Modbus address (dec)	Modbus address (hex)	Read coils (0x01)	 Read holding registers (0x03) 	Write single coil (0x05)	Write multiple registers (0x10)	ter list for devices with KE firmware from V3.02 (che	Access	Data type	Data length in bytes	Number of registers	Data	Example See programming guide in section "A" PSR 170804-17070	Profibus slot		0x100 0x100 0x100 0x100
1 21 41 61 81 101	0x0001 0x0015 0x0029 0x003D 0x0051 0x0065		x x x x x	‡ ‡	#	Device type Manufacturer Manufacturer address Manufacturer ZPF code Manufacturer phone number Manufacturer website	R R R R	char char char char char char	40 40 40 40 40 40	20 20 20 20 20	ASCII ASCII ASCII ASCII ASCII ASCII ASCII ASCII ASCII	PSB 10080-1000	1 1 1 1 1 1 1	1 2 3 4	0x0101 0x0102 0x0103 0x0104 0x0105 0x0106
123 125 127 129	0x0079 0x007B 0x007D 0x007F 0x0081 0x0083		x x x x			Nominal ovalage Nominal current Nominal power Max. Internal resistance Min. Internal resistance Article no.	R R R R	float float float float float char	4 4	2 2 2	Floating point number EEE754 ASCII	80 1000 30000 5 0.003	1 1 1 1 1	7 8 9 10 11 12	0x0107 0x0108 0x0109 0x010A 0x010B 0x010C
151 171 191 211 231	0x0097 0x00AB 0x00BF 0x00D3 0x00E7		x x x x		×	Serial no. User tota Firmware version (KE) Firmware version (HMI) Firmware version (DR)	R RW R R	char char char char	40 40 40	20 20 20	ASCII ASCII ASCII ASCII	1234560001	_	14 15 16	0x010D 0x010E 0x010F 0x0110 0x0111
402 405 407 408 409	0x0192 0x0195 0x0197 0x0198 0x0199	x x x	х	x x x	×	Remote mode DC output/input Condition of DC output/input after power fail alarm Condition of DC output/input after power fail alarm Condition of DC output/input after powering the device Operation mode (UP/UR)	RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2	1 1	Coil : Remote Coil : Output/input Coil : Auto-Con Reg : Power-Cn Coil : Operation mode	0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = auto 0xFFFF = off; 0xFFFE = restore 0x0000 = UP; 0xFF00 = UR	2 3 2 2	6	0x0200 0x0203 0x031C 0x0205 0x0206
410 411 416 417 418 425	0x019A 0x019B 0x01A0 0x01A1 0x01A2 0x01A9	x x		x x x x		Restart of the device (warm start) Acknowledge alarms Analog interface: Reference voltage (pin VREF) Analog interface: REM-SB level Analog interface: REM-SB action Condition of DC opulutifyrut after leaving remote	W W RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2	1 1 1	Coil : Restart Coil : Alarms Coil : VAEF Coil : VREF Coil : REM-SB Level Coil : REM-SB Action Coil :	0xF00 = execute 0xFF00 = exknowledge 0x0000 = 10V; 0xFF00 = 5V 0x0000 = 10V; 0xFF00 = inverted 0x0000 = ort; 0xFF00 = auto 0x0000 = off; 0xFF00 = unchanged	_	9 14 36 37	0x0207 0x0208 0x020D 0x0223 0x0224 0x0229
427 428 432	0x01AB 0x01AC 0x01B0	×	x	x	×	Voltage Controller Speed SEMI F47 Reset device to factory settings	RW RW	uint(16) uint(16)	2	1	Cool : Condition On/Off Coil : Condition	0.0000 = Normal (default); 0.0001 = Slow; 0.0001 = Slow; 0.0002 = Fast; 0.0000 = ori; 0.0001 = ori; 0.0001 = ori;	2	60	0x023B 0x023C 0x023C
441 442 443	0x01B8 0x01B9 0x01BA 0x01BB		x		×	Analog interface: Pin 14 configuration Analog interface: Pin 6 configuration Analog interface: Pin 15 configuration Analog interface: Pin 9 and 10 configuration	RW RW RW	uint(16) uint(16) uint(16)	2 2	1 1 1	Alarms 1 Alarms 2 Status DC / reg. mode Current and voltage monitor	0x0000 = GVP (default); 0x0001 = GVP; 0x00012 = GVP; 0x00013 = GVP + CCP; 0x00013 = GVP + CCP; 0x00014 = GVP + CCP; 0x00015 = GVP + CCP + GVP; 0x00011 = GVP; 0x0011 = GV	2 2	46	0x022B 0x022C 0x022D 0x0231
498 499 500 501	0x01F2 0x01F3 0x01F4 0x01F5		x x x		× × ×	Sirk mode: Set power value Sirk mode: Set current value Set voltage value Set voltage value	RW RW RW	uint(16) uint(16) uint(16) uint(16)	2 2 2 2	1 1 1	0x0000 - 0x00E5 (0 - 102%) 0x0000 - 0x00E5 (0 - 102%) 0x0000 - 0x00E5 (0 - 102%) 0x0000 - 0x00E6 (0 - 102%)	norm source of sales, "more source (EL): 0.0001 = Pin 10 (CMON) only signals sink current (EL): 0.0002 = Pin 10 (CMON) only signals source current (PS): 0.0003 = Current mode A [source current (PS) on pin 0 and sink current (EL) or pin 0.0003 = Current mode A [source current (PS) on pin 10 and sink current (EL) or pin 0.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 0.0003 = Pin 10 (CMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (CMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (CMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (PMON) signals ELIPS current (0.10 V = -100%0100%, 1.0003 = Pin 10 (P	2 2	20 23	0x0214 0x0213 0x0216 0x0217
502 503 504	0x01F6 0x01F7 0x01F8		x x	1	x x	Source mode: Set power value Source mode: Set resistance value Sirik mode: Set resistance value	RW RW	uint(16) uint(16) uint(16)	2 2	1 1	0x0000 - 0x00E5 (0 - 102%) variable - 0x0DE5 (x - 102%) variable - 0x0DE5 (x - 102%) the minimum percent value needs to be calculated from the rating, see technical specs variable - 0x0DE5 (x - 102%) The minimum percent value needs to be calculated from the rating, see technical specs	Power value (for translation see programming guide) Resistance value (for translation see programming guide) Resistance value (for translation see programming guide)	2	26	0x0218 0x0219 0x0215
505	0x01F8		x			Device state	R	uint(32)	4	2	The results of the second special spec	0x00 = free; 0x01 = local; 0x03 = USB; 0x04 = analog; 0x05 = Profibus; 0x06 = Ethernet; 0x08 = Master/Slave; 0x09 = R8232; 0x10 = CANoper; 0x12 = Modotta CTD + 19; 0x13 = Profinet 1P; 0x14 = Etherne 1P; 0x15 = Ethernet 2P; 0x16 = Modbus TCP 2P; 0x14 = EtherCAT; 0x1C = free (due to communication timeout (CTOI))	2 et	27	0x021A
											Bit 6 : Master-slave type Bit 7 : Output state Bit 9-10 : Regulation mode Bit 11 : Remote Bit 12 : PSB/PSBE operation mode	0 = Slave; 1 = Master 0 = 0ff, 1 = on 00 = CV; 01 = CR; 10 = CC; 11 = CP 0 = off, 1 = on 0 = source; 1 = sink			
											Bit 13 : Function generator Bit 14 : External sense Bit 15 : Alarms Bit 16 : OVP Bit 17 : OCP Bit 18 : OPP	0 = stopped; 1 = ruming 0 = off; 1 = on 0 = none; 1 = active 0 = none; 1 = active 0 = none; 1 = active			
											Bit 19 : OT Bit 21 : Power fail Bit 24 : UVD Bit 25 : OVD Bit 26 : UCD Bit 27 : OCD	0 = none; 1 = active			
507 508	0x01FB 0x01FC		x x			Actual voltage Actual current	R	uint(16)	2	1	Bit 28 : OPD Bit 29 : MSP Bit 30 : REM-SB Bit 31 : OCP/OPP-OCD/OPD cause 0x0000 - 0xFFFF (0 - 125%) 0x0000 - 0xFFFF (0 - 125%)	0 = none; 1 = active 0 = none; 1 = active 0 = none; 1 = active 0 = Do enabled; 1 = REM-SB disables power output 0 = source mode; 1 = sink mode Actual voltage (for translation see programming guide) Actual voltage (for translation see programming quide)	2		0x021B 0x021C
509 511	0x01FD 0x01FF		x			Actual power Device state 2	R	uint(16) uint(32)	2		0x0000 - 0xFFFF (0 - 125%) Bit 1 : SF alarm Bit 4 : Power derating Bit 5 : Semi F47	Actual power (or translation see programming guide) 0 = none; 1 = active 0 = none; 1 = active	2	30	0x021D 0x0212
520 521 522 523 524 525	0x0208 0x0209 0x020A 0x020B 0x020C 0x020D		x x x x	f		Court of OV alarms since power up Source mode: Court of OC alarms since power up Source mode: Court of OP alarms since power up Court of OT alarms since power up Court of OT alarms since power up Sink mode: Court of PF alarms since power up	R R R R	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2	1 1 1 1 1	0x0000 - 0xFFFF		3 3 3 3	21 22 23 23 24 25	0x0312 0x0313 0x0314 0x0315 0x0316 0x0317
526 527 550 553 556	0x020B 0x020E 0x020F 0x0226 0x0229 0x022C	=	x x x	+	_	Sink mode: Court of PF aisms since power up Court of OP aisms since power up (PSBIPSBE devices: sink mode) Court of SF alarms since power up Overvoltage protection threshold (OVP) Source mode: Overcurrent protection threshold (OCP) Source mode: Overpower protection threshold (OPP)	R R RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2 2	1	0x0000 - 0xFFFF 0x0000 - 0xFFFF 0x0000 - 0xFFFF 0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xE147 (0 - 110%)	CVP threshold (for translation see programming guide) CQP threshold (for translation see programming guide) OPP threshold (for translation see programming guide)	3 3 3 3	26 27 0 3 3	0x0317 0x0318 0x0319 0x02FE 0x0301 0x0304
559 560 561 562 563	0x022F 0x0230 0x0231 0x0232 0x0233		x x x x		x x x x	Source mode: Undervoltage detection (UVD) Source mode: Adjustable UVD notification Source mode: Overvoltage detection (OVD) Source mode: Adjustable OVD notification Source mode: Undercurrent detection (UCD)	RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2 2	1 1 1	0x0000 - 0x00E5 (0 - 102%) Adjustable UVD notification 0x0000 - 0x00E5 (0 - 102%) Adjustable OVD notification 0x0000 - 0x00E5 (0 - 102%)	UVD threshold (for translation see programming guide) 0x0000 = nothing: 0x0001 = signat; 0x0002 = warning; 0x0003 = alarm 0VD threshold (for translation see programming guide) 0x0000 = nothing: 0x0001 = signat; 0x0002 = warning; 0x0003 = alarm UCD threshold (for translation see programming guide)	3 3 3 3	9 10 11 12 13	0x0307 0x0308 0x0309 0x030A 0x030B
564 565 566 567 568 569	0x0234 0x0235 0x0236 0x0237 0x0238 0x0239		x x x x x		x x x x	Source mode: Adjustable UCD rostfication Source mode: Overcurrent detection (OCD) Source mode: Adjustable OCD rostfication Source mode: Overpower detection (OPD) Source mode: Overpower detection (OPD) Source mode: Adjustable OCP rostfication Sink mode: Overcurrent protection threshold OCP	RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2	1 1 1 1 1	Adjustable UCD notification 0x0000 - 0x00E5 (0 - 102%) Adjustable 0x0D notification 0x0000 - 0x00E5 (0 - 102%) Adjustable OPD notification 0x0000 - 0x00E5 (1 - 107%)	0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm OCD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm OPD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm OCP threshold (for translation see programming guide)	3 3 3 3 3	14 15 16 16 17 18 18 4	0x030C 0x030D 0x030E 0x030F 0x0310 0x0302
570 571 572 573 574 575	0x0239 0x023A 0x023B 0x023C 0x023D 0x023E 0x023F		x x x x x x x x x		x x x x	Sirk mode. Overcurrent protection treshold CPP Sirk mode. Overpower protection treshold CPP Sirk mode. Undercurrent detection UCD Sirk mode. Valigatable UCD redification Sirk mode. Algulatable UCD redification Sirk mode. Algulatable UCD redification Sirk mode. Overcurrent detection OCD Sirk mode. Algulatable UCD redification Sirk mode. Overcurrent detection OCD	RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2 2	1 1 1	0.00000 - 0.00147 (0 - 110%) 0.00000 - 0.00147 (0 - 110%) 0.00000 - 0.00DES (0 - 102%) Adjustable UCD notification 0.00000 - 0.0DES (0 - 102%) Adjustable OCD notification 0.00000 - 0.0DES (0 - 102%) Adjustable OCD notification 0.00000 - 0.0DES (0 - 102%)	CCP threshod (for translation see programming guide) UCD threshod (for translation see programming guide) UCD threshod (for translation see programming guide) B0000 = noffising .00001 = signat. 00002 = warning .00003 = alarm OCD threshod (for translation see programming guide) 0x000 = noffising .0x0001 = signat. 0x0002 = warning .0x0003 = alarm OCD threshod (for translation see programming guide)	3 3 3	3 31 3 32 3 33 3 34	0x0302 0x0305 0x031D 0x031E 0x031F 0x0320 0x0321
575 576 577 650 653 654	0x023F 0x0240 0x0241 0x028A 0x028D 0x028E	x x	x	x x	x	Sirk mode: Overpower detection OPD Sirk mode: Adjustable OPD notification Condition of DC output/input after OT atam Master-slave: Link mode on MS bus Master-slave: Enable MS Master-slave: Init MS	RW RW RW RW W	uint(16) uint(16)	2 2 2 2 2 2	1 1 1	0x0000 - 0xD0E5 (0 - 102%) Adjustable OPD notification Reg: Condition Coit Mode Coit: MS on/off Coit: MS start init	OPD threshold (for translation see programming guide) 0.00000 = nothing; 0.00001 = signal; 0.00002 = warning; 0.00003 = alarm 0.00000 = off; 0.0001 = restore (default) 0.00000 = Slave; 0.9FF00 = Master 0.00000 = off; 0.0FF00 = on 0.9FF00 = Start int	_	36	0x0321 0x0322 0x0323 0x03FD 0x0400 0x0401
655 656	0x028F 0x0290		×		×	Master-slave: Condition Master-slave: Total voltage in V	R	uint(16)	2		Reg: MS status Floating point number IEEE754	0.0000 – not initialised; 0x0001 = init numing; 0x0003 = set defaults; 0x0004 = setup interface; 0x0005 = assignment; 0xFFFC = disrupted; 0xFFFD = different models delected, init not OK; 0xFFFE = error; 0xFFFF = init OK; 0xFFFB = Temination not OK	4	5	0x0402 0x0403
656 658 660 662 666 667	0x0290 0x0292 0x0294 0x0296 0x029A 0x029B	×	x x	x x		Master-slave: Total voltage in V Master-slave: Total current in A Master-slave: Total prower in W Master-slave: Number of intitiatised slaves Master-slave: Bus termination Master-slave: Bus termination	R R R RW RW	float float float uint(16) uint(16)	4 4 2 2 2	2 2 1	Floating point number EEET784 Floating point number EEET784 Floating point number EEET784 Coil : Termination Coil : BIAS	80 5000 150000 183 00000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on	4 4 4	8 9	0x0403 0x0404 0x0405 0x0406 0x0407 0x0408
850 851 852 856	0x0352 0x0353 0x0354 0x0358	x x x		x x x	Ī	Function generator Arbitary; Startistop Function generator Arbitrary; Select U Function generator Arbitrary; Select I Function generator XY; Select mode	RW RW RW	uint(16) uint(16) uint(16) uint(16)	2 2 2		Coil : Start/Stop Coil : U Coil : I Reg: Mode	0x0000 = Stop; 0xFF00 = Start	5 5 5	i 0 i 1 i 2	0x04FC 0x04FD 0x04FE 0x050A
859 860	0x035B 0x035C		x x		×	Function generator Arbitrary: Start sequence Function generator Arbitrary: End sequence	RW	uint(16)	2	1	0x00010x0063 0x00010x0663		5	9 10	0x0505 0x0506
860 861 862 900	0x035C 0x035D 0x035E		x	×	_	Function generator Arbitrary: End sequence Function generator Arbitrary: Sequence cycles Function generator Arbitrary: Submit settings (only required for CAN, CANopen, EtherCAT CoE) Function generator Arbitrary: Setup for sequence 1	RW W W	uint(16) uint(16) uint(16) float	2 2 2	1 1 1	0x001_0x0063 0x000_0x03E7 Coil : Submit Albitrary Bytes 0-3: Us/ls(AC) in V or A Bytes 4-7: Us/ls(AC) in V or A	0x0000 = infinite 0xFF00 = Submit settings Floating point number in EEE754 format, see device manual for value range, chapter about function generator	5	11	0x0506 0x0507 0x05FE
											Bytes 4-7: Uefe(AC) in V or A Bytes 8-11: fs(1/T) in Hz Bytes 12-15: fs(1/T) in Hz Bytes 12-16: fs(1/T) in Hz Bytes 16-19: Angle in degrees Bytes 20-23: Usfa(DC) in V or A Bytes 24-27: Usfa(DC) in V or A	chapter about function generator Hateger in EEE754 format 010000 Hz Hateger in EEE754 format 010000 Hz Hateger in EEE754 format 010000 Hz Floating point rumber in EEE754 format, or350° Floating point rumber in EEE754 format, see device manual for value range, chapter about function generator			
↓ 2468	↓ 0x035D	1	ţ	1	×	i Function generatorArbitrary, Setup for sequence 99	↓ RW	↓ float	1 32	16	Bytes 28-31: Sequence time in µs ↓ Bytes 0-3: Us/ls(AC) in V or A Bytes 4-7: Us/lie(AC) in V or A Bytes 8-11: fs(1/T) in Hz	Floating point number in EEE754 format. 100 µs38,000,000,000 µs I Floating point number in EEE754 format, see device manual for value range, chapter about function generator. Neger in EEE754 format. 0.10000 Hz	6	98	0x065E
20	0		P		<u> </u>	Function reperator VV Table 4 (1921)		p)4			Bytes 12-15: fe(1/T) in Hz Bytes 16-19: Argie in degrees Bytes 20-23: Us/ls(DC) in V or A Bytes 20-23: Us/ls(DC) in V or A Bytes 26-31: Sequence time in µs Bitmode: set expent value for source mode (PS)	histoger in EEEF54 format 010000 Hz Happer in EEEF54 format 0350* Floating point rumber in EEEF54 format, see device manual for value range, chapter about function generator Floating point rumber in EEEF54 format 100 µs36,000,000,000 µs value = real set value of current* 0.8 / hom* 32768			0
2600 ↓ 6680	0x0A28 ↓ 0x1A18 0x2328	1	x x	ı .	× ×	Function generator XY: Table 1 (PS), block 0	RW ↓ RW	uint(16) uint(16) uint(16)	32 ↓ 32	16	All mode: set current value for source mode (PS) (16 values block) U mode: set current value for source mode (PS) (16 values block) 0x0000 - 0x00E5 (0 - 102%)	value = real set value of current * 0.8 / Inom * 32768 value = real set value of current * 0.8 / Inom * 32768 Voltage value (for translation see programming guide)	7	255	0x06FA 0x07F9 0x021E
9000 9001 9002 9003 9004 9005	0x2329 0x232A 0x232B 0x232C 0x232D		x x x x		x	Lower limit of voltage set value (U-min) Source mode: Upper limit of current set value (I-max) Source mode: Lower limit of current set value (I-min) Source mode: Upper limit of power set value (P-max) Sirik mode: Upper limit of power set value (P-max)	RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2 2	1 1	0x0000 - 0x00E5 (0 - 102%) 0x0000 - 0x00E5 (0 - 102%)	Voltage value (for translation see programming guide) Current value (for translation see programming guide) Current value (for translation see programming guide) Power value (for translation see programming guide) Power value (for translation see programming guide)	2 2 2	32 33 34 35 36	0x021F 0x0220 0x0221 0x0222 0x0223
9006 9007 9008	0x232E 0x232F 0x2330		x	1	×	Source mode: Upper limit of resistance set value (R-max) Sirk mode: Upper limit of resistance set value (R-max) Sirk mode: Upper limit of current set value (H-max)	RW	uint(16)	2	1	variable - ODDEE (x - 102%) The minimum percent value needs to be calculated from the rating, see lachrical specs variable - OXDDES (x - 102%) The minimum percent value needs to be calculated from the marking, see technical specs OXDDES (x - 102%) OXDOOD - OXDDES (5 - 102%)	Resistance value (for translation see programming guide) Resistance value (for translation see programming guide) Current value (for translation see programming guide)	_	37	0x0224 0x0226 0x0227
9008 9009 0007 0008 0010 0011	0x2331 0x2717	x x x	x	_	×	Sirk mode: Upper limit of current set value (Hnax) Sirk mode: Lower limit of current set value (Hnin) Elbernett TCP keep-alive timeout ElbernettPortestMedbus TCP: DHCP Protocot: Modbus Protocot: SCPI	RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2	1 1	0x0000 - 0xD0ES (0 - 102%) 0x0000 - 0xD0ES (0 - 102%) Coli: Keep-alive on/off Coli: MOBBUS on/off Coli: MOBBUS on/off	Current value (for translation see programming guide) Current value (for translation see programming guide) 0.00000 = 0ff; 0.0FF00 = on 0.00000 = 0ff; 0.0FF00 = on 0.00000 = 0ff; 0.0FF00 = on	2	_	0x0227 0x0228
0012 0013 0020		x x		x x		Restart interface card Modbus specification compilance AnyBus module: Type	RW RW R		2 2	- 1	Coit Seyt Orion Coit Restart Coit Mode Reg: Type	0.00000 - or; 0.00+0.00 - on 0.00000 - or; 0.00+0.00 - on 0.00000 - profile 0.00000 - or 0.00000 - or 0.000000 - or 0.000000 - or 0.000000 - or 0.00000000000000000000000000000000000			
												0.0012 = Modbus-TCP 1P 0.0013 = Profinet 1P 0.0014 = Ethernet 1P 0.0016 = Ethernet 2P 0.0016 = Modbus-TCP 2P 0.0017 = Profinet 2P			
0021 0041 0043 0251	0x2725 0x2739 0x273B 0x280B		x x x	#	×	AnyBus module: Interface type AnyBus module: Version number AnyBus module: Serial number Profibus: Hern rumber Profibus: Hern rumber	R R R	char uint(8) uint(32)	40 4 4 2	20 2 2	ASCII	000019 = CAN 00019 = CAN 00010 = CAN 00017 = SenerCAT 0000FF = no or urknown module plugged "Profibus DPV1"			0x07F9
0251 0252 0253 0269 0280 0300 0354	0x280B 0x280C 0x280D 0x281D 0x2828 0x283C 0x2872		x x x x x		× × × × × × × × × × × × × × × × × × ×	Profibus/CANopen: Node address Profibus/Profinet: User-defineable "Function tag" Profibus/Profinet: User-defineable "Location tag" Profibus/Profinet: User-defineable "Location tag" Profibus/Profinet: User-defineable installation date Profibus/Profinet: User-defineable description	RW RW RW RW RW	uint(16) uint(16) char char char char	40 54	11 20 27	ASCII ASCII ASCII ASCII	0A001 Profibus 0-125; CANopen: 0-127 "Test" "13.01.2012 09:59:00" "www.webpage.de" "Test"	8 8 8 8 8	3 1 3 2 3 3 4	0x07F9 0x07FA 0x07FB 0x07FC 0x07FD 0x07FE 0x07FF
0354 0502 0504 0506 0508 0535	0x2906 0x2908 0x290A 0x290C 0x2927		x x x x		×	Profinet Liser-defineable "Station name" EthernetModous TCP: P. address EthernetModous TCP: Subnet mask EthernetModous TCP: Subnet mask EthernetModous TCP: Gatway EthernetProfinetModous TCP: Host name EthernetProfinetModous TCP: Domain name		char uint(8) uint(8) uint(8) char char	200 4 4 4	100 2 2 2 27 27	ASCII Bytes 0-3: 0.255 Bytes 0-3: 0.255 Bytes 0-3: 0.255 Bytes 0-3: 0.255 ASCII ASCII	Test" 192-168.0.2 (default) 265.256.255.0 (default) 192-168.0.1 (default) 192-168.0.1 (default) 194-168.0.1 (default) 194-168.0.1 (default)	8	6	AU7FF
0562 0564 0566 0567 0570	0x2942 0x2944 0x2946 0x2947 0x294A		x x x x	-	× (×		RW RW RW R	uint(8) uint(8) uint(16) uint(8) uint(16)	4 4 2 6 2	2 2 1 3	Bytes 0-3: 0.255 Bytes 0-3: 0.255 5.6535 Bytes 0-5: 0.255 Connection speed	0.0.0 (default) 0.0.0 (default) Default: Sms 0.56:C2:C3:12:34 or 00-50:C2-C3-12-34 0.0000 = Ault: 0.0001 = 10Mbit half duplex 0.0001 = 10Mbit hilf durlex		Ė	
0571	0x294B		x	+	x	Ethernet/Modbus TCP: Connection speed Port 2 (2 port module)	RW		2		Connection speed	0.0003 = 100Mbit half duplex 0.00004 = 100Mbit hilf duplex 0.0000 = Auto; 0.0001 = 10Mbit half duplex; 0.0002 = 10Mbit half duplex; 0.0003 = 100Mbit half duplex; 0.0003 = 100Mbit half duplex;		_	
0572 0573 0700	0x294C 0x294D 0x29CC		x x	_	×	Ethernet (except for Modbus TCP): Port Ethernet TCP Socket timeout (in seconds) RS232/CANopen/CAN: Baud rate	RW RW RW	uint(16) uint(16) uint(16)	2 2	_	0.65535 5.65535 Baud rate	Common			
0701 0702 0704 0706	0x29CD 0x29CE 0x29D0 0x29D2	x	x	x	>	CAN: D format CAN: Termination CAN: Base ID CAN: Broadcast D	RW RW RW	uint(16) uint(32) uint(32)	2 2 4	2	Coit Base/Extended Coit Base termination 0x00000x17FF or 0x00000x17FFFFFF 0x00000x17FF or 0x00000x17FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF	0x0000 = Base (11 Bit); 0xFF00 = Extended (29 Bit) 0x0000 = off; 0xFF00 = on 0xf10xF00 = on 0xf10xF00 0xf10xF000 0xf10xF0000		F	
0709 0710 0712 0714	0x29D5 0x29D6 0x29D8 0x29DA 0x29DB	х	x x	x	×	CAN: Cyclic read: Base ID CAN: Cyclic read: Base ID CAN: Cyclic read time (in ms): Status CAN: Cyclic read time (in ms): Status CAN: Cyclic read time (in ms): Status	RW RW RW	uint(16) uint(32) uint(32) uint(16)	4 2 2	2	Coll: Data length 0x00000x07FF or 0x00000x1FFFFFFF 0x00000x07FF or 0x00000x1FFFFFFF 205000; 0 = off	0x0000 = Auto; 0xFF00 = Always 8 bytes Default: 0x100 Default: 0x200 Default: off Default: off		F	
0715 0716 0717 0718 0721 0722	0x29DB 0x29DC 0x29DD 0x29DE 0x29E1 0x29E2		x x x x x	#	×	CAN: Cyclic read time (in ms): Set value (U, L.P.,R) CAN: Cyclic read time (in ms): Limits 2 (P.,R) CAN: Cyclic read time (in ms): Limits 1 (U, I) CAN: Cyclic read time (in ms): Actual values U, L.P CAN: Cyclic read time (in ms): Set value (I, P.R) (only PSBIPSBE devices, sink mode) CAN: Cyclic read time (in ms): Set value (I, P.R) (only PSBIPSBE devices, sink mode)	RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2 2	1 1 1 1	205000; 0 == off 205000; 0 == off	Default: off			
0820	0x2A44 0x2A45	x	x	×	<u> </u>	Internal Ethernet interface: Status Internal Ethernet interface: TCP keep-alive timeout	R	uint(16)	2	1	Bits 0-8:- Bit 6: Keep-Alive Bit 7: DHCP 1 Bit 8: DHCP 2 Coli: Keep-alive on/off	0 = inactiv, 1 = activ 0 = DHCP deactivated; 1 = DHCP activated 0 = DHCP is not running, P has been not assigned; 1 = DHCP is running, P has been assigned 0.0000 = off; 0xFF00 = on			
0821 0822 0823 0825 0827 0829	0x2A45 0x2A46 0x2A47 0x2A49 0x2A4B 0x2A4D 0x2A68	x	_	×		internal Ethernet interface: DHCP Internal Ethernet interface: P address Internal Ethernet interface: Short mask Internal Ethernet interface: Stohen thank Internal Ethernet interface: Sateway Internal Ethernet interface: Host name Internal Ethernet interface: Domain name	RW RW RW RW RW	uint(16) uint(16) uint(8) uint(8) uint(8) char char	2 4 4 4 54 54	1 2 2 2 27	Coll: Keep-aive orviolf Coll: DHCP orviolf Bytes 0-3: 0.255 Bytes 0-3: 0.255 Bytes 0-3: 0.255 Sytes 0-3: 0.255 ASCII ASCII	0.00000 = off; 0.04F-00 = on 0.00000 = off; 0.0FF-00 = on 192: 180.02 (default) 192: 168.0.1 (default) 192: 168.0.1 (default) "Client" (default)		F	
0856 0883 0885 0888 0889	0x2A68 0x2A83 0x2A85 0x2A88 0x2A89		x x x x		×		RW R(W) RW RW	char uint(8) uint(8) uint(16) uint(16)	54 4 6 2 2	2 3 1	ASCII Bytes 0.3: 0.255 Bytes 0.5: 0.255 Bytes 0.5: 0.255 5.65535 (0 = timeout inactive) 0.4	"Workgroup" (default) 00.50 (Cdesult) 00.50 (Cdesult) 00.50 (C2 C3:12:34 or 00:50-C2-C3-12-34 5025 (default), except port 80 Default: 5 0 = off; 1 = MPP1; 2 = MPP2; 3 = MPP3; 4 = MPP4			0x08F8
1001 1002 1003 1004 1005	0x2AF9 0x2AFA 0x2AFB 0x2AFC 0x2AFD		x x x x		X X X X X	MPP Tracking: Uoc (Setup) MPP Tracking: Uoc (Setup) MPP Tracking: Umpp (Setup) MPP Tracking: Umpp (Setup) MPP Tracking: Pmpp (Setup) MPP Tracking: Pmpp (Setup)	RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2 2	1 1 1 1	0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Unom (for translation see programming guide) Current value in % of Inom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Current value in % of Inom (for translation see programming guide) Power value in % of Prom (for translation see programming guide)	9 9 9 9 9	3	0x08F9 0x08FA 0x08FB 0x08FC 0x08FC
1006 1007 1008 1009 1010 1011	0x2AFE 0x2AFF 0x2B00 0x2B01 0x2B02 0x2B03	×	x x x	×		MPP Tracking: DellaP (Selbu) MPP Tracking: Umpp (Result in MPP1/2/4) MPP Tracking: Impp (Result in MPP1/2/4) MPP Tracking: Pmpp (Result in MPP1/2/4) MPP Tracking: Pmpp (Result in MPP1/2/4) MPP Tracking: Start/Sup MPP Tracking: Finished (Function status for MPP1/2/4)	RW R R R RW	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2	_	0.0000 - 0.0CCCC (0 - 100%) Coli: Start/Stop Coli: Starts	Power value in % of Pnom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Current value in % of Inom (for translation see programming guide) Power value in % of Pnom (for translation see programming guide) 0,0000 = slop, SPF00 = start 0,0000 = slop, SPF00 = start 0,0000 = slop, SPF00 = finished	9 9 9 9	10	0x08FE 0x08FF 0x0900 0x0901 0x0902 0x0903
1012 1013 1014 1015	0x2B03 0x2B04 0x2B05 0x2B06 0x2B07	×	x	1	×	were rincaring riminated (uncloud salatus for were rincar) MPP Tracking risor during function MPP-Tracking steroad (Setup) MPP4 : Start MPP4 : Start	RW RW	uint(16) uint(16) uint(16) uint(16)	2 2		Coft stuttus Coft Error 0x0005 - 0xEA60 0x0001 - 0x0064	0x0000 = no error; 0xFF00 = error Regulation & measuring interval in milliseconds, either for tracking in modes 1 and 2 of for user curve progression in mode 3 Start voltage value out of 100 (related to registers 11100-11199) for use in MPP4 mode End voltage value out of 100 (related to registers 11100-11199) for use in MPP4 mode	9 9	12	0x0903 0x0904 0x0905 0x0906 0x0907
1016 1100 1120 1140 1160	0x2B08 0x2B5C 0x2B70 0x2B84 0x2B98		x x x x		×	MPP4 : Repetitions MPP Tracking: User curve (MPP4 mode) voltage values 1-20 MPP Tracking: User curve (MPP4 mode) voltage values 21-40 MPP Tracking: User curve (MPP4 mode) voltage values 41-80 MPP Tracking: User curve (MPP4 mode) voltage values 61-80	RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)	40 40 40 40	1 20 20 20 20	0x0000 - 0xFFFF 0x0000 - 0xCCCC (0 - 100%)	MPP4 mode 0x0000 = no repetitions Voltage value in % of Unom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide)	9 9 9 9	16 17 18 19 19 20	0x0908 0x0909 0x090A 0x090B 0x090C
1180 1200 1230	0x2BAC 0x2BC0 0x2BDE		x	1	×	MPP Tracking: User curve (MPP4 mode) voltage values 81-100 MPP Tracking: User curve (MPP4 mode) results 1-10 (10x Umon, Inon, Pmon) MPP Tracking: User curve (MPP4 mode) results 11-20 (10x Umon, Imon, Pmon)	RW R	uint(16) uint(16) uint(16)	40 60	30	0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Uhorm (for translation see programming guide) Voltage value in % of Incom Current value in % of Incom Power value in % of From (for translation see programming guide) Voltage value in % of Uhorn Current value in % of Incom	9	22	0x090D 0x090E 0x090F
1260	0x2BFC 0x2C1A		x	1	+	MPP Tracking: User curve (MPP4 mode) results 21-30 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 31-40 (10x Umon, Imon, Pmon)	R	uint(16)			0x0000 - 0xCCCC (0 - 100%)	Power value in % of Prom (for translation see programming guide) Voltage value in % of Unom Current value in % of Inom Power value in % of Prom (for translation see programming guide)	9		0x0910 0x0911
1320	0x2C1A 0x2C38	1	x	1	\int	MPP Tracking: User curve (MPP4 mode) results 31-40 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 41-50 (10x Umon, Imon, Pmon)	R	uint(16)			0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Unom Current Value in % of Inom Power value in % of Inom (for translation see programming guide) Voltage value in % of Unom Current Value in % of Unom Power value in % of Pnom Power value in % of Pnom	9		0x0911 0x0912
1350 1380	0x2C56		x		+	MPP Tracking: User curve (MPP4 mode) results 51-60 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 61-70 (10x Umon, Imon, Pmon)	R	uint(16)	60		0x0000 - 0xCCCC (0 - 100%)	Power value in % of Prom [for translation see programming guide) Voltage value in % of Unom Current value in % of Inom Power value in % of Prom [for translation see programming guide) Voltage value in % of Unom Current value in % of Inom Current value in % of Inom Current value in % of Inom	9		0x0913 0x0914
1410	0x2C92		х	1	+	MPP Tracking: User curve (MPP4 mode) results 71-80 (10x Umon, Imon, Pmon)	R	uint(16)	60	30	0x0000 - 0xCCCC (0 - 100%)	Current value in % of Incm Power value in % of Prom (for translation see programming guide) Voltage value in % of Incm Current value in % of Incm Power value in % of Incm (for translation see programming guide)	9	29	0x0915
1440 1470	0x2CB0 0x2CCE		x	+	+	MPP Tracking: User curve (MPP4 mode) results 81-90 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 91-100 (10x Umon, Imon, Pmon)	R	uint(16)	60		0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Unom Current value in % of Inom Power value in % of Prom (for translation see programming guide) Voltage value in % of Unom Current value in % of Inom	9	30	0x0916 0x0917
502 504	0x2CEC 0x2CEE 0x2CF0		x x x))	Battery discharge test (static): Max. power Battery discharge test (static): Max. resistance	RW RW	float float	4 4	2	Floating point number EEE754 Floating point number EEE754 Floating point number EEE754 Floating point number EEE754	Power value in % of Prom (for translation see programming guide) 0 - rated current 0 - rated power Min max resistance, 0 = OFF	11 11 11	1	0x0AF6 0x0AF7 0x0AF8
506 508 510 512	0x2CF2 0x2CF4 0x2CF6 0x2CF8		x x x	#	Х		RW RW RW	float float uint(32) uint(16)	4 4 2	2	Floating point number EEE/74 Floating point number EEE/74 Floating point number EEE/74 0x00000000 - 0x00000000 (0 - 10 h) Action when reaching max discharge capacity	0 - rated voltage 0 - spale voltage 0 - spale sp	11 11 11	3	0x0AF9 0x0AFA 0x0AFB
513 514 516 518	0x2CF9 0x2CFA 0x2CFC 0x2CFE		x x x		×	Battery discharge test (dynamic): Time of current level 1	RW RW RW	uint(16) float float	2	2 2	Action upon reaching the max. discharge time Floating point number EEE754 Floating point number EEE754 Floating point number EEE754	0.0002 Stop test 0.0000 = 0 nothing; 0.0001 = Signal (see register 11544); 0.0002 = Stop test 0 - rated current 0 - rated current	11 11 11	8 9	0x0AFE 0x0AFE 0x0AFF 0x0B00
518 520 522 524 526 528	0x2CFE 0x2D00 0x2D02 0x2D04 0x2D06 0x2D08		x x x x	#))	Battery discharge test (dysamic): Time of current level 1 Battery discharge test (dysamic): Time of current level 2 Battery discharge test (dysamic): Max power Battery discharge test (dysamic): Discharge voltage Battery discharge test (dysamic): Max capacity to discharge Battery discharge test (dysamic): Max capacity to discharge Battery discharge test (dysamic): Max discharge time	RW RW RW RW RW	float float float float uint(32)	4 4 4 4	2 2	Floating point number EEE754 Floating point number 0.00000000000000000000000000000000000	1 - 39000 s 1 - 39000 s 1 - 39000 s 0 - rated power 0 - rated voltage 0 - 99999 99 0>000010203 = 01:02:03 as HH.MM.SS, equivalent to [00][HRS][MN][SEC]	11	11 12 13	0x0B00 0x0B01 0x0B02 0x0B03 0x0B04 0x0B05
530	0x2D0A 0x2D0B		x	#	×	Battery discharge test (dynamic): Action upon reaching the max. discharge capacity Battery discharge test (dynamic): Action upon reaching the max. discharge time	RW	uint(16) uint(16)	2	1	Action	0x0000 = Do nothing: 0x0010 = Signal (see register 11544); 0x0002 = Sisp test 0x0000 = Do nothing; 0x0001 = Do nothing; 0x0010 = Signal (see register 11544); 0x0002 = Stop test	11	16	0x0B06 0x0B07
532 535 536	0x2D0C 0x2D0F	×	x	х	×	Battery test: Start/stop Battery test: Mode selection Battery test: Discharged capacity in Ah	RW RW	uint(16) uint(16)	2 2	1	Coll: Start/Stop Mode selection	0.000.2 - Supt wiss 0.0000 - Stop; 0xFF00 = Run 0.0000 - Battery test mode off (default); 0.0001 - Statet discharge; 0.0002 - Pulsed discharge; 0.0002 - Pulsed charge; 0.0003 - Statet charge; 0.0004 - Dynamic test	11	21	0x0B08 0x0B0B
536 538 540 544	0x2D10 0x2D12 0x2D14 0x2D14		x x x	1		Battery test: Discharged capacity in Ah Battery test: Discharged energy in Wh Battery test: Time at end of test Battery test: Status	RW RW RW	float float uint(16) uint(16)	8		x Ah x Wh HH-MM-SS.MS #BEZUG!	10.5 Ah 2345.3 Wh Word 0 - Hours (0-10) Word 1 - Minutes (0-59) Word 2 - Seconds (0-59) Word 3 - Milliseconds (0-99) O - none; 1 - active		23	0x0B0C 0x0B0D 0x0B0E 0x0B0E
.4	18 ل عد		*				R	18(16)	2	Í	Bit 0 :Running Bit 1 :Finished Bit 2 :Error occurred Bit 3 :Initalized Bit 4 :Maximum Ah reached (signal only)	0 = none; 1 = active 0 = none; 1 = active	111	∠5	.ve0F
											Bit 5 : Maximum time reached (signal only) Bit 6 : Maximum Air reached (end of test) Bit 7 : Maximum time reached (end of test) Bit 8 : Charging Bit 9 : Charging Bit 10 : Reseting	0 = none; 1 = active #BEZUGI			_
545 547 551 553 555	0x2D19 0x2D1B 0x2D1F 0x2D21 0x2D21 0x2D23		X X X X		> > > > > > > > > > > > > > > > > > >	Battery charge test (static): Charge current Battery charge test (static): Charge current Battery charge test (static): Max. capacity to charge Battery charge test (static): Max. charge time	RW RW RW RW	float float float float uint(32)	4 4 4	2 2 2	Floating point number EEE754 Floating point number EEE754 Floating point number EEE754 Floating point number EEE754 0x00000000 - 0x000x0000 (0 - 10 h)	0 - rated voltage 0 - rated current 0 - rated current 0 - rated current 0 - rated current 0 - 99999 99 0x00010203 = 01.02.03 as HH.MM.SS, equivalent to [00][SEK][MN][STD]	11	27 29 30 31	0x0B10 0x0B11 0x0B13 0x0B14 0x0B15
557 558 559	0x2D25 0x2D25 0x2D26		x	1	x	Battery charge test (static): Action upon reaching the max. capacity Battery charge test (static): Action upon reaching the max. charge time	RW	uint(16) uint(16)	2	1	Action Action Floating point number IEEE754	0x0000 = Do nothing; 0x0001 = Do nothing; 0x0001 = Signal (eer register 11544); 0x0002 = Stop test 0x00002 = Stop test 0x0001 = Signal (eer register 11544); 0x0002 = Stop test 0x10001 = Signal (eer register 11544); 0x0002 = Stop test	11	32	0x0B16 0x0B17 0x0B18
561 565 567 569 571	0x2D29 0x2D2D 0x2D2F 0x2D31 0x2D33		x x x x		3 3 3	Battery dynamic test (charge): Charge current Battery dynamic test (charge): Charge end current Battery dynamic test (charge): Charge end current Battery dynamic test (charge): Charge duration Battery dynamic test (discharge): Discharge current Battery dynamic test (discharge): Discharge end voltage	RW RW RW RW	float float float float float	4 4 4 4	2 2 2 2	Floating point number IEEE754	0 - rated current 0 - rated current 1 - 36000 s 0 - rated current 0 - rated voltage	11 11 11 11	35 37 38 39 40	0x0B19 0x0B1B 0x0B1C 0x0B1D 0x0B1E
573 575 577 579	0x2D35 0x2D37 0x2D39 0x2D3B		x x x		Х		RW RW RW	float float uint(32) uint(16)	4 4 2	2	Floating point number EEE754 Floating point number EEE754 0x00000000 - 0x000000000 (0 - 10 h) Action	1 - 36000 s 0 - 9999 99 0 000010303 - 91:02:03 as HH:MM:SS, equivalent to [OI][SEK][MN][STD] 0 0000 - Do nothing; 0 0000 - Do nothing; 0 0000 - Signal (see register 11544); 0 0000 - Signal (see segister 11544);	11 11 11	41 42 43	0x0B1F 0x0B20 0x0B21 0x0B22
580 581 582	0x2D3C 0x2D3D 0x2D3E		x x	#	×	Battery dynamic test: Action upon reaching the max time Battery dynamic test: Start with discharging or charging phase Battery dynamic test: Pause time between operations	RW RW	uint(16) uint(16)	2		Action Start with Floating point number IEEE754	0.0002 Stop test 0.0000 = Do nothing; 0.0001 = Signal (see register 11544); 0.0002 = Stop test 0.00002 = Charging; 0.00000 = Charging; 1. 300000 = Charging	11	46	0x0B23 0x0B24 0x0B25
584 000 001	0x2D3E 0x2D40 0x2EE0 0x2EE1 0x2EE2	×	x x	x	×	Battery dynamic test: Pause time between operations Battery dynamic test: Cycles Function generator PV: Start/Stop Function generator PV: Simulation mode Function generator PV: MPP Voltage	RW RW RW RW	float uint(16) uint(16) uint(16) uint(16)	2 2	1	Floating point number EEE754 Number Coil: Start/Stop Mode 0x0000 - 0xCCCC	1. 30000 s 0 = Infrite: 1.999 0x0000 = Stop: 0xFF00 = Start 0x0000 = Stop: 0xF001 = Irradiation/temperature; 0x0002 = Umpp/Impp; 0x0003 = Daily trend Irradiation/temp.: 0x0004 = Daily trend Irradiation/temp.: 0x0004 = Daily trend Umpp/Impp MPP vottage (for translation see programming guide)		48	0x0B25 0x0B26 0x09F7 0x09F8 0x09F9
002 003 004 005	0x2EE3 0x2EE4 0x2EE5 0x2EE6 0x2EE7	x	x	x x		Function generator PV: MPP Current Function generator PV: MPP Power Function generator PV: Interpolation Function generator PV: Day trend (mode) Function generator PV: Day trend (clear completely)	R R RW RW W	uint(16) uint(16) uint(16) uint(16) uint(16)	2 2 2 2 2 2		0x0000 - 0xCCCC 0x0000 - 0xCCCC 0x0000 - 0xCCCC 0xit terpolation Colit Mode Colit Clear 1 100000	MPP current (for translation see programming guide) MPP power (for translation see programming guide) 0x0000 = off, 0xFF00 = on 0x0000 = road only, 0xFF00 = write 0xFF00 = clear	10 10 10 10	3 4 5 6 7	0x09FA 0x09FB 0x09FC 0x09FD 0x09FE
006 007	0x2EE8 0x2EEA	1	x	+	3	Function generator P-V: Day term (index) Function generator P-V: Day trend (index) Function generator P-V: Day trend index data		uint(16)	12	2		09F-102 - Golar Currently selected index Tradiation or U-MPP (for translation see register 12053) or U-MPP (for translation see programming guide) Module temperature (for translation see register 12052) or I-MPP (for translation see programming guide) Dealtime of Index	10	8	0x09FE 0x0A00
		ı		•				uint(16)	2	1		Dwelltime of index 0x0000 = Manual; 0x0001 = cSI technology; 0x0002 = Thin film technology	10	10	0x0A01
007	0x2EF0 0x2EF1 0x2EF2 0x2EF3 0x2EF4	×	x	x x x	×	Function generator PV: Technology Function generator PV: Input mode Function generator PV: Activate data recording Function generator PV: Clear recorded data Function generator PV: Actual record count	RW RW RW	uint(16) uint(16) uint(16) uint(32)	2 2	1 1	Technology Coli: Mode Coli: Record Coli: Clear 0x000000000000x0008CA00	0x0000 = MPP; 0xFF00 = ULIK 0x0000 = halt; 0xFF00 = continue 0xFF00 = clear 0x000000F = 15 recorded values	10 10 10	12	0x0A02 0x0A03 0x0A04 0x0A05

