)
32             cnt[R[j]+1]++;
33         for(int j=1;j<=maxR;j++)
34             cnt[j]+=cnt[j-1];
35         for(int j=len-i;j<len;j++)
36             SA[cnt[R[j]]++]=j;
37         for(int j=0;j<len;j++)
38         {
39             int k=tSA[j]-i;
40             if(k<0)
41                 continue;
42             SA[cnt[R[k]]++]=k;
43         }
44         int num=0;
45         maxR=0;
46         R[SA[0]]=num;
47         for(int j=1;j<len;j++)
48         {
49             if(tR[SA[j-1]]<tR[SA[j]] || tR[SA[j]
50                 -1]+i<tR[SA[j]+i])
51                 num++;
52             R[SA[j]]=num;
53             maxR=max(maxR,R[SA[j]]);
54         }
55     }
56     if (len == 1)
57         SA[0] = R[0] = 0;
58 }
59 void build_H() {
60     memset(H,0,sizeof(int)*(len+10));
61     for(int i=0;i<len;i++)
62     {
63         if(R[i]==0)
64             continue;
65         int &t=H[R[i]];
66         if(i>0)
67             t=max(0,H[R[i-1]]-1);
68         while(S[i+t]==S[SA[R[i]-1]+t]) t++;
69     }
70 }

```

4.5 Suffix Array(SAIS, twt)

```

1 struct SA{
2 #define REP(i,n) for ( int i=0; i<int(n); i
  ++ )
3 #define REP1(i,a,b) for ( int i=(a); i<=int
  (b); i++ )
4 static const int MXN = 300010;
5 bool _t[MXN*2];
6 int _s[MXN*2], _sa[MXN*2], _c[MXN*2], x[
  MXN], _p[MXN], _q[MXN*2], hei[MXN], r[
  MXN];
7 int operator [] (int i){ return _sa[i]; }
8 void build(int *s, int n, int m){
9     memcpy(_s, s, sizeof(int) * n);
10    sais(_s, _sa, _p, _q, _t, _c, n, m);
11    mkhei(n);
12 }
13 void mkhei(int n){
14     REP(i,n) r[_sa[i]] = i;
15     hei[0] = 0;
16     REP(i,n) if(r[i]) {
17         int ans = i>0 ? max(hei[r[i-1]] - 1,
18             0) : 0;
19         while(_s[i+ans] == _s[_sa[r[i]-1]+ans]
20             ) ans++;
21         hei[r[i]] = ans;
22     }
23 void sais(int *s, int *sa, int *p, int *q
24     , bool *t, int *c, int n, int z){
25     bool uniq = t[n-1] = true, neq;
26     int nn = 0, nmzx = -1, *nsa = sa + n, *
27         ns = s + n, lst = -1;
28 #define MS0(x,n) memset((x),0,n*sizeof(*(x)
29     ))
30 #define MAGIC(XD) MS0(sa, n); \
31     memcpy(x, c, sizeof(int) * z); \
32     XD; \
33     memcpy(x + 1, c, sizeof(int) * (z - 1))
34     ; \
35     REP(i,n) if(sa[i] && !t[sa[i]-1]) sa[x[
36         s[sa[i]-1]]++] = sa[i]-1; \
37     memcpy(x, c, sizeof(int) * z); \
38     for(int i = n - 1; i >= 0; i--) if(sa[i]
39         ] && t[sa[i]-1]) sa[--x[s[sa[i]-1]]]
40         = sa[i]-1;
41     MS0(c, z);
42     REP(i,n) uniq &= ++c[s[i]] < 2;
43     REP(i,z-1) c[i+1] += c[i];
44     if (uniq) { REP(i,n) sa[--c[s[i]]] = i;
45         return; }
46     for(int i = n - 2; i >= 0; i--) t[i] =
47         (s[i]==s[i+1] ? t[i+1] : s[i]<s[i
48             +1]);
49     MAGIC(REP1(i,1,n-1) if(t[i] && !t[i-1])
50         sa[--x[s[i]]]=p[q[i]=nn++]=i);
51     REP(i, n) if (sa[i] && t[sa[i]] && !t[
52         sa[i]-1]) {
53         neq=lst<0||memcmp(s+sa[i],s+lst,(p[q[
54             sa[i]]+1]-sa[i])*sizeof(int));
55         ns[q[lst=sa[i]]]=nmzx+=neq;
56     }
57 }

```

```

43    sais(ns, nsa, p + nn, q + n, t + n, c +
44        z, nn, nmzx + 1);
45    MAGIC(for(int i = nn - 1; i >= 0; i--)
46        sa[--x[s[p[nsa[i]]]]] = p[nsa[i]]);
47 }
48 void suffix_array(int* ip, int len) {
49     // should padding a zero in the back
50     // s is int array, n is array length
51     // s[0..n-1] != 0, and s[n] = 0
52     // resulting SA will be length n+1
53     ip[len++] = 0;
54     sa.build(ip, len, 128);
55     // original 1-base
56     for (int i=0; i<l; i++) {
57         hei[i] = sa.hei[i + 1];
58         sa[i] = sa._sa[i + 1];
59     }
60 }

```

4.6 Aho-Corasick-2016ioicamp

```

1 // AC code of 2016ioicamp 54
2 const int MAXNM=100010;
3 int pp[MAXNM];
4
5 const int sizz=100010;
6 int nx[sizz][26],spt;
7 int fl[sizz],efl[sizz],ed[sizz];
8 int len[sizz];
9 int newnode(int len_=0) {
10     for(int i=0;i<26;i++)nx[spt][i]=0;
11     ed[spt]=0;
12     len[spt]=len_;
13     return spt++;
14 }
15 int add(char *s,int p) {
16     int l=1;
17     for(int i=0;s[i];i++) {
18         int a=s[i]-'a';
19         if(nx[p][a]==0) nx[p][a]=newnode(1);
20         p=nx[p][a];
21         l++;
22     }
23     ed[p]=1;
24     return p;
25 }
26 int q[sizz],qs,qe;
27 void make_fl(int root) {
28     fl[root]=efl[root]=0;
29     qs=qe=0;
30     q[qe++]=root;
31     for(;qs!=qe;){
32         int p=q[qs++];
33         for(int i=0;i<26;i++) {
34             int t=nx[p][i];
35             if(t==0) continue;
36             int tmp=fl[p];
37             for(;tmp&&nx[tmp][i]==0;) tmp=fl[tmp]
38                 ;
39             fl[t]=tmp?nx[tmp][i]:root;
40             efl[t]=ed[fl[t]]?fl[t]:efl[fl[t]];

```



```

40     q[qe++]=t;
41 }
42 }
43 }
44 char s[MAXNM];
45 char a[MAXNM];
46
47 int dp[MAXNM][4];
48
49 void mmax(int &a,int b) {
50     a=max(a,b);
51 }
52
53 void match(int root) {
54     int p=root;
55     for(int i=1;s[i];i++) {
56         int a=s[i]-'a';
57         for(;p&nx[p][a]==0;p=f1[p]);
58         p=p?nx[p][a]:root;
59         for(int j=1;j<=3;j++)
60             dp[i][j]=dp[i-1][j];
61         for(int t=p;t=t=efl[t]) {
62             if(!ed[t])
63                 continue;
64             for(int j=1;j<=3;j++)
65                 mmax(dp[i][j],dp[i-len[t]][j-1]+(pp[i]-pp[i-len[t]]));
66         }
67     }
68 }
69
70 int main() {
71     int T;
72     scanf("%d",&T);
73     while(T--) {
74         int n,m;
75         scanf("%d%d",&n,&m);
76         scanf("%s",s+1);
77         for(int i=1;i<=n;i++)
78             scanf("%d",pp+i);
79         for(int i=1;i<=n;i++)
80             pp[i]+=pp[i-1];
81         spt=1;
82         int root=newnode();
83         for(int i=0;i<m;i++) {
84             scanf("%s",a);
85             add(a,root);
86         }
87         make_f1(root);
88         for(int i=1;i<=n;i++)
89             dp[i][1]=dp[i][2]=dp[i][3]=0;
90         match(root);
91         printf("%d\n",dp[n][3]);
92     }
93     return 0;
94 }

```

4.7 Palindrome Automaton

```

1 const int MAXN=100050;
2 char s[MAXN];
3 int n; // n:string length
4

```

```

5 typedef pair<PII,int> PD;
6 vector<PD> pal;
7
8 int ch[MAXN][26], fail[MAXN], len[MAXN],
   cnt[MAXN];
9 int edp[MAXN];
10 int nid=1;
11 int new_node(int len_) {
12     len[nid]=len_;
13     return nid++;
14 }
15
16 void build_pa() {
17     int odd_root=new_node(-1);
18     int even_root=new_node(0);
19     fail[even_root]=odd_root;
20     int cur=even_root;
21     for(int i=1;i<=n;i++) {
22         while(1) {
23             if(s[i-len[cur]-1] == s[i]) break;
24             cur=fail[cur];
25         }
26         if(ch[cur][s[i]-'a']==0) {
27             int nt=ch[cur][s[i]-'a']=new_node(len
               [cur]+2);
28             int tmp=fail[cur];
29             while(tmp && s[i-len[tmp]-1]!=s[i])
30                 tmp=fail[tmp];
31             if(tmp==0) fail[nt]=even_root;
32             else {
33                 assert(ch[tmp][s[i]-'a']);
34                 fail[nt]=ch[tmp][s[i]-'a'];
35             }
36             edp[nt]=i;
37         }
38         cur=ch[cur][s[i]-'a'];
39         cnt[cur]++;
40     }
41     for(int i=nid-1;i>even_root;i--) {
42         cnt[fail[i]]+=cnt[i];
43         pal.PB( MP( MP(edp[i]-len[i]+1, len[i])
44             , cnt[i]) ));
45     }
46 }

```

4.8 Suffix Automaton(bcw)

```

1 // par : fail link
2 // val : a topological order ( useful for
   DP )
3 // go[x] : automata edge ( x is integer in
   [0,26) )
4
5 struct SAM{
6     struct State{
7         int par, go[26], val;
8         State () : par(0), val(0){ FZ(go); }
9         State (int _val) : par(0), val(_val){
10             FZ(go); }
11     };
12     vector<State> vec;
13     int root, tail;
14 }

```



```

14 void init(int arr[], int len){
15     vec.resize(2);
16     vec[0] = vec[1] = State(0);
17     root = tail = 1;
18     for (int i=0; i<len; i++)
19         extend(arr[i]);
20 }
21 void extend(int w){
22     int p = tail, np = vec.size();
23     vec.PB(State(vec[p].val+1));
24     for ( ; p && vec[p].go[w]==0; p=vec[p].
25         par)
26         vec[p].go[w] = np;
27     if (p == 0){
28         vec[np].par = root;
29     } else {
30         if (vec[vec[p].go[w]].val == vec[p].
31             val+1){
32             vec[np].par = vec[p].go[w];
33         } else {
34             int q = vec[p].go[w], r = vec.size
35                 ();
36             vec.PB(vec[q]);
37             vec[r].val = vec[p].val+1;
38             vec[q].par = vec[np].par = r;
39             for ( ; p && vec[p].go[w] == q; p=
40                 vec[p].par)
41                 vec[p].go[w] = r;
42         }
43     }
44     tail = np;
45 }
46 }
47 };

```

5 graph

5.1 Bipartite matching($O(N^3)$)

```

1 // NTUJ1263
2 bool is(ll x) {
3     ll l=1,r=2000000,m;
4     while(l<=r) {
5         m=(l+r)/2;
6         if(m*m==x)
7             return 1;
8         if(m*m<x)
9             l=m+1;
10        else
11            r=m-1;
12    }
13    return 0;
14 }
15
16 VI odd,even;
17 int in[300];
18 VI e[300];
19 int match[300];
20 bool vis[300];
21
22 bool DFS(int x) {
23     vis[x]=1;
24     for(int u:e[x]) {

```

```

25         if(match[u]==-1 || (!vis[match[u]]&&DFS
26             (match[u]))) {
27             match[u]=x;
28             match[x]=u;
29             return 1;
30         }
31     }
32     return 0;
33 }
34 int main() {
35     int N;
36     while(scanf("%d",&N)==1) {
37         odd.clear();
38         even.clear();
39         for(int i=0;i<N;i++)
40             e[i].clear();
41         for(int i=0;i<N;i++) {
42             scanf("%d",in+i);
43             if(in[i]%2==0)
44                 even.pb(i);
45             else
46                 odd.pb(i);
47         }
48         for(int i:even)
49             for(int j:odd)
50                 if(is(1ll*in[i]*in[i]+1ll*in[j]*in[
51                     j]) && __gcd(in[i],in[j])==1)
52                     e[i].pb(j), e[j].pb(i);
53         int ans=0;
54         fill(match,match+N,-1);
55         for(int i=0;i<N;i++)
56             if(match[i]==-1) {
57                 fill(vis,vis+N,0);
58                 if(DFS(i))
59                     ans++;
60             }
61         printf("%d\n",ans);
62     }
63     return 0;
64 }

```

5.2 KM($O(N^4)$)

```

1 const int INF=1016; //> max(a[i][j])
2 const int MAXN=650;
3 int a[MAXN][MAXN]; // weight [x][y] , two
4 // set of vertex
5 int N; // two set: each set have exactly N
6 // vertex
7
8 bool DFS(int x) {
9     vis[x]=1;
10    for(int i=0;i<N;i++) {
11        if(weight[x]+weight[N+i]!=a[x][i])
12            continue;
13        vis[N+i]=1;
14        if(match[N+i]==-1 || (!vis[match[N+i]
15            ]&&DFS(match[N+i]))) {
16            match[N+i]=x;
17            match[x]=N+i;

```

```

16     return 1;
17 }
18 }
19 return 0;
20 }
21
22 int KM() {
23     fill(weight, weight+N*N, 0);
24     for(int i=0;i<N;i++) {
25         for(int j=0;j<N;j++)
26             weight[i]=max(weight[i], a[i][j]);
27     }
28     fill(match, match+N*N, -1);
29     for(int u=0;u<N;u++) {
30         fill(vis, vis+N*N, 0);
31         while(!DFS(u)) {
32             int d=INF;
33             for(int i=0;i<N;i++) {
34                 if(!vis[i]) continue;
35                 for(int j=0;j<N;j++)
36                     if(!vis[N+j])
37                         d=min(d, weight[i]+weight[N+j]-a[i][j]);
38             }
39             for(int i=0;i<N;i++)
40                 if(vis[i])
41                     weight[i]-=d;
42             for(int i=N;i<N*N;i++)
43                 if(vis[i])
44                     weight[i]+=d;
45             fill(vis, vis+N*N, 0);
46         }
47     }
48     int ans=0;
49     for(int i=0;i<N*N;i++) ans+=weight[i];
50     return ans;
51 }
24     memset(inp,0,sizeof(inp));
25     while(1) {
26         u = djs[u];
27         inp[u] = true;
28         if(u == st) break;
29         u = bk[pr[u]];
30     }
31     while(1) {
32         v = djs[v];
33         if(inp[v]) return v;
34         v = bk[pr[v]];
35     }
36     return v;
37 }
38 void upd(int u) {
39     int v;
40     while(djs[u] != nb) {
41         v = pr[u];
42         inb[djs[u]] = inb[djs[v]] = true;
43         u = bk[v];
44         if(djs[u] != nb) bk[u] = v;
45     }
46 }
47 void blo(int u,int v) {
48     nb = lca(u,v);
49     memset(inb,0,sizeof(inb));
50     upd(u); upd(v);
51     if(djs[u] != nb) bk[u] = v;
52     if(djs[v] != nb) bk[v] = u;
53     for(int tu = 1; tu <= V; tu++)
54         if(inb[djs[tu]]) {
55             djs[tu] = nb;
56             if(!inq[tu]){
57                 qe.push(tu);
58                 inq[tu] = 1;
59             }
60         }

```

5.3 general graph matching(bcw)

```

1 #define FZ(x) memset(x,0,sizeof(x))
2 struct GenMatch { // 1-base
3     static const int MAXN = 250;
4     int V;
5     bool el[MAXN][MAXN];
6     int pr[MAXN];
7     bool inq[MAXN],inp[MAXN],inb[MAXN];
8     queue<int> qe;
9     int st,ed;
10    int nb;
11    int bk[MAXN],djs[MAXN];
12    int ans;
13    void init(int _V) {
14        V = _V;
15        FZ(el); FZ(pr);
16        FZ(inq); FZ(inp); FZ(inb);
17        FZ(bk); FZ(djs);
18        ans = 0;
19    }
20    void add_edge(int u, int v) {
21        el[u][v] = el[v][u] = 1;
22    }
23    int lca(int u,int v) {
24        for(int i=1; i<=V; i++)
25            djs[i] = i;
26        while(qe.size()) qe.pop();
27        qe.push(st);
28        inq[st] = 1;
29        ed = 0;
30        while(qe.size()) {
31            int u = qe.front(); qe.pop();
32            for(int v = 1; v <= V; v++)
33                if(el[u][v] && (djs[u] != djs[v])
34                    && (pr[u] != v)) {
35                    if((v == st) || ((pr[v] > 0) &&
36                        bk[pr[v]] > 0))
37                        blo(u,v);
38                    else if(bk[v] == 0) {
39                        bk[v] = u;
40                        if(pr[v] > 0) {
41                            if(!inq[pr[v]]) qe.push(pr[v]);
42                        }
43                    } else {
44                        ed = v;
45                        return;
46                    }
47                }
48        }
49    }
50    int solve() {
51        init(V);
52        for(int i=1; i<=V; i++)
53            if(!inq[i]) qe.push(i);
54        while(qe.size()) {
55            int u = qe.front(); qe.pop();
56            for(int v=1; v<=V; v++)
57                if(el[u][v] && !inq[v]) {
58                    if(djs[u] < djs[v])
59                        djs[v] = djs[u];
60                    if(djs[u] == djs[v])
61                        bk[v] = u;
62                    if(v == st)
63                        ed = v;
64                    qe.push(v);
65                }
66        }
67        return ed;
68    }
69    int main() {
70        int n,m;
71        while(scanf("%d%d",&n,&m)) {
72            if(n==0) break;
73            V = n;
74            ans = 0;
75            for(int i=1; i<=m; i++) {
76                int u,v;
77                scanf("%d%d",&u,&v);
78                add_edge(u,v);
79            }
80            int st,ed;
81            scanf("%d%d",&st,&ed);
82            int res = solve();
83            if(res == 0)
84                printf("No solution\n");
85            else
86                printf("%d\n",res);
87        }
88        return 0;
89    }
90 }

```

```

memset(inp,0,sizeof(inp));
while(1) {
    u = djs[u];
    inp[u] = true;
    if(u == st) break;
    u = bk[pr[u]];
}
while(1) {
    v = djs[v];
    if(inp[v]) return v;
    v = bk[pr[v]];
}
return v;
}
void upd(int u) {
    int v;
    while(djs[u] != nb) {
        v = pr[u];
        inb[djs[u]] = inb[djs[v]] = true;
        u = bk[v];
        if(djs[u] != nb) bk[u] = v;
    }
}
void blo(int u,int v) {
    nb = lca(u,v);
    memset(inb,0,sizeof(inb));
    upd(u); upd(v);
    if(djs[u] != nb) bk[u] = v;
    if(djs[v] != nb) bk[v] = u;
    for(int tu = 1; tu <= V; tu++)
        if(inb[djs[tu]]) {
            djs[tu] = nb;
            if(!inq[tu]){
                qe.push(tu);
                inq[tu] = 1;
            }
        }
}
void flow() {
    memset(inq,false,sizeof(inq));
    memset(bk,0,sizeof(bk));
    for(int i = 1; i <= V;i++)
        djs[i] = i;

    while(qe.size()) qe.pop();
    qe.push(st);
    inq[st] = 1;
    ed = 0;
    while(qe.size()) {
        int u = qe.front(); qe.pop();
        for(int v = 1; v <= V; v++)
            if(e1[u][v] && (djs[u] != djs[v])
                && (pr[u] != v)) {
                if((v == st) || ((pr[v] > 0) &&
                    bk[pr[v]] > 0))
                    blo(u,v);
                else if(bk[v] == 0) {
                    bk[v] = u;
                    if(pr[v] > 0) {
                        if(!inq[pr[v]]) qe.push(pr[v]);
                    }
                } else {
                    ed = v;
                    return;
                }
            }
    }
}

```

```

86     }
87     }
88 }
89 }
90 void aug() {
91     int u,v,w;
92     u = ed;
93     while(u > 0) {
94         v = bk[u];
95         w = pr[v];
96         pr[v] = u;
97         pr[u] = v;
98         u = w;
99     }
100 }
101 int solve() {
102     memset(pr,0,sizeof(pr));
103     for(int u = 1; u <= V; u++)
104         if(pr[u] == 0) {
105             st = u;
106             flow();
107             if(ed > 0) {
108                 aug();
109                 ans ++;
110             }
111         }
112     return ans;
113 }
114 } gm;

```

5.4 Max clique(bcw)

```

1 class MaxClique {
2 public:
3     static const int MV = 210;
4
5     int V;
6     int el[MV][MV/30+1];
7     int dp[MV];
8     int ans;
9     int s[MV][MV/30+1];
10    vector<int> sol;
11
12    void init(int v) {
13        V = v; ans = 0;
14        FZ(el); FZ(dp);
15    }
16
17    /* Zero Base */
18    void addEdge(int u, int v) {
19        if(u > v) swap(u, v);
20        if(u == v) return;
21        el[u][v/32] |= (1<<(v%32));
22    }
23
24    bool dfs(int v, int k) {
25        int c = 0, d = 0;
26        for(int i=0; i<(V+31)/32; i++) {
27            s[k][i] = el[v][i];
28            if(k != 1) s[k][i] &= s[k-1][i];
29            c += __builtin_popcount(s[k][i]);
30        }
31        if(c == 0) {

```

```

32        if(k > ans) {
33            ans = k;
34            sol.clear();
35            sol.push_back(v);
36            return 1;
37        }
38        return 0;
39    }
40    for(int i=0; i<(V+31)/32; i++) {
41        for(int a = s[k][i]; a ; d++) {
42            if(k + (c-d) <= ans) return 0;
43            int lb = a&(-a), lg = 0;
44            a ^= lb;
45            while(lb!=1) {
46                lb = (unsigned int)(lb) >> 1;
47                lg ++;
48            }
49            int u = i*32 + lg;
50            if(k + dp[u] <= ans) return 0;
51            if(dfs(u, k+1)) {
52                sol.push_back(v);
53                return 1;
54            }
55        }
56    }
57    return 0;
58 }
59
60 int solve() {
61     for(int i=V-1; i>=0; i--) {
62         dfs(i, 1);
63         dp[i] = ans;
64     }
65     return ans;
66 }
67 };

```

5.5 EdgeBCC

```

1 const int MAXN=1010;
2 const int MAXM=5010;
3 VI e[MAXN];
4 int low[MAXN],lv1[MAXN],bel[MAXN];
5 bool vis[MAXN];
6 int cnt;
7 VI st;
8 void DFS(int x,int l,int p) {
9     st.PB(x);
10    vis[x]=1;
11    low[x]=lv1[x]=1;
12    bool top=0;
13    for(int u:e[x]) {
14        if(u==p && !top) {
15            top=1;
16            continue;
17        }
18        if(!vis[u]) {
19            DFS(u,l+1,x);
20        }
21        low[x]=min(low[x],low[u]);
22    }
23    if(x==1 || low[x]==1) {
24        while(st.back()!=x) {

```

```

25     bel[st.back()]=cnt;
26     st.pop_back();
27 }
28 bel[st.back()]=cnt;
29 st.pop_back();
30 cnt++;
31 }
32 }
33 int main() {
34     int T;
35     scanf("%d",&T);
36     while(T--) {
37         int N,M,a,b;
38         scanf("%d%d",&N,&M);
39         fill(vis,vis+N+1,0);
40         for(int i=1;i<=N;i++)
41             e[i].clear();
42         while(M--) {
43             scanf("%d%d",&a,&b);
44             e[a].PB(b);
45             e[b].PB(a);
46         }
47         cnt=0;
48         DFS(1,0,-1);
49         /*****/
50     }
51     return 0;
52 }

```

5.6 VerticeBCC

```

1  const int MAXN=10000;
2  const int MAXE=100000;
3
4  VI e[MAXN+10];
5  vector<PII> BCC[MAXE];
6  int bccnt;
7  vector<PII> st;
8  bool vis[MAXN+10];
9  int low[MAXN+10],level[MAXN+10];
10
11 void DFS(int x,int p,int l) {
12     vis[x]=1;
13     level[x]=low[x]=l;
14     for(int u:e[x]) {
15         if(u==p)
16             continue;
17         if(vis[u]) {
18             if(level[u]<l) {
19                 st.PB(MP(x,u));
20                 low[x]=min(low[x],level[u]);
21             }
22         }
23         else {
24             st.PB(MP(x,u));
25             DFS(u,x,l+1);
26             if(low[u]>=l) {
27                 PII t=st.back();
28                 st.pop_back();
29                 while(t!=MP(x,u)) {
30                     BCC[bccnt].PB(t);
31                     t=st.back();
32                     st.pop_back();

```

```

33     }
34     BCC[bccnt].PB(t);
35     bccnt++;
36 }
37 low[x]=min(low[x],low[u]);
38 }
39 }
40 }
41
42 int main() {
43     int T,N,M;
44     scanf("%d",&T);
45     while(T--) {
46         scanf("%d%d",&N,&M);
47         for(int i=0;i<N;i++)
48             e[i].clear();
49         int cnt=0;
50         while(1) {
51             int x,y;
52             scanf("%d%d",&x,&y);
53             if(x==-1 && y==-1)
54                 break;
55             cnt++;
56             e[x].PB(y);
57             e[y].PB(x);
58         }
59         for(int i=0;i<N;i++) { // no multi-edge
60             sort(ALL(e[i]));
61             e[i].erase(unique(ALL(e[i])),e[i].end
62                 ());
63         }
64         fill(vis,vis+N,0);
65         while(bccnt)
66             BCC[--bccnt].clear();
67         DFS(0,-1,0);
68         /****/
69     }
70     return 0;

```

5.7 Dominating Tree

```

1  const int MAXN = 200000 + 10;
2
3  VI e[MAXN], re[MAXN];
4  int par[MAXN], num[MAXN], t, rn[MAXN];
5  int sd[MAXN], id[MAXN];
6  PII p[MAXN];
7  VI sdom_at[MAXN];
8
9  void dfs(int u) {
10     num[u] = ++t;
11     rn[t] = u;
12     for(int v : e[u]) {
13         if(num[v]) continue;
14         par[v] = u;
15         dfs(v);
16     }
17 }
18
19 void LINK(int x, int y) {
20     p[x].F = y;
21     if(sd[y] < sd[p[x].S]) p[x].S = y;

```

```

22 }
23
24 int EVAL(int x) {
25     if(p[p[x].F].F != p[x].F) {
26         int w = EVAL(p[x].F);
27         if(sd[w] < sd[p[x].S]) p[x].S = w;
28         p[x].F = p[p[x].F].F;
29     }
30     return p[x].S;
31 }
32
33 void DominatingTree(int n) {
34     // 1-indexed
35     par[1] = 1;
36     fill(num, num+n+1, 0);
37     fill(rn, rn+n+1, 0);
38     t = 0;
39     dfs(1);
40
41     for(int i=1; i<=n; i++) {
42         p[i] = MP(i, i);
43     }
44     for(int i=1; i<=n; i++) {
45         sd[i] = (num[i] ? num[i] : MAXN+10);
46         id[i] = i;
47     }
48     for(int i=n; i>1; i--) {
49         int v = rn[i];
50         if(!v) continue;
51         for(int u : re[v]) {
52             int w = EVAL(u);
53             sd[v] = min(sd[v], sd[w]);
54         }
55         sdom_at[rn[sd[v]]].PB(v);
56         LINK(v, par[v]);
57
58         for(int w : sdom_at[par[v]]) {
59             int u = EVAL(w);
60             id[w] = (sd[u]<sd[w] ? u : par[v]);
61         }
62         sdom_at[par[v]].clear();
63     }
64
65     for(int i=2; i<=n; i++) {
66         int v = rn[i];
67         if(!v) break;
68         if(id[v] != rn[sd[v]]) id[v] = id[id[v]
69         ];
70     }

```

5.8 Min Cut

```

1 const int MAXN = 500 + 50;
2 int w[MAXN][MAXN];
3 ll cost[MAXN];
4 bool out[MAXN];
5
6 int N, M;
7 ll go(int V) {
8     fill(cost, cost + N, 0);
9     cost[0] = -1;
10    int nxt = 0, lst = 0;

```

```

11    for(int i = 0; i < N; i++) {
12        if(out[i]) continue;
13        cost[i] += w[0][i];
14        if(cost[i] > cost[nxt]) nxt = i;
15    }
16    while(V > 2) {
17        int u = nxt;
18        if(cost[u] <= 0) return 0;
19        cost[u] = -1;
20        for(int i = 0; i < N; i++) {
21            if(cost[i] == -1 || out[i]) continue;
22            cost[i] += w[u][i];
23            if(cost[i] > cost[nxt]) nxt = i;
24        }
25        V--;
26        lst = u;
27    }
28    if(cost[nxt] <= 0) return 0;
29    out[nxt] = true;
30    for(int i = 0; i < N; i++)
31        w[i][lst] = w[lst][i] = (w[lst][i] + w[
32        nxt][i]);
33    return cost[nxt];
34 }
35
36 ll min_cut() {
37     fill(out, out + N, false);
38     ll res = go(N);
39     for(int v = N - 1; v > 1; v--) {
40         res = min(go(v), res);
41         if(res == 0) return res;
42     }
43     return res;

```

5.9 DMST with sol(bcw)

```

1 const int INF = 1029384756;
2
3 struct edge_t{
4     int u,v,w;
5     set< pair<int,int> > add, sub;
6     edge_t() : u(-1), v(-1), w(0) {}
7     edge_t(int _u, int _v, int _w) {
8         u = _u; v = _v; w = _w;
9         add.insert({u, v});
10    }
11    edge_t& operator += (const edge_t& obj) {
12        w += obj.w;
13        FOR (it, obj.add) {
14            if (!sub.count(*it)) add.insert(*it);
15            else sub.erase(*it);
16        }
17        FOR (it, obj.sub) {
18            if (!add.count(*it)) sub.insert(*it);
19            else add.erase(*it);
20        }
21        return *this;
22    }
23    edge_t& operator -= (const edge_t& obj) {
24        w -= obj.w;
25        FOR (it, obj.sub) {
26            if (!sub.count(*it)) add.insert(*it);

```

```

27     else sub.erase(*it);
28 }
29 for (auto it : obj.add) {
30     if (!add.count(it)) sub.insert(it);
31     else add.erase(it);
32 }
33 return *this;
34 }
35 }eg[MXN*MXN],prv[MXN],EDGE_INF(-1,-1,INF);
36 int N,M;
37 int cid,incyc[MXN],contracted[MXN];
38 vector<int> E[MXN];
39
40 edge_t dmst(int rt){
41     edge_t cost;
42     for (int i=0; i<N; i++){
43         contracted[i] = incyc[i] = 0;
44         prv[i] = EDGE_INF;
45     }
46     cid = 0;
47     int u,v;
48     while (true){
49         for (v=0; v<N; v++){
50             if (v != rt && !contracted[v] && prv[
51                 v].w == INF) break;
52         }
53         if (v >= N) break; // end
54         for (int i=0; i<M; i++){
55             if (eg[i].v == v && eg[i].w < prv[v].
56                 w)
57                 prv[v] = eg[i];
58         }
59         if (prv[v].w == INF) // not connected
60             return EDGE_INF;
61         cost += prv[v];
62         for (u=prv[v].u; u!=v && u!=-1; u=prv[u
63             ].u);
64         if (u == -1) continue;
65         incyc[v] = ++cid;
66         for (u=prv[v].u; u!=v; u=prv[u].u){
67             contracted[u] = 1;
68             incyc[u] = cid;
69         }
70         for (int i=0; i<M; i++){
71             if (incyc[eg[i].u] != cid && incyc[eg
72                 [i].v] == cid){
73                 eg[i] -= prv[eg[i].v];
74             }
75         }
76         for (int i=0; i<M; i++){
77             if (incyc[eg[i].u] == cid) eg[i].u =
78                 v;
79             if (incyc[eg[i].v] == cid) eg[i].v =
80                 v;
81             if (eg[i].u == eg[i].v) eg[i--] = eg
82                 [--M];
83         }
84         for (int i=0; i<N; i++){
85             if (contracted[i]) continue;
86             if (prv[i].u>=0 && incyc[prv[i].u] ==
87                 cid)
88                 prv[i].u = v;
89         }
90         prv[v] = EDGE_INF;
91     }
92 }

```

```

84     return cost;
85 }
86
87 void solve(){
88     edge_t cost = dmst(0);
89     for (auto it : cost.add){ // find a
90         solution
91         E[it.F].PB(it.S);
92         prv[it.S] = edge_t(it.F,it.S,0);
93     }
94 }

```

5.10 Them.

1. Max (vertex) independent set = Max clique on Complement graph
2. Min vertex cover = $|V|$ - Max independent set
3. On bipartite: Min vertex cover = Max Matching(edge independent)
4. Any graph with no isolated vertices: Min edge cover + Max Matching = $|V|$

6 data structure

6.1 Treap

```

1 const int N = ;
2 struct Treap {
3     static Treap mem[N], *pmem;
4     int sz, pri;
5     ll val, sum, add;
6     Treap *l, *r;
7     Treap() {}
8     Treap(ll _val):
9         l(NULL), r(NULL), sz(1), pri(rand()),
10         val(_val), sum(_val), add(0) {}
11 } Treap::mem[N], *Treap::pmem = Treap::mem;
12 Treap* make(ll val) {
13     return new (Treap::pmem++) Treap(val);
14 }
15 inline int sz(Treap *t) {
16     return t ? t->sz : 0;
17 }
18 inline ll sum(Treap *t) {
19     return t ? t->sum + t->add * sz(t) : 0;
20 }
21 inline void add(Treap *t, ll x) {
22     t->add += x;
23 }
24 void push(Treap *t) {
25     t->val += t->add;
26     if(t->l) t->l->add += t->add;
27     if(t->r) t->r->add += t->add;
28     t->add = 0;
29 }
30 void pull(Treap *t) {
31     t->sum = sum(t->l) + sum(t->r) + t->val;
32     t->sz = sz(t->l) + sz(t->r) + 1;
33 }

```

```

33 Treap* merge(Treap *a, Treap *b) {
34     if(!a || !b) return a ? a : b;
35     else if(a->pri > b->pri) {
36         push(a);
37         a->r = merge(a->r, b);
38         pull(a);
39         return a;
40     }
41     else {
42         push(b);
43         b->l = merge(a, b->l);
44         pull(b);
45         return b;
46     }
47 }
48 void split(Treap* t, int k, Treap *&a,
49           Treap *&b) {
49     if(!t) a = b = NULL;
50     else if(sz(t->l) < k) {
51         a = t;
52         push(a);
53         split(t->r, k - sz(t->l) - 1, a->r, b);
54         pull(a);
55     }
56     else {
57         b = t;
58         push(b);
59         split(t->l, k, a, b->l);
60         pull(b);
61     }
62 }

```

6.2 copy on write treap

```

1 #include <cstdlib>
2 #include <cstdio>
3 #include <algorithm>
4 #include <climits>
5 #include <cstring>
6
7 using namespace std;
8
9 const int N = 1000000 + 10;
10
11 struct Treap {
12     char val;
13     int sz, refs;
14     Treap *l, *r;
15
16     Treap() {}
17     Treap(char _val):
18         val(_val), sz(1), refs(0), l(NULL),
19         r(NULL) {}
20 };
21 Treap* make(Treap* t) {
22     return new Treap(*t);
23 }
24
25 Treap* make(char _val) {
26     return new Treap(_val);
27 }
28

```

```

29 void print_ref(Treap* t) {
30     if(!t) return;
31     print_ref(t->l);
32     printf("%d ", t->refs);
33     print_ref(t->r);
34 }
35
36 void print(Treap* t) {
37     if(!t) return;
38     print(t->l);
39     putchar(t->val);
40     print(t->r);
41 }
42
43 void takeRef(Treap* t) {
44     if(t) t->refs++;
45 }
46
47 void dropRef(Treap* t) {
48     if(t) {
49         char c = t->val;
50         t->refs--;
51         if(t->refs <= 0) {
52             dropRef(t->l);
53             dropRef(t->r);
54             delete t;
55         }
56     }
57 }
58
59 int sz(Treap* t) {
60     return t ? t->sz : 0;
61 }
62
63 int rnd(int m) {
64     static int x = 851025;
65     return (x = (x*0xdefaced+1) & INT_MAX)
66         % m;
67 }
68
69 void pull(Treap* t) {
70     t->sz = sz(t->l) + sz(t->r) + 1;
71 }
72
73 Treap* merge(Treap* a, Treap* b) {
74     if(!a || !b) {
75         Treap* t = a ? make(a) : make(b);
76         t->refs = 0;
77         takeRef(t->l);
78         takeRef(t->r);
79         return t;
80     }
81
82     Treap* t;
83     if( rnd(a->sz+b->sz) < a->sz ) {
84         t = make(a);
85         t->refs = 0;
86         t->r = merge(a->r, b);
87         takeRef(t->l);
88         takeRef(t->r);
89     }
90     else {
91         t = make(b);
92         t->refs = 0;
93         t->l = merge(a, b->l);

```



```

93     takeRef(t->l);
94     takeRef(t->r);
95 }
96
97 pull(t);
98 return t;
99 }
100
101 void split(Treap* t, int k, Treap* &a,
    Treap* &b) {
102     if(!t) a = b = NULL;
103     else if(sz(t->l) < k) {
104         a = make(t);
105         a->refs = 0;
106         split(a->r, k-sz(t->l)-1, a->r, b);
107         takeRef(a->l);
108         takeRef(a->r);
109         pull(a);
110     }
111     else {
112         b = make(t);
113         b->refs = 0;
114         split(b->l, k, a, b->l);
115         takeRef(b->l);
116         takeRef(b->r);
117         pull(b);
118     }
119 }
120
121 void print_inorder(Treap* t) {
122     if(!t) return;
123     putchar(t->val);
124     print_inorder(t->l);
125     print_inorder(t->r);
126 }
127
128 char s[N];
129
130 int main() {
131     int m;
132     scanf("%d", &m);
133     scanf("%s", s);
134     int n = strlen(s);
135     int q;
136     scanf("%d", &q);
137
138     Treap* t = NULL;
139     for(int i = 0; i < n; i++) {
140         Treap *a = t, *b = make(s[i]);
141         t = merge(a, b);
142         dropRef(a);
143         dropRef(b);
144     }
145
146     while(q--) {
147         int l, r, x;
148         scanf("%d%d%d", &l, &r, &x);
149         r++;
150
151         Treap *a, *b, *c, *d;
152         a = b = c = d = NULL;
153         split(t, l, a, b); dropRef(a);
154         split(b, r-l, c, d); dropRef(b);
155         dropRef(d);
156         split(t, x, a, b); dropRef(t);
157
158         Treap* t2 = merge(c, b); dropRef(b);
159         dropRef(c);
160
161         t = merge(a, t2); dropRef(a); dropRef(t2);
162         if(t->sz > m) {
163             Treap* t2 = NULL;
164             split(t, m, t2, a); dropRef(a);
165             dropRef(t);
166             t = t2;
167         }
168
169         print(t);
170         putchar('\n');
171     }
172     return 0;
173 }

```

6.3 copy on write segment tree

```

1  const int N = ;
2  const int Q = ;
3  struct Seg {
4      static Seg mem[N*80], *pmem;
5      int val;
6      Seg *tl, *tr;
7      Seg() :
8          tl(NULL), tr(NULL), val(0) {}
9      Seg* init(int l, int r) {
10         Seg* t = new (pmem++) Seg();
11         if(l != r) {
12             int m = (l+r)/2;
13             t->tl = init(l, m);
14             t->tr = init(m+1, r);
15         }
16         return t;
17     }
18     Seg* add(int k, int l, int r) {
19         Seg* _t = new (pmem++) Seg(*this);
20         if(l==r) {
21             _t->val++;
22             return _t;
23         }
24         int m = (l+r)/2;
25         if(k <= m) _t->tl = tl->add(k, l, m);
26         else _t->tr = tr->add(k, m+1, r);
27         _t->val = _t->tl->val + _t->tr->val;
28         return _t;
29     }
30 } Seg::mem[N*80], *Seg::pmem = mem;
31
32 int query(Seg* ta, Seg* tb, int k, int l,
    int r) {
33     if(l == r) return l;
34     int m = (l+r)/2;
35     int a = ta->tl->val;
36     int b = tb->tl->val;
37     if(b-a >= k) return query(ta->tl, tb->tl,
        k, l, m);
38     else return query(ta->tr, tb->tr, k
        -(b-a), m+1, r);

```

39|};

6.4 Treap+(HOJ 92)

```

1 const int INF = 103456789;
2 struct Treap {
3     int pri, sz, val, chg, rev, sum, lsum,
4       rsum, mx_sum;
5     Treap *l, *r;
6     Treap() {}
7     Treap(int _val) :
8         pri(rand()), sz(1), val(_val), chg(
9             INF), rev(0), sum(_val), lsum(
10                _val), rsum(_val), mx_sum(_val),
11                l(NULL), r(NULL) {}
12 };
13 int sz(Treap* t) {return t ? t->sz : 0;}
14 int sum(Treap* t) {
15     if(!t) return 0;
16     if(t->chg == INF) return t->sum;
17     else return t->chg*t->sz;
18 }
19 int lsum(Treap* t) {
20     if(!t) return -INF;
21     if(t->chg != INF) return max(t->chg,
22         (t->chg)*(t->sz));
23     if(t->rev) return t->rsum;
24     return t->lsum;
25 }
26 int rsum(Treap* t) {
27     if(!t) return -INF;
28     if(t->chg != INF) return max(t->chg,
29         (t->chg)*(t->sz));
30     if(t->rev) return t->lsum;
31     return t->rsum;
32 }
33 int mx_sum(Treap* t) {
34     if(!t) return -INF;
35     if(t->chg != INF) return max(t->chg,
36         (t->chg)*(t->sz));
37     return t->mx_sum;
38 }
39 void push(Treap* t) {
40     if(t->chg != INF) {
41         t->val = t->chg;
42         t->sum = (t->sz) * (t->chg);
43         t->lsum = t->rsum = t->mx_sum = max
44             (t->sum, t->val);
45         if(t->l) t->l->chg = t->chg;
46         if(t->r) t->r->chg = t->chg;
47         t->chg = INF;
48     }
49     if(t->rev) {
50         swap(t->l, t->r);
51         if(t->l) t->l->rev ^= 1;
52         if(t->r) t->r->rev ^= 1;
53         t->rev = 0;
54     }
55 }
56 void pull(Treap* t) {
57     t->sz = sz(t->l)+sz(t->r)+1;
58     t->sum = sum(t->l)+sum(t->r)+t->val;

```

```

52     t->lsum = max(lsum(t->l), sum(t->l)+max
53         (0, lsum(t->r))+t->val);
54     t->rsum = max(rsum(t->r), sum(t->r)+max
55         (0, rsum(t->l))+t->val);
56     t->mx_sum = max(max(mx_sum(t->l),
57         mx_sum(t->r)), max(0, rsum(t->l))+
58         max(0, lsum(t->r))+t->val);
59 }
60 Treap* merge(Treap* a, Treap* b) {
61     if(!a || !b) return a ? a : b;
62     if(a->pri > b->pri) {
63         push(a);
64         a->r = merge(a->r, b);
65         pull(a);
66         return a;
67     }
68     else {
69         push(b);
70         b->l = merge(a, b->l);
71         pull(b);
72         return b;
73     }
74 }
75 void split(Treap* t, int k, Treap* &a,
76     Treap* &b) {
77     if(!t) {
78         a = b = NULL;
79         return;
80     }
81     push(t);
82     if(sz(t->l) < k) {
83         a = t;
84         push(a);
85         split(t->r, k-sz(t->l)-1, a->r, b);
86         pull(a);
87     }
88     else {
89         b = t;
90         push(b);
91         split(t->l, k, a, b->l);
92         pull(b);
93     }
94 }
95 void del(Treap* t) {
96     if(!t) return;
97     del(t->l);
98     del(t->r);
99     delete t;
100 }

```

6.5 Leftist Tree

```

1 #include <bits/stdc++.h>
2 using namespace std;
3 struct Left {
4     Left *l,*r;
5     int v,h;
6     Left(int v_) : v(v_), h(1), l(0), r(0) {}
7 };
8 int height(Left *p) { return p ? p->h : 0; }

```

```

11
12 Left* combine(Left *a, Left *b) {
13     if(!a || !b) return a ? a : b ;
14     Left *p ;
15     if( a->v > b->v ) {
16         p = a;
17         p -> r = combine( p -> r , b );
18     }
19     else {
20         p = b;
21         p -> r = combine( p -> r , a );
22     }
23     if( height( p->l ) < height( p->r ) )
24         swap( p->l , p->r );
25     p->h = min( height( p->l ) , height( p->r ) ) + 1;
26     return p;
27 }
28 Left *root;
29
30 void push(int v) {
31     Left *p = new Left(v);
32     root = combine( root , p );
33 }
34 int top() { return root? root->v : -1; }
35 void pop() {
36     if(!root) return;
37     Left *a = root->l , *b = root->r ;
38     delete root;
39     root = combine( a , b );
40 }
41 void clear(Left* &p) {
42     if(!p)
43         return;
44     if(p->l) clear(p->l);
45     if(p->r) clear(p->r);
46     delete p;
47     p = 0 ;
48 }
49
50 int main() {
51     while (T--) {
52         clear(root);
53         /** do something **/
54     }
55     return 0;
56 }
13 }
14 inline void pull(int x) {
15     node[x].mx = max(node[x].val, max(node[
16         node[x].ch[0]].mx, node[node[x].ch
17         [1]].mx));
18 }
19 inline void push(int x) {
20     if(node[x].rev) {
21         node[node[x].ch[0]].rev ^= 1;
22         node[node[x].ch[1]].rev ^= 1;
23         swap(node[x].ch[0], node[x].ch[1]);
24         node[x].rev ^= 1;
25     }
26 }
27 void push_all(int x) {
28     if(!isroot(x)) push_all(node[x].pa);
29     push(x);
30 }
31 inline void rotate(int x) {
32     int y = node[x].pa, z = node[y].pa, d =
33     node[y].ch[1]==x;
34     node[x].pa = z;
35     if(!isroot(y)) node[z].ch[node[z].ch
36     [1]==y] = x;
37     node[y].ch[d] = node[x].ch[d^1];
38     node[node[x].ch[d^1]].pa = y;
39     node[x].ch[!d] = y;
40     node[y].pa = x;
41     pull(y);
42     pull(x);
43 }
44 void splay(int x) {
45     push_all(x);
46     while(!isroot(x)) {
47         int y = node[x].pa;
48         if(!isroot(y)) {
49             int z = node[y].pa;
50             if((node[z].ch[1]==y) ^ (node[y].ch
51             [1]==x)) rotate(y);
52             else rotate(x);
53         }
54         rotate(x);
55     }
56 }
57 inline int access(int x) {
58     int last = 0;
59     while(x) {
60         splay(x);
61         node[x].ch[1] = last;
62         pull(x);
63         last = x;
64         x = node[x].pa;
65     }
66     return last;
67 }
68 inline void make_root(int x) {
69     node[access(x)].rev ^= 1;
70     splay(x);
71 }
72 inline void link(int x, int y) {
73     make_root(x);
74     node[x].pa = y;
75 }
76 inline void cut(int x, int y) {
77     make_root(x);

```

6.6 Link Cut Tree

```

1 const int MAXN = ;
2 struct SplayTree {
3     int val, mx, ch[2], pa;
4     bool rev;
5     void init() {
6         val = mx = -1;
7         rev = false;
8         pa = ch[0] = ch[1] = 0;
9     }
10 } node[MAXN*2];
11 inline bool isroot(int x) {
12     return node[node[x].pa].ch[0]!=x && node[
13     node[x].pa].ch[1]!=x;

```

```

73 access(y);
74 splay(y);
75 node[y].ch[0] = 0;
76 node[x].pa = 0;
77 }
78 inline void cut_parent(int x) {
79     x = access(x);
80     splay(x);
81     node[node[x].ch[0]].pa = 0;
82     node[x].ch[0] = 0;
83     pull(x);
84 }
85 inline int find_root(int x) {
86     x = access(x);
87     while(node[x].ch[0]) x = node[x].ch[0];
88     splay(x);
89     return x;
90 }
91 int find_mx(int x) {
92     if(node[x].val == node[x].mx) return x;
93     return node[node[x].ch[0]].mx == node[x].mx
        ? find_mx(node[x].ch[0]) : find_mx(
            node[x].ch[1]);
94 }
95 inline void change(int x,int b){
96     splay(x);
97     node[x].data=b;
98     up(x);
99 }
100 inline int query_lca(int u,int v){
101     /*retrun: sum of weight of vertices on the
        chain (u->v)
102     sum: total weight of the subtree
103     data: weight of the vertex */
104     access(u);
105     int lca=access(v);
106     splay(u);
107     if(u==lca){
108         return node[lca].data+node[node[lca].ch
            [1]].sum;
109     }else{
110         return node[lca].data+node[node[lca].ch
            [1]].sum+node[u].sum;
111     }
112 }

```

6.7 Heavy Light Decomposition

```

1 const int MAXN = 10000 + 10;
2 vector<PII> e[MAXN];
3 int val[MAXN];
4 int sz[MAXN], max_son[MAXN], p[MAXN], dep[
    MAXN];
5 int link[MAXN], link_top[MAXN], cnt;
6 void find_max_son(int u) {
7     sz[u] = 1;
8     max_son[u] = -1;
9     for(int i=0; i<SZ(e[u]); i++) {
10         PII tmp = e[u][i];
11         int v = tmp.F;
12         if(v == p[u]) continue;
13
14         p[v] = u;

```

```

15         dep[v] = dep[u]+1;
16         val[v] = tmp.S;
17         find_max_son(v);
18         if(max_son[u]<0 || sz[v]>sz[ max_son[u]
            ]) max_son[u] = v;
19         sz[u] += sz[v];
20     }
21 }
22 void build_link(int u, int top) {
23     link[u] = ++cnt;
24     link_top[u] = top;
25     if(max_son[u] > 0) build_link(max_son[u]
        ], top);
26     for(int i=0; i<SZ(e[u]); i++) {
27         PII tmp = e[u][i];
28         int v = tmp.F;
29         if(v==p[u] || v==max_son[u]) continue;
30         build_link(v, v);
31     }
32 }
33 int query(int a, int b) {
34     int res = -1;
35     int ta = link_top[a], tb = link_top[b];
36     while(ta != tb) {
37         if(dep[ta] < dep[tb]) {
38             swap(a, b);
39             swap(ta, tb);
40         }
41         res = max(res, seg->qry(link[ta], link[
            a], 1, cnt));
42         ta = link_top[a=p[ta]];
43     }
44     if(a != b) {
45         if(dep[a] > dep[b]) swap(a, b);
46         a = max_son[a];
47         res = max(res, seg->qry(link[a], link[b
            ], 1, cnt));
48     }
49     return res;
50 }

```

6.8 Disjoint Sets + offline skill

```

1 const int MAXN = ;
2 bool q[MAXN];
3 struct DisJointSet {
4     int p[MAXN], sz[MAXN], gps;
5     vector<pair<int*, int> > h;
6     VI sf;
7     void init(int n) {
8         for(int i=1; i<=n; i++) {
9             p[i] = i;
10            sz[i] = 1;
11        }
12        gps = n;
13    }
14    void assign(int *k, int v) {
15        h.PB(MP(k, *k));
16        *k = v;
17    }
18    void save() {
19        sf.PB(SZ(h));
20    }

```

```

21 void load() {
22     int last = sf.back(); sf.pop_back();
23     while(SZ(h) != last) {
24         auto x = h.back(); h.pop_back();
25         *x.F = x.S;
26     }
27 }
28 int find(int x) {
29     return x==p[x] ? x : find(p[x]);
30 }
31 void uni(int x, int y) {
32     x = find(x), y = find(y);
33     if(x == y) return;
34     if(sz[x] < sz[y]) swap(x, y);
35     assign(&sz[x], sz[x]+sz[y]);
36     assign(&p[y], x);
37     assign(&gps, gps-1);
38 }
39 } djs;
40 struct Seg {
41     vector<PII> es;
42     Seg *tl, *tr;
43     Seg() {}
44     Seg(int l, int r) {
45         if(l == r) tl = tr = NULL;
46         else {
47             int m = (l+r) / 2;
48             tl = new Seg(l, m);
49             tr = new Seg(m+1, r);
50         }
51     }
52     // add an edge e from time a to time b
53     void add(int a, int b, PII e, int l, int
54         r) {
55         if(a <= l && r <= b) es.PB(e);
56         else if(b < l || r < a) return;
57         else {
58             int m = (l+r) / 2;
59             tl->add(a, b, e, l, m);
60             tr->add(a, b, e, m+1, r);
61         }
62     }
63     void solve(int l, int r) {
64         djs.save();
65         for(auto p : es) djs.uni(p.F, p.S);
66         if(l == r) {
67             if(q[l]); // answer the query here
68         }
69         else {
70             int m = (l+r) / 2;
71             tl->solve(l, m);
72             tr->solve(m+1, r);
73         }
74         djs.load();
75     };
5 //int _x, _y;
6 Seg1D() :
7     tl(NULL), tr(NULL), val(0), tmp(-1), _x
8     (-1), _y(-1) {}
9
10 query1D(int x1, int x2, int y1, int y2
11     , int l, int r) {
12     /*
13     if no Brian improvement, dont need to
14     pass x1 and x2
15     if(tmp >= 0) {
16         if(x1<=_x&&_x<=x2 && y1<=_y&&_y<=y2)
17             return tmp;
18         else return 0;
19     }
20     */
21     if(y1 <= l && r <= y2) return val;
22     else if(r < y1 || y2 < l) return 0;
23     else {
24         int m = (l+r)/2;
25         ll a = tl ? tl->query1D(x1, x2, y1,
26             y2, l, m) : 0;
27         b = tr ? tr->query1D(x1, x2, y1,
28             y2, m+1, r) : 0;
29         return gcd(a, b);
30     }
31 }
32 void update1D(int x, int y, ll num, int l
33     , int r) {
34     if(l == r) {
35         val = num;
36         return;
37     }
38     /*
39     if(tmp < 0 && !tl && !tr) {
40         tmp = val = num;
41         _x = x;
42         _y = y;
43         return;
44     }
45     else if(tmp >= 0) {
46         int m = (l+r)/2;
47         if(_y <= m) {
48             if(!tl) tl = new Seg1D();
49             tl->update1D(_x, _y, tmp, l, m);
50         }
51         else {
52             if(!tr) tr = new Seg1D();
53             tr->update1D(_x, _y, tmp, m+1, r);
54         }
55         tmp = _x = _y = -1;
56     }*/
57     int m = (l+r)/2;
58     if(y <= m) {
59         if(!tl) tl = new Seg1D();
60         tl->update1D(x, y, num, l, m);
61     }
62     else {
63         if(!tr) tr = new Seg1D();
64         tr->update1D(x, y, num, m+1, r);
65     }
66     ll a = tl ? tl->val : 0;
67     ll b = tr ? tr->val : 0;
68     val = gcd(a, b);
69 }

```

6.9 2D Segment Tree

```

1 struct Seg1D {
2     Seg1D *tl, *tr;
3     ll val;
4     // ll tmp;

```

```

58
59
60
61 }
62 };

```

```

63 struct Seg2D {
64     Seg2D *t1, *tr;
65     Seg1D *t2;
66     Seg2D() :
67         t1(NULL), tr(NULL), t2(NULL) {}
68     ll query2D(int x1, int x2, int y1, int y2
69         , int l, int r) {
69         if(x1 <= l && r <= x2) {
70             if(!t2) t2 = new Seg1D();
71             return t2->query1D(x1, x2, y1, y2, 0,
72                 C-1);
73         }
74         else if(x2 < l || r < x1) return 0;
75         else {
76             int m = (l+r)/2;
77             ll a = t1 ? t1->query2D(x1, x2, y1,
78                 y2, l, m) : 0,
79                 b = tr ? tr->query2D(x1, x2, y1,
80                 y2, m+1, r) : 0;
81             return gcd(a, b);
82         }
83     }
84 void update2D(int x, int y, ll num, int l
85     , int r) {
86     int m = (l+r)/2;
87     if(l == r) {
88         if(!t2) t2 = new Seg1D();
89         t2->update1D(x, y, num, 0, C-1);
90         return ;
91     }
92     if(x <= m) {
93         if(!t1) t1 = new Seg2D();
94         t1->update2D(x, y, num, l, m);
95     }
96     else {
97         if(!tr) tr = new Seg2D();
98         tr->update2D(x, y, num, m+1, r);
99     }
100     if(!t1) t1 = new Seg2D();
101     if(!tr) tr = new Seg2D();
102     ll a = t1->t2 ? t1->t2->query1D(l, m, y
103         , y, 0, C-1) : 0,
104         b = tr->t2 ? tr->t2->query1D(m+1, r,
105         y, y, 0, C-1) : 0;
106     if(!t2) t2 = new Seg1D();
107     t2->update1D(x, y, gcd(a, b), 0, C-1);
108 }
109 };

9 bool lt(tp a, tp b) { return a < b-EPS; }
10 bool le(tp a, tp b) { return !lt(b, a); }
11 bool gt(tp a, tp b) { return lt(b, a); }
12 bool ge(tp a, tp b) { return !lt(a, b); }

13 struct coor {
14     tp x, y, z;
15     coor(tp _x=0, tp _y=0, tp _z=0): x(_x), y
16         (_y), z(_z) {}
17     coor operator+(const coor p) const {
18         return coor(x+p.x, y+p.y, z+p.z); }
19     coor operator-(const coor p) const {
20         return coor(x-p.x, y-p.y, z-p.z); }
21     coor operator*(const tp a) const { return
22         coor(x*a, y*a, z*a); }
23     coor operator/(const tp a) const { return
24         coor(x/a, y/a, z/a); }
25     tp operator*(const coor p) const { return
26         x*p.x + y*p.y + z*p.z; }
27     db atan() const {
28         db ret = atan2(y, x);
29         if(ret<0) ret += 2*PI;
30         return ret;
31     }
32     bool operator==(const coor p) const {
33         return eq(x, p.x) && eq(y, p.y) && eq(
34             z, p.z); }
35     void input() { cin >> x >> y; }
36     // 2D only
37     tp operator%(const coor p) const { return
38         x*p.y - y*p.x; }
39     bool operator<(const coor p) const {
40         if(x != p.x) return x<p.x;
41         if(y != p.y) return y<p.y;
42         return z<p.z;
43     }
44 };
45 tp abs2(const coor a) { return a.x*a.x+a.y*
46     a.y+a.z*a.z; }
47 db abs(const coor a) { return sqrt(abs2(a))
48     ; }
49 coor perp(const coor p) { return coor(-p.y,
50     p.x); } // +0.5pi

41 bool polar(const coor a, const coor b) {
42     // integral
43     if(a.y*b.y<0) return a.y>0;
44     if(b.y==0 and b.x>0) return false;
45     if(a.y==0 and a.x>0) return true;
46     return a%b>0;
47     //floating
48     return a.atan() < b.atan();
49 }

```

7 geometry

7.1 Basic

```

1 typedef double tp;
2 typedef double db;
3
4 const db PI = acos(-1.0);
5 const tp INF = 1e18;
6 const tp EPS = 1e-9;
7
8 bool eq(tp a, tp b) { return a-b<=EPS && b-
    a<=EPS; }

```

7.2 CircleCover

```

1 #define N 1021
2
3 struct Circ {
4     coor O;
5     db R;
6     Circ(coor _o=0, db _r=0): O(_o), R(_r) {}
7 };

```



```

8
9 struct CircleCover{
10     int C; Circ c[ N ];
11     bool g[ N ][ N ], overlap[ N ][ N ];
12     // Area[i] : area covered by at least i
        circles
13     db Area[ N ];
14     void init( int _C ){ C = _C; }
15     bool CCinter( Circ& a , Circ& b , coor&
        p1 , coor& p2 ){
16         coor o1 = a.O , o2 = b.O;
17         db r1 = a.R , r2 = b.R;
18         tp d2 = abs2(o1-o2);
19         db d = abs(o1-o2);
20         if( d > r1 + r2 ) return false;
21         if( d < max(r1, r2) - min(r1, r2) )
            return false;
22         //if( d > r1 + r2 ) return false;
23         coor u=(o1+o2)*0.5 + (o1-o2)*((r2*r2-r1
            *r1)/(2*d2));
24         db A=sqrt((r1+r2+d)*(r1-r2+d)*(r1+r2-d)
            *(-r1+r2+d));
25         coor v=coor( o1.y-o2.y , -o1.x + o2.x )
            * A / (2*d2);
26         p1 = u + v; p2 = u - v;
27         return true;
28     }
29     struct Teve {
30         coor p; db ang; int add;
31         Teve() {}
32         Teve(coor _a, db _b, int _c):p(_a), ang
            (_b), add(_c){}
33         bool operator<(const Teve &a)const
34         {return ang < a.ang;}
35     }eve[ N * 2 ];
36     int sign(db x) {
37         return x < 0 ? -1 : x > 0;
38     }
39     // strict: x = 0, otherwise x = -1
40     bool disjunct( Circ& a, Circ &b, int x )
41     {return sign( abs( a.O - b.O ) - a.R - b.
        R ) > x;}
42     bool contain( Circ& a, Circ &b, int x )
43     {return sign( a.R - b.R - abs( a.O - b.O
        ) ) > x;}
44     bool contain(int i, int j){
45         /* c[j] is non-strictly in c[i]. */
46         return (sign(c[i].R - c[j].R) > 0 ||
47             (sign(c[i].R - c[j].R) == 0 && i <
                j) ) && contain(c[i], c[j], -1);
48     }
49     void solve(){
50         for( int i = 0 ; i <= C + 1 ; i ++ )
51             Area[ i ] = 0;
52         for( int i = 0 ; i < C ; i ++ )
53             for( int j = 0 ; j < C ; j ++ )
54                 overlap[i][j] = contain(i, j);
55         for( int i = 0 ; i < C ; i ++ )
56             for( int j = 0 ; j < C ; j ++ )
57                 g[i][j] = !(overlap[i][j] ||
                    overlap[j][i] ||
58                     disjunct(c[i], c[j], -1));
59         for( int i = 0 ; i < C ; i ++ ){
60             int E = 0, cnt = 1;
61             for( int j = 0 ; j < C ; j ++ )

```

```

62         if( j != i && overlap[j][i] )
63             cnt ++;
64         for( int j = 0 ; j < C ; j ++ )
65             if( i != j && g[i][j] ){
66                 coor aa, bb;
67                 CCinter(c[i], c[j], aa, bb);
68                 db A=atan2(aa.y - c[i].O.y, aa.x
                    - c[i].O.x);
69                 db B=atan2(bb.y - c[i].O.y, bb.x
                    - c[i].O.x);
70                 eve[E ++] = Teve(bb, B, 1);
71                 eve[E ++] = Teve(aa, A, -1);
72                 if(B > A) cnt ++;
73             }
74         if( E == 0 ) Area[ cnt ] += PI * c[i]
            .R * c[i].R;
75         else{
76             sort( eve , eve + E );
77             eve[E] = eve[0];
78             for( int j = 0 ; j < E ; j ++ ){
79                 cnt += eve[j].add;
80                 Area[cnt] += (eve[j].p % eve[j +
                    1].p) * .5;
81                 db theta = eve[j + 1].ang - eve[j]
                    .ang;
82                 if (theta < 0) theta += 2. * PI;
83                 Area[cnt] +=
84                     (theta - sin(theta)) * c[i].R*c
                        [i].R * .5;
85             }
86         }
87     }
88 } oracle;
89

```

7.3 ConvexHull

```

1 typedef vector<coor> VP;
2
3 // Convex Hull
4 // keep redundant points or not
5 VP CH(VP arr, bool keep=false) {
6     sort(ALL(arr));
7     VP upper, lower;
8     for(int i=0; i<SZ(arr); i++) {
9         if(i>0 and arr[i] == arr[i-1])
10             continue;
11         coor c = arr[i];
12         while(SZ(upper)>=2) {
13             int last = SZ(upper)-1;
14             coor a = upper[last-1], b=upper[last]
                ];
15             if(!lt((c-a)%(b-a), 0) or (!keep and
                le((c-a)%(b-a), 0)))
16                 upper.pop_back();
17             else
18                 break;
19         }
20         upper.PB(c);
21         while(SZ(lower)>=2) {
22             int last = SZ(lower)-1;
23             coor a = lower[last-1], b=lower[last]
                ];

```



```

24     if(gt((c-a)%(b-a), 0) or (!keep and
25         ge((c-a)%(b-a), 0)))
26         lower.pop_back();
27     else
28         break;
29     }
30     lower.PB(c);
31 }
32 for(int i=SZ(upper)-2; i>0; i--)
33     lower.PB(upper[i]);
34 return lower;
35 }

```

7.4 HalfPlaneNSquare

```

1 typedef vector<coor> poly;
2 void cut(poly &tar, const coor vec, const
3     db c) {
4     poly tmp;
5     coor st = tar[0];
6     tar.PB(st);
7     for(int k = 1; k < SZ(tar); k++) {
8         coor ed = tar[k];
9         db a = st*vec, b = ed*vec;
10        coor v2 = st * ((b-c)/(b-a)) + ed * ((c
11            -a)/(b-a));
12
13        if(le(a, c))
14            tmp.PB(st);
15        if((lt(a, c) and gt(b, c)) || (gt(a, c)
16            and lt(b, c)))
17            tmp.PB(v2);
18        st = ed;
19    }
20    tar.clear();
21    for(int i=0; i<SZ(tmp); i++)
22        tar.PB(tmp[i]);
23 }
24
25 void polyIntersect(poly &P, const poly &Q)
26 {
27     for(int i=0; i<SZ(Q); i++) {
28         coor v = perp(Q[(i+1)%SZ(Q)]-Q[i])*(-1)
29             ;
30         v = v/abs(v);
31         cut(P, v, v*Q[i]);
32     }
33 }

```

7.5 LineIntersection

```

1 coor line_inter(const coor p1, const coor
2     v1, const coor p2, const coor v2) {
3     if(eq(v1*v2, 0.0))
4         return coor(INF, INF);
5     db k = ((p2-p1)*v2) / (v1*v2);
6     return p1 + v1*k;
7 }

```

7.6 OldCircleInter

```

1 void CircleInter(coor o1, db r1, coor o2,
2     db r2) {
3     if(r2>r1)
4         swap(r1, r2), swap(o1, o2);
5     db d = (o2-o1).abs();
6     coor v = o2-o1;
7     v = v / v.abs();
8     coor t = coor(v.y, -v.x);
9
10    db area;
11    vector<coor> pts;
12    if(d > r1+r2+EPS)
13        area = 0;
14    else if(d < r1-r2)
15        area = r2*r2*PI;
16    else if(r2*r2+d*d > r1*r1){
17        db x = (r1*r1 - r2*r2 + d*d) / (2*d);
18        db th1 = 2*acos(x/r1), th2 = 2*acos((d-
19            x)/r2);
20        area = (r1*r1*(th1 - sin(th1)) + r2*r2
21            *(th2 - sin(th2))) / 2;
22        db y = sqrt(r1*r1 - x*x);
23        pts.PB(o1 + v*x + t*y), pts.PB(o1 + v*x
24            - t*y);
25    } else {
26        db x = (r1*r1 - r2*r2 - d*d) / (2*d);
27        db th1 = acos((d+x)/r1), th2 = acos(x/
28            r2);
29        area = r1*r1*th1 - r1*d*sin(th1) + r2*
30            r2*(PI-th2);
31        db y = sqrt(r2*r2 - x*x);
32        pts.PB(o2 + v*x + t*y), pts.PB(o2 + v*x
33            - t*y);
34    }
35    //Area: area
36    //Intersections: pts
37 }

```

7.7 PolyCircleIntersect

```

1 // Divides into multiple triangle, and sum
2 // up
3 // oriented area
4 int sign(db x) { return x < 0 ? -1 : x > 0; }
5
6 db area2(coor pa, coor pb, db r){
7     if( abs(pa) < abs(pb) ) swap(pa, pb);
8     if( abs(pb) < EPS ) return 0;
9     db S, h, theta;
10    db a = abs( pb ), b = abs( pa ), c = abs(
11        pb - pa );
12    db cosB = (pb * (pb - pa)) / a / c, B =
13        acos(cosB);
14    db cosC = (pa * pb) / a / b, C = acos(
15        cosC);
16    if(a > r){
17        S = (C/2)*r*r;
18        h = a*b*sin(C)/c;
19        if (h < r && B < PI/2) S -= (acos(h/r)*
20            r*r - h*sqrt(r*r-h*h));
21    } else if(b > r){
22

```

```

16     theta = PI - B - asin(sin(B)/r*a);
17     S = .5*a*r*sin(theta) + (C-theta)/2*r*r
    ;
18 }else S = .5*sin(C)*a*b;
19 return S;
20 }
21 db area(coor ori, db r, const poly &P) {
22     db S = 0;
23     int n = SZ(P);
24     for(int i = 0; i < n; ++i) {
25         coor v1=P[i]-ori, v2=P[(i+1)%n]-ori;
26         S += area2(v1, v2, r) * sign(v1%v2);
27     }
28     return fabs(S);
29 }

```

7.8 SegmentIntersection

```

1 int ori(const coor o, const coor a, const
    coor b) {
2     tp val = (a-o)%(b-o);
3     return gt(val, 0) - lt(val, 0);
4 }
5 bool SegmentIntersect(const coor p1, const
    coor p2, const coor q1, const coor q2) {
6     if( eq((p2-p1)%(q2-q1), 0) ) {
7         if( ori(p1, p2, q1) ) return false;
8         return le( ( p1 - q1 ) * ( p2 - q1 ),
9             0) ||
10             le( ( p1 - q2 ) * ( p2 - q2 ),
11                 0) ||
12             le( ( q1 - p1 ) * ( q2 - p1 ), 0)
13             ||
14             le( ( q1 - p2 ) * ( q2 - p2 ), 0);
15 }
16 return (ori( p1, p2, q1 ) * ori( p1, p2,
    q2 ) <= 0) &&
17 (ori( q1, q2, p1 ) * ori( q1, q2,
    p2 ) <= 0);

```

7.9 Triangulation

```

1 typedef vector<coor> poly;
2 const int N = 105;
3
4 bool inside(const coor pnt, const poly &P)
    {
5     int n = SZ(P);
6     for(int i=0; i<n; i++) {
7         coor p1=P[i], p2=P[(i+1)%n];
8         if(lt((p1-pnt) % (p2-pnt), 0))
9             return false;
10    }
11    return true;
12 }
13
14 int prv[N], nxt[N];
15 bool isear(int x, const poly &P) {
16     int n = SZ(P);
17     int x1 = nxt[x], x2=prv[x];

```

```

18     coor v=P[x], v1=P[x1], v2=P[x2];
19     if(le((v1-v)%(v2-v), 0)) return false;
20     poly cand;
21     cand.PB(v), cand.PB(v1), cand.PB(v2);
22     for(int j=0; j<n; j++) {
23         if(j==x or j==x1 or j==x2) continue;
24         if(inside(P[j], cand))
25             return false;
26     }
27     return true;
28 }
29
30 vector<poly> triangulation(const poly &P) {
31     bool used[N]={}, ear[N]={};
32     int n = SZ(P);
33     for(int i=0; i<n; i++) prv[i] = (i-1+n)%
        n, nxt[i] = (i+1)%n;
34     queue<int> que;
35     for(int i=0; i<n; i++) {
36         ear[i] = isear(i, P);
37         if(ear[i]) que.push(i);
38     }
39     vector<poly> ret;
40     while(true) {
41         assert(!que.empty());
42         int head=que.front();
43         que.pop();
44         if(used[head] or !ear[head]) continue;
45         poly trian;
46         int x1 = nxt[head], x2 = prv[head];
47         trian.PB(P[head]), trian.PB(P[x1]),
48             trian.PB(P[x2]);
49         ret.PB(trian);
50         used[head]=true;
51         nxt[x2] = x1, prv[x1] = x2;
52         if(prv[x2] == x1) break;
53         ear[x1] = isear(x1, P), ear[x2] = isear
54             (x2, P);
55         if(ear[x1]) que.push(x1);
56         if(ear[x2]) que.push(x2);
57     }
58     return ret;

```

7.10 Smallest circle problem

```

1 const int MAXN = ;
2 struct PT {
3     double x, y;
4     PT() {}
5     PT(double x, double y):
6         x(x), y(y) {}
7     PT operator+(const PT &b) const {
8         return (PT) {x+b.x, y+b.y};
9     }
10    PT operator-(const PT &b) const {
11        return (PT) {x-b.x, y-b.y};
12    }
13    PT operator*(const double b) const {
14        return (PT) {x*b, y*b};
15    }
16    PT operator/(const double b) const {

```

```

17     return (PT) {x/b, y/b};
18 }
19 double operator%(const PT &b) const {
20     return x*b.y - y*b.x;
21 }
22 double len() const {
23     return sqrt(x*x + y*y);
24 }
25 PT T() const {
26     return (PT) {-y, x};
27 }
28 } p[MAXN];
29 void update(PT a, PT b, PT c, PT &o, double
    &r) {
30     if(c.x < 0.0) o = (a+b) / 2.0;
31     else {
32         PT p1 = (a+b)/2.0, p2 = p1 + (b-a).T();
33         PT p3 = (a+c)/2.0, p4 = p3 + (c-a).T();
34         double a123 = (p2-p1)%(p3-p1), a124 = (
            p2-p1)%(p4-p1);
35         if(a123 * a124 > 0.0) a123 = -a123;
36         else a123 = abs(a123), a124 = abs(a124
            );
37         o = (p4*a123 + p3*a124) / (a123 + a124)
            ;
38     }
39     r = (a-o).len();
40 }
41 void solve(PT &o, double &r) {
42     random_shuffle(p, p+n);
43     PT a = p[0], b = p[1], c(-1.0, -1.0);
44     o = (a+b) / 2.0;
45     double r = (a-o).len();
46     for(int i = 2; i < n; i++) {
47         if((p[i]-o).len() <= r) continue;
48         a = p[i], b = p[0], c = (PT) {-1.0,
            -1.0};
49         update(a, b, c, o, r);
50         for(int j = 1; j < i; j++) {
51             if((p[j]-o).len() <= r) continue;
52             b = p[j], c = (PT) {-1.0, -1.0};
53             update(a, b, c, o, r);
54             for(int k = 0; k < j; k++) {
55                 if((p[k]-o).len() <= r) continue;
56                 c = p[k];
57                 update(a, b, c, o, r);
58             }
59         }
60     }
61 }

```

8 Others

8.1 Random

```

1 const int seed=1;
2
3 mt19937 rng(seed);
4 int randint(int lb,int ub) { // [lb, ub]
5     return uniform_int_distribution<int>(lb,
        ub)(rng);
6 }

```

8.2 Fraction

```

1 struct Frac {
2     ll a,b; // a/b
3     void relax() {
4         ll g=__gcd(a,b);
5         if(g!=0 && g!=1)
6             a/=g, b/=g;
7         if(b<0)
8             a*=-1, b*=-1;
9     }
10     Frac(ll a_=0,ll b_=1): a(a_), b(b_) {
11         relax();
12     }
13     Frac operator + (Frac x) {
14         relax();
15         x.relax();
16         ll g=__gcd(b,x.b);
17         ll lcm=b/g*x.b;
18         return Frac(a*(lcm/b)+x.a*(lcm/x.b),lcm
            );
19     }
20     Frac operator - (Frac x) {
21         relax();
22         x.relax();
23         Frac t=x;
24         t.a*=-1;
25         return *this+t;
26     }
27     Frac operator * (Frac x) {
28         relax();
29         x.relax();
30         return Frac(a*x.a,b*x.b);
31     }
32     Frac operator / (Frac x) {
33         relax();
34         x.relax();
35         Frac t=Frac(x.b,x.a);
36         return (*this)*t;
37     }
38     bool operator < (Frac x) {
39         ll lcm=b/__gcd(b,x.b)*x.b;
40         return ( (lcm/b)*a < (lcm/x.b)*x.a );
41     }
42 };

```

8.3 Slope Optimization

```

1 bool bye(PLL p1, PLL p2, PLL p3) {
2     ll a1 = p1.F, b1 = p1.S;
3     ll a2 = p2.F, b2 = p2.S;
4     ll a3 = p3.F, b3 = p3.S;
5
6     return (a1-a3)*(b2-b1) >= (b3-b1)*(a1-
        a2);
7 }
8 /* slope is decreasing */
9 while(SZ(ch)>=2 && bye(ch[SZ(ch)-2], ch.
    back(), v[i])) ch.pop_back();

```