Read coils (0x01)	× Read holding registers (0x03)	Write single coil (0x05)	Write single register (0x06) Write multiple registers (0x1	Description Device class	Access	Data type	Data length in bytes	Number of registers	Data	Example 20, 32, 34, 36 = ELR 9000 39 = EL 9000 B	Profibus slot / Profinet subslot	Profibus/Profinet index in slot
1 21 41 61 81 01	x x x x x			Device type Manufacturer Manufacturer address Manufacturer ZIP code Manufacturer phone number Manufacturer website	R R R R	string string string string string string	9 40 9 40 9 40 9 40	20 20 20 20 20	ASCII ASCII ASCII ASCII ASCII ASCII ASCII ASCII Esculia point number IEEE754	ELR 9080-170	1 1 1 1 1 1 1	1 2 3 4 5 6
21 23 25 27 29 31 51	x x x x x x			Nominal voltage Nominal current Nominal power Max. Internal resistance Min. Internal resistance Afficie no. Serial no.	R R R R R	float float float float float string	t 4 t 4 t 4 g 40 g 40	20	Floating point number IEEE754 ASCII ASCII	80 170 3500 12 0.005 33230401 100010002	1 1 1	7 8 9 10 11 12
71 91 111 131	x x x x	x	x	Ober text Firmware version (KE) Firmware version (DR) Remote mode	RW R R R	string string string string string uint(16)	40 40 40 40	20	ASCII ASCII ASCII ASCII Coii : Remote	0x0000 = off: 0xFF00 = on	1	14 15 16 17
05 x 07 x 08 09 x 10	x	x x x x	x	DC input Condition of DC input after power fail alarm Condition of DC input after powering the device Operation mode (UIP/UIR) Restart of the device (warm start) Acknowledge alarms Restart of the device (warm start)	RW RW RW W W	uint(16) uint(16) uint(16) uint(16)) 2) 2) 2) 2) 2) 2		Coil : Input Coil : Auto-On Reg : Power-On Coil : Operation mode Coil : Restart Coil : Alarms	0x0000 = off; 0xFF00 = auto-on 0x0000 = off; 0xFFF00 = auto-on 0xFFFF = off; 0xFFFE = restore 0x0000 = UIP; 0xFF00 = UIR 0xFF00 = execute 0xF000 = acknowledge	2 3 2 2 2 2	4 30 6 7 8 9
16 x 17 x 18 x 22 x 25 x 32	x	x x x x x	x	Analog interface: Reference voltage (pin VREF) Analog interface: REM-SB isvel Analog interface: REM-SB action Speed of internal voltage controller DC input after leaving remote Reset device to factory settings Analog interface: Pin 14 configuration	RW RW RW RW W RW	uint(16)	2) 2 2) 2 2) 2 1) 2 2) 2 2) 2		Coil : VREF Coil : REM-SB Level Coil : REM-SB Action Coil : Controller speed Coil : Condition Coil : Reset Alarms 1	0.00000 = 10V; 0xFF00 = 5V 0.00000 = normat; 0xFF00 = DC auto 0.00000 = DC ort; 0xFF00 = DC auto 0.00000 = Slow, 0xFF00 = fast 0.00000 = 0ff; 0xFF00 = unchanged 0xFF00 = Trigger reset 0.00000 = CVP (default); 0.00001 = OCP; 0.00002 = OPP; 0.00003 = OVP + OCP; 0.00004 = OVP + OCP;	2	14 12 13 38 42 43 44
41	x		x	Analog interface: Pin 6 configuration Analog interface: Pin 15 configuration	RW	uint(16)			Alarms 2 Status DC	0x005 = OCP + OCP; 0x006 = OVP + OCP + OPP 0x0000 = OT + PF (default); 0x0001 = OT; 0x0002 = PF 0x0000 = CV; 0x0001 = DC output status		45
600 601 602 603	x x x		x x x	Set voltage value Set current value Set power value Set power value Set resistance value Device state	RW RW RW RW) 2		0x0000 - 0xD0E5 (0 - 102%) variable - 0xCCC (x - 100%) The minimum wake depends on the model and needs to be calculated, refer to programming guide Bit 0 - 4: Control location	Voltage value (for translation see programming guide) Current value (for translation see programming guide) Power value (for translation see programming guide) Resistance value (for translation see programming guide) 0.000 = free; 0.001 = local; 0.003 = USB, 0.004 = analog; 0.005 = Profibus; 0.006 = Ethernet; 0.008 = Master/Slave; 0.009 = RS232;	2 2 2	23 24 25 26
									Bit 5 :- Bit 6 :- Master-slave type Bit 7 : Input state Bit 8 :-	0x10 = CANopen; 0x12 = Modbus TCP 1P; 0x13 = Profinet 1P; 0x14 = Ethernet 1P; 0x15 = Ethernet 2P; 0x16 = Modbus TCP 2P; 0x17 = Profinet 2P; 0x18 = GP1B; 0x19 = CAN; 0x1A = EtherCAT 0 = Slave; 1 = Master 0 = off; 1 = on		
									Bit 10-9: Regulation mode Bit 11 : Remote Bit 12 :- Bit 13 : Function generator Bit 14 : External sense Bit 14 : External sense Bit 15 : Alarms Bit 16 : OVP	00 = CV; 01 = CR; 10 = CC; 11 = CP 0 = off; 1 = on 0 = stopped; 1 = running 0 = off; 1 = on 0 = none; 1 = active 0 = none; 1 = active		
									Bit 17 : OCP Bit 18 : OPP Bit 19 : OPT Bit 20 : OTP Bit 21 : Power fail 1 Bit 22 : Power fail 2 Bit 23 : Power fail 3	0 = none; 1 = active	- - - -	
									Bit 24 : UVD Bit 25 : OVD Bit 26 : UCD Bit 27 : OCD Bit 27 : OCD Bit 28 : OPD Bit 29 : MSS Bit 30 : REM-SB	0 = none; 1 = active 0 = CR = Master-slave in secure mode 0 = DC enabled; 1 = REM-SB disables power output	- - - - -	
i07 i08 i09 i20 i21	x x x			Actual voltage Actual current Actual power Count of OV alarms since power up Count of OC alarms since power up	R R R	uint(16) uint(16) uint(16) uint(16)) 2		0x0000 - 0xFFFF (0 - 125%) 0x0000 - 0xFFFF (0 - 125%) 0x0000 - 0xFFFF (0 - 125%) 0x0000 - 0xFFFF 0x0000 - 0xFFFF 0x0000 - 0xFFFF	Actual voltage (for translation see programming guide) Actual current (for translation see programming guide) Actual power (for translation see programming guide) Count Count	2 2 3 3	28 29 30 20 21
i22 i23 i24 i50	x x x		x x	Count of OP alarms since power up Count of OT alarms since power up Count of PF alarms since power up Overvoltage protection threshold (OVP) Overcurrent protection threshold (OCP)	RW RW	uint(16)) 2		0x0000 - 0xFFFF 0x0000 - 0xFFFF 0x0000 - 0xFFFF ELR 0x0000 - 0xE147 (0 - 110%) E198: 0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xE147 (0 - 110%)	Count Count Count OVP threshold (for translation see programming guide) OCP threshold (for translation see programming guide)	3	23 24 0 3
656 659 660 661 662 663 664	x x x x x x		x x x x x x x x x	Overpower protection threshold (OPP) Undervoltage detection (UVD) Adjustable UVD notification Overvoltage detection (OVD) Adjustable OVD notification Undercurrent detection (UCD) Adjustable UCD notification	RW RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)) 2) 2) 2) 2		0x0000 - 0xE147 (0 - 110%) 0x0000 - 0xD0E5 (0 - 102%) Adjustable UVD notification 0x0000 - 0xD0E5 (0 - 102%) Adjustable OVD notification 0x0000 - 0xD0E5 (0 - 102%) Adjustable OVD notification 0x0000 - 0xD0E5 (0 - 102%) Adjustable UCD notification	OPP threshold (for translation see programming guide) \(\text{VD threshold (for translation see programming guide)} \) 0x0000 = nothing: 0x0001 = signat, 0x0002 = warning: 0x0003 = alarm \(\text{QVD threshold (for translation see programming guide)} \) 0x0000 = nothing: 0x0001 = signat; 0x0002 = warning: 0x0003 = alarm \(\text{UC threshold (for translation see programming guide)} \) 0x0000 = nothing: 0x0001 = signat; 0x0002 = warning: 0x0003 = alarm	3 3 3	6 9 10 11 12 13
65 666 667 668 50 x	x x x	x	x x x	Overcurrent detection (OCD) Adjustable OCD notification Overpower detection (OPD) Adjustable OPD notification Master-slave: Link mode Master-slave: Link mode of Share-Bus	RW RW RW RW	uint(16) uint(16) uint(16) uint(16)) 2) 2) 2) 2		0x0000 - 0x00E5 (0 - 102%) Adjustable OCD notification 0x0000 - 0x00E5 (0 - 102%) Adjustable OPD notification Coil : Mode Coil : Mode Coil : Mode	OCD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signat; 0x0002 = warring; 0x0003 = alarm 0PD threshold (for translation see programming guide) 0x0000 = nothing; 0x0001 = signat; 0x0002 = warring; 0x0003 = alarm 0x0000 = Slave; 0xFF00 = Master 0x0000 = Slave; 0xFF00 = Master	3 3	15 16 17 18 0
i53 x i54 i55	x	x x	х	Master-slave: Enable MS Master-slave: Init MS Master-slave: Condition Master-slave: Total voltage	RW RW W R	uint(16) uint(16) uint(16)) 2		Coil : MS on/off Coil : MS start init Reg : MS status Floating point number IEEE754	0x0000 = off; 0xFF00 = on 0xFF00 = Start init 0x0000 = not initiatised; 0x0001 = init running; 0x0003 = set defaults; 0x0004 = setup interface; 0x0005 = assignment; 0xFFFC = disrupted; 0xFFFD = different models detected, init not OK; 0xFFFE = error; 0xFFFF = init OK 500	4 4 4	2 3 4 5
56 60 62 50 x 51 x 52 x	x x x	x x		Master-slave: Total current Master-slave: Total power Master-slave: Number of initialised slaves Function generator Arbitany: Start/stop Function generator Arbitany: Select U	RW RW RW	floar floar uint(16) uint(16) uint(16)	t 4 t 4) 2		Floating point number IEEE754 Floating point number IEEE754 Coil : Start/Stop Coil : U	450 (5 units with 90 A rating each) 52.5 (5 units with 10.5 kW rating each) 115 0x0000 = Stop; 0xFF00 = Start 0x0000 = not assigned; 0xFF00 = Assign function to voltage	4 4 4 4 5	7 8 9 0 1
552 x 554 x 555 x 559 660 661	x x x	x x x	x x x	Function generator Arbitrary: Select I Function generator XY: Select U-I mode Function generator XY: Select I-U mode Function generator XY: Select I-U mode Function generator Arbitrary: Start sequence Function generator Arbitrary: End sequence Function generator Arbitrary: End sequence Function generator Arbitrary: Sequence cycles Function generator Arbitrary: Submit settings	RW RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)) 2		Coil : I Coil : UI Coil : I-U Dx001: I-U Dx001:0x0063 0x00010x0063 0x00000x05E7 Coil : Submit Arbitary	0x0000 = not assigned; 0xFF00 = Assign function to current 0x0000 = not assigned; 0xFF00 = Assign function to U-I curve 0x0000 = not assigned; 0xFF00 = Assign function to I-U curve 0x0000 = infinite 0xFF00 = Submit selected settings	5 5 5 5 5	4 5 9 10
000	x		×	Function generator Arbitrary: Setup for sequence 1	RW	floa	t 32	16	Bytes 0-3: Us/Is(AC) in V Bytes 4-7: Ue/Ie(AC) in V Bytes 8-11: fs(1/T) in Hz Bytes 12-15: fs(1/T) in Hz Bytes 16-19: Angle in degrees Bytes 20-23: Us/Is(DC) in V Bytes 27: Us/Is(DC) in V	Floating point number in IEEE754 format, see device manual for value range, chapter about function generator Integer in IEEE754 format 010000 Hz Integer in IEEE754 format 010000 Hz Integer in IEEE754 format 010000 Hz Integer in IEEE754 format 0350* Floating point number in IEEE754 format, see device manual for value range, chapter about function generator	6	0
68	¥	1	х	i. Function generatorArbitrary: Setup for sequence 99	↓ RW	floar	↓ ↓ t 32	↓ 2 16	Bytes 28-31: Sequence time in µs ↓ Bytes 0-3: Us/Is(AC) in V Bytes 4-7: Us/Is(AC) in V	Floating point number in IEEE/754 format ELR.9000: 100 µs36,000,000,000 µs While current mode: EL.9000 B: 10 µs36,000,000,000 µs ↓ Floating point number in IEEE/754 format, see device manual for value range, chapter about function generator		↓ 98
									Bytes 8-11: fs(1/T) in Hz Bytes 12-15: fe(1/T) in Hz Bytes 12-15: fe(1/T) in Hz Bytes 16-19: Angle in degrees Bytes 20-23: Usl's(JCC) in V Bytes 24-27: Uel'le(DC) in V Bytes 28-31: Sequence time in µs	Integer in IEEE754 format 010000 Hz Integer in IEEE754 format 010000 Hz Integer in IEEE754 format 010000 Hz Integer in IEEE754 format 03097 Floating point number in IEEE754 format, see device manual for value range, chapter about function generator Floating point number in IEEE754 format ELR 9000 100 Jun. 36,000.000,000 us EL 9000 8: 10 jun. 36,000.000 (00 jun.		
600 1	x ↓ x	1	x x	Function generator: XIY table, block 0 Function generator: XIY table, block 255	RW	uint(16)	1	16 1	Ul mode: set voltage value IU mode: set current value (16 values block) Ul mode: set voltage value IU mode: set voltage value IU mode: set current value	EL 9000 B: 10 µs36.000.000 µs		0 ↓ 255
000 101 102 103	x x x		X X X X X X	Upper limit of voltage set value (U-max) Lower limit of voltage set value (U-min) Upper limit of current set value (I-max) Lower limit of current set value (I-min) Upper limit of power set value (P-max)	RW RW RW RW) 2) 2) 2) 2		IU mode: set current value (16 values block) 0x0000 - 0x00E5 (0 - 102%)	Voltage value (for translation see programming guide) Voltage value (for translation see programming guide) Current value (for translation see programming guide) Current value (for translation see programming guide)	2 2 2	31 32 33 34 35
07 x 08 x 10 x 11 x	х	x x x x	х	Upper limit of resistance set value (R-max) Ethernet: TCP keep-alive Profinet/Modbus TCP: DHCP Protocot: Modbus Protocot: SCPI Restart Interface card	RW RW RW RW W	uint(16) uint(16) uint(16) uint(16) uint(16) uint(16)			0x0000 - 0x00E5 (0 - 102%) Coit Keep-alive on/off Coit DHCP on/off Coit SCPI on/off Coit SCPI on/off Coit Restart	Power value (for translation see programming guide) Resistance value (for translation see programming guide) 0x0000 = off; 0xFF00 = on 0xFF00 = Trigger restart		35
113 x	x	x		Modbus specification complance AnyBus module: Type	RW	uint(16)	2) 2		Coli: Mode Reg: Type	0x000		
121 141 143 151 152	x x x x x		x x	AnyBus module: Interface type AnyBus module: Version number AnyBus module: Serial number Profibus: Ident number Profibus: Ident number Profibus/CNpon: Slave address Profibus/Profinet: User-defineable "Function tag"	R R(W) RW RW	uint(8) uint(32)) 4) 4) 2) 2] 32	16	ASCII	0x00FF = no module present "Profibus DPV1" 0xA001 Profibus: 0-125, CANopen: 0-127 "Test"	8 8 8	0 1 2
69 80 600 54 602 604 606	x x x x x x		x x x x x x x x x x x x x x x x x x x	Profibus/Profinet User-defineable "Location tag" Profibus/Profinet User-defineable installation date Profibus/Profinet User-defineable description Profinet User-defineable "Station name" Ethernef/Profinet/Modbus TCP: IP address Ethernef/Profinet/Modbus TCP: Subnet mask Ethernef/Profinet/Modbus TCP: Subnet mask	RW RW RW RW RW RW	string string string string uint(8) uint(8) uint(8)	22 3 40 3 54 3 200 4 4 0 4	20	ASCII ASCII ASCII Bytes 0-3: 0.255 Bytes 0-3: 0.255 Bytes 0-3: 0.255	"Test" "13.01.2012 09:59:00" "www.webpage.de" "Test" 192.168.0.2 (default) 192.168.0.1 (default)	8 8 8	3 4 5 6
608 635 662 664 666 667	x x x x x		x x x x x x	Ehernet/Profinet/Modbus TCP: Host name Ehernet/Profinet/Modbus TCP: Domain name Ehernet/Profinet/Modbus TCP: DNS 1 Ehernet/Profinet/Modbus TCP: DNS 2 RS232/USB: Connection timeout in milliseconds Ehernet/Profinet/Modbus TCP: MAC Ehernet/Profinet/Modbus TCP: MAC	RW RW RW RW RW RW	string string uint(8) uint(8) uint(16) uint(16) uint(16)	9 54 9 54 0 4 0 2 0 6	_	ASCII ASCII Bytes 0-3: 0255 Bytes 0-3: 0255 Bytes 0-6: 0255 Bytes 0-6: 0255	"Client" (default) 0.0.0 (default) 0.0.0 (default) 0.0.0 (default) Default Sins 0.0.00 (default) Default Sins 0.00 (0.20 21:234 or 00-50-C2-C3-12-34		
771 772 773	x x x		x x x x x	Ethernet/Profinet/Modbus TCP: Connection speed Ethernet port 2 Ethernet/Profinet/Modbus TCP: Port Ethernet/TCP Socket timeout (in seconds) RS232/CANopen/CAN: Baud rate	RW RW RW	uint(16)) 2) 2) 2) 2		SMTP Error SMTP test 0.65535 0.5.65535 Baud rate	0x001 = 10Mbit half duplex 0x0002 = 10Mbit half duplex 0x0002 = 10Mbit half duplex 0x0003 = 100Mbit half duplex 0x0000 = Auto 0x0001 = 10Mbit half duplex 0x0001 = 10Mbit half duplex 0x0002 = 10Mbit half duplex 0x0003 = 10mbit half duplex		
'01 x		x		CAN: ID format	RW	uint(16)) 2		Coit Base/Extended	CAN CANopen RS232 0x00: 10kbps 10kbps 2400 Bd 0x01: 20kbps 20kbps 4800 Bd 0x02: 50kbps 50kbps 9800 Bd 0x03: 100kbps 100kbps 19200 Bd 0x04: 125kbps 38400 Bd 006 0x05: 250kbps 125kbps 38400 Bd 0x06: 500kbps 500kbps 15200 Bd 0x07: 1Mbps 1 0x08: 11kbps - 0x09: Autobaud - 0x0000 = Base (11 Bit); 0xFF0x = Extended (29 Bit)		
02 x 04 06 09 x	x x	x	x x x	CAN: Termination CAN: Base ID CAN: Broadcast ID CAN: Data length CAN: Cyclic read: Base ID CAN: Cyclic read: Base ID	RW RW RW RW	uint(16) uint(32) uint(32) uint(16) uint(32) uint(32)	2) 2 4) 4 1) 4 2) 2 4) 4		Colt Bus termination 0x00000x7FF or 0x00000x1FFFFFFF 0x00000x1FFFFFFF 0x00000x1FFFFFFF 0x00000x1FFFFFFF 0x00000x1FFFFFFFF 0x00000x1FFFFFFFFFFFFFFFFFFFFFFFFFFFF	0x0000 = off; 0xFF00 = on 0x0000 = Auto; 0xFF00 = Always 8 bytes		
114 115 116 117 118	x x x x x		x x x x x x x x x	CAN: Cyclic read time (in ms): Status CAN: Cyclic read time (in ms): Set value (U, I, P, R) CAN: Cyclic read time (in ms): Limits 2 (P, R) CAN: Cyclic read time (in ms): Limits 1 (U, I) CAN: Cyclic read time (in ms): Actual values U, I, P GPIB address (option 3W)	RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)	2) 2 2) 2 2) 2 2) 2 2) 2		0.0000001FFFFFFFF 205000; 0 == OFF 130	Default OFF Default OFF Default OFF Default OFF Default OFF Default OFF		
000 001 002 003 004	x x x x x		x x x x x x x x x	MPP tracking: MPP-Mode MPP tracking: Uoc (setup) MPP tracking: Lec (setup) MPP tracking: Ump (setup) MPP tracking: Impp (setup) MPP tracking: Impp (setup) MPP tracking: Pmpp (setup)	RW RW RW RW RW	uint(16) uint(16) uint(16) uint(16) uint(16)) 2) 2) 2) 2) 2) 2		0.4 0x0000 - 0xCCCC (0 - 100%)	0 = MPPT off; 1 = MPP1; 2 = MPP2; 3 = MPP3; 4 = MPP4 Votage value in % of Unom (for translation see programming guide) Current value in % of Inom (for translation see programming guide) Vottage value in % of Unom (for translation see programming guide) Current value in % of Inom (for translation see programming guide) Power value in % of Prom (for translation see programming guide)	9 9 9 9 9	0 1 2 3 4 5
006 007 008 009 110 x 111 x	x x x	x	x	MPP tracking: DeltaP (setup) MPP tracking: Umpp (result of MPP1/2/4) MPP tracking: Impp (result of MPP1/2/4) MPP tracking: Pmpp (result of MPP1/2/4) MPP tracking: Start/Stop MPP tracking: Status (of MPP1/2/4) MPP tracking: Status (of MPP1/2/4) MPP tracking: Error	RW R R R RW RW		2) 2 2) 2 3) 2 3) 2 4) 2 5) 2		0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%) Coll: Start/Stop Coll: Error	Power value in % of Pnom (for translation see programming guide) Voltage value in % of Unom (for translation see programming guide) Current value in % of Inom (for translation see programming guide) Power value in % of Pnom (for translation see programming guide) 0x0000 = stop: 0xFF00 = start 0x0000 = running: 0xFF00 = finished 0x0000 = no error; 0xFF00 = error	9	6 7 8 9 10 11
113 114 115 116	x x x		x x x x x x	MPP tracking: Interval (setup) MPP4: Start MPP4: End MPP4: Repetitions MPP4: Repetitions MPP1 racking: User curve (MPP4 mode) voltage values 1-20	RW RW RW RW	uint(16)) 2) 2) 2) 2	20 20	0x0005 - 0xEA60 0x0001 - 0x0064 0x0001 - 0x0064 0x0000 - 0xFFFF	Segulation & measuring interval in miliseconds, either for tracking in modes 1 and 2 or for user curve progression in mode 4 2 or for user curve progression in mode 4 Start valtage value out of 100 (related to registers 11100-11199) for use in MPP4 mode End voltage value out of 100 (related to registers 11100-11199) for use in MPP4 mode 0,00000 = no repetitions	9 9	13 14 15 16
00 20 40 60 80	x x x x		x x x	MPP Tracking: User curve (MPP4 mode) voltage values 1-20 MPP Tracking: User curve (MPP4 mode) voltage values 21-40 MPP Tracking: User curve (MPP4 mode) voltage values 41-60 MPP Tracking: User curve (MPP4 mode) voltage values 61-80 MPP Tracking: User curve (MPP4 mode) voltage values 61-100 MPP Tracking: User curve (MPP4 mode) voltage values 61-100 MPP Tracking: User curve (MPP4 mode) voltage values 61-100	RW RW RW RW RW	uint(16) uint(16)) 40) 40	20 20 20	0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%)	Voltage value in % of Uhom (for translation see programming guide) Voltage value in % of Uhom (for translation see programming guide) Voltage value in % of Uhom (for translation see programming guide) Voltage value in % of Uhom (for translation see programming guide) Voltage value in % of Uhom Current value in % of Hom Voltage value in % of Hom	9 9 9	17 18 19 20 21
30	x			MPP Tracking: User curve (MPP4 mode) results 11-20 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 21-30 (10x Umon, Imon, Pmon)	R	uint(16)			0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%)	Power value in % of Phom (for transition see programming guide) Voltage value in % of Unom Courrent value in % of Phom Power value in % of Phom (for transition see programming guide) Voltage value in % of Unom Current value in % of Inom Power value in % of Phom For the World of the	9	23
90	x			MPP Tracking: User curve (MPP4 mode) results 31-40 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 41-50 (10x Umon, Imon, Pmon)	R	uint(16)			0x0000 - 0xCCCC (0 - 100%)	Power value in % of Pnom (ffor translation see programming guide) Voltage value in % of Unom Current value in % of Inom Power value in % of Pnom (for translation see programming guide) Voltage value in % of Unom Current value in % of Inom	9	25
50	x			MPP Tracking: User curve (MPP4 mode) results 51-60 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 61-70 (10x Umon, Imon, Pmon)	R	uint(16)			0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%)	Power value in % of Pnom (for translation see programming guide) Votage value in % of Unom Current value in % of Inom Power value in % of Pnom (for translation see programming guide) Votage value in % of Unom Current value in % of Inom Power value in % of Pnom	9	27
10	x			MPP Tracking: User curve (MPP4 mode) results 71-80 (10x Umon, Imon, Pmon) MPP Tracking: User curve (MPP4 mode) results 81-90 (10x Umon, Imon, Pmon)	R	uint(16)			0x0000 - 0xCCCC (0 - 100%) 0x0000 - 0xCCCC (0 - 100%)	(for translation see programming guide) Voltage value in % of Unom Current value in % of Inom Power value in % of Pnom (for translation see programming guide) Voltage value in % of Unom Current value in % of Inom Power value in % of Pnom	9	29
000	x x x		x	MPP Tracking: User curve (MPP4 mode) results 91-100 (10x Umon, Imon, Pmon) Battery discharge test (static): Max. current Battery discharge test (static): Max. power	RW RW	uint(16)	t 4	30	0x0000 - 0xCCCC (0 - 100%) Floating point number IEEE754 Floating point number IEEE754	(for translation see programming guide) Voltage value in % of Unom Current value in % of Inom Power value in % of Pnom (for translation see programming guide) 0 - rated current 0 - rated power	11	31
004 006 008 010	x x x x		x x x x	Seatory discharge test (static). Wax resistance Battery discharge test (static) tax resistance Battery discharge test (static): Discharge voltage Battery discharge test (static): Max capacity to discharge Battery discharge test (static): Max discharge time Battery discharge test (static): Action upon reaching the max discharge capacity	RW RW RW RW	floa:			Floating point number IEEE/34 Floating point number IEEE/74 Floating point number IEEE/74 Floating point number IEEE/74 0x00000000 - 0x000x0000 (0 - 10 h) Action when reaching max. discharge capacity	Min max resistance, 0 = OFF 0 - rated voltage 0 - 99999 99 0x00010203 = 01:02:03 as HH:MM:SS, equivalent to [00][SEK][MIN][STD]	11 11 11 11 11	3 4 5
i13 i14 i16 i18	x x x x		x x x x x x x	Battery discharge test (dynamic): Current level 2 Battery discharge test (dynamic): Time of current level 1 Battery discharge test (dynamic): Time of current level 2	RW RW RW RW	floa floa floa floa	t 4 t 4 t 4		0x0000 - 0x0002 Floating point number IEEE754 Floating point number IEEE754 Floating point number IEEE754 Floating point number IEEE754	0x0000 = Do nothing: 0x001 = Signal (see register 11544); 0x0002 = Slop best 0 - rated current 0 - rated current 1 - 36000 s 1 - 36000 s	11	7 8 9 10
22 24 26 28	x x x x		x x x	Battery discharge test (dynamic): Max power Battery discharge test (dynamic): Discharge vottage Battery discharge test (dynamic): Max capacity to discharge Battery discharge test (dynamic): Max discharge time Battery discharge test (dynamic): Action upon reaching the max discharge capacity	RW RW RW RW	float float float uint(32) uint(16)	t 4 t 4) 4		Floating point number IEEE754 Floating point number IEEE754 Floating point number IEEE754 0x00000000 - 0x000A00000 (0 - 10 h) 0x0000 - 0x0002	0 - rated power 0 - rated votage 0 - rated votage 0 - 99999 99 0x00010203 = 01:02:03 as H+t-MM:SS, equivalent to [00][SEK][MIN][STD] 0x0000 = Do nothing: 0x0001 = Signal (see register 11544); 0x0002 = Stop to test	11 11 11 11	11 12 13 14 15
31 32 x 33 x 34 x	x	x	x	Battery discharge test (dynamic): Action upon reaching the max. discharge time Battery test: Start/stop Battery test: Status 1 Battery test: Error status Battery test: Mode selection	RW RW R R	uint(16) uint(16) uint(16) uint(16) uint(16)) 2) 2) 2) 2		0x0000 - 0x0002 Coit: Start/Stop Coit: Test status Coit: Error status 0x0000 - 0x0002	0x0000 = Do nothing; 0x0001 = Do nothing; 0x0001 = Signal (see register 11544); 0x0002 = Signs (see register 11544); 0x0002 = Sign; 0xFF00 = Run 0x00000 = Runing or not started; 0x00FF = Finished 0x0000 = No error; 0x00FF = Error 0x0000 = Battery test mode off (default); 0x0001 = Signs mode; 0x0001 =	11 11 11	17 18 19 20 21
36 38 40	x x x			Battery test: Discharged capacity in Ah Battery test: Discharged energy in Wh Battery test: Time at end of test	R R R	floa floa uint(16)	t 4	1 2	x Ah x Wh HH-MM-SS:MS	0x0002 = Dynamic mode 10.5 Ah 10.5 Ah Word 0 = Hours (0·10) Word 1 = Mnutes (0·59) Word 2 = Seconds (0·59) Word 3 = Miliseconds (0·59) Word 3 = Miliseconds (0·599)	11	22 23 24
44	х			Battery test: Status 2	R	uint(16)	2	1	Bit 0: Battery test mode off (default) Bit 1: Running Bit 2: Finished Bit 3: Error occurred Bit 4: Initalized	0 = none; 1 = active	11	25