Hi there...

This code is written on the basis of standard library ''servo.h''.

Arduino PWM pulse is pushed on the servo or whatever be the system on which you want to hear this.

And this code is really efficient to use and of less time complexity and space complexity at the same time.

There is no need of including any other library on your arduino IDE because all functions can work with standard library.

1.) 'servo' function is used to define the servos. Please note that maximum of 12 servos can work effectively with this code and with one Arduino Uno Board [necessary to keep attention on hardware side as well].

2.) ' .attach' function is used to attach those servos with different PWM-constrained digital I/O pins.

3.) 'int' is data type used to initialize globally position of the servo as '0'.

4.) 'delay' function is used to set timer to delay the operation by some milliseconds. Time specified along with delay function should be in 'milliseconds'.

5.) Rest functions are defined with the code very clearly.

Procedure and every possible detail are given in my report attached.