TARANG SHAH

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EDUCATION

Carnegie Mellon University - School of Computer Science (Robotics Institute)

Pittsburah, PA

MASTER OF SCIENCE IN ROBOTIC SYSTEMS DEVELOPMENT

Aug 2019 - May 2021

Electives: Computer Vision, Deep Learning, Visual Learning & Rec, Computer Graphics, SLAM, Image Synthesis; 4.05 GPA

BITS Pilani (Birla Institute of Technology & Science, Pilani)

Pilani, India

BACHELOR OF ENGINEERING IN ELECTRONICS AND INSTRUMENTATION

Aug 2011 - May 2015

WORK EXPERIENCE

Aurora Innovation

Pittsburgh, PA

SENIOR SOFTWARE ENGINEER

Jan 2023 - Present

- Software Engineer in the Map Content Creation team. Building software pipelines, tools and services to help create and update map content faster.
- Working on various map data elements and algorithms to automate generation and validation of map data.
- Led development of tooling to process, validate and convert map data from tooling friendly HD Map formats to robot friendly AV Map formats.

Argo Al Pittsburgh, PA

SOFTWARE ENGINEER · Working on running workloads of the core vehicle autonomy software on cloud based infra for evaluation and testing

• Building scripts and tools for developers to run cloud jobs on large datasets and optimize various aspects including compute, storage and time

CMU – Argo Al Center for Autonomous Vehicle Research– Prof. John Dolan

Pittsburgh, PA

Pittsburgh, PA

Jul 2021 - Dec 2022

RESEARCH ASSISTANT

Sep 2020 - May 2021

• Built datasets and prototyped modeling approaches for scenario level anomaly detection (ITSC 2021)

Developed pipelines for data collection, visualization in the CARLA Simulator. Including custom controllers and scenarios.

SOFTWARE ENGINEER INTERN Jun 2020 - Aug 2020

Developed pipeline for associating external map data with internal HD Map format at the Data Science team (geospatial matching)

• Enhanced object-detection pipeline to extract raw results on unlabeled data to estimate data importance (cloud data retrieval and inference)

HERE Technologies Mumbai, India

SENIOR DATA SCIENTIST

Argo Al

Jul 2019 - Aug 2019

SENIOR SOFTWARE ENGINEER Oct 2018 - Jun 2019

- Built deep learning based vision models and tools to automate extraction of map data from street images at the Map Creation team
- Trained and deployed object detection models for detecting 300+ traffic signs in street images using TensorFlow Object Detection framework (based on Faster-RCNN, SSD). Helped increase Recall and Precision to 80%+.
- Designed and built cloud-based pipelines for data sampling, annotation, training and evaluation, using cost optimized cloud infra (AWS)
- Developed mobile object detection models for hazard detection as 20%-Time project, now launched as a new product HERE LiveSense SDK SOFTWARE ENGINEER II Apr 2017 - Sep 2018

Designed, built, and deployed a service for highway sign parsing (OCR, scene text and icon extraction) and reduced human effort by 5X per user

Octoloop Systems Gurgaon, India

CO FOUNDER • Octoloop Systems built robots for industries and warehouses. Involved in all aspects of an early-stage technology startup.

• Built an industrial robotic arm for automated Pick and Place tasks in factories and warehouses. Y-Combinator W2017 onsite interviewee

PROJECTS

Extracting behavior from Traffic Videos & Simulation of Realistic Behavior for Traffic Agents

CMU Capstone Project

Apr 2016 - Mar 2017

SOFTWARE ENGINEERING & PROJECT MANAGER

Jan 2020 - Dec 2020

- Extracting visual parameters for learning behaviors from real world video data and simulation in the Carla Simulator
- Built computer vision pipeline for detecting and tracking vehicles from traffic camera videos to bird's eye view. Sponsored by Auro by Ridecell Inc.

Resnets for Classification Networks from Scratch in PyTorch with Ensemble Selection

Intro to Deep Learning (CMU)

• Implemented ResNet from scratch and trained multiple models with varying parameters

Sep 2020 - Nov 2020

• Stood in top 10 amongst 250+ students by building an ensemble selector for choosing the best set of models

PUBLICATIONS & AWARDS

Robust gesture recognition using Kinect: A comparison between DTW and HMM, Optik - International Journal for Light and Electron Optics - 2015 CurbScan: Curb Detection and Tracking Using Multi-Sensor Fusion, IEEE Conference on Intelligent Transportation Systems (ITSC) - 2020 Simulation-Based Benchmark for Behavioral Anomaly Detection in Autonomous Vehicles, IEEE ITSC - 2021

Vision/ML/Data Science: Pandas, PyTorch, Jupyter, SQL, OpenCV, Carla Simulator, TensorFlow Cloud: Compute, Storage, Autoscaling infra (EC2, EC2 Spot, S3, Lambda, ECS), Docker Tools: Git, Jira **Programming:** Python, C++, C, JavaScript, Java Web: HTML, CSS, NodeJS, Express