Modbus address (dec)	dress (hex)	(0x01)	Read holding registers (0x03)	single coll (UXUS)	(10)	r devices with KE firmware from V2.29 (standard) of	v V2.	11 (G	Data length in bytes	Number of registers	ck the installed version in your device's MENU in item		Profibus slot / Profinet subslot	Profibus/Profinet index in slot	EtherCAT SDO/PDO?
0 1 21 41 61 81	0x0001 0x0015 0x0029 0x003D 0x0051		X X X X X			Device class Device lype Manufacturer address Manufacturer ZP code Manufacturer Phore number	R R R R	cha cha cha cha cha	40 40 40 40 40	20 20 20 20 20	ASCII	58 = PSB 9000 Series PSB 9080-120	1 1 1 1	0 1 2 3 4	x x x x
101 121 123 125 127	0x0079 0x007B 0x007D 0x007F		x x x x			Manufacturer website Nominal voltage Nominal current Nominal power Max. Internal resistance Mix. Internal resistance	R R R R	cha floa floa floa floa floa	t 4 t 4 t 4	2 2 2	Floating point number IEEE754 Floating point number IEEE754 Floating point number IEEE754	80 120 5000 25 0.02	1 1 1 1 1	10	x x x x
131 151 171 191 211	0x0097 0x00AB 0x00BF		x x x x		x	Article no. Serial no. User text Firmware version (KE) Firmware version (HM) Firmware version (FE)	R RW RW R	cha cha	40 40 40 40	20 20	ASCII ASCII ASCII	30000301 1234560001	1 1 1 1 1	13 14 15 16	x x x
402 405 407 408	0x0192 0x0195 0x0197	x x		x x		Firmware version (DR) Remote mode DC output/input Condition of DC output/input after power fail alarm Condition of DC output/input after powering the device	RW RW RW	uint(16 uint(16 uint(16	2 2 2	1	Coil : Remote Coil : Output/input Coil : Auto-On	0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on 0xFFFF = off; 0xFF00 = auto	2 2 3	1	x x x
409 410 411 416 417	0x019A 0x019B 0x01A0 0x01A1	x x		x x x		Operation mode (UPAUR) Restart of the device (warm start) Acknowledge alarms Analog interface: Reference voltage (pin VREF) Analog interface: REM-SB level	RW W W RW	uint(16 uint(16 uint(16 uint(16	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	1 1 1 1	Coil : Operation mode Coil : Restart Coil : Alarms Coil : : VREF Coil : REM-SB Level	0x0000 = UIP; 0xFF00 = UIR 0xFF00 = execute 0xFF00 = acknowledge 0xx0000 = 10V; 0xFF00 = 5V 0x0000 = normal; 0xFF00 = inverted	2 2 2 2	9 14 12	
418 425 432 440	0x01A9 0x01B0	x x	_	x x	:	Analog interface: REM-SB action Condition of DC output/input after leaving remote Reset device to factory settings Analog interface: Pin 14 configuration	RW RW RW	uint(16	2 2 2	1	Coil : Condition Coil : Condition Alarms 1	0x0000 = off; 0xFF00 = auch 0x0000 = off; 0xFF00 = unchanged 0xFF00 = Trigger reset 0x0000 = OVP (default); 0x000 = OVP; 0x000 = OPP;	2 2 2	13 42 43 44	x
441	0x01B9		х	,		Analog interface: Pin 6 configuration	RW	uint(16) 2	1	Alarms 2	0x0003 = OVP + OCP; 0x0004 = OVP + OPP; 0x0005 = OVP + OPP; 0x0006 = OVP + OCP + OPP 0x0000 = OT + PF (default); 0x0001 = OT; 0x0002 = PF	2	45	х
	0x01BA 0x01BB		x	,		Analog interface: Pin 15 configuration Analog interface: Pins 9 and 10 configuration	RW	uint(16	2) 2	1	Current and voltage monitor	0.0000 = CV; 0.0001 = DC output status 0.00001 = DC output status 0.00001 = DG output status 0.00001 = Distant (VMON on pin 9 and CMON on Pin 10 / Pin 10 signals current flom source or sink); 0.00001 = Pin 10 (CMON) only signals sink current (EL); 0.00002 = Pin 10 (CMON) only signals source current (PS); 0.00003 = Current mode A [source current (PS) on pin 9 and sink current (EL) on pin 10 (full range); 0.00004 = Current mode B [source current (PS) on pin 10 and sink current (EL) on pin 9 (full range); 0.00005 = Pin 10 (CMON) signals ELIPS current (010 V ~= -100%0100%, half range signal)	2	50	
498 499 500 501 502 503	0x01F3 0x01F4 0x01F5		x x x x)	:	Sink mode: Set power value Sink mode: Set ocurrent value Set voitage value Set current value (PSB/PSBE devices: source mode) / Irradiation (Simple PV) Source mode: Set power value Source mode: Set resistance value	RW RW RW RW RW	uint(16 uint(16	2) 2 2) 2 2) 2 2) 2	1 1	0x0000 - 0xD0ES (0 - 102%) (0x0000 - 0xD0ES (0 - 102%) 0x0000 - 0xD0ES (0 - 102%) 0x0000 - 0xD0ES (0 - 102%) 0x0000 - 0xD0ES (0 - 102%) variable - 0xD0ES (x - 102%) The minimum percent value needs to be calculated from	Power value (for translation see programming guide) Current value (for translation see programming guide) Voltage value (for translation see programming guide) Current value (for translation see programming guide) Power value (for translation see programming guide) Resistance value (for translation see programming guide)	2	21 20 23 24 25 26	
	0x01F8		x)		Sink mode: Set resistance value Device state	RW	uint(16 uint(32) 2	1 2	The minimum percent value needs to be calculated from the rating, see technical specs Bit 0-4: Control location	Resistance value (for translation see programming guide) 0x00 = free: 0x01 = locati 0x03 = USB: 0x04 = analog; 0x05 = Profilbus; 0x06 = Ethernet: 0x08 = Master/Slaye: 0x09 = RS232; 0x10 = CANoper; 0x12 = Modbus TCP 1P; 0x13 = Profinet 1P; 0x14 = Ethernet 1P: 0x15 = Ethernet 2P; 0x16 = Modbus TCP 2P;	2	22	
											Bit 6 : Master-slave type Bit 7 : Output state Bit 9-10 : Regulation mode	0x17 = Profinet 2P; 0x18 = GPB; 0x19 = CAN; 0x1A = EtherCAT 0 = Stave; 1 = Master 0 = off; 1 = on 0 = off; 1 = on 0 = off; 1 = CP; 10 = CC; 11 = CP 0 = off; 1 = on			
											Bit 12 : PSB/PSBE 9000 operation mode	0 = source; 1 = sink 0 = stopped; 1 = running 0 = off; 1 = on 0 = none; 1 = active 0 = none; 1 = active			
											Bit 18 : OPP Bit 19 : OT Bit 21-23: Power fail Bit 24 : UVD	0 = none; 1 = active			
											Bit 26 : UCD Bit 27 : OCD Bit 28 : OPD Bit 29 : MSP Bit 30 : REM-SB	0 = none; 1 = active 0 = none; 1 = none;			
508	0x01FC 0x01FD	1	x x x		<u> </u>	Actual voltage Actual current Actual power Court of OV alarms since power up	R R	uint(16 uint(16 uint(16	2 2	1	0x0000 - 0xFFFF (0 - 125%) 0x0000 - 0xFFFF (0 - 125%)	0 = source mode; 1 = sirk mode Actual voltage (for translation see programming guide) Actual current (for translation see programming guide) Actual power (for translation see programming guide)		28 29 30	
521 522 523	0x0209 2 0x020A 3 0x020B 4 0x020C		x x x x			Court of OY alarms since power up Source mode: Court of OC alarms since power up Source mode: Court of OP alarms since power up Court of OT alarms since power up Court of OF alarms since power up Sink mode: Court of PF alarms since power up	R R R		2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2		0x0000 - 0xFFFF			21 22 23 24 25	x
	0 0x0226 0 0x0229 0 0x022C		x x x)		Sink mode: Count of OP alarms since power up Overvoltage protection threshold (OVP) Source mode: Overcurrent protection threshold (OCP) Source mode: Overpower protection threshold (OPP)	RW RW RW	uint(16 uint(16) 2	1 1 1	0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xE147 (0 - 110%)	OVP tireshold (for translation see programming guide) OCP tireshold (for translation see programming guide) OCP tireshold (for translation see programming guide)	3 3	6	x x
559 560 561 562 563	0 0x0230 0x0231 0x0232 0x0232		x x x x)		Source mode: Undervoltage detection (UVD) Source mode: Adjustable UVD notification Source mode: Overvoltage detection (OVD) Source mode: Adjustable OVD notification Source mode: Undercurrent detection (UCD) Source mode: Undercurrent detection (UCD) Source mode: Adjustable UCD notification	RW RW RW RW	uint(16 uint(16 uint(16 uint(16	2) 2) 2) 2) 2	_	Adjustable OVD notification 0x0000 - 0xD0E5 (0 - 102%)	UVD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm OVD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm UCD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm	3 3 3	10 11 12 13	x x x
565 566 567 568 569	0x0236 0x0237 0x0238 0x0238		x x x x)	1	Source mode: Overcurrert detection (OCD) Source mode: Adjustable OCD notification Source mode: Overpower detection (OPD) Source mode: Adjustable OPD notification Sink mode: Overcurrent protection threshold OCP	RW RW RW RW	uint(16 uint(16 uint(16 uint(16) 2) 2) 2) 2	1 1 1	0x0000 - 0xD0E5 (0 - 102%) Adjustable OCD notification 0x0000 - 0xD0E5 (0 - 102%) Adjustable OPD notification	CCD treshold (for translation see programming guide) 0x0000 - nothing; 0x0001 = signat; 0x0002 = warning; 0x0003 = alarm OPD treshold (for translation see programming guide) 0x0000 - nothing; 0x0001 = signat; 0x0002 = warning; 0x0003 = alarm CCP treshold (for translation see programming guide)	3 3 3	15 16 17 18 4	x x x
570 571 572 573 574 575	0x023A 0x023B 0x023C 0x023C 0x023D 0x023E 0x023F		x x x x)	i .	Sink mode: Overpower protection threshold OPP Sink mode: Undercurrent detection UCD Sink mode: Adjustable UCD molification Sink mode: Adjustable UCD molification Sink mode: Overcurrent detection OCD Sink mode: Overpower detection OFD Sink mode: Overpower detection OPD	RW RW RW RW	uint(16 uint(16 uint(16 uint(16 uint(16 uint(16	2 2 2 2 2	1 1 1 1	0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xD0E5 (0 - 102%) Adjustable UCD notification 0x0000 - 0xD0E5 (0 - 102%) Adjustable OCD notification	OPP threshold (for translation see programming guide) UCD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signat 0x0002 = warring; 0x0003 = alairm 0x0000 = nothing; 0x0001 = signat 0x0002 = warring; 0x0003 = alairm 0x0000 = nothing; 0x0001 = signat 0x00002 = warring; 0x0003 = alairm 0x0000 = nothing; 0x0001 = signat 0x00002 = warring; 0x0003 = alairm	3 3 3 3	31 32 33	х
576 577 650 653	0x0240 0x0241 0x028A 0x028D	1	x	x		Sink mode: Adjustable OPD notification Condition of DC output/input after OT alarm Master-slave: Link mode on MS bus Master-slave: Enable MS	RW RW RW	uint(16 uint(16 uint(16 uint(16	2 2	1 1	Adjustable OPD notification Reg: Condition Coil: Mode Coil: MS on/off	0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm 0x0000 = off; 0x0001 = restore (default) 0x0000 = Slave; 0xFF00 = Master 0x0000 = Slave; 0xFF00 = on	3 3 4 4	36 37 0 3	x
654 655 656	0x028E 0x028F 0x0290		x	×		Master-slave: hit MS Master-slave: Condition Master-slave: Total voltage in V	W R	uint(16 uint(16		1 1 2	Coll: MS start init Reg: MS status Floating point number IEEE754	0xFF00 = Start init 0x0000 = not initialised; 0x0001 = init running; 0x0003 = set defaults; 0x0004 = setup initrace; 0x0005 = assignment; 0xFFF0 = disrupted; 0xFFF0 = different models detected, init not OK; 0xFFFE = error; 0xFFFF = init OK 500	4	5	x
658 660 662 850	0x0292 0x0294 0x0296 0x0352	1	x x x	x x	£	Master-slave: Total courset in A Master-slave: Total power in A Master-slave: Total power in W Master-slave: Number of initialised slaves Function generator Arbitrary: Start/stop Function generator Arbitrary: Steet U	R R R	floa floa uint(16	t 4 t 4	1	Floating point number IEEE754 Floating point number IEEE754 Coil : Start/Stop	0000 150000 135 0x0000 = Slop; 0xFF00 = Start 0x0000 = not assigned; 0xFF00 = Assign function to voltage	4 4 5	7 8 9	x x x
852 856 859	0x0354	x x		x			RW RW RW	uint(16 uint(16 uint(16 uint(16	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	1 1 1	Coil : U Coil : I Reg: Mode	0.00000 = not assigned; 0xFF00 = Assign function to voltage 0x00000 = not assigned; 0xF000 = Assign function to current 0x00000 = deact valed; 0x6001 = 1.0 Source; 0x6001 = 1.0 Source; 0x60001 = 1.0 Source; 0x60002 = 1.0 Sink; 0x60002 = 1.0 Sink; 0x600000 = 1.0 Sink; 0x60000 = FV 1: 0x600000 = FV 1: 0x600000 = FV 1: 0x60000 = FV 2: 0x60000 = Battery	5	9	x
861 862	0x035D	<u> </u>	x	x	×	Function generator Arbitrary; Setup for sequence 1 Function generator Arbitrary; Setup for sequence 1	RW W	uint(16	2 32	1	0x00000x03E7 Coil : Submit Arbitrary	0x0000 = infinite 0xFF00 = Submit settings Floating point number in IEEE754 format, see device manual for value range, chapter about function generator	5	0	x
											Bytes 8-11: fs(1/T) in Hz Bytes 12-15: fs(1/T) in Hz Bytes 16-19: Angle in degrees Bytes 20-23: Us/fs(DC) in V Bytes 24-27: Ue/le(DC) in V	Integer in EEE754 format: 010000 Hz Integer in EEE754 format: 010000 Hz Integer in EEE754 format 0"3099 Integer in EEE754 format 0"399" Floating point marber in EEE754 format, see device manual for value range, chapter about function generator			
↓ 2468	↓ 8 0x035D	↓ 	1	1 1	×	Function generatorArbitrary: Setup for sequence 99	↓ RW	floa	. ↓ t 32	16	Bytes 28-31: Sequence time in µs	Floating point number in IEEE754 format: 100 µs36,000,000,000 µs Floating point number in IEEE754 format see device manual for value range, chapter about function generator Wedger in EEE754 format: 010000 Hz	6	98	×
											Bytes 16-19: Angle in degrees Bytes 20-23: Us/fs[OC] in V Bytes 24-27: Us/fs[OC] in V Bytes 28-31: Sequence time in µs	hteger in IEEE784 format: 0*359* Floating point number in IEEE784 format, see device manual for value range, chapter about function generator Floating point number in IEEE784 format: 100 µs36,000,000,000 µs			L
2600 ↓ 6680	1	1	x ×	1 1	×	Function generator XY: Table 1 (PS), block 0	RW ↓ RW) 32 ↓) 32	1	IU mode: set current value for source mode (PS) (16 values block) IU mode: set current value for source mode (PS) (16 values block)	value = real set value of current * 0.8 / hom * 32768	7	0 ↓ 255	x ×
9000 9001 9002 9003 9004 9005			x x x x)	I	Upper limit of voltage set value (U-max) Lower limit of voltage set value (U-min) Source mode: Upper limit of current set value (I-min) Source mode: Upper limit of current set value (I-min) Source mode: Lower limit of current set value (I-min) Source mode: Upper limit of power set value (P-max)	RW RW RW RW	uint(16	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	1 1 1 1	0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%)	Voltage value (for translation see programming guide) Voltage value (for translation see programming guide) Current value (for translation see programming guide) Current value (for translation see programming guide) Power value (for translation see programming guide)	2 2 2	31 32 33 34 35	x x x
9005	0x232E		x)		Sink mode: Upper limit of power set value (P-max) Source mode: Upper limit of resistance set value (R-max) Sink mode: Upper limit of resistance set value (R-max)	RW	uint(16 uint(16 uint(16) 2	1	variable - 0xD0E5 (x - 102%) The minimum percent value needs to be calculated from the rating, see technical specs	Power value (for translation see programming guide) Resistance value (for translation see programming guide) Resistance value (for translation see programming guide)	2	36 37 39	x
9008 9009 0007 0008	0x2717 0x2718	_		x	_	Sink mode: Upper limit of current set value (I-max) Sink mode: Lower limit of current set value (I-min) Ethernet: TCP keep-alive timeout Ethernet/Profinet/Modbus TCP: DHCP	RW RW RW	uint(16 uint(16 uint(16) 2	1	0x0000 - 0xD0E5 (0 - 102%) 0x0000 - 0xD0E5 (0 - 102%) Coil: Keep-alive on/off Coil: DHCP on/off	Currert value (for translation see programming guide) Current value (for translation see programming guide) 0x0000 = off; 0xFF00 = on 0x0000 = off; 0xFF00 = on	2	40	x
0010 0011 0012 0013 0020	0x271C 0x271D	x x x	\pm	x x x		Protocol SCPI Restart interface card Modbus specification compliance Ary@us module: Type	RW RW RW RW	uint(16	2 2 2 2 2	1	Coll: Restart Coll: Mode Reg: Type	0x8000 = 0ff, 0xFF00 = on 0x6000 = off, 0xFF00 = on 0xFF00 * Trigger restart 0x0000 = Limited (default); 0xFF00 = Full 0x0000 = Profile 0x0000 = Profile 0x0000 = Profile			_
												0x0010 = CANopen 0x0011 = Devicenet 0x0012 = Modobus-TCP 1P 0x0013 = Profinet 1P 0x0014 = Ethernet 1P 0x0015 = Ethernet 2P			İ
	0x2725	_	x			Any6us module: Interface type	R	0110		20		0x0016 = Modbus-TCP 2P 0x0017 = Politier t2P 0x0019 = CAN 0x0016 = EtherCAT 0x00FF = no or unknown module plugged "Profibus DPV1"			
0251 0252 0253 0269	0x280C 0x280D 0x281D		x x x x)		AnyBus module: Version number AnyBus module: Serial number Profibus: Ident number Profibus: CANoper: Node address Profibus: CANoper: Node address Profibus/Profinet: User-defineable "Function tag" Profibus/Profinet: User-defineable "Location tag"	R RW RW RW	uint(16 cha cha) 4) 2) 2 ; 32 ; 22	11	ASCII	0xA001 Profibus: 0-125; CANopen: 0-127 "Test"	8 8 8	0 1 2 3	
0280 0300 0354 0502 0504 0506	0x2828 0x283C 0x2872 0x2906 0x2908 0x2908		X X X X		x x x	Profibus/Profinet User-defineable instalation date Profibus/Profinet User-defineable description Profinet User-defineable "Station name" Ethemet/Modbus TCP: P. address Ethemet/Modbus TCP: Subnot mask Ethemet/Modbus TCP: Subnot mask	RW RW RW RW	cha cha	54	27 100 2 2		"13.01.2012 09:59:00" "www.webpage.de" "Test" 192.168.0.2 (default) 192.168.0.1 (default) 192.168.0.1 (default)	8 8	4 5 6	_ -
0508 0535 0562 0564 0566	0x290C 0x2927 0x2942 0x2944 0x2944 0x2946		X X X X	,	X X X	Ethernet/Profinet/Modbus TCP: Host name Ethernet/Profinet/Modbus TCP: Donain name Ethernet/Modbus TCP: DNS 1 Ethernet/Modbus TCP: DNS 2 RS232/USB: Connection timeout in milliseconds	RW RW RW RW	cha cha uint(8 uint(8 uint(16	54 54 4 4 2	27 27 2 2 1	ASCII ASCII Bytes 0-3: 0255 Bytes 0-3: 0255 565535	"Clent" (default) "Workgroup" (default) 0.0.00 (default) 0.0.00 (default) 0.0.00 (default) Default: Sms			
0567 0570	0x294A		x)		Ethernet/Profinet/Modbus TCP: MAC Ethernet/Modbus TCP: Connection speed Part 1 (1 & 2 part modules)	RW	uint(16) 6	1	Connection speed	0.550 (2.5312.34 or 00.50-(2.433-12.34 0.00000 = Auto; 0.00001 = 10Mbit half duplex; 0.00002 = 10Mbit flad duplex; 0.00003 = 100Mbit half duplex; 0.00004 = 100Mbit full duplex			_
	0x294B		x)		Ethernet/Modbus TCP: Connection speed Port 2 (2 port module) Ethernet/Modbus TCP: Port Ethernet/TCP Socket timeout (in seconds)	RW RW	uint(16) 2	1	065535	0x0000 = 10Mbit half duplex; 0x0001 = 10Mbit half duplex; 0x0002 = 10Mbit half duplex; 0x0003 = 100Mbit half duplex; 0x0004 = 100Mbit half duplex; 0x0004 = 100Mbit half duplex 9026 (default), except port 80			
		_	x	,	_	RS232/CANopen/CAN: Baud rate	RW		2		Baud rate	CAN			
0701 0702 0704 0706	0x29CD 0x29CE 0x29D0 0x29D0	x	_	x	×	CAN: D format CAN: Termination CAN: Base ID CAN: Broadcast ID	RW RW RW	uint(16 uint(32) 2) 2) 4	1 2	Coil: Base/Extended Coil: Bus termination 0x00000x07FF or 0x00000x1FFFFFFFF 0x00000x07FF or	0x09: Autobaud 0x0000 = Base (11 Bit); 0xFF00 = Extended (29 Bit) 0xx0000 = off; 0xFF00 = on Default: 0x0000 Default: 0x7FF			_
0709 0710 0712	0x29D6	\perp	x x	×	×	CAN: Oata length CAN: Cyclic read: Base ID CAN: Cyclic send: Base ID CAN: Cyclic send: Base ID CAN: Cyclic send: Base ID	RW RW RW	uint(32 uint(32) 2	2	0x00000x07FF or 0x00000x1FFFFFFFF 0x00000x37FF or 0x00000x1FFFFFFFF	0x0000 = Auto; 0xFF00 = Always 8 bytes Default: 0x100 Default: 0x200 Default: 0x200			
0715 0716 0717 0718 0721	0x29DB 0x29DC 0x29DD 0x29DD		x x x	3		CAN: Cyclic read time (in ms): Set value (U, I, P, R) CAN: Cyclic read time (in ms): Limits 2 (P, R) CAN: Cyclic read time (in ms): Limits 1 (U, I) CAN: Cyclic read time (in ms): Actual values U, I, P CAN: Cyclic read time (in ms): Set value (I, P, R) (only PSB/PSBE devices, sink mode)	RW RW RW RW	uint(16 uint(16 uint(16 uint(16	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	1 1 1	205000; 0 == off 205000; 0 == off 205000; 0 == off 205000; 0 == off 205000; 0 == off	Default off			_
0722 0900 1000 1001 1002	0x2A94 0x2AF8	<u> </u>	x x x)		CAN Cyclic read time (in ms): Limits 3 (i, P, R) (only PSB/PSBE devices, sink mode) GPB address (option 3W) MPP Tracking: MPP-Mode MMPP Tracking: Unc (Setup) MPP Tracking: the (Setup)	RW RW RW RW	uint(16 uint(16 uint(16	2 2	1 1	130 0.4 0x0000 - 0xCCCC (0 - 100%)	Default: off 0 = off; 1 = MPP1; 2 = MPP2; 3 = MPP3; 4 = MPP4 Voltage value in % of Unom (for translation see programming guide) Currert value in % of hom (for translation see programming guide)	9	0 1	×
1003 1004 1005 1006			x x x)		MPP Tracking: Umpp (Sekup) MPP Tracking: Umpp (Sekup) MPP Tracking: Pmpp (Sekup) MPP Tracking: DeltaP (Sekup) MPP Tracking: DeltaP (Sekup) MPP Tracking: DeltaP (Sekup)	RW RW RW RW	uint(16 uint(16 uint(16 uint(16 uint(16	2 2 2 2	1 1 1	0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Unom (for translation see programming guide) Curret value in % of home (for translation see programming guide) Power value in % of Prom (for translation see programming guide) Power value in % of Prom (for translation see programming guide) Power value in % of Prom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide)	9 9	3 4 5 6	x x x
1008 1009 1010 1011 1012 1013	0x2B02 0x2B03 0x2B04	x x	x	x		MPP Tracking: https://dischulin.MPP1/2/4) MPP Tracking: Prepp (Result in MPP1/2/4) MPP Tracking: Start/Stop MPP Tracking: Finished (Function status for MPP1/2/4) MPP Tracking: Error during function MPP-Tracking: Error during function MPP-Tracking: Interval (Setup)	R RW R R	uint(16 uint(16 uint(16 uint(16 uint(16 uint(16	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2		Coll: Start/Stop Coll: Status Coll: Error	Current value in % of horn (for translation see programming guide) Power value in % of Prom (for translation see programming guide) 0x0000 = stop; 0xFF00 = start 0x00000 = nunning; 0xFF00 = finished 0x0000 = no enter; 0xFF00 = error Regulation & measuring interval in milliseconds, either for tracking in modes 1	9 9 9	9 10 11 12	
1014			x	,	:	MPP4 : Start MPP4 : Trid MPP4 : Repositions	RW RW	uint(16 uint(16) 2	1 1	0x0001 - 0x0064 0x0001 - 0x0064	and 2 of for user curve progression in mode 3 Start voltage value out of 100 (related to registers 11100-11199) for use in MPP4 mode End voltage value out of 100 (related to registers 11100-11199) for use in MPP4 mode 0,0000 — no repetitions	9	14	x
1100 1120 1140 1160 1180	0x2B5C 0x2B70 0x2B84 0x2B98 0x2BAC		x x x x		x x x	MPP Tracking: User curve (MPP4 mode) voltage values 1-20 MPP Tracking: User curve (MPP4 mode) voltage values 21-40 MPP Tracking: User curve (MPP4 mode) voltage values 41-60 MPP Tracking: User curve (MPP4 mode) voltage values 61-80 MPP Tracking: User curve (MPP4 mode) voltage values 81-100	RW RW RW RW	uint(16 uint(16 uint(16 uint(16	40 40 40 40 40 40	20 20 20 20	0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Unom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide)	9 9	17 18 19 20 21	x x x
1200	0 0x2BC0 0 0x2BDE		x	+	 	MPP Tracking: User curve (MPP4 mode) results 1-10 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 11-20 (10x Umon, Imon, Pmon)	R	uint(16			0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Unom Currert value in % of Inom Power value in % of Prom (for translation see programming guide) Voltage value in % of Unom Currert value in % of Inom Power value in % of Prom	9	22	
1230	0 0x2BFC		x	+	‡	MPP Tracking: User curve (MPP4 mode) results 21-30 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 31-40 (10x Umon, Imon, Pmon)	R	uint(16			0x0000 - 0xCCCC (0 - 100%)	(for translation see programming guide) Voltage value in % of furom Currert value in % of furom Power value in % of Prom (for translation see programming guide) Voltage value in % of Urom	9	24	
1260	0 0x2C1A 0 0x2C38		x		-	MPP Tracking: User curve (MPP4 mode) results 31-40 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 41-50 (10x Umon, Imon, Pmon)	R	uint(16			0x0000 - 0xCCCC (0 - 100%)	Curren't value in % of hom Power value in % of Prom (for translation see programming guide) Voltage value in % of Unom Curren't value in % of hom Power value in % of Prom	9	25	
1260	0 0x2C56 0 0x2C74		x		+	MPP Tracking: User curve (MPP4 mode) results 51-60 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 61-70 (10x Umon, Imon, Pmon)	R	uint(16			0x0000 - 0xCCCC (0 - 100%)	(for translation see programming guide) Voltage value in % of Unom Curret value in % of Inom Power value in % of Prom (for translation see programming guide) Voltage value in % of Unom	9	27	
1290 1320	0x2C92		x	+		MPP Tracking: User curve (MPP4 mode) results 71-80 (10x Umon, Imon, Pmon)	R	uint(16	60	30	0x0000 - 0xCCCC (0 - 100%)	Current value in % of hom Power value in % of Prom (for translation see programming guide) Voltage value in % of Unrom Current value in % of hrom Power value in % of Prom (for translation see programming guide)	9	29	
1290 1320 1350 13410	↓ 「	\dagger	x	1	1	MPP Tracking: User curve (MPP4 mode) results 81-90 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 91-100 (10x Umon, Imon, Pmon)	R	uint(16			0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Unom Current value in % of hom Dewer value in % of Prom (for translation see programming guide) Voltage value in % of Unom Current value in % of hom	9	30	
1290 1320 1350 13410	0 0x2CB0		x x	 	×	Battery discharge test (static): Max. power Battery discharge test (static): Max. resistance	RW RW	floa	t 4	2	Floating point number IEEE754 Floating point number IEEE754 Floating point number IEEE754	Power value in % of Pnom (for translation see programming guide) 0 - rated current 0 - rated power Min max. resistance, 0 = OFF	11 11	2	x x
1260 1290 1320 1350 13410 1440 1470	0x2CCE		х	,	×	Battery discharge test (static): Discharge voltage	RW RW RW	floa floa uint(32	4 t 4 t 4) 4	2 2	Floating point number IEEE754 Floating point number IEEE754 0x00000000 - 0x0000A0000 (0 - 10 h) Action when reaching max. discharge capacity	0 - rated voltage 0 - 99999.99 0x00010203 = 01:02:03 as HH+MM:SS, equivalent to [00][HRS][MIN][SEC] 0x0000 = Do nothing; 0x0001 = Signal (see register 11544);	11 11 11 11	3	x x x
1290 1320 1350 1380 1440 1470 1502 1504 1506	0x2CCE 0x2CEC 0x2CEC 0x2CEE 0x2CF0 0x2CF2 0x2CF4		x x x	1	×	Battery discharge test (static): Action upon reaching the max. discharge time Battery discharge test (dynamic): Current level 1 Battery discharge test (dynamic): Current level 2	RW RW		t 4	1 2	Action upon reaching the max. discharge time	0x0001 = Signal (see register 11544); 0x0002 = Stop lest t 0x0002 = Stop lest t 0x00001 = Signal (see register 11544); 0x0001 = Signal (see register 11544); 0x0002 = Stop lest t 0 - rated current	11	7 8 9	x
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1290 1320 1350 1380 1440 1440 1470 1502 1504 1518 1516 1518 1516 1518 1518 1518 1518	0x2CCE 0x2CEC 0x2CEE 0x2CF0 0x2CF0 0x2CF4 0x2CF6 0x2CF6 0x2CF6 0x2CF8 0x2CF9 0x2CF9 0x2CFA 0x2CFC 0x2CFC 0x2CFA 0x2CFC 0x2CFA 0x2CFC 0x2CFA		x x x x x x x x x x x x x x x x x x x	,	X X X	Battery discharge test (dynamic): Time of current level 2 Battery discharge test (dynamic): Max. power Sattery discharge test (dynamic): Discharge voltage Battery discharge test (dynamic): Max. capacity to discharge	RW RW RW RW	floa	t 4 t 4	2 2	Floating point number IEEE754 Floating point number IEEE754		11	15 16	x
1290 1320 1330 1360 1360 1360 1360 1360 1360 136	0x2CCE 0x2CEC 0x2CEC 0x2CED 0x2CF0 0x2CF4 0x2CF6 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CFB		x x x x x x x x x x x x x x x x x x x)	x x x x	Battery discharge test (dynamic): Time of current level 2 Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Discharge voltage	RW RW	floa	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	2 2	Floating point number EEE754 Floating point number EEE764 Floating point number EEE764 Floating point number EEE764 Cxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx	0x00010203 = 01:02:03 as H+MM:SS, equivalent to [00][HRS][MN][SEC] 0x0000 = Do nothing; 0x0001 = Signal (see register 11544); 0x0002 = Stop test 0x0000 = Do nothing; 0x0001 = Signal (see register 11544);	. [18	x
1290 13320 1350 1350 1350 1350 1350 1350 1350 135	0x2CCE 0x2CEC 0x2CEC 0x2CED 0x2CF0 0x2CF2 0x2CF4 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CFB 0x2CFB 0x2CFB 0x2CFB 0x2DFB 0x2DOB 0x2DOB 0x2DOB 0x2DOB	x	x x x x x x x x x x x x x x x x x x x	,	x x x x	Battery discharge test (dynamic): Time of current level 2 Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Discharge voltage Battery discharge test (dynamic): Max. capacity to discharge Battery discharge test (dynamic): Max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge capacity	RW RW RW RW	floa floa floa uint(32 uint(16 uint(16	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	2 2 2 2 1 1	Floating point number EEET74	0x0000 = Do nothing; 0x0001 = Signal (see register 11544); 0x0002 = Stop test 0x0000 = Do nothing; 0x0001 = Signal (see register 11544); 0x0002 = Stop test 0x0002 = Stop test 0x0000 = Stop; 0xFF00 = Run 0x0000 = Stop; 0xFF00 = Run 0x0000 = Stop; 0xFF00 = Run 0x00001 = Static discharge; 0x0001 = Static discharge; 0x00003 = Static charge;	11	22 23 24	
1320 1320 1330 1340 1350 1360 1360 1360 1360 1360 1360 1360 136	0x2CCE 0x2CEC 0x2CEC 0x2CED 0x2CF0 0x2CF0 0x2CF1 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF0 0x2CFB 0x2CFB 0x2DF0 0x2DF0 0x2D04 0x2D04 0x2D08 0x2D08 0x2D0B 0x2D0B 0x2D0B 0x2D0B 0x2D0B 0x2D0C	x	x x x x x x x x x x x x x x x x x x x)	x x x x	Battery discharge test (dynamic): Time of current level 2 Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Discharge voltage Battery discharge test (dynamic): Max. capacity to discharge Battery discharge test (dynamic): Max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge capacity Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge time	RW RW RW RW RW	floa floa floa uint(32 uint(16 uint(16	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	2 2 2 2 1 1 1 1 1 2	Floating point number EEET74	0x0000 = Do nothing; 0x0001 = Signal (see register 11544); 0x0002 = Stop Lest 0x0001 = Stop Lest 0x0001 = Stop Lest 0x0001 = Do nothing; 0x0001 = Signal (see register 11544); 0x0001 = Stop Lest 0x00002 = Stop Lest 0x00000 = Stop; 0xFF00 = Run 0x00000 = Stop; 0xFF00 = Rid 0x00001 = Stop; 0xFF00 = Rid 0xFF00001 = Rid 0xFF0001 = Rid 0xFF001 =	11	1	×
11290 11320	0x2CCE 0x2CEC 0x2CEC 0x2CEC 0x2CF2 0x2CF3 0x2CF4 0x2CF4 0x2CF6 0x2CF6 0x2CF6 0x2CF6 0x2CF6 0x2CF6 0x2CF6 0x2DF0 0x2D04 0x2D04 0x2D08 0x2D04 0x2D08 0x2D04 0x2D04 0x2D05 0x2D04 0x2D04 0x2D06 0x2D06 0x2D07 0x2D07 0x2D07 0x2D08 0x2D09 0x2D10 0x2D10 0x2D11 0x2D18 0x2D19 0x2D18 0x2D19 0x2D19 0x2D19 0x2D19	×	x x x x x x x x x x x x x x x x x x x)	x x x x	Battery discharge test (dynamic): Time of current levet 2 Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. discharge voltage Battery discharge test (dynamic): Max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge capacity Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery test: Start/stop Battery test: Start/stop Battery test: Discharged capacity in Ah Battery test: Discharged capacity in Ah Battery test: Discharged energy in Wh Battery test: Time at end of test Battery charge test (static): Max. Voltage Battery charge test (static): Charge current Battery charge test (static): Max. capacity to charge	RW R	floa floa floa uint(32 uint(16 uint(16 uint(16 uint(16 uint(16 uint(16 uint(16 doa floa doa floa floa floa floa floa floa floa fl	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	2 2 2 2 1 1 1 1 1 1 1 1 1 2 2 2 2 2 2 2	Floating point number EEEE74 Floating point number EEEE754 Floating point number EEEE754 Floating point number EEEE754 Rob00000000 - 0x000A0000 (0 - 10 h) Action Action Coil: Start/Stop Mode selection xAh x Wh HHMM:SS.MS Bit 0 : Battery test mode off (default) Floating point number EEEE754 Floating point number EEE754 Floating point number EEE754 Floating point number EEE754 Floating point number EEE754	Dx0000 = Do nothing; Dx0000 = Signal (see register 11544); Dx0000 = Signal (see register 11544); Dx0000 = Do nothing; Dx0000 = Signal (see register 11544); Dx0000 = Signal (see register 11544); Dx0000 = Step: OxFF00 = Run Dx00000 = Batter (see register 11544); Dx0000 = Step: OxFF00 = Run Dx00000 = Step: OxFF00 = Run Dx00000 = Patiend sticharter; Dx00001 = Patiend sticharter; Dx00001 = Patiend sticharter; Dx00001 = Patiend sticharter; Dx00001 = Dx00000 = Patiend (see Step: Dx000000000000000000000000000000000000	111 111 111 111 111	26 27 29 30	
1290 11320 1	0x2CCE 0x2CEC 0x2CEC 0x2CEC 0x2CEC 0x2CF2 0x2CF3 0x2CF4 0x2CF2 0x2CF3 0x2CF4 0x2CF3 0x2CF3 0x2CF4 0x2CF3 0x2CF4 0x2CF3 0x	x	x x x x x x x x x x x x x x x x x x x)	x x x x x x x x x x x x x x x x x x x	Battery discharge test (dynamic): Time of current level 2 Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. capacity to discharge Battery discharge test (dynamic): Max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge capacity Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery test: Start/stop Battery test: Start/stop Battery test: Mode selection Battery test: Discharged capacity in Ah Battery test: Discharged energy in Wh Battery test: Time at end of test Battery test: Status 2 Battery charge test (static): Charge current Battery charge test (static): Charge current Battery charge test (static): Charge current	RW R	floa floa floa int(32 int(16 int(16) int(16) int(16) int(16) floa int(16) floa floa floa floa floa floa floa floa	1 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	2 2 2 2 1 1 1 2 2 2 2 2 2 2 2 1 1	Floating point number EEET74	0x0000 = Do nothing; 0x00010 = Signal (see register 11544); 0x0001 = Signal (see register 11544); 0x00010 = Signal (see register 11544); 0x0001 = Signal (see register 11544); 0x0001 = Signal (see register 11544); 0x0001 = Signal (see register 11544); 0x001 = Signal (see register 11544); 0x001 = On nothing; 0x0001 = Signal (see register 11544);	11 11 11 11	26 27 29	x
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11290 11320	0x2CCE 0x2CEC 0x2CEC 0x2CEC 0x2CEC 0x2CF8 0x2CF0 0x2CF0 0x2CF0 0x2CD0 0x2D00 0x2D00 0x2D00 0x2D00 0x2D00 0x2D01	x	x x x x x x x x x x x x x x x x x x x)	X	Battery discharge test (dynamic): Time of current level 2 Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. dapacity to discharge Battery discharge test (dynamic): Max. discharge time Battery discharge test (dynamic): Max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge capacity Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery test: Start/stop Battery test: Start/stop Battery test: Discharged capacity in Ah Battery test: Discharged capacity in Ah Battery test: Discharged capacity in Ah Battery test: Time at end of test Battery test: Status 2 Battery charge test (static): Action upon reaching the max. discharge time Battery charge test (static): Max. voltage Battery charge test (static): Max. charge time Battery charge test (static): Action upon reaching the max. capacity Battery charge test (static): Action upon reaching the max. charge time Battery charge test (static): Action upon reaching the max. charge time Battery charge test (static): Action upon reaching the max. charge time Battery dynamic test (charge): Charge current Battery dynamic test (charge): Discharge end voltage Battery dynamic test (discharge): Discharge end voltage	RW R	float	1 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	2 2 2 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Floating point number EEET54	0x0000 = Do nothing; 0x00001 = Signal (see register 11544); 0x0002 = Stop less test 0x0000 = Do nothing; 0x0001 = Signal (see register 11544); 0x0001 = Signal (see register 11544); 0x0000 = Stop Stop; 0xFF00 = Run 0x00000 = Stop; 0xFF00 = Run 0x00000 = Stop; 0xFF00 = Run 0x00000 = Stop; 0xFF00 = Run 0x00001 = Static discharge; 0x00001 = Static discharge; 0x00003 = Pulsed discharge; 0x00003 = Pulsed discharge; 0x00004 = Dyaminic test 10.5 Ah 1	111 111 111 111 111 111 111 111 111 11	26 27 29 30 31 32 33 34 35 37 38 39 40	x x x x x x
1290 1320 1320 1320 1320 1320 1320 1320 132	0x2CCE 0x2CEC 0x2CEC 0x2CEC 0x2CEC 0x2CF2 0x2CF3 0x2CF4 0x2CF6 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF8 0x2CF0 0x2CF1 0x	***************************************	x x x x x x x x x x x x x x x x x x x)	X	Battery discharge test (dynamic): Time of current level 2 Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. power Battery discharge test (dynamic): Max. dapacity to discharge Battery discharge test (dynamic): Max. dapacity to discharge Battery discharge test (dynamic): Max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge capacity Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery test: Start/stop Battery test: Start/stop Battery test: Discharged capacity in Ah Battery test: Status 2 Battery test: Status 2 Battery charge test (status): Amax. Voltage Battery charge test (status): Amax. Charge time Battery charge test (status): Max. charge time Battery charge test (status): Action upon reaching the max. charge time Battery charge test (status): Action upon reaching the max. charge time Battery charge test (status): Charge current Battery charge test (status): Charge current Battery charge test (status): Charge current Battery dynamic test (charge): Charge current Battery dynamic test (discharge): Discharge end voltage	RW R	fion floa int(32 int(16 int(16) int(16	2	2 2 2 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Floating point number EEET54 Cxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx	0x0000 = Do nothing; 0x00001 = Signal (see register 11544); 0x0002 = Stop test 1 0x00001 = Signal (see register 11544); 0x00001 = Signal (see register 11544); 0x0001 = Signal (see register 11544); 0x00001 = Signal (see register 11544); 0x00001 = Signal (see register 11544); 0x00001 = Static discharge; 0x00003 = Static charge; 0x00002 = Pused sidcharge; 0x00003 = Static charge; 0x0003 = Static charge; 0x00004 = Dynamic test 10.5 Ah 10.	111 11 1	26 27 29 30 31 32 33 34 35 37 38 39 40 41 42	x x x x x x x
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