PSB	E 10	0000	0 se	eries	s: re	gis	ster list for devices with KE firmware from V3.02 (ct	neck th	e installe	d vers	ion in	your device's MENU in item INFO HW, SW)					
(cap)		(hex)	sters (0x03))x05)	er (0x06)	jisters (0x10				se	ırs					(×	500
us address		us address (bolding regi	single coil (Write single register (0x	multiple reg		s	уре	length in bytes	er of registe			us slot	Profibus Index	rofinet Index (hex)	EtherCAT SDO/PDO?
Modbo 1	0x00		Read	Write	Write:		Description Device class Device class	Access	Unit(16) Data		Data ASCII	Example See programming guide in section "A" PSSE 10380-1000	Brofibus 1	0 0	0x0100	× × Ether(
21 41 61 81		015 029 03D)				Manufacturer Manufacturer address Manufacturer ZP code Manufacturer ZP communicaturer ZP code	R R R	cha cha cha	r 40 r 40 r 40	20 20 20	ASCII ASCII ASCII ASCII		1 1 1	2 C 3 C	0x0102 0x0103 0x0104 0x0105	x x x
101 121 123 125	0x00 0x00 0x00	065 079 07B)	E			Manufacturer website Nominal voltage Nominal current	R R	cha floa floa	t 40 t 4	20 2 2	ASCII Floating point number IEEE754 Floating point number IEEE754	80 1000	1 1	6 C	0x0106 0x0107 0x0108 0x0109	X X
131 151 171	0x00 0x00	083 097 AB)	-			Norninal power Article no. Sedial no. User text	R R R	floa cha cha cha	r 40 r 40 r 40	20 20 20	Floating point number EEE754 ASCII ASCII ASCII	30000 30000841 1234560001	1 1 1	12 0 13 0	0x010C 0x010D 0x010E	x x x
191 211 231	0x00 0x00	D3 E7)				Firmware version (KE) Firmware version (+MI) Firmware version (DR)	R R	cha cha cha	r 40	20	ASCII ASCII ASCII		1 1	16 C	0x010F 0x0110 0x0111	x x
402 405 407 408	0x01 0x01 0x01 0x01	195 > 197 >	x x	x x	×		Remote mode DC output/input Condition of DC output/input after power fail alarm Condition of DC output/input after power fail alarm	RW RW RW	uint(16 uint(16 uint(16 uint(16) 2	1 1	Coil : Remote Coil : Output/input Coil : Auto-On Reg : Power-On	0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = auto 0xFFFF = off; 0xFFEE = restore	2 3 2	4 0 30 0	0x0200 0x0203 0x031C 0x0205	x x x
410 411 416 417	0x01 0x01 0x01 0x01	19B	x x	x x x			Restart of the device (warm start) Acknowledge alarms Analog interface: Reference voltage (pin VREF) Analog interface: REM-SB level	W W RW	uint(16 uint(16 uint(16 uint(16		1	Coil : Restart Coil : Alarms Coil : VREF Coil : REM-SB Level	0xFF00 = execute 0xFF00 = acknowledge 0x0000 = 10V; 0xFF00 = 5V 0x0000 = normal; 0xFF00 = inverted	2 2 2	9 0	0x0207 0x0208 0x020D 0x0223	x x x
418 425 427	0x01 0x01 0x01	A9 >	x	x	x		Analog interface: REM-SB action Condition of DC output/input after leaving remote Voltage Controller Speed	RW RW	uint(16 uint(16 uint(16) 2	1	Coil : REM-SB Action Coil : Condition Level	0x0000 = off; 0xFF00 = auto 0x0000 = off; 0xFF00 = unchanged 0x0000 = Normal (default); 0x0001 = Slow;	2 2	42 0	0x0224 0x0229 0x023B	x
428	0x01.	B0 >	x	×	х		SEMIF47 Reset device to factory settings	RW	uint(16 uint(16) 2	1	On/Off Coil : Condition	0x0002 = Fast; 0x0000 = off; 0x0001 = on; 0xFF00 = Trigger reset	2	43 0	0x023C 0x022A	x
440	0x01	IB8	,		x		Analog interface: Pin 14 configuration	RW	uint(16) 2	1	Alarms 1	0x0000 = OVP (default); 0x0001 = OCP; 0x0002 = OPP; 0x0003 = OVP - OCP; 0x0004 = OVP - OPP;	2	44 0	0x022B	x
441	0x01	IB9	>		×		Analog interface: Pin 6 configuration	RW	uint(16) 2	1	Alarms 2	0x0005 = OCP + OPP; 0x0005 = OVP + OCP + OPP 0x0005 = OVP + OCP + OPP 0x0000 = OT + PF (default); 0x0001 = OT;	2	45 0	0x022C	×
442			×		x		Analog interface: Pin 15 configuration Analog interface: Pins 9 and 10 configuration	RW	uint(16 uint(16) 2		Status DC / reg. mode Current and voltage monitor	0x0002 = PF 0x0000 = CV; 0x0001 = DC output status 0x0000 = Default (VMON on pin 9 and CMON on Pin 10 / Pin 10 signals current	2		0x022D	x
													from source or sink); 0x0001 = Pin 10 (CMON) only signals sink current (EL); 0x0002 = Pin 10 (CMON) only signals source current (PS); 0x0003 = Current mode A [source current (PS) on pin 9 and sink current (EL) on pin 10 (full rance):				
													0x0004 = Current mode B [source current (PS) on pin 10 and sink current (EL) on pin 9 (full range)]; 0x0005 = Pin 10 (EMON) signals EL/PS current (010 V = -100%0100%, half range signal)				
498 499 500	0x01	IF3 IF4	>		X X		Sink mode: Set power value Sink mode: Set current value Set vollage value Set vollage value	RW RW	uint(16 uint(16) 2	1	0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Power value (for translation see programming guide) Current value (for translation see programming guide) Voltage value (for translation see programming guide) Voltage value (for translation see programming guide)	_	20 0	0x0214 0x0213 0x0216	X X
501 502 505	0x01 0x01	IF6))	+	x		Source mode: Set current value Source mode: Set power value Device state	RW RW	uint(16 uint(16 uint(32) 2	- 1	0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) Bit 0-4: Control location	Current value (for translation see programming guide) Power value (for translation see programming guide) 0x00 = free; 0x01 = local; 0x03 = USB; 0x04 = analog; 0x05 = Profibus; 0x06 = Ethernet; 0x08 = Master/Slave; 0x09 = RS232; 0x10 = CANDepr; 0x12 = Modbus TCP 1P; 0x13 = Profilint 1P; 0x14 = Ethernet		25 0	0x0217 0x0218 0x021A	x
												Bit 6 : Master-slave type	1P; 0x15 = Ethernet 2P; 0x16 = Modbus TCP 2P; 0x17 = Profinet 2P; 0x18 = GPIB; 0x19 = GAN; 0x1A = EtherCAT; 0x1C = free (due to communication timeout (CTO))				
												Bit 7 : Output state Bit 9-10 : Regulation mode Bit 11 : Remote	0 = Slave; 1 = Master 0 = off; 1 = on 00 = CV; 10 = CC; 11 = CP 0 = off; 1 = on				
												Bit 12 : PSB/PSBE operation mode Bit 14 : External sense Bit 15 : Alarms Bit 16 : OVP	0 = source; 1 = sink 0 = off; 1 = on 0 = one; 1 = active 0 = none; 1 = active				
												Bit17 : OCP Bit18 : OPP Bit19 : OT Bit21 : Power fail	0 = none; 1 = active 0 = none; 1 = active 0 = none; 1 = active 0 = none: 1 = active				
507	0x01	ER	,				Actual voltage	В	uint(16			Bit 29 : MSP Bit 30 : REM-SB Bit 31 : OCP/OPP cause 0x0000 - 0xFFFF (0 - 125%)	0 = none; 1 = active 0 = DC enabled; 1 = REM-SB disables power output 0 = DC enabled; 1 = REM-SB disables power output 0 = source mode; 1 = sink mode Actual voltage (for translation see programming guide)	2	28 (0x021B	v
508 509 511	0x01	FC FD)	E			Actual current Actual power Device state 2	R R R	uint(16 uint(16 uint(32) 2		0x0000 - 0xFFFF (0 - 125%) 0x0000 - 0xFFFF (0 - 125%) Bit 1 : SF alarm	Actual current (for translation see programming guide) Actual power (for translation see programming guide) 0 = none; 1 = active	2 2	29 C	0x021C 0x021D 0x0212	х
520			,	-			Count of OV alarms since power up	R	uint(16) 2		Bit 4 : Power derating Bit 5 : Semi F47 0x0000 - 0xFFFF	0 = none; 1 = active 0 = none; 1 = active	3		0x0312	x
521 522 523 524	0x02 0x02 0x02 0x02	20A 20B	>				Source mode: Court of CO alarms since power up Source mode: Court of OP alarms since power up Court of OT alarms since power up Court of FF alarms since power up	R R R	uint(16 uint(16 uint(16 uint(16		- 1	0x0000 - 0xFFFF 0x0000 - 0xFFFF 0x0000 - 0xFFFF 0x0000 - 0xFFFF		3 3 3	22 C	0x0313 0x0314 0x0315 0x0316	x x x
525 526 527	0x02 0x02 0x02	20E)				Sirk mode: Count of PF alarms since power up Count of OP alarms since power up (PSB/PSBE devices: sink mode) Count of SF alarms since power up Count of SF alarms since power up	R R	uint(16 uint(16 uint(16) 2	- 1	0x0000 - 0xFFFF 0x0000 - 0xFFFF 0x0000 - 0xFFFF		3 3	26 0	0x0317 0x0318 0x0319	x x
550 553 556 569	0x02 0x02 0x02	229 2C	>		x x x		Overvoltage protection threshold (OVP) Source mode: Overcurrent protection threshold (OCP) Source mode: Overpower protection threshold (OCP) Source mode: Overpower protection threshold OCP Sink mode: Overcurrent protection threshold OCP	RW RW RW	uint(16 uint(16 uint(16 uint(16) 2	1	0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xE147 (0 - 110%)	OVP threshold (for translation see programming guide) OCP threshold (for translation see programming guide) OCP threshold (for translation see programming guide) OCP threshold (for translation see programming guide)	3 3 3	3 C	0x02FE 0x0301 0x0304 0x0302	x x x
570 577	0x02	23A 241))		x		Sink mode: Overpower protection threshold OPP Condition of DC output/input after OT alarm	RW	uint(16 uint(16) 2	1	0x0000 - 0xE147 (0 - 110%) Reg: Condition	CCP threshold (for translation see programming guide) CPP threshold (for translation see programming guide) 0x0000 = off; 0x0001 = restore (default)	3	7 C	0x0305 0x0323	x
650 653 654 655	0x02 0x02 0x02 0x02	8D >	X X	x x	×		Master-slave: Link mode on MS bus Master-slave: Erable MS Master-slave: Condition Master-slave: Condition	RW RW W	uint(16 uint(16 uint(16 uint(16) 2	1 1	Coil: Mode Coil: MS on/off Coil: MS start init Reg: MS status	0x0000 = Slave; 0xFF00 = Master 0x0000 = 0ff; 0xFF00 = on 0xFF00 = Start init 0x0000 = not initialised; 0x0001 = init naming; 0x0003 = set defaults; 0x0004 = 0x0001	4 4 4	3 C	0x03FD 0x0400 0x0401 0x0402	x x x
656	0x02	290					Master-slave: Total voltage in V	Р	floa	t 4	2	Floating point number IEEE754	setup interface; 0x0005 = assignment; 0xFFFC = disrupted; 0xFFFD = different models detected, nit not OK; 0xFFFE = error; 0xFFFF = init OK; 0xFFFB = Termination not OK	4	6.0	0x0403	
658 660 662 666	0x02 0x02 0x02	292 294 296))				Master-slave: Total current in A Master-slave: Total power in W Master-slave: Number of initialised slaves	R R R	floa floa uint(16	t 4	2 2	Floating point number IEEE754 Floating point number IEEE754	5000 150000 163	4 4 4	7 C 8 C	0x0404 0x0405 0x0406 0x0407	x x x
9000	0x02	9B >	x x	×	х		Master-slave: Bus termination Master-slave: Bus bias Upper limit of voltage set value (U-max)	RW RW	uint(16 uint(16 uint(16) 2	1	Coil : Termination Coil : BIAS 0x0000 - 0xD0E5 (0 - 102%)	0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on Voltage value (for translation see programming guide)	2	31 0	0x0408 0x021E	
9001 9002 9003 9004	0x23 0x23 0x23 0x23	32A 32B))		x x x		Lover limit of voltage set value (U-min) Source mode: Upper limit of current set value (I-max) Source mode: Lower limit of current set value (I-min) Source mode: Upper limit of power set value (P-max)	RW RW RW	uint(16 uint(16 uint(16 uint(16) 2	1 1 1	0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Voltage value (for translation see programming guide) Current value (for translation see programming guide) Current value (for translation see programming guide) Power value (for translation see programming guide)	2 2 2	33 C	0x021F 0x0220 0x0221 0x0222	x x x
9005 9008 9009	0x23 0x23 0x23	330))	_	x x		Sink mode: Upper limit of power set value (P-max) Sink mode: Upper limit of current set value (I-max) Sink mode: Lower limit of current set value (I-min)	RW RW	uint(16 uint(16 uint(16) 2	- 1	0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Power value (for translation see programming guide) Current value (for translation see programming guide) Current value (for translation see programming guide)	2 2	40 0	0x0223 0x0227 0x0228	X X
10007 10008 10010 10011	0x27 0x27 0x27 0x27	718 > 71A > 71B >	_	x x x			Ethernet TCP keep-alive timeout EthernetProfinetModbus TCP: DHCP Protocot Modbus Protocot SCPI	RW RW RW	uint(16 uint(16 uint(16 uint(16) 2	1 1	Coil: Keep-alive on/off Coil: DHCP on/off Coil: MDDBUS on/off Coil: SCPI on/off	0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on				
10012 10013 10020	0x27 0x27 0x27	'1D >	X X	x			Restart Interface card Modbus specification compliance AnyBus module: Type	RW RW	uint(16 uint(16 uint(16) 2	1 1	Coil: Restart Coil: Mode Reg: Type	0xFF00 = Trigger restart 0x0000 = Limited (default); 0xFF00 = Full 0x0005 = Profibus 0x0005 = Profibus 0x0005 = S8232				H
													0x0010 = CANopen 0x0011 = Devicenet 0x0012 = Modbus-TCP 1P 0x0013 = Profinet 1P 0x0014 = Ethermet 1P				
													0x0015 = Ethernet 2P 0x0016 = Modbus-TCP 2P 0x0016 = Modbus-TCP 2P 0x0017 = Profinet 2P 0x0019 = CAN				
10021		739))	_			AnyBus module: Interface type AnyBus module: Version number		cha uint(8			ASCII	0x001A = EtherCAT 0x00FF = no or unknown module plugged "Profibus DPV1"		1	<u>=</u>	
10043 10251 10252 10253 10269	0x28 0x28 0x28	80B 10C 10D))		x	x	AngBus module: Serial number Profibus: Ident number Profibus: GANopen: Node address Profibus/GANopen: Node address Profibus/GProfinet: User-defineable "Function tag"	RW RW RW	uint(16 uint(16 cha) 2 r 32		ASCII	0xA001 Profibus: 0-125 ; CANopen: 0-127 "Test"	8 8	1 0	0x07F9 0x07FA 0x07FB	
10280 10300 10354	0x28 0x28 0x28 0x28	328 33C 372))	_		x x	Profitus/Profinet User-defineable "Location tag" Profitus/Profinet User-defineable installation date Profitus/Profinet User-defineable installation date Profitus/Profinet User-defineable description Profinet User-defineable "Station name" EhmentMiddins TCP P address SEPTIMENT SEPTIMENT PROFITURES	RW RW RW RW	cha cha cha cha	r 40 r 54 r 200	20 27 100	ASCII ASCII ASCII BMes 0-3: 0. 255	"Test" "13.01.2012 09-59:00" "www.webpage.de" "Test" 192 168 0.2 (default)	8 8	4 C	0x07FC 0x07FD 0x07FE 0x07FF	Ħ
10502 10504 10506 10508	0x29 0x29 0x29	908 90A 90C))			x x	ElbemetModbus TCP: Paddress ElbemetModbus TCP: Subret mask ElbemetModbus TCP: Gateway ElbemetModbus TCP: Host name	RW RW RW	uint(8 uint(8 uint(8 cha) 4) 4 r 54	2 27	Bytes 0-3: 0.255 Bytes 0-3: 0.255 Bytes 0-3: 0.255 ASCII	192.168.0.2 (default) 255.255.255.0 (default) 192.168.0.1 (default) "Client" (default)		1	<u> </u>	
10535 10562 10564 10566	0x29 0x29 0x29 0x29	942 944 946))	_	x	x	Elbemet/Profinet/Modbus TCP: Domain name Ethemet/Modbus TCP: DNS 1 Ethemet/Modbus TCP: DNS 2 RS232/USB: Connection timeout in milliseconds	RW RW RW	cha uint(8 uint(8 uint(16	54) 4) 4) 2	2	ASCII Bytes 0-3: 0255 Bytes 0-3: 0255 5.65535	"Workgroup" (default) 0.0.0 (default) 0.0.0 (default) Default: 5ms	Ħ	1	<u> </u>	
10567 10570	0x29		X	-	х		Elbernet/Profinet/Modbus TCP: MAC Elbernet/Modbus TCP: Connection speed Port 1 (1 & 2 port modules)	RW	uint(8 uint(16) 6		Bytes 0-5: 0255 Connection speed	00:50:C2:C3:12:34 or 00:50:C2:C3:12:34 0x0000 = Auto; 0x0001 = 10Mbit half duplex; 0x0002 = 10Mbit ful duplex; 0x0002 = 10Mbit half duplex;	H	1		\prod
10571	0x29	94B	×		х	I	Ethernet/Modbus TCP: Connection speed Port 2 (2 port module)	RW	uint(16) 2	1	Connection speed	0x0035 = 100Mbit half duplex 0x0004 = 100Mbit full duplex 0x0000 = Auto; 0x0001 = 10Mbit half duplex 0x0002 = 10Mbit full duplex	H			H
10572 10573	0x29 0x29))		x		Ethernet (except for Modbus TCP): Port Ethernet TCP Socket timeout (in seconds)	RW	uint(16 uint(16) 2	1	0.65535 5.65535	0x0003 = 100Mbit half duplex 0x0004 = 100Mbit full duplex 5025 (default), except port 80 0 = timeout inactive; 5 = 5 s (default)				
10700	0x29	СС	>		х		RS232/CANopen ⁱ CAN: Baud rate	RW	uint(16) 2	1	Baud rate	CAN CANopen RS232 0x00: 10kbps 10kbps 2400 Bd 0x01: 20kbps 20kbps 4800 Bd 0x02: 50kbps 50kbps 9600 Bd				
													0x03: 100kbps 100kbps 19200 Bd 0x04: 125kbps 125kbps 38400 Bd 0x05: 250kbps 250kbps 57600 Bd 0x06: 500kbps 500kbps 115200 Bd				
10701	0x29 0x29		_	x			CAN: D format CAN: Termination	RW	uint(16 uint(16) 2		Coil: Base/Extended Coil: Bus termination	0x07: 1Mbps 800kbps 0x08: 1Mbps 0x09: Autobaud 0x0000 Base (11 Bit): 0xFF00 = Extended (29 Bit) 0x0000 = 0ff; 0xFF00 = on			_	\parallel
10702 10704 10706	0x29 0x29 0x29	D0	×	×		x	CAN: Broadcast D	RW RW	uint(16 uint(32 uint(32) 4	2	0x00000x07FF or 0x00000x1FFFFFFF 0x00000x07FF or 0x00000x1FFFFFFF	Default: 0x000 Default: 0x7FF	H	1		Ħ
10709 10710 10712	0x29 0x29 0x29	D6	X	X		х	CAN: Data length CAN: Cyclic read: Base ID CAN: Cyclic send: Base ID	RW RW	uint(16 uint(32 uint(32) 2	2	Coil: Data length 0x00000x07FF or 0x00000x1FFFFFFFF 0x00000x07FF or	0x0000 = Auto; 0xFF00 = Always 8 bytes Default: 0x100 Default: 0x200		#		Ħ
10714 10715 10716	0x29 0x29 0x29	DA DB DC	2		x x		CAN: Cyclic read time (in ms): Status CAN: Cyclic read time (in ms): Set value (U, I, P, R) CAN: Cyclic read time (in ms): Limits 2 (P, R)	RW RW	uint(16 uint(16 uint(16) 2	1 1	0x00000x1FFFFFFF 205000; 0 == off 205000; 0 == off 205000; 0 == off	Default off Default off Default off	H	#	<u>=</u>	Ħ
10717 10718 10721 10722	0x29 0x29 0x29 0x29	DD DE 9E1))		x x x		CAN: Cyclic read time (in ms): Limits 1 (U, I) CAN: Cyclic read time (in ms): Actual values U, I, P CAN: Cyclic read time (in ms): Set value (I, P, R) (only PSBIPSBE devices, sink mode) CAN: Cyclic read time (in ms): Limits 3 (I, P, R) (only PSBIPSBE devices, sink mode)	RW RW RW	uint(16 uint(16 uint(16 uint(16	2 2 2 2	1 1	205000; 0 == off 205000; 0 == off 205000; 0 == off 205000; 0 == off	Default: off Default: off Default: off Default: off		1	_	
10820	0x2A	_	7				CARK Cyclic read unit (imms), Limits 3 (L.P., K) (unity F36ir-36e devices, sink mode) Internal Ethernet Interface: Status	R	uint(16) 2		20900, 0 0il Bits 0-5: - Bit 6: Keep-Alive Bit 7: DHCP 1 Bit 8: DHCP 2	Defination: 0 = inactiv; 1 = activ 0 = DHCP deactivated; 1 = DHCP activated 0 = DHCP is not running, P has been not assigned; 1 = DHCP is running, P		#	<u>=</u>	
10821 10822 10823	0x2# 0x2# 0x2#	A46 >	_	x			Internal Ethernet interface: TCP keep-alive timeout Internal Ethernet interface: DHCP Internal Ethernet interface: P address	RW RW	uint(16 uint(16 uint(8		1	Coil: Keep-alive on'off Coil: DHCP on'off Bytes 0-3: 0.255	U = UHCP' is not running, iP has been not assigned; 1 = UHCP' is running, iP has been assigned; 0.0000 = off; 0.0FF00 = on 0.0000 = off; 0.0FF00 = on 192;168.02 (default)	H	#	<u>=</u>	\exists
10823 10825 10827 10829 10856	0x2A 0x2A 0x2A 0x2A	A49 A4B A4D	2	_		x x	Internal Ethernel Interface: Subnet mask Internal Ethernel Interface: Subnet mask Internal Ethernel Interface: Gateway Internal Ethernel Interface: Gateway Internal Ethernel Interface: Donain name	RW RW RW	uint(8 uint(8 uint(8 cha	r 54	2 2 27	Bytes 0-3: 0.255 Bytes 0-3: 0.255 Bytes 0-3: 0.255 ASCII ASCII	192.186.0.1 (default) 192.168.0.1 (default) 192.168.0.1 (default) 192.168.0.1 (default)		#	<u> </u>	Ħ
10883 10885 10888	0x2A 0x2A 0x2A	A83 A85 A88	2		x	х	Internal Ethernet interface: DNS Internal Ethernet interface: MAC Internal Ethernet interface: Port	RW R(W) RW	uint(8 uint(8 uint(16) 4) 6) 2	3	Bytes 0-3: 0.255 Bytes 0-5: 0.255 0.65535	0.0.0.0 (default) 00:50:C2:C3:12:34 or 00-50-C2-C3-12-34 5025 (default), except port 80		#		Ħ
21000	0x2A) x	<u> </u>	х	[Internal Ethernet interface: TCP Socket timeout. (in seconds) Operation counter: total time	RW	uint(16 uint(16) 2		5.65535 (0 = timeout inactive) DDDDD:HH:MM	Default: 5 Word 0 = Days (0-85535) Word 1 = Hours (0-23) Word 2 = Minutes (0-99)	2	53	0x0234	
21003	0x52		3				Operation counter: DC on time Operation counter: DC off time	R	uint(16 uint(16			DDDDD:HH:MM	Word 2 = Mirutes (0-59) Word 1 = aps (0-55335) Word 1 = Hours (0-23) Word 2 = Mirutes (0-53) Word 0 = Days (0-55535)	2		0x0235	
21009 21011	0x52 0x52	211) 	-			Operation counter: Energy in kWh (PSB/PSBE: source mode) Operation counter: Capacity in Ah (PSB/PSBE: source mode)	R	floa	t 4		Floating point number EEE754 Floating point number EEE755	Word 1 = House (0-29) Word 2 = Minutes (0-29)	2 2	56 57	0x0237 0x0238	
21013 21015	0x52	215	x x	F			Operation counter: Separating in with ('Outro Oct.' Souther include) Operation counter: Secondary energin in With ("PSBIPSBE sink mode only) Operation counter: Secondary capacity in Ah (PSBIPSBE sink mode only)	R	floa	t 4	2	Floating point number EEE756 Floating point number EEE757		2	58	0x0239 0x023A	<u>-</u>