

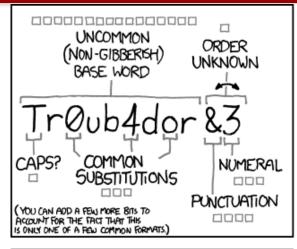
# **PA2 Notes; Basic Parallel Programming**

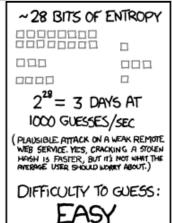
ITP 435 Week 2, Lecture 1

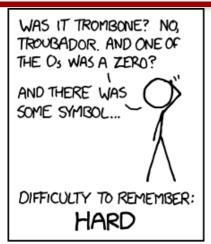


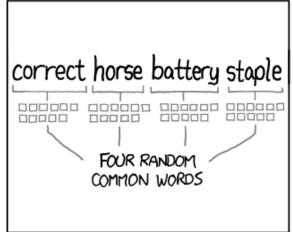
#### PA 2: Passwords

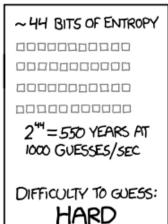


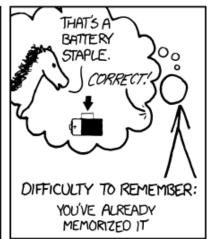












THROUGH 20 YEARS OF EFFORT, WE'VE SUCCESSFULLY TRAINED EVERYONE TO USE PASSWORDS THAT ARE HARD FOR HUMANS TO REMEMBER, BUT EASY FOR COMPUTERS TO GUESS.

#### PA 2: Passwords



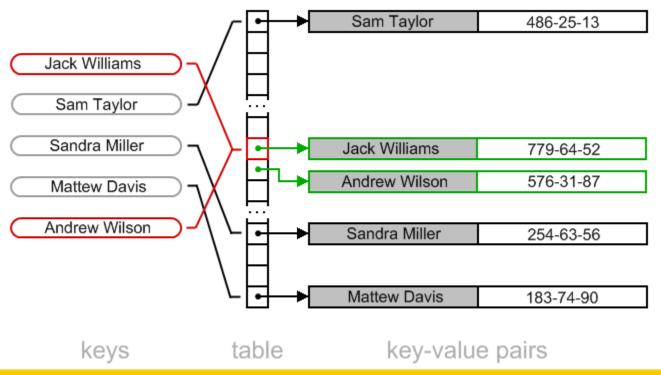
Given some passwords encrypted (with the very insecure) sha1,
 figure out the original plain-text!

- Part 1 Implement open addressed hash table (for cache performance)
- Part 2 Implement a "dictionary" style attack
- Part 3 Implement a "brute force" style attack

# **Open Addressed Hash Table**



- Basic idea: If there's a collision, rather than chaining with a linked list, find the next available index and save the element there
- Here, Jack was added first and then Andrew was a collision:



### Why not buckets?





- An open-addressed hash table has much better cache performance, which in many cases can make it significantly faster
- We'll talk more about cache performance next week!

#### HashTable declaration



```
template <typename KeyType, typename ValueType,
typename HashFuncType = std::hash<KeyType>>
class HashTable
```

- Key and Value types are templated
- Optionally, can specify a function object type for the hashing function (defaults to std::hash) – used for test cases
- We support rehashing/growing if the hash table gets full, but we don't support deleting individual elements (for simplicity)

#### HashTable member data



```
// Underlying hash table array
std::pair<KeyType, ValueType>* mTableData;
// Tracks whether an index is occupied
std::vector<bool> mOccupancy;
// Allocated capacity of hash table array
size t mCapacity;
// Number of elements in HashTable
size t mSize;
// Hash function
HashFuncType mHashFunc;
```

You should not add anything else!!

#### HashTable::Insert



bool Insert(const KeyType& key, const ValueType&
value)

- Try index at hashFuncResult % capacity
- If not occupied, insert, otherwise find the next available index
- If you reach the end and still no space, wrap around to index 0
- Insert only returns false if the key is already in the table.
   Otherwise, it returns true
- \*\*\*If the table is full when you try to insert, Rehash the table with double the current capacity

### HashTable::Rehash



bool Rehash(size\_t newCapacity)

- If the new capacity is less than the number of elements in the table, returns false
- Otherwise will make a new backing array of the requested capacity and hash everything into the new table

#### HashTable::Find



### ValueType\* Find(const KeyType& key) const

- Finds the element, if it exists, using the same "linear probing" technique from Insert
- If you encounter an unoccupied index, then it's not in the table
- Don't get stuck in an infinite loop
- Returns pointer to value if found, nullptr otherwise

#### HashTable::ForEach



- Executes given function on each element in the table more on this soon
- Removes need for iterators mostly

### **In-class Week 2 Lecture 2**



• Let's trace through hash table find and insert!



### **HashTable Rule of 5 Functions**



- You've gotta implement them all!
- Check previous lecture's notes

# **HashTable order to implement**



- 1. Find
- 2. Insert
- 3. ForEach
- 4. Rule of 5 functions

And then hopefully you pass all the test cases

# **Dictionary Attack**





# **Dictionary Attack**



- 1. Take a list of common passwords
- Encrypt them using sha1
- Store in the hash table (key is encrypted string, value is original text)
- 4. Then lookup each "unknown" sha1 encrypted password and see if it's in the dictionary

## **Passphrase Brute Force**



 Given a list of words, generate all possible 4 word permutations like:

correcthorsebatterystaple
handbusinessworkcorrect
jobfactbookmoney
worldworldplacenight
nightbookgovernmentissue

 Use sha1 on each permutation and see if it's in the hash table of unknown passwords

#### **Number of Phrases**

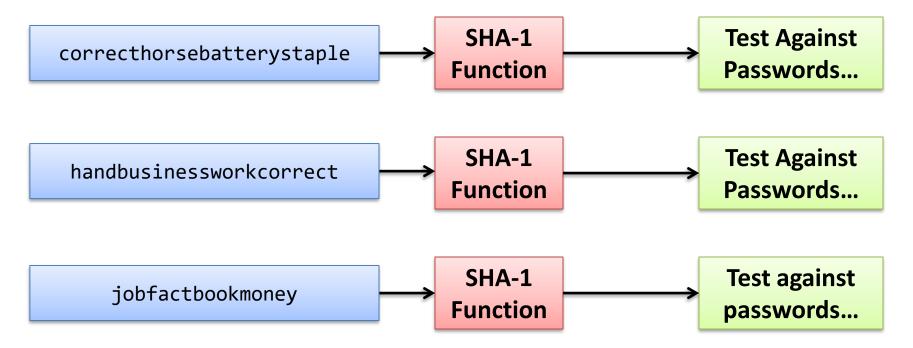


- The biggest input file contains 50 possible words, so...
- 50<sup>4</sup> = 6,250,000
- It's not really a crazy amount, but increasing the number of words significantly increases this

## **Dependencies?**



 Are there any dependencies between all the different permutations?



# **A Serial Implementation**

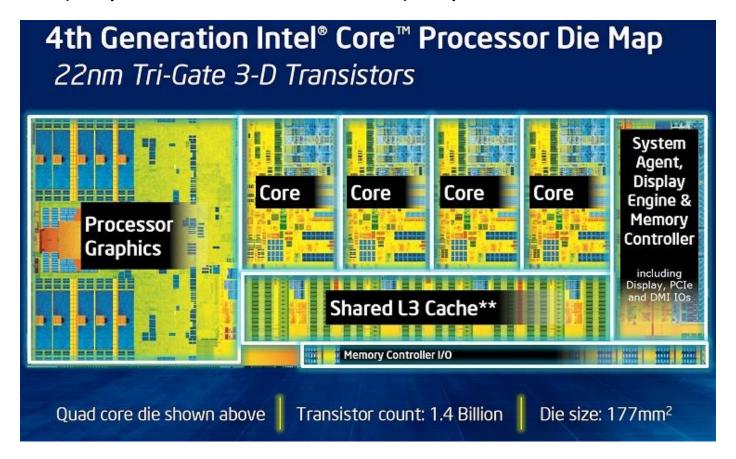


- In a serial implementation, we would just test a single permutation at a time
- On my desktop machine, the full test cases (50<sup>4</sup> phrases) took
   ~3.7s
- Serial code does not take full advantage of modern CPUs!

#### **Multicore CPUs**



 Modern CPUs are multi-core, meaning they can run multiple threads (sequences of instructions) in parallel





# **A Parallel Approach**



- If rewrite the brute force algorithm to handle multiple permutations at once...
- We can test several permutations at once, which results in a significant speedup

- The parallel implementation was first 1.6s, then 1.2s, then 0.55s, then 0.20s as I optimized it further.
- Much better than 3.7s
- (But this can still be improved!)

## **Primality Test**



- A primality test returns whether or not a number is prime
- A naïve primality test (courtesy of Wikipedia):

```
bool isPrime(unsigned long n) {
   if (n <= 3) {
      return n > 1;
   } else if (n % 2 == 0 || n % 3 == 0) {
      return false;
   } else {
      for (unsigned long i = 5; i * i <= n; i += 6) {</pre>
         if (n % i == 0 || n % (i + 2) == 0) {
            return false;
      return true;
```

## **Primality Test in Action**



- Suppose we have a file with 5 million randomly-generated unsigned integers
- For each of these integers, we want to perform a primality test,
   and save the result in a struct encapsulating the number:

```
struct Number {
   unsigned value;
   bool isPrime;
   Number(unsigned v) {
     value = v;
     isPrime = false;
   }
};
```

## **A Serial Implementation**



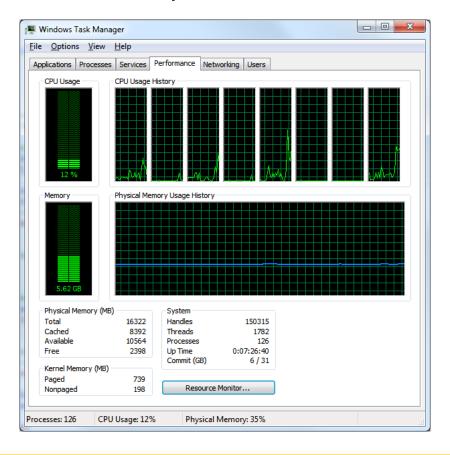
Here's a basic serial implementation

```
std::vector<Number> numbers;
numbers.reserve(NUMBER COUNT);
// Populate vector with numbers from file
// ...
// Start high frequency timer (custom class I created)
Timer timer;
timer.start();
// Test each number (serial)
for (auto& n : numbers) {
   n.isPrime = isPrime(n.value);
}
// Get time elapsed
double elapsed = timer.getElapsed();
std::cout << "Took " << elapsed << " seconds" << std::endl;</pre>
```

# **Serial Implementation in Action**



- Took ~12.5 seconds on this older machine
- Max CPU utilization was only 12%:



### std::for each



Instead of this:

```
// Test each number (serial)
for (auto& n : numbers) {
   n.isPrime = isPrime(n.value);
```

You can include <algorithm> and do:

```
std::for_each(numbers.begin(), numbers.end(),
   [](Number& n) {
      n.isPrime = isPrime(n.value);
});
```

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# **Lambda Expressions**



### **Lambda Expressions – Motivation**



By default, std::sort sorts in ascending order:

```
std::vector<int> v;
v.emplace_back(10);
v.emplace_back(-10);
v.emplace_back(100);
std::sort(v.begin(), v.end());
// v = {-10, 10, 100}
```

What if we want descending order?

### A Custom Comparator!



```
std::sort(v.begin(), v.end(), [](int a, int b) {
    // Return a greater than b instead of less
    return a > b;
});
// v = {100, 10, -10}
```

This uses a new syntax...

### **Lambda Expressions**



A lambda expression is an inline declaration of a function and implementation

```
[](int a, int b) {
    // Return a greater than b instead of less
    return a > b;
}
```

- In other languages, this may be called anonymous functions (like in JavaScript)
- Let's explain this crazy syntax!

# **Lambda Expression Syntax**



```
Capture Clause (empty in this case)

[](int a, int b) {

return a > b;

Body of function Parameters
```

# Lambda Expression Syntax, Another Example



# **Capture Clause**



- This is used to "capture" variables that exist outside the lambda expression, and use them inside the lambda
- Variables can be captured by value or reference:

```
Capture ALL local variables by value (not recommended)
[=]
// Capture ALL local variables by reference (not recommended)
[&]
// Capture x by value and y by reference
[x, &y]
// Capture count by reference, and all other locals by value
[=, &count]
// Capture this by value (can't be captured by reference)
// If you want to use any member functions or variables in the
// lambda, you have to capture this.
[this]
```

#### Lambdas stored in variables



- You're allowed to store lambdas in a variable
- Instead of figuring out the type, use auto
- Our previous example could be:

```
auto greater = [](int a, int b) {
    return a > b;
};
std::sort(v.begin(), v.end(), greater);
// v = {100, 10, -10}
```

# Specifying the Type of a Lambda



• If you need to specify the type, use the std::function template class (in the <functional> header):

```
std::function<bool(int, int)> greater =
   [](int a, int b) {
    return a > b;
};
```

- (This says the lambda returns a bool and takes in two ints as parameters)
- To call it, use like a function:

```
bool result = greater(5, 10);
```



# **Parallel Algorithms**



### std::for\_each



Instead of this:

```
// Test each number (serial)
for (auto& n : numbers) {
   n.isPrime = isPrime(n.value);
}

    You can include <algorithm> and do:

std::for_each(numbers.begin(),numbers.end(),
   [](Number& n) {
      n.isPrime = isPrime(n.value);
});
```

## **Parallel Algorithms**



### As of C++17, STL algorithms now support parallelization

Table 1 — Table of parallel algorithms

	3	
adjacent_find	all_of	any_of
copy_if	copy_n	count
equal	exclusive_scan	fill
find	find_end	find_first_of
find_if_not	for_each	for_each_n
generate_n	includes	inclusive_scan
inplace_merge	is_heap	is_heap_until
is_sorted	is_sorted_until	<pre>lexicographical_compare</pre>
merge	min_element	minmax_element
move	none_of	nth_element
partial_sort_copy	partition	partition_copy
remove	remove_copy	remove_copy_if
replace	replace_copy	replace_copy_if
reverse	reverse_copy	rotate
search	search_n	set_difference
<pre>set_symmetric_difference</pre>	set_union	sort
stable_sort	swap_ranges	transform
transform_inclusive_scan	transform_reduce	uninitialized_copy
uninitialized_fill	uninitialized_fill_n	unique
	adjacent_find copy_if equal find find_if_not generate_n inplace_merge is_sorted merge move partial_sort_copy remove replace reverse search set_symmetric_difference stable_sort transform_inclusive_scan	copy_if equal exclusive_scan find find_end find_if_not for_each generate_n includes inplace_merge is_heap is_sorted is_sorted_until merge min_element move none_of partial_sort_copy partition remove remove_copy replace replace_copy reverse search_n set_symmetric_difference set_union stable_sort swap_ranges transform_inclusive_scan transform_reduce

## **Using Parallel Algorithms**



- You need to include <algorithm> like usual, but you also need to include <execution>
- Supported STL algorithms now have an overloaded version that includes an execution policy as the first parameter
- Old version (still works if you want to use it):

```
std::for_each(v.begin(), v.end(), ...);
```

New version (supports execution policy):

```
std::for_each(std::execution::par, v.begin(),
v.end(), ...);
```

## **Clang/Mac Important Note**



- Clang's STL implementation on Mac doesn't support parallel algorithms, so we're using someone's partial implementation of it (which works for us)
- But requires this janky code...

```
#if defined(__APPLE__)
// On Apple platforms, import a 3rd-party parallel implementation
#define PSTLD_HEADER_ONLY
#define PSTLD_HACK_INTO_STD
#include "pstld.h"
#else
// On other platforms, STL works!
#include <algorithm>
#include <execution>
#endif
```

#### **Execution Policies**



- std::execution::seq
  - This is just like algorithms behaved before parallel algorithms
  - The algorithm runs on a single thread in sequential order from the start to end of the range
- std::execution::par
  - The work can be split up between multiple threads
  - However, each thread will work on a contiguous part of the sequence and in sequential order for its part
- std::execution::par\_unseq
  - The work can be parallel and also interleaved with no guaranteed ordering between elements

## Parallelization is not guaranteed



Keep in mind that the execution policies are suggestions:

"If the implementation cannot parallelize or vectorize (e.g. due to lack of resources), all standard execution policies can fall back to sequential execution."

 Also note that not every compiler currently supports parallel algorithms (for example, clang's STL implementation does not)

### std::for\_each, parallel



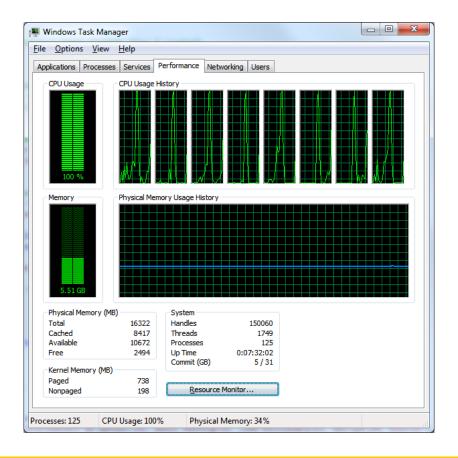
Instead of this:

```
std::for_each(numbers.begin(),numbers.end(),
   [](Number& n) {
      n.isPrime = isPrime(n.value);
});
  Add the parallel execution policy!
std::for each(std::execution::par, numbers.begin(),
   numbers.end(),
   [](Number& n) {
      n.isPrime = isPrime(n.value);
});
```

## std::for\_each, parallel, in action



- Takes only ~2.27 seconds, a 5.5x improvement
- We also hit max CPU utilization!



## **Embarrassingly Parallel**



The problem we just solved is considered an *embarrassingly parallel problem* – a problem for which little or no effort is
 required to separate the problem into parallel tasks

- Some other examples:
  - Brute forcing passwords (as we do in PA2)
  - Rendering independent frames (computer graphics)
  - Simulating independent particles
  - Many different types of fractal/noise algorithms

### **Another Example**



Suppose you have this double for loop:

```
for (int i = 0; i < 20; i++) {
    std::string temp; // some temp data...
    for (int j = 0; j < 20; j++) {
        // Do stuff with 2D vector v...
        v[i][j] = /*...*/;
    }
}</pre>
```

- How to convert it to a parallel for\_each?
- Idea: Convert the outermost loop to a for\_each but leave the rest the same

#### Naïve idea: vector of indices



Make a vector of the values of i and for\_each over that:

```
// Construct a vector of 20 elements
std::vector<int> indices(20);
// std::iota will put the values from 0 to n into the vector
std::iota(indices.begin(), indices.end(), 0);
// Now do the for each
std::for each(std::execution::par, indices.begin(), indices.end(),
   // Capture v by reference so we can use it inside the lambda!
   [&v](int i) {
      std::string temp; // some temp data...
      for (int j = 0; j < 20; j++) {
         // Do stuff with 2D vector v...
        v[i][j] = /*...*/;
      }
});
```

### **Better Idea: Subdivide into ranges**



```
// Construct a vector of pairs of the ranges
std::vector<std::pair<int, int>> ranges{
   \{0, 5\}, \{5, 10\}, \{10, 15\}, \{15, 20\}
};
// for each over the pairs
std::for_each(std::execution::par, ranges.begin(), ranges.end(),
   [&v](const std::pair<int, int>& r) {
      for (int i = r.first; i < r.second; ++i) {
         std::string temp; // some temp data...
         for (int j = 0; j < 20; j++) {
            // Do stuff with 2D vector v...
            v[i][j] = /*...*/;
});
```

## How many pieces to split into?



- Rather than hard-coding the number of splits, it's best to think in terms of how many cores you have, and programmatically split based on that
- std::thread::hardware\_concurrency() in <thread> tells you the number of cores
- You can use something like:

```
unsigned numSplits = std::max(4u, std::thread::hardware_concurrency());
```

(So always split into at least 4 pieces, but into more pieces if you have more cores)

## Is parallel always better?



• There's a cost associated with parallelization

Too many calls can be significantly slower!

#### **Grain Size**



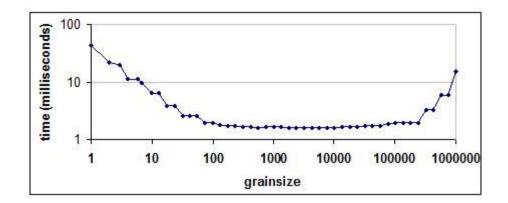
 A grain size determines the smallest size piece the workload is broken down into

 If the grain size is too small (as in the first parallel Fibonacci implementation), then the parallel solution will be slower than the serial one

#### **Grain Size**



- A grain size determines the smallest size piece the workload is broken down into
- Too small of a grain size and overhead dominates, too big and you don't take advantage of parallelization



So, we need to be smart about how we split up work

#### **Common Parallel Pitfall**



Sharing data between parallel operations is okay if it's read-only

However, if you write to shared data, you have to be very careful

```
std::vector<int> test = { 1, 1, 2, 3, 5 };
std::vector<int> copy;
// Let's use parallel for each to copy!
std::for_each(std::execution::par, test.begin(), test.end(),
   [&](int i) {
      copy.push_back(i); // This is bad...
});
for (auto i : copy) {
   std::cout << i << std::endl;</pre>
```

## **Result of Parallel Copy**



Surprisingly, it doesn't crash, but we copy out of order:

1

1

5

2

J

## **STL Collections and Parallel Programming**



 You should assume that adding/removing elements from an STL collection is unsafe in a parallel algorithm — they aren't designed for this

 Reading specific elements should be okay, as long as no one else is adding/removing elements at the same time

 Writing to specific elements may be okay, depending on how it's done



## One Last Look at Execution Policies...



#### **Execution Policies**



- std::execution::seq
  - This is just like algorithms behaved before parallel algorithms
  - The algorithm runs on a single thread in sequential order from the start to end of the range
- std::execution::par
  - The work can be split up between multiple threads
  - However, each thread will work on a contiguous part of the sequence and in sequential order for its part
- std::execution::par\_unseq
  - The work can be parallel and also interleaved with no guaranteed ordering between elements

## **Example**



- Suppose we have two input vectors
- We can transform it into one output vector our transform will multiply the pairs of elements together

Old (sequential) way:

```
std::transform(
  inputA.begin(), inputA.end(), // Begin/end of 1st input range
  inputB.begin(), // Begin of 2nd input range
  destSeq.begin(), // Begin of destination range
  [](float x, float y) { return x * y; } // Lambda
);
```

### How does sequential execute?



- Suppose there's 100 elements.
- This will execute in sequence with no parallelization:

```
destSeq[0] = inputA[0] * inputB[0]
destSeq[1] = inputA[1] * inputB[1]
destSeq[2] = inputA[2] * inputB[2]
destSeq[3] = inputA[3] * inputB[3]
destSeq[4] = inputA[4] * inputB[4]
destSeq[5] = inputA[5] * inputB[5]
destSeq[6] = inputA[6] * inputB[6]
destSeq[7] = inputA[7] * inputB[7]
destSeq[99] = inputA[99] * inputB[99]
```

### **Parallel Execution Policy**



The transform call looks the same except for specifying the policy:

```
std::transform(
    std::execution::par, // Parallel execution policy
    inputA.begin(), inputA.end(), // Begin/end of 1st input range
    inputB.begin(), // Begin of 2nd input range
    destPar.begin(), // Begin of destination range
    [](float x, float y) { return x * y; } // Lambda
);
```

### How does parallel execute?



- Potentially it will split the range into multiple threads
- (For example, if it's two threads and there's 100 elements)

Thread 0	Thread 1
<pre>destSeq[0] = inputA[0] * inputB[0] destSeq[1] = inputA[1] * inputB[1] destSeq[2] = inputA[2] * inputB[2] destSeq[3] = inputA[3] * inputB[3] destSeq[4] = inputA[4] * inputB[4] destSeq[5] = inputA[5] * inputB[5]</pre>	<pre>destSeq[50] = inputA[50] * inputB[50] destSeq[51] = inputA[51] * inputB[51] destSeq[52] = inputA[52] * inputB[52] destSeq[53] = inputA[53] * inputB[53] destSeq[54] = inputA[54] * inputB[54] destSeq[55] = inputA[55] * inputB[55]</pre>
<pre>destSeq[6] = inputA[6] * inputB[6] destSeq[7] = inputA[7] * inputB[7] destSeq[49] = inputA[49] * inputB[49]</pre>	<pre>destSeq[56] = inputA[56] * inputB[56] destSeq[57] = inputA[57] * inputB[57] destSeq[99] = inputA[99] * inputB[99]</pre>

### Parallel/Unsequenced Execution Policy



Just has a different policy:

```
std::transform(
    std::execution::par_unseq, // Parallel/unsequenced policy
    inputA.begin(), inputA.end(), // Begin/end of 1st input range
    inputB.begin(), // Begin of 2nd input range
    destPairUnseq.begin(), // Begin of destination range
    [](float x, float y) { return x * y; } // Lambda
);
```

## How does parallel\_unsequenced execute?



 Potentially could interleave the operations and potentially could vectorize operations

Thread 0	Thread 1
<pre>destSeq[0] = inputA[0] * inputB[0] destSeq[2] = inputA[2] * inputB[2] destSeq[4] = inputA[4] * inputB[4] destSeq[6] = inputA[6] * inputB[6]</pre>	<pre>destSeq[1] = inputA[1] * inputB[1] destSeq[3] = inputA[3] * inputB[3] destSeq[5] = inputA[5] * inputB[5] destSeq[7] = inputA[7] * inputB[7]</pre>
<pre>destSeq[98] = inputA[98] * inputB[98]</pre>	 destSeq[99] = inputA[99] * inputB[99]

### Parallelization is not guaranteed



Keep in mind that the execution policies are suggestions:

"If the implementation cannot parallelize or vectorize (e.g. due to lack of resources), all standard execution policies can fall back to sequential execution."