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Deterministic Interleaver Design for Turbo Codes

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1. Introduction

The construction of a turbo code is usually done by the parallel concatenation of two convolutional codes via an interleaver. The good BER performance of turbo codes is attributed to the interleaver. Interleavers are generally grouped into random and deterministic interleavers. Deterministic interleavers perform interleaving via algorithms. For long frame sizes a deterministic interleaver that outperforms the random interleaver is yet to be found. In this research, we attempt to design a deterministic interleaver which performs as well as the random interleaver especially for long interleaver frame sizes.

2. System Model

2.1 Encoding and Decoding

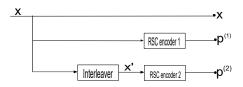
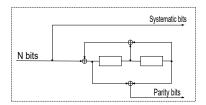


図 1 Turbo Encoder

The system diagram for the turbo encoder is shown in figure 1. It is made up of identical Recursive Systematic Convolutional (RSC) encoders which are connected in parallel via an interleaver. The RSC encoders have constraint length K and output nbits for every k bits input at time t. From here onward we refer to the RSC encoders as component encoders (CE). An information sequence \mathbf{x} of length N-M is fed into the CE1, where M=K-1. M tail-bits are added to return CE1 to the all-zero state. \mathbf{x} and the M tail-bits are used to produce the upper parity check bits $\mathbf{p}^{(1)}$ of length N. \mathbf{x} and the M tail-bits are then fed into the interleaver. The interleaved information sequence \mathbf{x}' of length N is then fed into CE2 to produce $\mathbf{p}^{(2)}$ of length N. \mathbf{x} (with extra tail-bits), $\mathbf{p}^{(1)}$ and $\mathbf{p}^{(2)}$ are multiplexed, BPSK modulated and transmitted over the AWGN

channel. At the receiver, the received signal \mathbf{y} is split into $\{\mathbf{y}^x,\mathbf{y}^{p^{(1)}},\mathbf{y}^{p^{(2)}}\}$, where $\mathbf{y}^x,\mathbf{y}^{p^{(1)}},\mathbf{y}^{p^{(2)}}$ correspond to the systematic, upper and lower parity sequence respectively. These inputs are fed into the Turbo Decoder which performs an iterative decoding process based on the Max-Log-MAP algorithm. Finally, an estimation is made to determine the transmitted information bit sequence.

2.2 RSC encoders and τ -seperated weight error events



2 $\left[\frac{1+D^2}{1+D+D^2}\right]$ (5/7) RSC Encoder

RSC encoders are characterized by their cycle length (τ) which is defined as the length of the cycle of the parity output of the encoder when the input \mathbf{x} is [1,0,0,0,....][5]. For example, the RSC encoder in figure (2)has a parity output y of [1, 1, 1, 0, 1, 1, 0, 1, 1, 0, ...]. The cycle is [1, 1, 0] and the cycle length $\tau = 3$. With the knowledge of the cycle and the cycle length τ of the RSC encoder we wish to explore the effect of weight-2minputs where the pair of "1" bits are seperated by $\tau - 1$ "0" bits. We shall refer to to these inputs as τ -separated weight-2m input error events (or simply as τ weight-2m errors for simplicity sake), where $m = \{1, 2, ...\}$. In general, the minimum codeword weight associated with weight 2 inputs is known as the effective free distance $(d_{eff})[2]$ Figure(3) shows the effect of τ weight-2 errors on the codeword weight.



It can be seen that τ weight-2m errors result in a low-weight parity output, which inturn results in a low-weight parity codeword. From the above example, we see that τ weight-2m errors have the potential to produce low weight codeword with high multiplicity if they are present in both component encoders of the turbo encoder.

3. Interleaver Design for Turbo Codes



 \boxtimes 4 τ weight-2 error

3.1 Linear Interleaver

The index mapping function of the linear interleaver is given by $\Pi_{\mathfrak{L}_N}(i) \equiv Di \mod N, \ qcd(N,D) = 1$.

D is the interleaver depth. $s=Dt \mod N$ is the input - output distance relationship. When $t=a\tau$ and $s=b\tau$, a low weight codeword may be produced. To prevent this error event from occuring we choose D that produces the largest value of $\min (t+s)$ which corresponds to a large d_{eff} value. We are able to find good interleavers with large d_{eff} values using this procedure. However we realized that for large frame sizes, the performance of the linear interleaver is dominated by τ weight-4 error events which produce lower weight codewords than d_{eff} and also have high multiplicity as N increases

3.2 Multi-Shift Interleaver

The Multi-Shift Interleaver alters the value of D for every position shift. We introduce two new variable, the cycle set \mathbb{D} and step size Δs . The cycle set $\mathbb{D} = \{d_0, d_1, ..., d_{V-1}\}, \ V = N/\Delta s, \ d_i = d_{i-1} + \Delta s, \ d_0 = D.$

For $N=2^r, r \in \{1,2,...\}$, we set $\Delta s=2^q, q \in \{2,3,...,r-1\}$. The algorithm for the Multi-Shift Interleaver is shown below.

1.
$$p_0 = 0$$

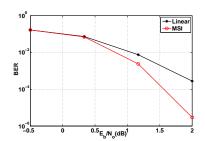
2.
$$p_i = p_{i-1} + d_{((i-1) \mod V)} \mod N$$

3.2.1 Search For Good Interleavers

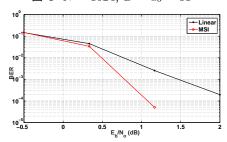
We first fix the value d_0 and determine the elements of the cycle set. For each element in Δs , we calculate the hamming weight of the turbo codewords due to τ weight-2 errors using the procedure

in Figure 3 and record d_{eff} . The value of Δs that is chosen is the one that produces the largest value of d_{eff} for a given value of d_0 . This is repeated for all odd integer values of d_0 between $(\sqrt{N}, N/2)$. The best interleaver is $(d_0, \Delta s)$ with $\max d_{eff}$ followed by $\min \Delta s$ and lowest multiplicity.

4. Results



 \boxtimes 5 $N = 1024, D = d_0 = 31$



 \square 6 $N = 16384, D = d_0 = 127$

The performance of the linear Interleaver as well as the multi-shift interleaver are compared via simulation. Interleaver length N=1024 and N=16384 are shown in figure 5 and figure 6 respectively. For medium and large frame sizes, the multi-shift interleaver outperforms the linear interleaver.

5. Conclusion and Future Work

In this research, the multi-shift interleaver was introduced. It outperforms the linear interleaver for both medium and long frame sizes.

Future work include the comparison of the multishift interleaver to other interleavers and deriving theoretical BER upper bounds for the multishift interleaver.

参考文献

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