ELEC4010N Final Project

Semi-Supervised Classification

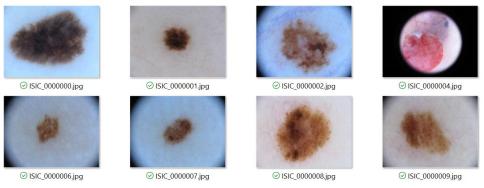
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Domain Generalization on Fundus Images

Semi-Supervised Classification

Data

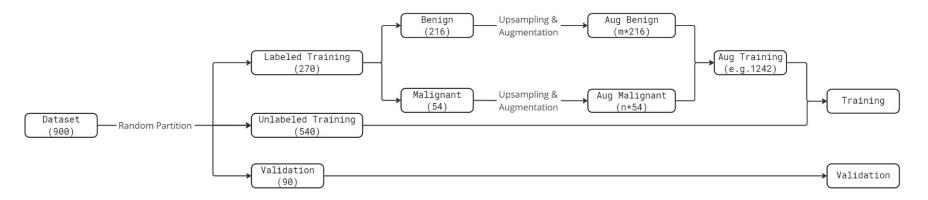
Dataset: ISBI2016_ISIC_Part3_Training_Data



Randomly partition 900 images into labeled training (270), unlabeled training (540), validation (90)

Class imbalance problem exists!

We are free to do upsampling and augmentation only on training data



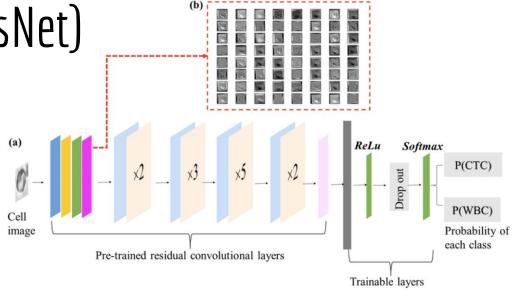
Residual Network (ResNet)

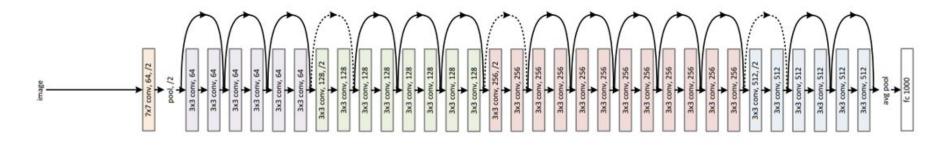
Used for supervised binary classification

Will be used as **Student Model**

Pretrained

Dropout with p = 0.5





BCE Focal Loss

Class imbalance problem exists! **Focal Loss**

BCE Focal Loss = Combination of BCE Loss & Focal Loss

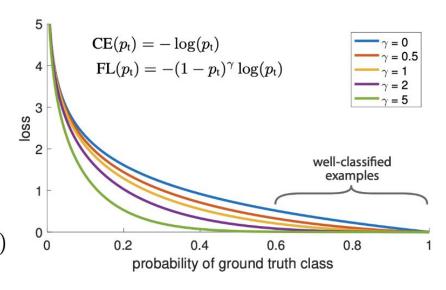
$$\mathrm{BCELoss}(y, ar{y}) = -(y \log(ar{y}) + (1-y) \log(1-ar{y}))$$

 $FocalLoss(p_t) = -\alpha_t (1 - p_t)^{\gamma} \log(p_t)$

$$\text{BCEFocalLoss}\left(p_{t}\right) = -(\alpha_{t}(1-p_{t})^{\gamma}\log(p_{t}) + (1-\alpha_{t})p_{t}^{\gamma}\log(1-p_{t}))$$



Alpha should be about the **ratio of the classes**, ratio = alpha: 1 - alpha, e.g. alpha = 0.75 for 3:1



Mean Teacher Model

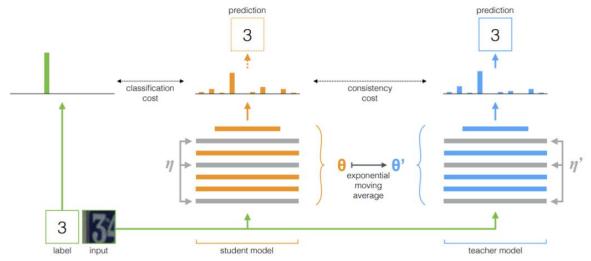
Student Model: ResNet, Supervised Loss, predict for unlabeled data

```
# Mean Teacher Model
# Student model would be ResNet50 model
class MeanTeacherModel(nn.Module):
    # Core
    def __init__(self, student_model, ema_decay):
        super().__init__()
        self.student_model = student_model
        self.teacher_model = copy.deepcopy(student_model)
        self.ema_decay = ema_decay
```

Teacher Model: Deep-copy of Student Model, update the weight by Exponential Moving Average, Consistency Loss

Total Loss = Supervised Loss + Consistency Loss

$$heta_t' = lpha heta_{t-1}' + (1-lpha) heta_t$$



Training

Supervised Loss: BCE Focal Loss

Consistency Loss: MSE Loss

Class imbalance problem exists!

Use **sigmoid ramp-up** and **variable momentum** to speed up the loss towards consistency loss

```
def update teacher model(self, current epoch, momentum=0.9995):
   # The momentum increases from 0 to ema decay
   # Useful for improving quickly at the beginning
   momentum = min(1 - 1 / (current epoch + 1), self.ema decay)
   with torch.no grad():
        for student_params, teacher_params in zip(self.student_model.paramet
            teacher_params.data.mul_(momentum).add_((1 - momentum) * student
# Adjust the weight of the consistency loss to rely on teacher's prediction
# The weight factor decreases from 1 to 0 during the first 5 epochs
def sigmoid rampup(self, current epoch):
   current epoch = np.clip(current epoch, 0.0, 5.0)
   phase = 1.0 - current epoch / 5.0
   return np.exp(-5.0 * phase * phase).astype(np.float32)
# The weight decreases from 10
def get_consistency_weight(self, current_epoch):
   return 10 * self.sigmoid rampup(current epoch)
```

```
# Load ResNet50 as Student model and Mean Teacher model
resnet_model = get_resnet50(pre_trained=True)
base_model = ResnetModel(resnet_model, 1).to(device)
mean_teacher_model = MeanTeacherModel(base_model, ema_decay=0.99).to(device)

# Optimizer, loss functions and scheduler
optimizer = Adam(mean_teacher_model.parameters(), lr=1e-4, weight_decay=1e-5)
supervised_criterion = BCEFocalLoss()
consistency_criterion = nn.MSELoss()

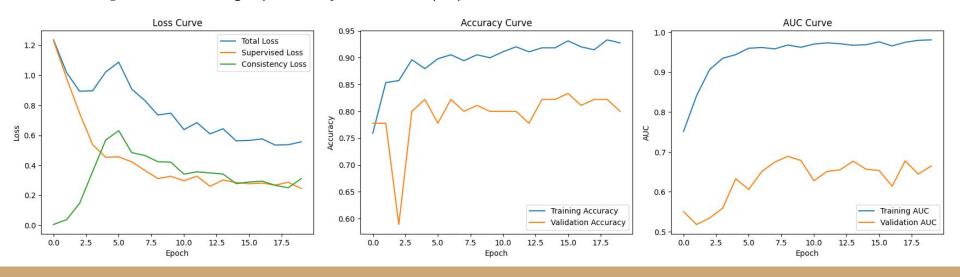
epochs = 15
scheduler = CosineAnnealingLR(optimizer=optimizer, T_max=epochs)
```

Results

With the **ramp-ups**, the **consistency loss** becomes **significant** fast, better performance

Using upscaling and augmentations, it always shows **good learning in training**, but **sometimes validation is flat**

Balancing the classes might potentially worsen the performance somehow



Domain Generalization on Fundus Images

Domain Generalization

- Problems
 - Deep neural network does not generalize too well
 - Out-of-distribution may consider as domain shifting

- Proposed Solution
 - Data Augmentation (Fourier Transform)
 - Phase, Amplitude information
 - Mean Teacher Model
 - Compare student & teacher outputs

Data

Dataset: Fundus Dataset

(Multi-label: Background, Optic Disk, Optic Cup)

Domain 1: Drishti-GS dataset 101 images (50, 51)

Domain 2: RIM-ONE_r3 dataset **159** images (99, 60)

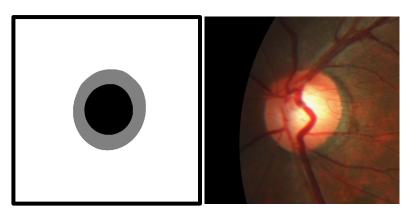
Domain 3: REFUGE training 400 images (320, 80)

Domain 4: REFUGE val **400** images (320, 80)

Data Partition:

Train on a **combination of 3** domains and test on the 1 domain

E.g. Train: [Domain1 , Domain2, Domain3], Test: [Domain 4]



```
## 3 classes
label = cv2.imread("/content/train/mask/G-1-L.png")
np.unique(label)
Critical array([ 0, 128, 255], dtype=uint8)
```

Fourier Augmentation

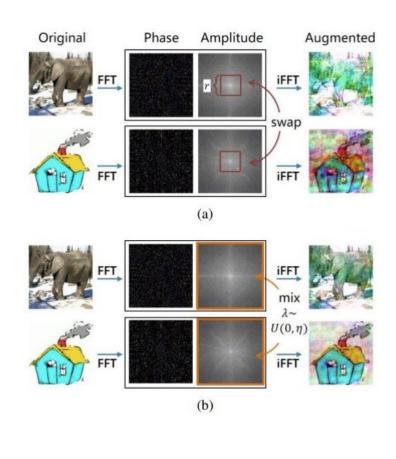
- 1. Obtain the amplitudes and phases of the images
- AS strategy (Amplitude Swap)
 Overwhelming for model to learn

AM strategy (Amplitude Mixup) by linear interpolation

$$\hat{\mathcal{A}}(x_i^k) = (1 - \lambda)\mathcal{A}(x_i^k) + \lambda\mathcal{A}(x_{i'}^{k'})$$

3. Obtain the **soften probability losses** of original & augmented

$$egin{aligned} \mathcal{L}_{ ext{cls}}^{ ext{ori}} &= -y_i^k \logigl(\sigmaigl(figl(x_i^k, hetaigr)igr)igr) \ \mathcal{L}_{ ext{cls}}^{ ext{ori}} &= -y_i^k \logigl(\sigmaigl(figl(x_i^k, hetaigr)igr)igr) \end{aligned}$$



Fourier Augmented Co-Teacher (FACT)

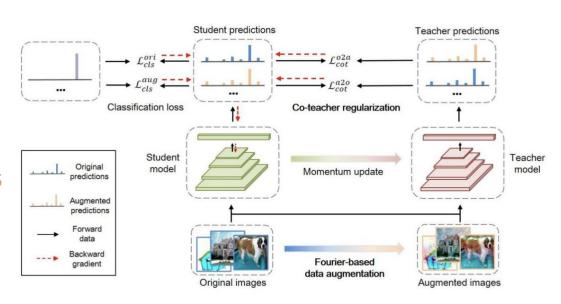
Both original data & Fourier augmented data were fed into both Student model & Teacher model

Co-Teacher regularization: Use **Kullback-Leibler (KL) divergence** to ensure the **consistency**

$$egin{aligned} \mathcal{L}_{ ext{cot}}^{a2o} &= ext{KL} \Big(\sigma \Big(f_{ ext{stu}} \left(\hat{x}_i^k
ight) / T \Big) \| \sigma ig(f_{ ext{tea}} \left(x_i^k ig) / T ig) ig) \ \mathcal{L}_{ ext{cot}}^{o2a} &= ext{KL} \Big(\sigma ig(f_{ ext{stu}} \left(x_i^k \right) / T ig) \| \sigma ig(f_{ ext{tea}} \left(\hat{x}_i^k ig) / T ig) ig] ig) \ \mathcal{L}_{FACT} &= \mathcal{L}_{cls}^{ori} + \mathcal{L}_{cls}^{aug} + eta ig(\mathcal{L}_{cot}^{a2o} + \mathcal{L}_{cot}^{o2a} ig) \end{aligned}$$

Supervised loss: Soft Dice Loss

Total loss = Supervised Loss + Consistency Loss



Evaluation Metrics

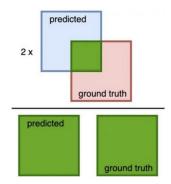
Dice Loss

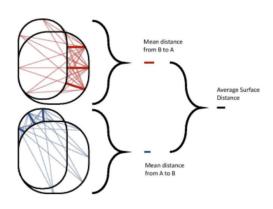
$$\mathrm{Dice} = rac{2TP}{2TP + FP + FN}$$

Average Surface Distance (ASD)

Treat each type of label as binary segmentation mask

$$ext{ASD}(A,B) = rac{1}{|S(A)| + |S(B)|} \left(\sum_{a \in S(A)} \min_{b \in S(B)} \|a - b\| + \sum_{b \in S(B)} \min_{a \in S(A)} \|b - a\|
ight)$$





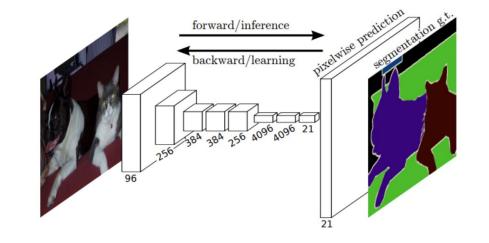
U-Net

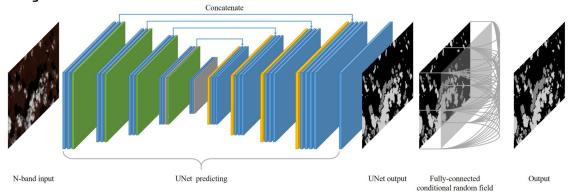
Use for multi-class segmentation

- (in_channels=3, out_channels=3)
- Extract important information
- Produce segmentation prediction

As **Student Model** with **pre-trained** encoder weights

- Apply softmax function
- [batch_size, 3, img_size, img_size]





Training

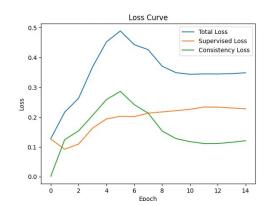
Supervised Loss: MSE Loss

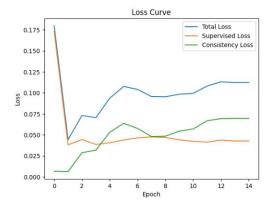
• Taking mean squared error (MSE) between the logit vectors

```
# MSE Loss
loss_ori_tea = consistency_criterion(scores_aug, scores_ori_tea)
loss_aug_tea = consistency_criterion(scores_ori, scores_aug_tea)
```

Consistency Loss: KL Divergence

- Empirically, the consistency losses based on KL divergence are **more able to converge**
- Calculating loss on softened probability distributions

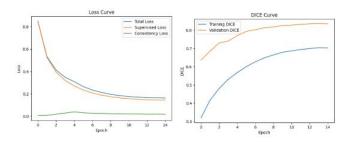




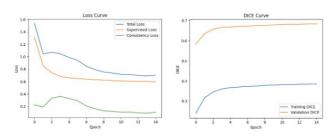
Results

Better than Baseline

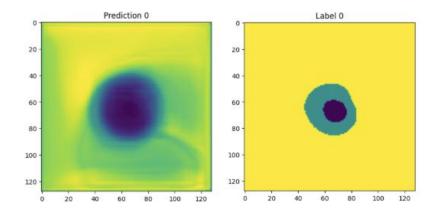
MSE Loss might be **better** than KL Divergence



MSE Loss



KL Divergence



Train	Test	Model	Mean Test Dice	OC Test ASD	OD Test ASD
123	4	Baseline	0.5389	40.0272	31.9848
		FACT	0.6494	36.0975	21.2270
124	3	Baseline	0.5518	28.2954	26.8578
		FACT	0.7138	31.1686	5.6759
134	2	Baseline	0.5512	38.4887	28.7364
		FACT	0.7476	34.0680	7.5351
234	1	Baseline	0.5638	30.8448	24.2397
		FACT	0.7881	25.8820	7.3002

Reference

- Tarvainen, A., Valpola, H. (2017). Mean teachers are better role models: Weight-averaged consistency targets improve semi-supervised deep learning results. arXiv:1703.01780
- Wang, S., Yu, L., Li, K., Yang, X., Fu, C.-W., Heng, P.-A. (2020). DoFE: Domain-oriented Feature Embedding for Generalizable Fundus Image Segmentation on Unseen Datasets. IEEE Transactions on Medical Imaging. (https://github.com/emma-sjwang/Dofe)
- Xu, Q., Zhang, R., Zhang, Y., Wang, Y., Tian, Q. (2021). A Fourier-Based Framework for Domain Generalization. In Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR).
 (https://github.com/MediaBrain-SJTU/FACT)
- Laine, S., & Aila, T. (2017). Temporal Ensembling for Semi-Supervised Learning. International Conference on Learning Representations (ICLR). arXiv:1610.02242