6.5-2 For the differentiator system found in Ex. 6.21, the input is  $x_c(t) = \text{sinc}(Bt/\pi)$ , where  $B = 10000\pi$ , and the sampling interval is  $T = 10^{-4}$ . Sketch the signals and the corresponding spectra at (a) the input of the C/D converter, (b) the input of  $H(\Omega)$ , (c) the output of  $H(\Omega)$ , and (d) the output of the D/C converter. Is the system doing what is expected of it? Explain.

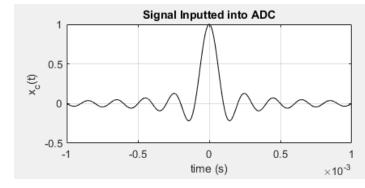
In example 6.21:

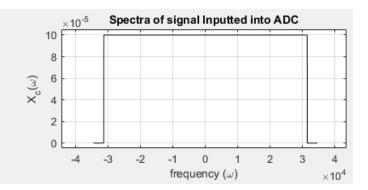
$$H_{\rm c}(\omega) = \begin{cases} j\omega & |\omega T| \le \pi \\ 0 & \text{otherwise} \end{cases}$$

$$H(\Omega) = H_{\rm c}(\Omega/T) = \frac{j\Omega}{T}, \qquad |\Omega| \le \pi.$$

$$h[n] = Th_{\mathbf{c}}(nT) = \frac{T}{2\pi} \int_{-\pi/T}^{\pi/T} j\omega e^{j\omega nT} d\omega = \begin{cases} \frac{\cos(\pi n)}{nT} & n \neq 0\\ 0 & n = 0 \end{cases}$$

a) Input into C/D converter

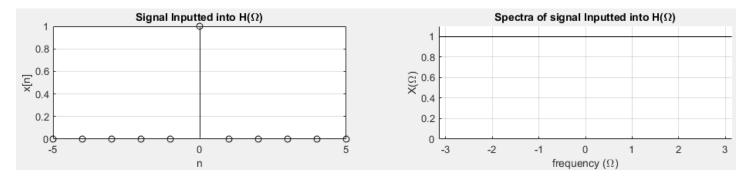




b) Input into  $H(\Omega)$ 

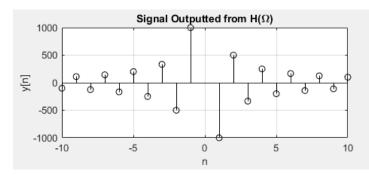
When sampled at 1ms, we end up with just a value of 1 at n = 0

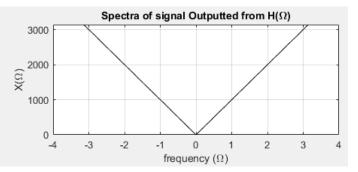
Delta ←→ Constant



c) 
$$y[n] = x[n] * h[n] = \delta[n] * h[n] = h[n]$$

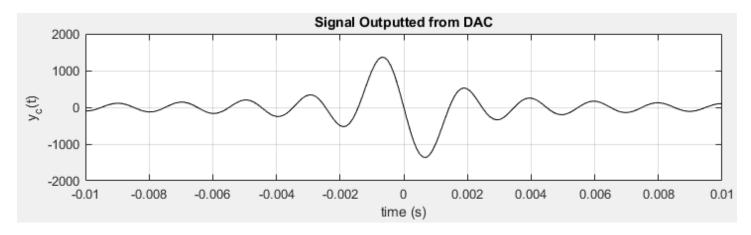
From ex. 6.21 we know that 
$$h[n] = \begin{cases} \frac{\cos(\pi n)}{nT} & n \neq 0 \\ 0 & n = 0 \end{cases}$$
 and  $H(\Omega) = \frac{j\Omega}{T}$ 





## d) If we have ideal interpolation we can use eq. 4.2

$$y(t) = \sum_{n=-\infty}^{\infty} y[n] \operatorname{sinc}\left(\frac{t - nT}{T}\right)$$



## MATLAB:

```
cgate = @(t) (abs(t) < 0.5) + 0.5.*(abs(t) == 0.5);
ddelta = @(n) (n<0.000001 & n>-0.000001);
                                                        % discrete Kronecker delta
                                  % Width of signal in time domain
B = 10000*pi;
T = 0.001;
                                  % sampling interval of 1 ms
DACmax = 3.3;
DACmin = 0;
xc = Q(t) sinc(t.*B/pi);
                             % Continuous time input
Xc = @(w) (pi/B).*cgate(w ./ (2*B));
x = Q(n) \times C(n.*T) .* (mod(n,1)==0);% Discrete time sampled signal
X = 0 (w) 1;
y = @(n) ((cos(pi.*n)./(n.*T)).*(n~=0) + 0.*(n==0)).*(mod(n,1)==0);
Y = @(w) w.*j/T .* (abs(w) <= pi);
\text{%yc} = \text{@(t)} \text{ DACmax.*(sinc(t.*B/pi)} >= \text{0)} + \text{DACmin.*(sinc(t.*B/pi)} <= \text{0)};
% Sketch xc(t)
subplot (4,2,1); t = -T:T/1000:T;
plot(t,xc(t),'k'); xlabel('time (s)'); ylabel('x_c(t)');
```

```
title('Signal Inputted into ADC'); grid on;
% Sketch Xc(w)
subplot(4,2,2); w = -B-B/10:B/1000:B+B/10;
plot(w,Xc(w),'k'); xlabel('frequency (\omega)'); ylabel('X c(\omega)');
title('Spectra of signal Inputted into ADC'); grid on;
% Sketch x[n]
subplot (4,2,3); n = -5:5;
stem(n,x(n),'k'); xlabel('n'); ylabel('x[n]');
title('Signal Inputted into H(\Omega)'); grid on;
% Sketch X(W)
subplot(4,2,4);
yline(1,'k'); xlabel('frequency (\Omega)'); ylabel('X(\Omega)');
title('Spectra of signal Inputted into H(\Omega)'); grid on; axis([-pi pi 0 1.1]);
% Sketch y[n]
subplot (4,2,5); n = -20:20;
stem(n,y(n),'k'); xlabel('n'); ylabel('y[n]');
title('Signal Outputted from H(\Omega)'); axis tight; grid on;
% Sketch Y(W)
subplot(4,2,6); W = -pi:0.001:pi;
plot(W,abs(Y(W)),'k'); xlabel('frequency (\Omega)'); ylabel('X(\Omega)');
title('Spectra of signal Outputted from H(\Omega)'); grid on;
% Sketch y(t)
N = 1000;
subplot(4,2,7); t = -0.01:0.0001:0.01;
yc = 0;
for n = -N:N
    if n \sim = 0
        yc = yc + y(n) \cdot sinc((t - n*T) \cdot /T);
    end
end
plot(t,yc,'k'); xlabel('time (s)'); ylabel('y c(t)');
title('Signal Outputted from DAC'); grid on;
% Sketch Yc(w)
subplot (4,2,8); w = -B-B/10:B/1000:B+B/10;
% plot(w,Yc(w),'k'); xlabel('frequency (\omega)'); ylabel('Y c(\omega)');
title('Spectra of signal Outputted from DAC'); grid on;
```