PS 9000 1U / 2U / 3U (from 2014) register list for KE firmware from V3.05 (standard) / V2.11 (GPIB) (the currently installed version can be checked in the Menu under "About HW, SW")													
ModBus address (dec)	ModBus address (hex)	ad coils (0x01)	ad holding registers (0x03)	te single coil (0x05)	te single register (0x06)	te multiple registers (0x10)		Access	Data type	a length in bytes	Number of registers		
			Read	Write	Write	Write	Description	_		Data		Data	Example or description
0	0x0000	_	X				Device class Device type	R R	uint(16) char	40	20	ASCII	28, 30, 38 = PS 9000 Serie PS 9080-60 2U
21	0x0015	5	Х				Manufacturer	R	char	40	20	ASCII	
41 61	0x0029		X				Manufacturer address Manufacturer ZIP code	R R	char char	40 40		ASCII ASCII	
81 101	0x0051		X				Manufacterer phone number Manufacturer website	R R	char char	40 40		ASCII ASCII	80
121	0x0079	9	Х				Nominal voltage	R	float	4	2	Floating point number IEEE754	60
123 125	0x007E	_	X				Nominal current Nominal power	R R	float	4		Floating point number IEEE754 Floating point number IEEE754	1500
131	0x0083	3	Х				Article no.	R	char	40	20	ASCII	06230209
151 171	0x0097		X			Х	Serial no. User text	R RW	char char	40		ASCII ASCII	1234567890
191 211	0x00BF 0x00D3	3	X				Firmware version (KE) Firmware version (HMI)	R R	char char	40		ASCII ASCII	V3.02 16.08.2016 V2.08 22.09.2016
231	0x00E7	7	X				Firmware version (DR)	R	char	40		ASCII	V1.0.4.1 30.06.2016
402	0x0192	2 x	1	Х			Remote mode	RW	uint(16)	2	1	Coils : Remote	0x0000 = off; 0xFF00 = on
405	0x0195	х		Х			DC output	RW	uint(16)	2	1	Coils : Output	0x0000 = off; 0xFF00 = on
407 408	0x0197 0x0198	3	Х	Х	Х		Condition of DC output after PF alarm Condition of DC output after power ON	RW RW	uint(16) uint(16)	2	1	Reg : Condition	0x0000 = off; 0xFF00 = auto 0xFFFF = off; 0xFFFE = Restore
410 411	0x019A			X X			Restart of the device (warm start) Acknowledge alarms	RW RW	uint(16) uint(16)	2		Coils : Restart Coils : Alarms	0xFF00 = execute 0xFF00 = acknowledge
416	0x01A0) х		х			Analog interface: Reference voltage (pin VREF)	RW	uint(16)	2	1	Coils : VREF	0x0000 = 10V; 0xFF00 = 5V
417 418	0x01A2	_		X			Analog interface: REM-SB level Analog interface: REM-SB action	RW RW	uint(16) uint(16)	2		Coils : REM-SB Level Coils : REM-SB Action	0x0000 = normal; 0xFF00 = inverted 0x0000 = DC off; 0xFF00 = DC on/off
425	0x01A9			Х			Condition of DC output after leaving remote	RW	uint(16)	2	1	Coils : Condition	0x0000 = off; 0xFF00 = auto
440	0x01B8		x		x		Analog interface: Pin 14 configuration	RW	uint(16)	2		Reg: Alarms 1	0x0000 = OVP (default); 0x0001 = OCP; 0x0002 = OPP; 0x0003 = OVP + OCP; 0x0004 = OVP + OPP; 0x0005 = OCP + OPP; 0x0006 = OVP + OCP + OPP
441	0x01B9	9	х		х		Analog interface: Pin 6 configuration	RW	uint(16)	2	1	Reg: Alarms 2	0x0000 = OT + PF (default); 0x0001 = OT; 0x0002 = PF
442	0x01BA	1	х		х		Analog interface: Pin 15 configuration	RW	uint(16)	2	1	Reg: Status DC	0x0000 = CV; 0x0001 = DC on/off
500		_	х		х		Set voltage value	RW	uint(16)	2		0x0000 - 0xD0E5 (0 - 102%)	Voltage value (for translation see programming guide)
501 502	0x01F6		X		x		Set current value Set power value	RW RW	uint(16) uint(16)	2		0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Current value (for translation see programming guide) Power value (for translation see programming guide)
505	0x01F9	9	х				Device state	R	uint(32)	4	2	Bit 0-4: Control location	0x00 = free; 0x01 = local; 0x02 = remote; 0x03 = USB; 0x04 = analog; 0x06 = Ethernet
												Bit 7 : DC output state	0 = off; 1 = on
												Bit 9-10 : Regulation mode Bit 11 : Remote	00 = CV; 01 = CR; 10 = CC; 11 = CP 0 = off; 1 = on
												Bit 14 : Remote sensing Bit 15 : Alarms	0 = off; 1 = on 0 = none; 1 = active
												Bit 15 : Alarms Bit 16 : OVP	0 = none; 1 = active
												Bit 17 : OCP Bit 18 : OPP	0 = none; 1 = active 0 = none; 1 = active
												Bit 19 : OT	0 = none; 1 = active
												Bit 21 : Power fail Bit 22 : Power fail	0 = none; 1 = active 0 = none; 1 = active
												Bit 23 : Power fail	0 = none; 1 = active
												Bit 24 : UVD Bit 25 : OVD	0 = none; 1 = active 0 = none; 1 = active
												Bit 26 : UCD Bit 27 : OCD	0 = none; 1 = active 0 = none; 1 = active
												Bit 28 : OPD	0 = none; 1 = active
507	0x01FE	3	х				Actual voltage	R	uint(16)	2	1	Bit 30 : REM-SB 0x0000 - 0xFFFF (0 - 125%)	0 = DC enabled; 1 = REM-SB disables DC output Actual voltage (for translation see programming guide)
508 509	0x01F0	;	x				Actual current Actual power	R R	uint(16)	2	1	0x0000 - 0xFFFF (0 - 125%) 0x0000 - 0xFFFF (0 - 125%)	Actual current (for translation see programming guide) Actual power (for translation see programming guide)
520	0x0208	3	Х				Count of OV alarms since power up	R	uint(16)	2	1	0x0000 - 0xFFFF	Count
521 522	0x0208		X				Count of OC alarms since power up Count of OP alarms since power up	R R	uint(16) uint(16)	2		0x0000 - 0xFFFF 0x0000 - 0xFFFF	Count Count
523	0x020E	3	Х				Count of OT alarms since power up	R	uint(16)	2	1	0x0000 - 0xFFFF	Count
524 550	0x0200	_	X		х		Count of PF alarms since power up Overvoltage protection threshold (OVP)	R RW	uint(16) uint(16)	2		0x0000 - 0xFFFF 0x0000 - 0xE147 (0 - 110%)	Count OVP threshold (for translation see programming guide)
553 556	0x0229		X		X		Overcurrent protection threshold (OCP) Overpower protection threshold (OPP)	RW RW	uint(16) uint(16)	2		0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xE147 (0 - 110%)	OCP threshold (for translation see programming guide) OPP threshold (for translation see programming guide)
577	0x0241	ı	х		х		Condition of DC output after OT alarm	RW	uint(16)	2	1	Reg: Condition	0x0000 = off; 0x0001 = Restore
9000	0x2328		X		X		Upper limit of voltage set value (U-max) Lower limit of voltage set value (U-min)	RW	uint(16) uint(16)	2		0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Voltage value (for translation see programming guide) Voltage value (for translation see programming guide)
9002	0x232A 0x232E	1	Х		Х		Upper limit of current set value (I-max) Lower limit of current set value (I-min)	RW RW	uint(16) uint(16)	2	1	0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Current value (for translation see programming guide)
9003	0x232C	_	X		X		Upper limit of current set value (i-min) Upper limit of power set value (P-max)	RW	uint(16)	2		0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Current value (for translation see programming guide) Power value (for translation see programming guide)
10007	0x2717	7 x		х			Ethernet: TCP keep-alive	RW	uint(16)	2	1	Coils: Keep-alive on/off	0x0000 = off; 0xFF00 = on
10008	0x2718	3 x		х			Ethernet: DHCP	RW	uint(16)	2	1	Coils: DHCP on/off	0x0000 = off; 0xFF00 = on
10010 10011	0x271A	_	L	X	H	E	Protocol: Modbus Protocol: SCPI	RW RW	uint(16) uint(16)	2		Coils: MODBUS on/off Coils: SCPI on/off	0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on
10017 10502	0x272′ 0x2906		X			х	Ethernet: DHCP status Ethernet: IP address	R RW	uint(16) uint(8)	2		Bit0: DHCP running Bytes 0 - 3: 0255	0 = manual; 1 = DHCP 192.168.0.2 (default)
10504	0x2908	3	Х			х	Ethernet: Subnet mask	RW	uint(8)	4	2	Bytes 0 - 3: 0255	255.255.255.0 (Standard)
10506 10508	0x290A		X			X	Ethernet: Gateway Ethernet: Host name	RW RW	uint(8) char	4 54		Bytes 0 - 3: 0255 ASCII	192.168.0.1 (default) "Client" (default)
10535	0x2927	7	Х			х	Ethernet: Domain name	RW	char	54	27	ASCII	"Workgroup" (default)
10562 10566	0x2942 0x2946		X	E	H	Х	Ethernet: DNS USB: Connection timeout (in milliseconds)	RW R	uint(8) uint(16)	2		Bytes 0 - 3: 0255 565535	0.0.0.0 (default) Default: 5 ms
10567 10572	0x2947 0x2940		x				Ethernet: MAC Ethernet: Port	R R	uint(8) uint(16)	6	3	Bytes 0 - 5: 0255 065536 (except 80)	00:50:C2:C3:12:34 or 00-50-C2-C3-12-34 5025 (default)
10573	0x294E)	Х				Ethernet: TCP Socket timeout (in seconds)	R	uint(16)	2	1	565535, 0 = inactive	Default: 5 s
10900	0x2A94	+	Х		I		GPIB address (option 3W)	R	uint(16)	2	1	130	Default: 1