

ELEC4010N Final Project

Semi-Supervised Classification

&

Domain Generalization on Fundus Images

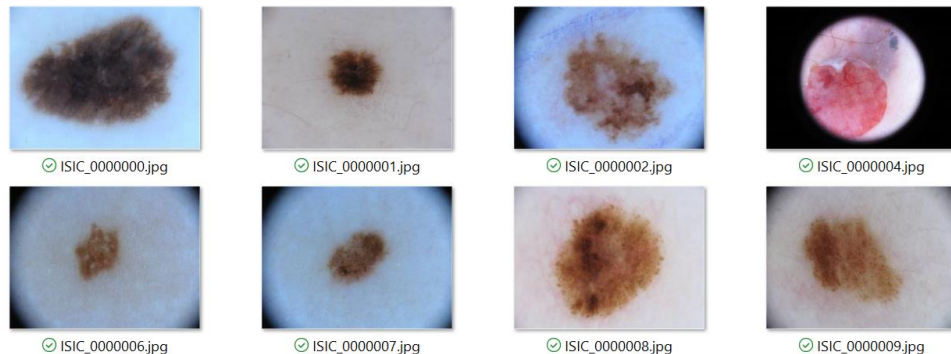


Semi-Supervised Classification



Data

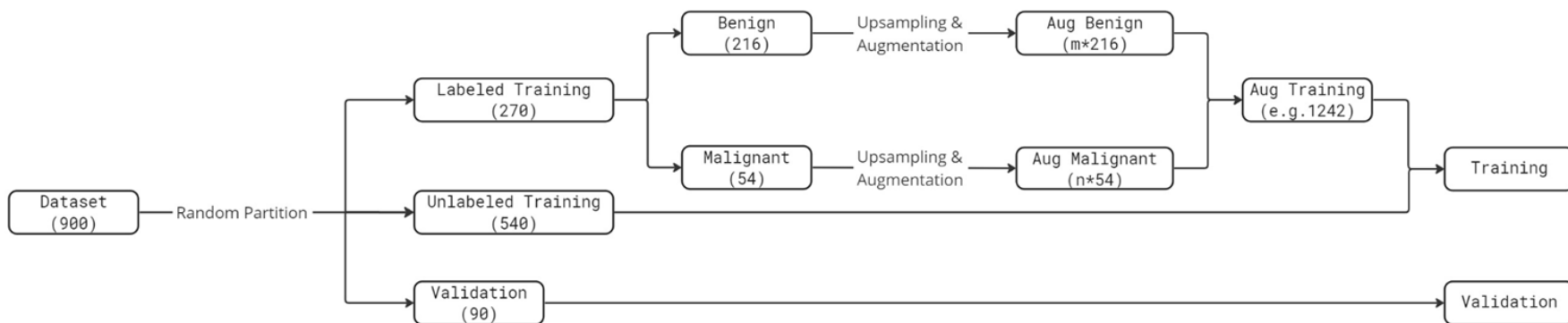
Dataset: ISBI2016_ISIC_Part3_Training_Data



Randomly partition **900** images into **labeled training (270)**, **unlabeled training (540)**, **validation (90)**

Class imbalance problem exists!

We are free to do **upsampling** and **augmentation** only on training data



BCE Focal Loss

Class imbalance problem exists! **Focal Loss**

BCE Focal Loss = Combination of BCE Loss & Focal Loss

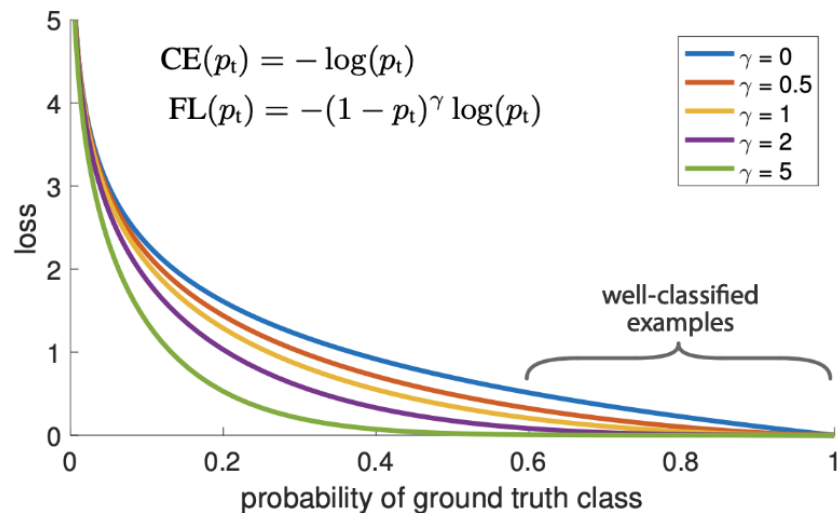
$$\text{BCELoss}(y, \bar{y}) = -(y \log(\bar{y}) + (1 - y) \log(1 - \bar{y}))$$

$$\text{FocalLoss}(p_t) = -\alpha_t(1 - p_t)^\gamma \log(p_t)$$

$$\text{BCEFocalLoss}(p_t) = -(\alpha_t(1 - p_t)^\gamma \log(p_t) + (1 - \alpha_t)p_t^\gamma \log(1 - p_t))$$

Gamma is used to control **how important the minor class is**

Alpha should be about the **ratio of the classes**, ratio = alpha : 1 - alpha, e.g. alpha = 0.75 for 3:1



Mean Teacher Model

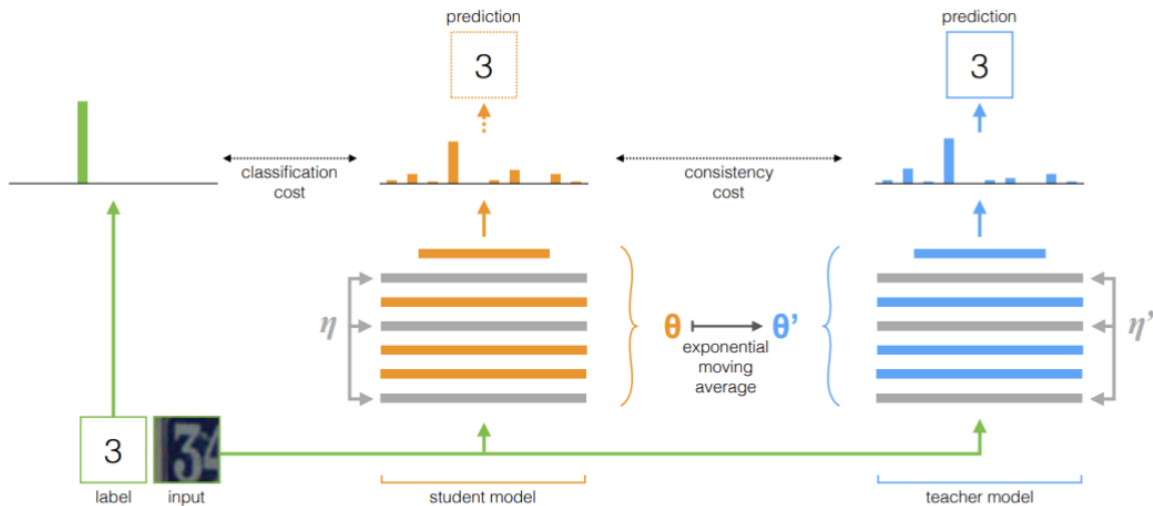
Student Model: ResNet, **Supervised Loss**, predict for unlabeled data

Teacher Model: Deep-copy of Student Model, update the weight by **Exponential Moving Average**, **Consistency Loss**

Total Loss = Supervised Loss + Consistency Loss

```
# Mean Teacher Model
# Student model would be ResNet50 model
class MeanTeacherModel(nn.Module):
    # Core
    def __init__(self, student_model, ema_decay):
        super().__init__()
        self.student_model = student_model
        self.teacher_model = copy.deepcopy(student_model)
        self.ema_decay = ema_decay
```

$$\theta'_t = \alpha \theta'_{t-1} + (1 - \alpha) \theta_t$$



Training

Supervised Loss: BCE Focal Loss

Consistency Loss: MSE Loss

Class imbalance problem exists!

Use **sigmoid ramp-up** and **variable momentum** to speed up the loss towards consistency loss

```
def update_teacher_model(self, current_epoch, momentum=0.9995):
    # The momentum increases from 0 to ema_decay
    # Useful for improving quickly at the beginning
    momentum = min(1 - 1 / (current_epoch + 1), self.ema_decay)
    with torch.no_grad():
        for student_params, teacher_params in zip(self.student_model.parameters(),
                                                  self.teacher_model.parameters()):
            teacher_params.data.mul_(momentum).add_((1 - momentum) * student_params.data)

    # Adjust the weight of the consistency loss to rely on teacher's prediction
    # The weight factor decreases from 1 to 0 during the first 5 epochs
def sigmoid_rampup(self, current_epoch):
    current_epoch = np.clip(current_epoch, 0.0, 5.0)
    phase = 1.0 - current_epoch / 5.0
    return np.exp(-5.0 * phase * phase).astype(np.float32)

# The weight decreases from 10
def get_consistency_weight(self, current_epoch):
    return 10 * self.sigmoid_rampup(current_epoch)
```

```
# Load ResNet50 as Student model and Mean Teacher model
resnet_model = get_resnet50(pre_trained=True)
base_model = ResnetModel(resnet_model, 1).to(device)
mean_teacher_model = MeanTeacherModel(base_model, ema_decay=0.99).to(device)

# Optimizer, loss functions and scheduler
optimizer = Adam(mean_teacher_model.parameters(), lr=1e-4, weight_decay=1e-5)
supervised_criterion = BCEFocalLoss()
consistency_criterion = nn.MSELoss()

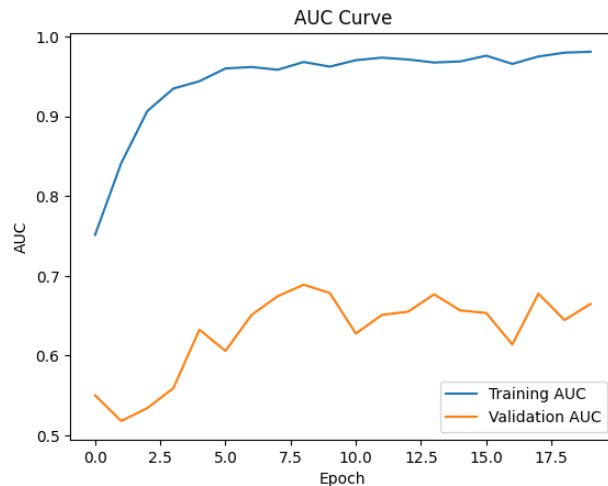
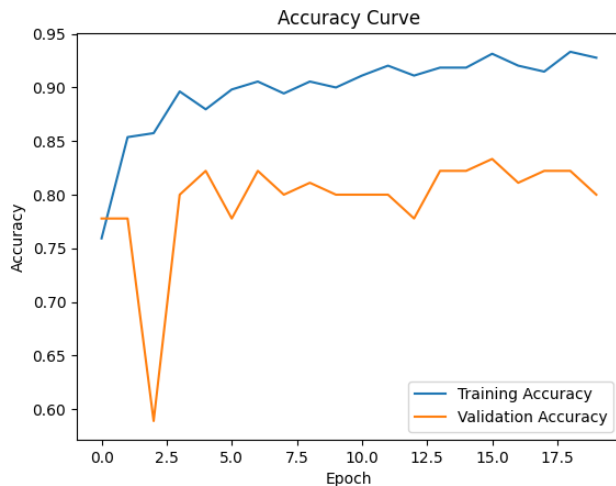
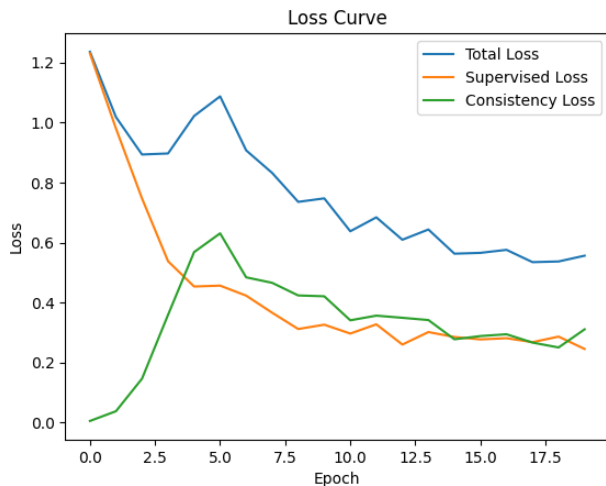
epochs = 15
scheduler = CosineAnnealingLR(optimizer=optimizer, T_max=epochs)
```

Results

With the **ramp-ups**, the **consistency loss** becomes **significant** fast, better performance

Using upscaling and augmentations, it always shows **good learning in training**, but **sometimes validation is flat**

Balancing the classes might potentially **worsen** the performance somehow





Domain Generalization on Fundus Images



Domain Generalization

- Problems
 - Deep neural network does not generalize too well
 - Out-of-distribution may consider as domain shifting
- Proposed Solution
 - Data Augmentation (Fourier Transform)
 - Phase, Amplitude information
 - Mean Teacher Model
 - Compare student & teacher outputs

Data

Dataset: Fundus Dataset

(Multi-label: Background, Optic Disk, Optic Cup)

Domain 1: Drishti-GS dataset **101** images (50, 51)

Domain 2: RIM-ONE_r3 dataset **159** images (99, 60)

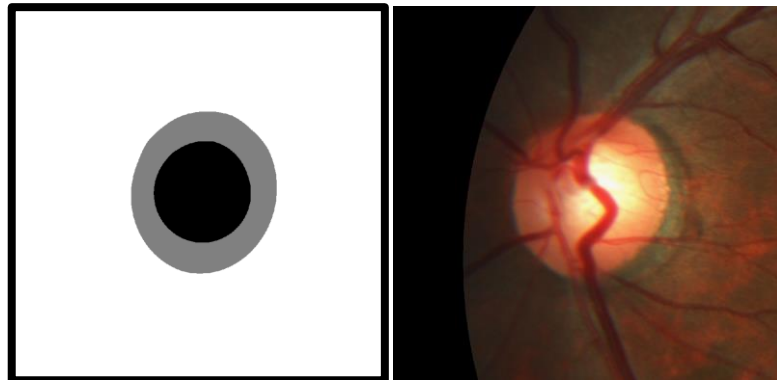
Domain 3: REFUGE training **400** images (320, 80)

Domain 4: REFUGE val **400** images (320, 80)

Data Partition:

Train on a **combination of 3** domains and test on the 1 domain

E.g. Train: [Domain1 , Domain2, Domain3], Test: [Domain 4]



```
## 3 classes
label = cv2.imread("/content/train/mask/G-1-L.png")
np.unique[label]]

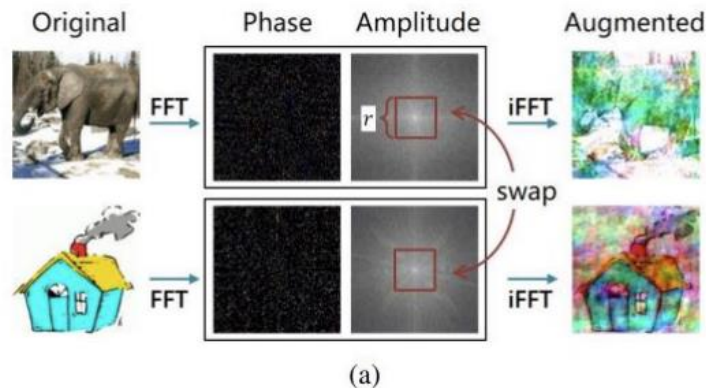
array([ 0, 128, 255], dtype=uint8)
```

Fourier Augmentation

1. Obtain the amplitudes and phases of the images

2. **AS strategy (Amplitude Swap)**

Overwhelming for model to learn



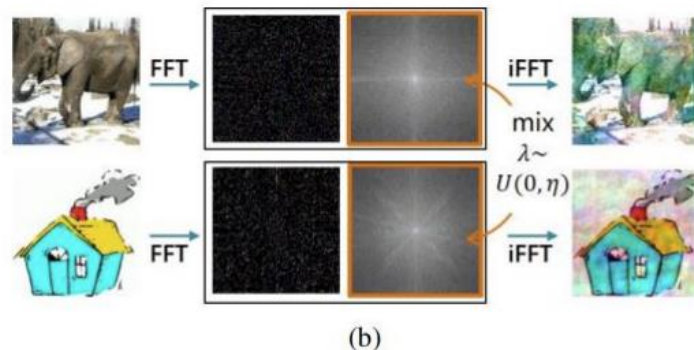
AM strategy (Amplitude Mixup) by linear interpolation

$$\hat{\mathcal{A}}(x_i^k) = (1 - \lambda)\mathcal{A}(x_i^k) + \lambda\mathcal{A}(x_{i'}^{k'})$$

3. Obtain the **soften probability losses** of original & augmented

$$\mathcal{L}_{\text{cls}}^{\text{ori}} = -y_i^k \log(\sigma(f(x_i^k, \theta)))$$

$$\mathcal{L}_{\text{cls}}^{\text{ori}} = -y_i^k \log(\sigma(f(x_i^k, \theta)))$$



Fourier Augmented Co-Teacher (FACT)

Both **original data** & **Fourier augmented data** were fed into both **Student model** & **Teacher model**

Co-Teacher regularization: Use **Kullback-Leibler (KL) divergence** to ensure the **consistency**

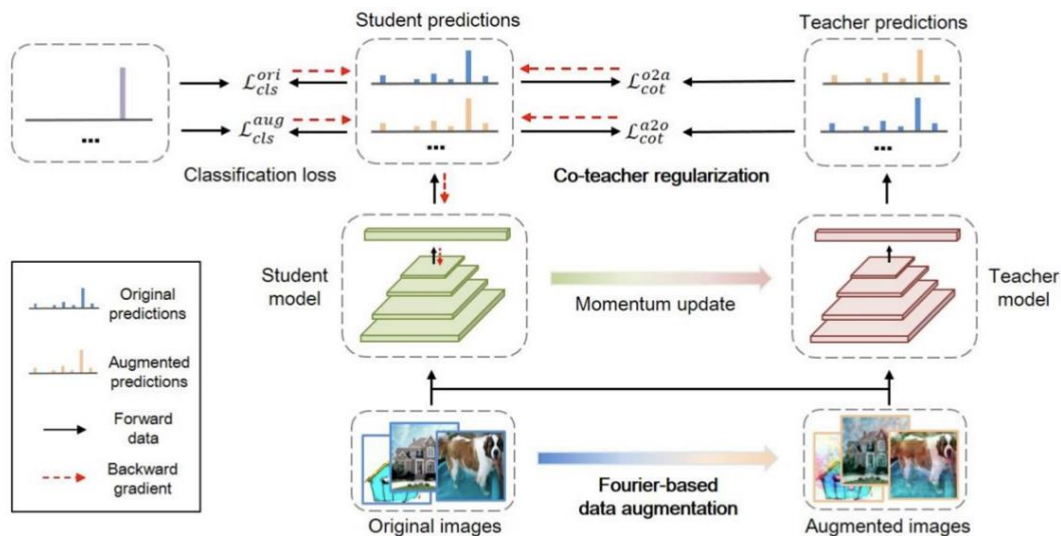
$$\mathcal{L}_{cot}^{a2o} = \text{KL}\left(\sigma\left(f_{stu}\left(\hat{x}_i^k\right) / T\right) \parallel \sigma\left(f_{tea}\left(x_i^k\right) / T\right)\right)$$

$$\mathcal{L}_{cot}^{o2a} = \text{KL}\left(\sigma\left(f_{stu}\left(x_i^k\right) / T\right) \parallel \sigma\left(f_{tea}\left(\hat{x}_i^k\right) / T\right)\right)$$

$$\mathcal{L}_{FACT} = \mathcal{L}_{cls}^{ori} + \mathcal{L}_{cls}^{aug} + \beta\left(\mathcal{L}_{cot}^{a2o} + \mathcal{L}_{cot}^{o2a}\right)$$

Supervised loss: Soft Dice Loss

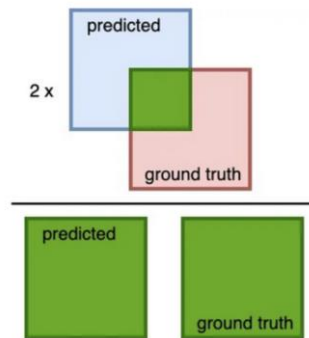
Total loss = Supervised Loss + Consistency Loss



Evaluation Metrics

Dice Loss

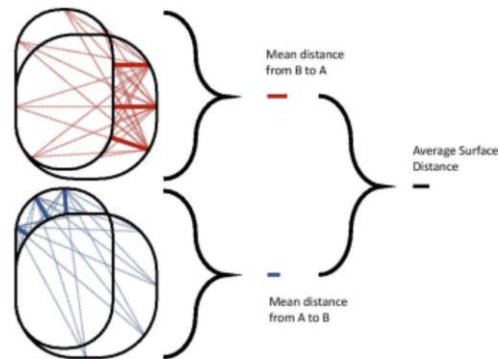
$$\text{Dice} = \frac{2TP}{2TP + FP + FN}$$



Average Surface Distance (ASD)

Treat each type of label as binary segmentation mask

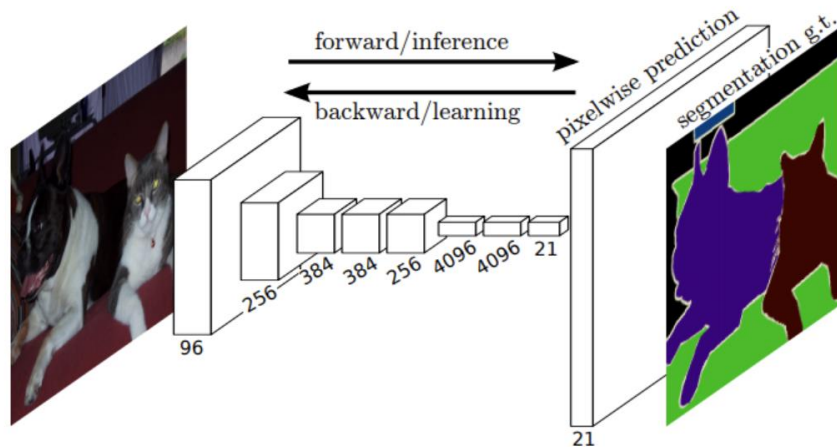
$$\text{ASD}(A, B) = \frac{1}{|S(A)| + |S(B)|} \left(\sum_{a \in S(A)} \min_{b \in S(B)} \|a - b\| + \sum_{b \in S(B)} \min_{a \in S(A)} \|b - a\| \right)$$



U-Net

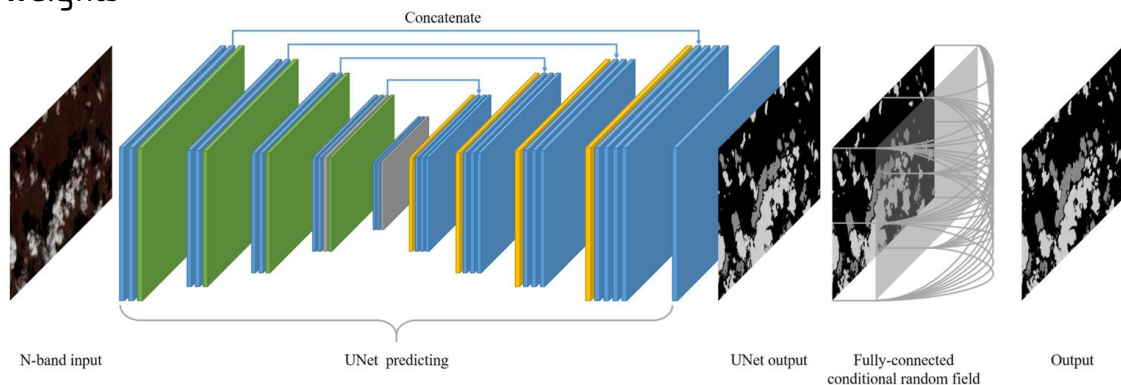
Use for **multi-class segmentation**

- (in_channels=3, out_channels=3)
- Extract important information
- Produce segmentation prediction



As **Student Model** with **pre-trained** encoder weights

- Apply **softmax** function
- [batch_size, 3, img_size, img_size]



Training

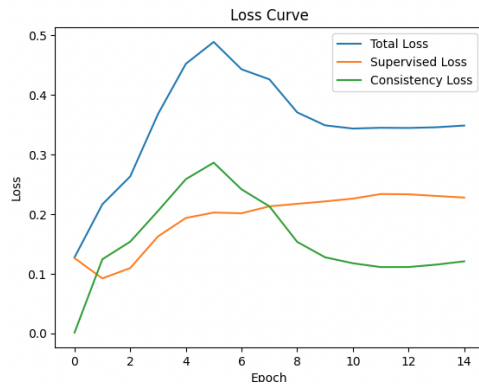
Supervised Loss: MSE Loss

- Taking mean squared error (MSE) between the logit vectors

```
# MSE Loss
```

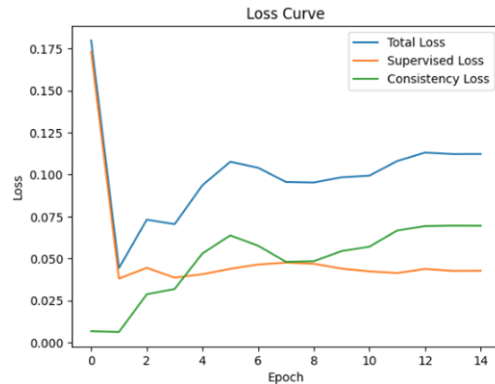
```
loss_ori_tea = consistency_criterion(scores_aug, scores_ori_tea)
```

```
loss_aug_tea = consistency_criterion(scores_ori, scores_aug_tea)
```



Consistency Loss: KL Divergence

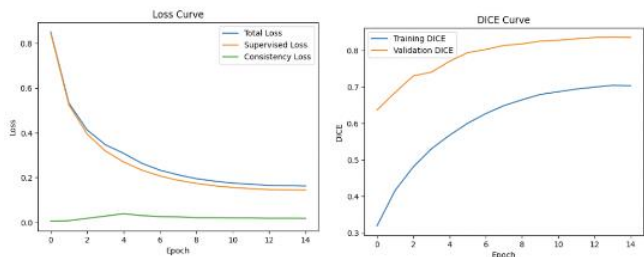
- Empirically, the consistency losses based on KL divergence are **more able to converge**
- Calculating loss on softened probability distributions



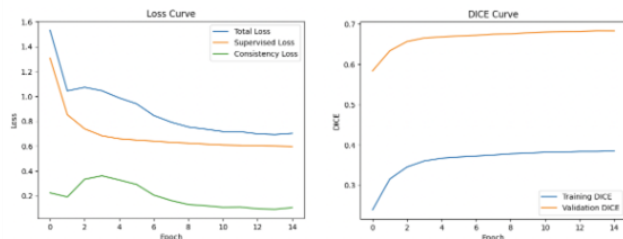
Results

Better than Baseline

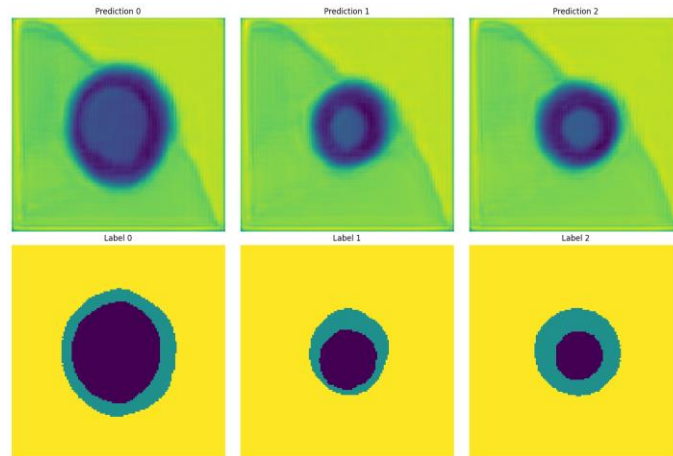
MSE Loss might be **better** than KL Divergence



MSE Loss



KL Divergence



Train	Test	Model	Mean Test Dice	OC Test ASD	OD Test ASD
123	4	Baseline	0.5781	36.9649	27.7053
		FACT	0.8730	7.4794	1.7167
124	3	Baseline	0.6057	35.9788	24.8685
		FACT	0.9039	6.2443	0.6492
134	2	Baseline	0.6988	24.0777	15.9232
		FACT	0.8527	8.2105	1.4624
234	1	Baseline	0.6376	30.5020	21.3653
		FACT	0.8996	5.3635	1.2530

Reference

- Tarvainen, A., Valpola, H. (2017). Mean Teachers Are Better Role Models: Weight-averaged Consistency Targets Improve Semi-supervised Deep Learning Results. *arXiv:1703.01780*
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- Kim, T., Oh, J., Kim, N., Cho, S., & Yun, S. (2021). Comparing Kullback-Leibler Divergence and Mean Squared Error Loss in Knowledge Distillation. *Proceedings of International Joint Conference on Artificial Intelligence (IJCAI)*. *arXiv: 2105.08919*