

INTRODUCTION TO OPTIMISATION Course

ÉCOLE CENTRALE DE LYON
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- Convex optimisation appears everywhere in science and engineering, mostly on the form of a convex program:

$$\underset{x \in K \subset \mathbb{R}^n}{\text{argmin}} \quad f(x)$$

where

- K is a convex constraint set
- $f(x)$ is a convex function

Example:

LINEAR INVERSE problems:

(MEDICAL IMAGING, PHOTOGRAPHY, ASTRONOMY, ETC.)

$$y = Ax$$

↓ ↓
LINEAR IMAGE WE
DEGRADATION WANT TO RECOVER
PROCESS

WE CAN RECOVER A SPARSE IMAGE BY SOLVING:

$$\underset{x \in K}{\text{argmin}} \quad \|x\|_1$$

where $K = \{x \in \mathbb{R}^n / y = Ax\}$

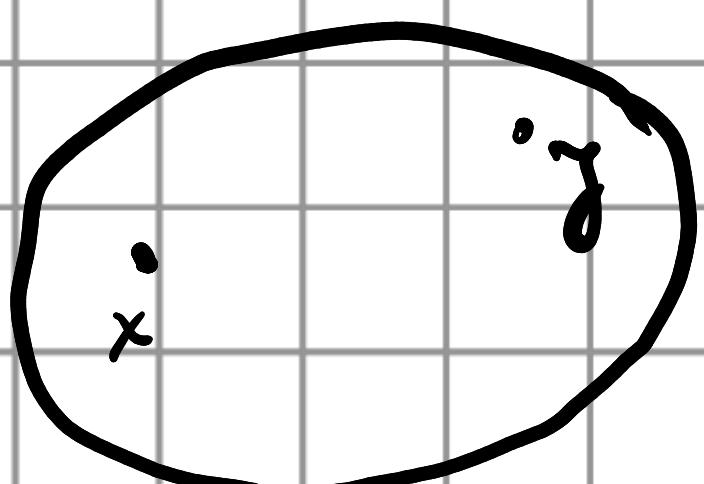
REFERENCES :

- "MATHEMATICAL INTRODUCTION TO COMPRESSED SENSING"
by Foucart and Rauhut (Appendix B)
- "CONVEX OPTIMIZATION" by Boyd and Vandenberghe
(Chapters 2, 3, 4, 5, 9)
- "PROXIMAL ALGORITHMS" by Parikh et al.
(Chapters 2, 3, 4)

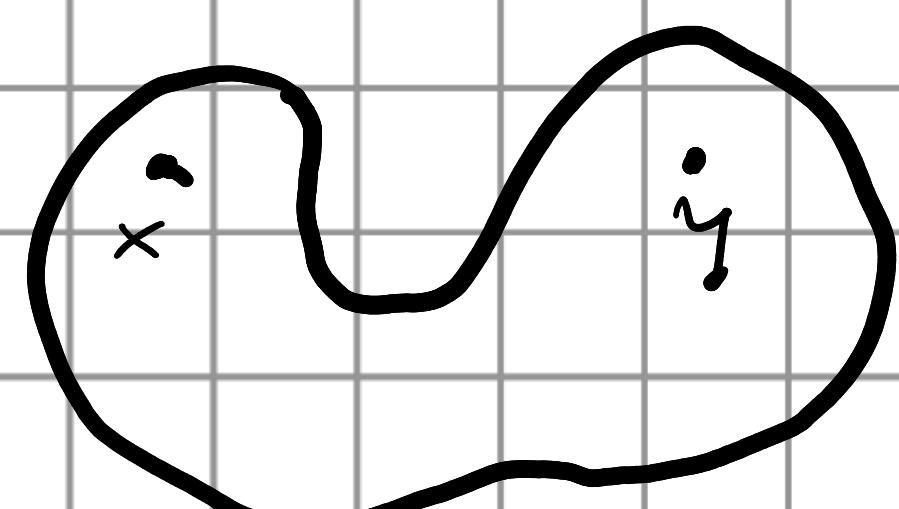
CONVEX SETS

Def convex set is a subset $K \subseteq \mathbb{R}^n$

if $t \in [0, 1]$, $tx + (1-t)y \in K$
 $x, y \in K$



CONVEX



NON-CONVEX

- THE INTERSECTION OF CONVEX SETS IS CONVEX!
- THE UNION OF CONVEX SETS IS NOT NECESSARILY CONVEX.

Def CONVEX HULL OF A SUBSET $K \subset \mathbb{R}^m$

$$\text{Conv}(K) = \left\{ \sum_{j=1}^N t_j x_j : N \geq 1, t_j \geq 0, \sum_{j=1}^N t_j = 1, x_1, \dots, x_N \in K \right\}$$

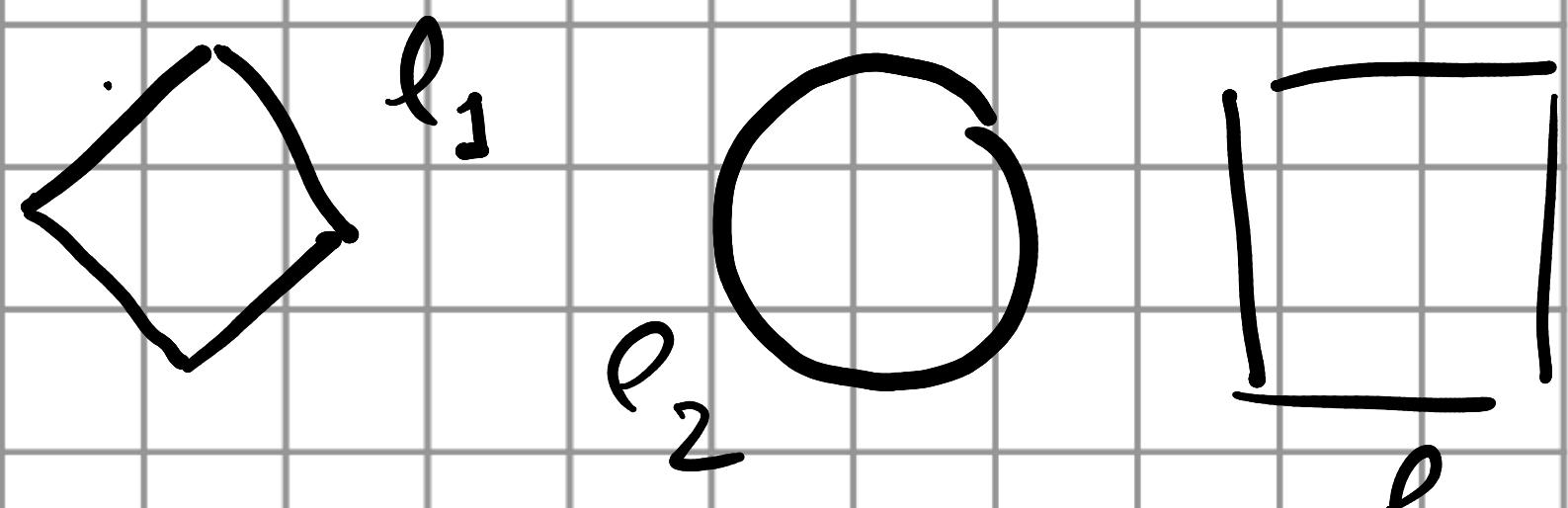


$$K \subseteq \text{conv}(K)$$

- IT IS THE SMALLEST SET CONTAINING K
- K IS CONVEX $\Leftrightarrow \text{conv}(K) = K$

- EXAMPLES OF CONVEX SETS.

- p -BALLS $B_p^r = \{x : \|x\|_p \leq r\}$



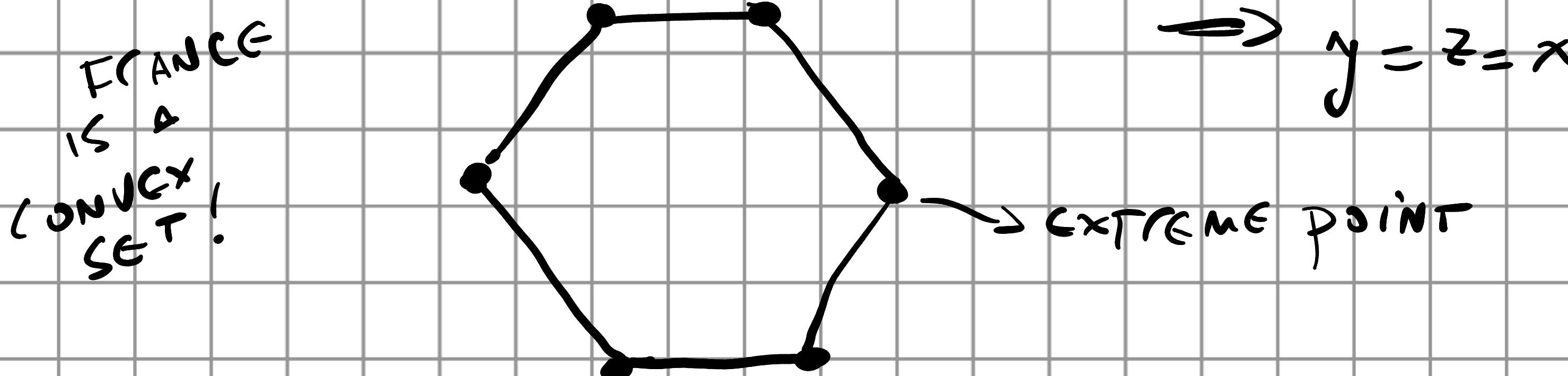
- AFFINE SUBSPACES $\{x : Ax = y\}$

- HALF SPACES $(\omega, \gamma) \{x : x^\top \omega \leq \gamma\}$

DEF: EXTREME POINTS

Let $K \subset \mathbb{R}^n$ be a convex set. A point $x \in K$ is an extreme point if $x = ty + (1-t)z$ and

$$y, z \in K \\ t \in [0, 1]$$

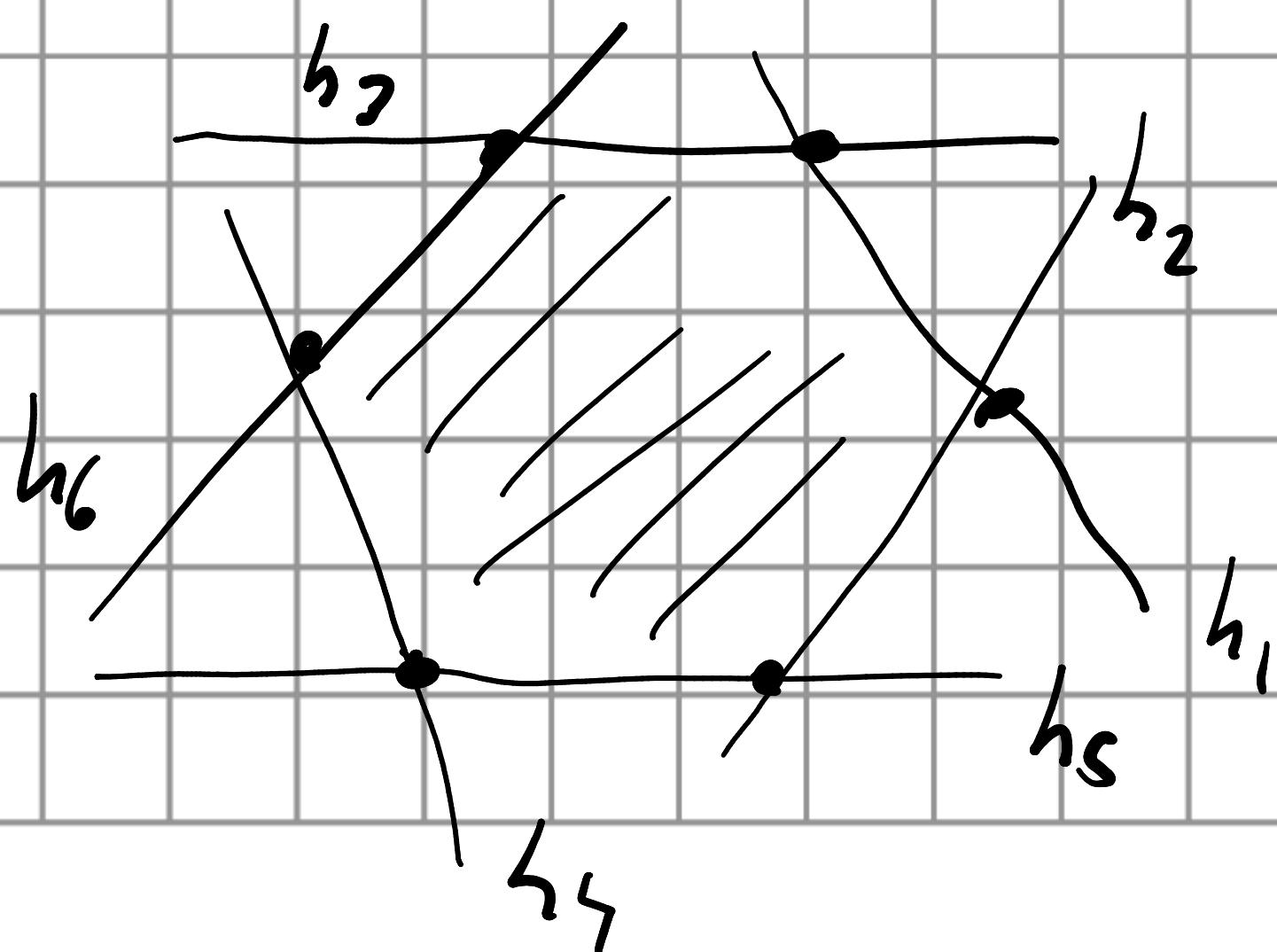


THEOREM: A convex set is the convex hull of its extreme points.

DUALITY:

Any convex set can be represented as an intersection of a collection H of halfspaces

$$K = \bigcap_{h \in H} h$$



Convex Functions

$$f: \mathbb{R}^n \rightarrow]-\infty, \infty] = \mathbb{R} \cup \{\infty\}$$

WITH CONVENTION $x+\infty = \infty, x \in \mathbb{R}$

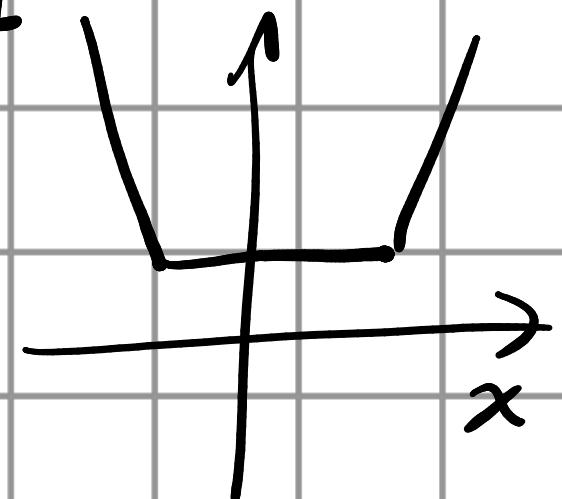
$2\infty = \infty, 1 > 0$

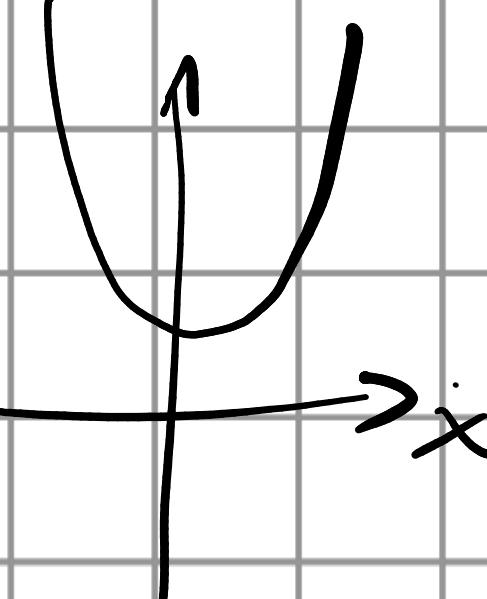
Domain:

$$\text{dom}(f) = \{x \in \mathbb{R}^n, f(x) \neq \infty\}$$

- A FUNCTION IS proper IF $\text{dom}(f)$ is
NOT EMPTY.

DEFINITIONS : $f: \mathbb{R}^n \rightarrow]-\infty, \infty]$ IS CALLED

+  • CONVEX if $f(tx + (1-t)y) \leq tf(x) + (1-t)f(y)$
 $\forall x, y \in \mathbb{R}^n, \forall t \in [0, 1]$

+  • STRICTLY CONVEX if
 $f(tx + (1-t)y) < tf(x) + (1-t)f(y)$
 $\forall x, y \in \mathbb{R}^n, \forall t \in]0, 1[$

• STRONGLY CONVEX WITH PARAM $\delta > 0$ if
 $f(tx + (1-t)y) \leq tf(x) + (1-t)f(y) - \frac{\delta}{2}t(1-t)\|x-y\|^2$

Useful properties:

$f: \mathbb{R} \rightarrow \mathbb{R}$ convex non decreasing

$g: \mathbb{R}^n \rightarrow \mathbb{R}$ convex

$\Rightarrow f \circ g$ is convex

EXAMPLE $g(x) = x^2$ $f(x) = ax$ $a \geq 0$

$f \circ g(x) = ax^2$ is convex
for any $a \geq 0$

Examples of Convex Functions:

QUADRATIC
FUNCTION

$f(x) = x^T A x$
is convex if $A \in \mathbb{R}^{n \times n}$ is positive
semi-definite

AND is strongly convex

if A is positive
definite
with $R = \lambda_{\min}(A)$

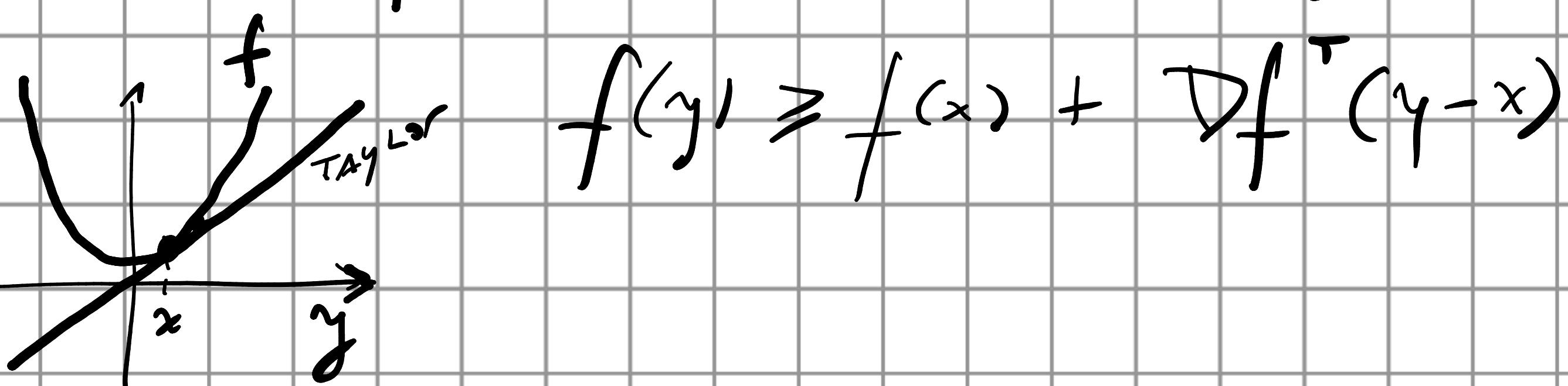
INDICATOR

$f(x) = \frac{1}{x \in K}$ where K is a convex
set

$$= \begin{cases} +\infty & \text{if } x \notin K \\ 0 & \text{if } x \in K \end{cases}$$

Proposition: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a DIFFERENTIABLE FUNCTION

- f is convex if $\forall x, y \in \mathbb{R}^n$



- f is strongly convex if $\forall x, y \in \mathbb{R}^n$

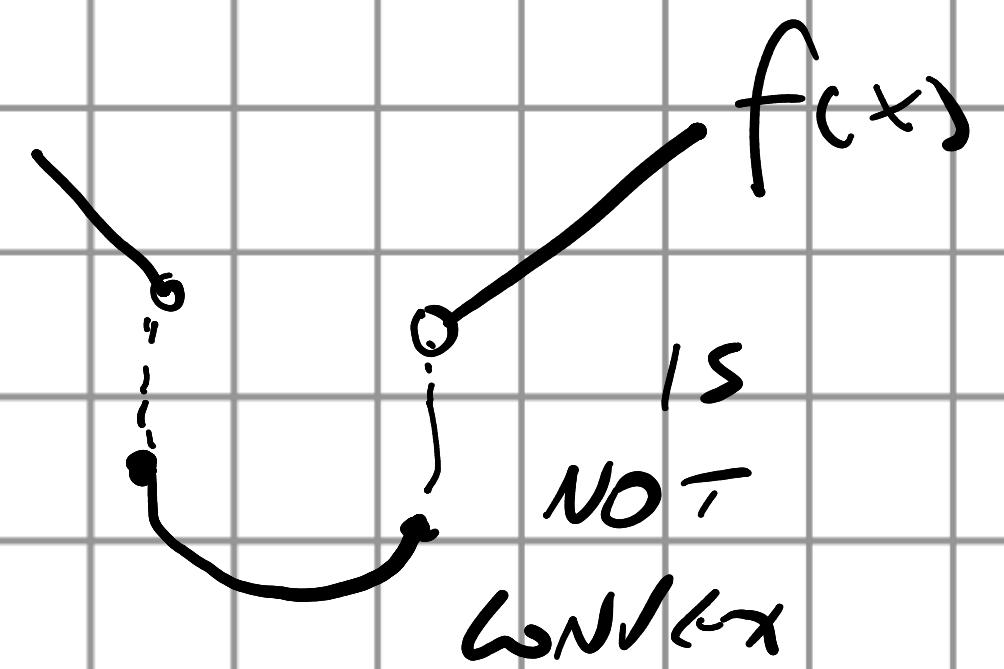
$$f(y) \geq f(x) + Df^T(y-x) + \frac{\delta}{2} \|y-x\|^2$$

- If f is TWICE DIFFERENTIABLE then it is convex

if $\forall x \in \mathbb{R}^n \quad D^2f(x) \succeq 0$ (matrix is PSD)

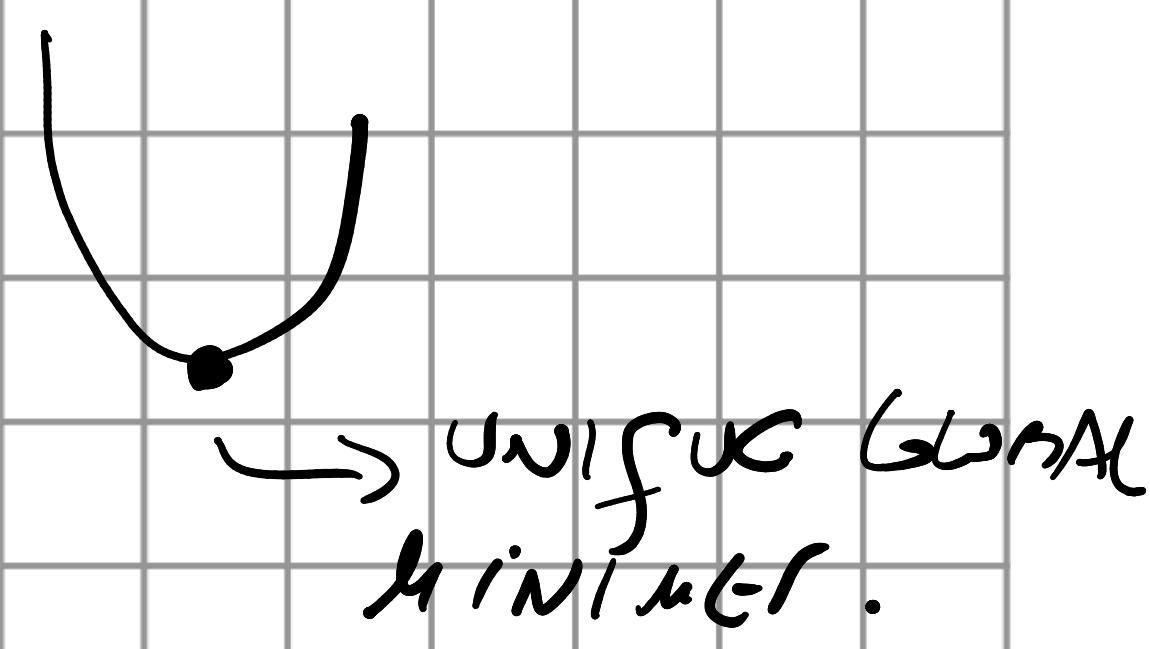
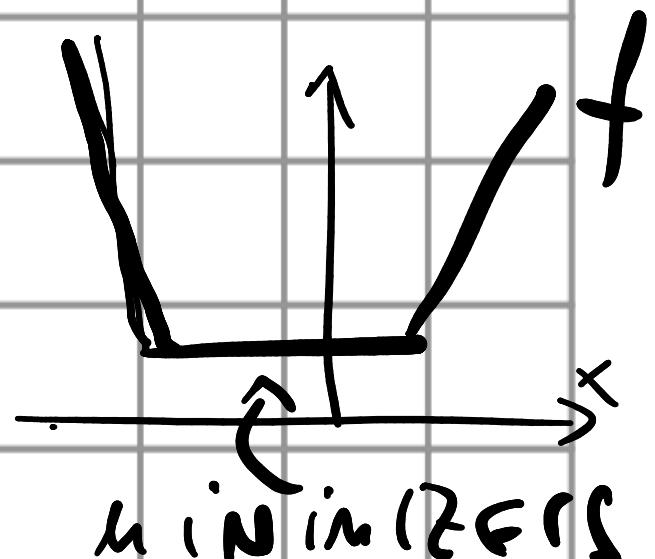
• it is strictly convex if $D^2f(x) > 0$

- A convex function is continuous on the interior of its domain



!! Prop. $f: \mathbb{R}^m \rightarrow [-\infty, +\infty]$ be a convex function

- A local minimizer of f is a global minimizer
- The set of minimizers is convex
- If f is strictly convex there is a unique minimizer

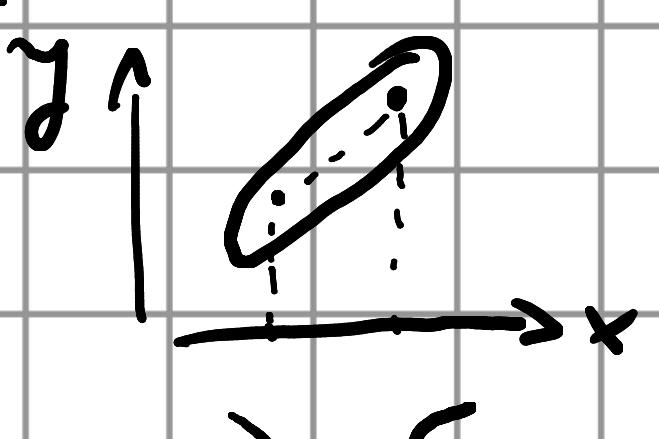


Theorem

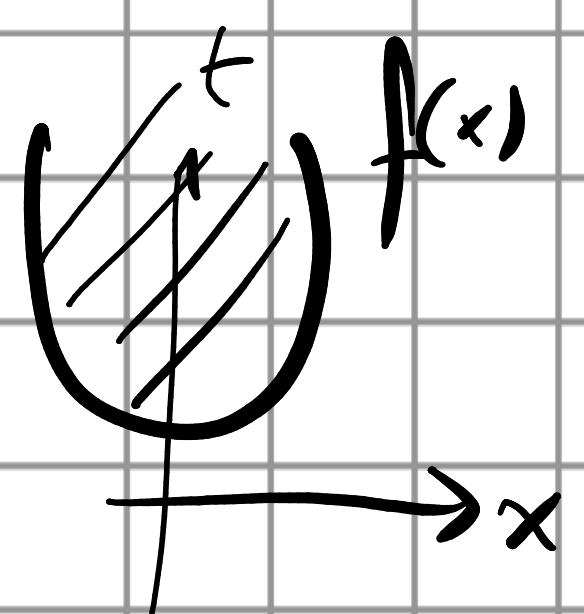
Let $f: \mathbb{R}^m \times \mathbb{R}^m \rightarrow [-\infty, +\infty]$ be a convex function.

THEN $g(x) = \inf_{y \in \mathbb{R}^m} f(x, y)$ is a convex function

$$g: \mathbb{R}^m \rightarrow [-\infty, +\infty]$$



Epigraph:



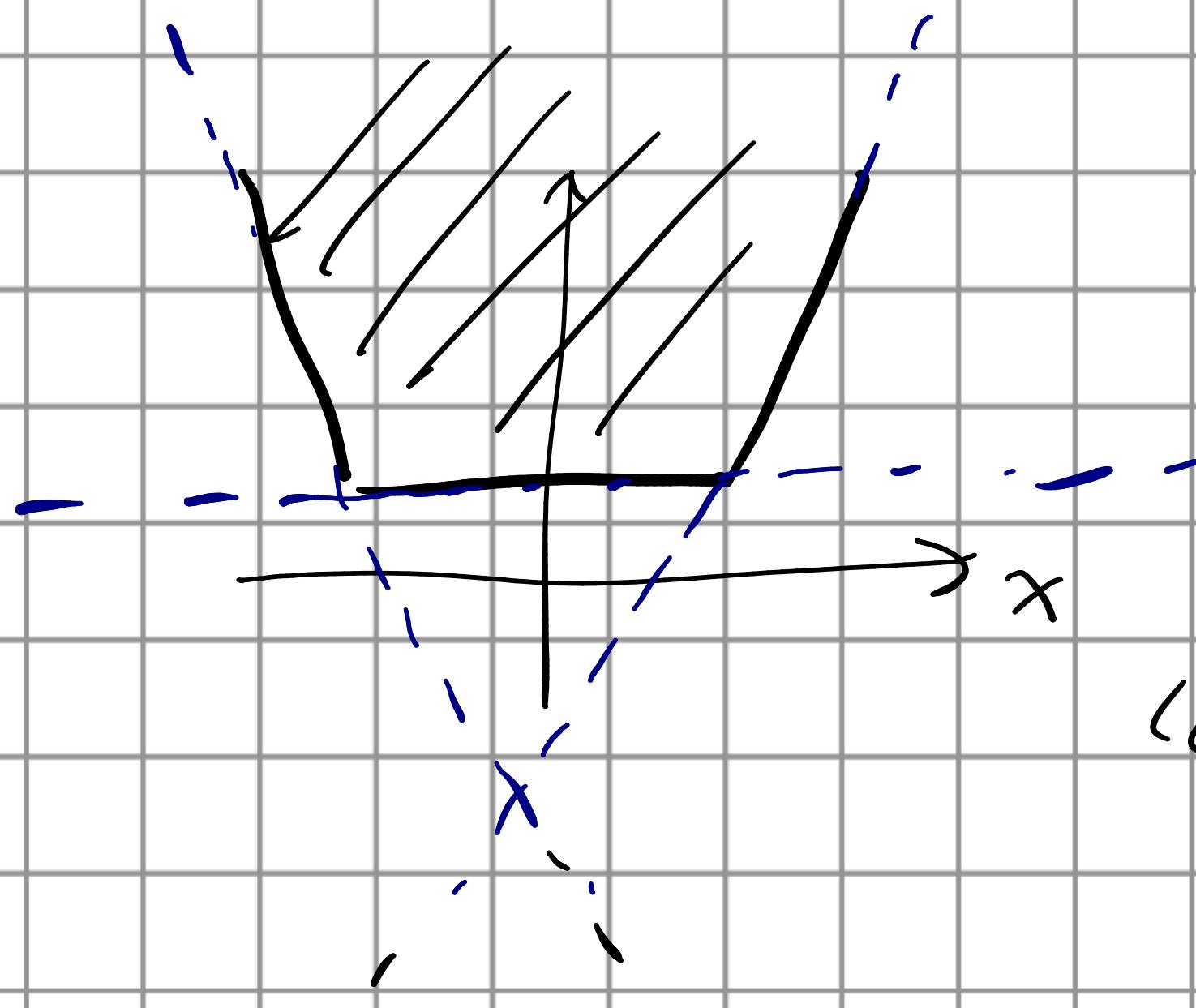
$$\text{epi}(f) = \left\{ (t, x) \in \mathbb{R}^{m+1}, f(x) \leq t \right\}$$

epi(f)
is a convex set

$\Leftrightarrow f$ is a convex function

Convex Conjugate

DUALITY FOR FUNCTIONS:

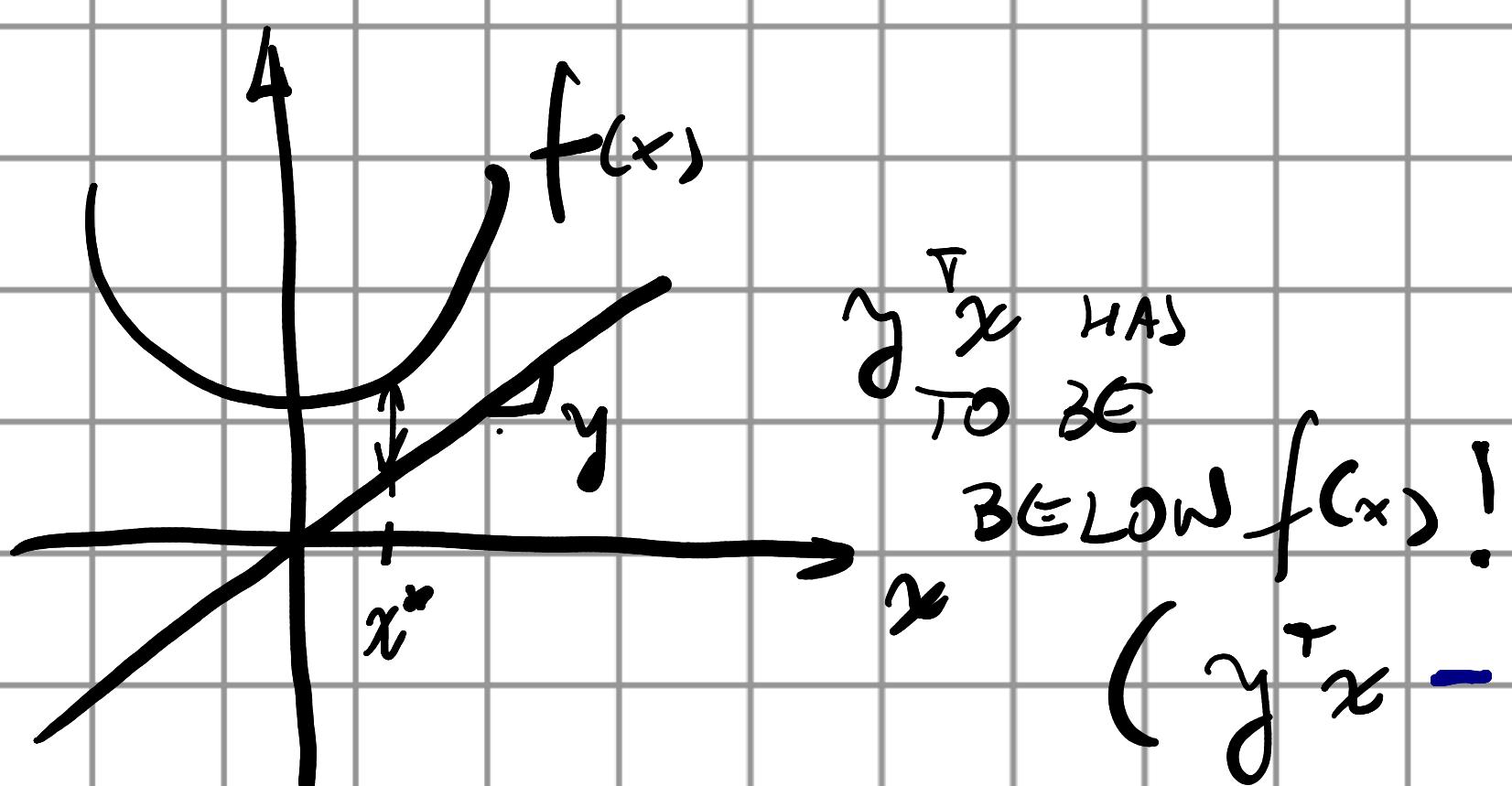


IDEA: $\text{epi}(f)$ CAN BE EXPRESSED AS INTERSECTION OF HALFSPACES



CONVEX f CAN BE EXPRESSED AS SUPREMUM OVER LINEAR FUNCTIONS

$$f(x) = \sup_y y^T x - f^*(y)$$



HOW SHOULD WE CHOOSE IT?

DEFINITION: FENNEL-DUAL (CONVEX CONJUGATE)

$$f^*(y) = \sup_x y^T x - f(x)$$

CAN BE APPLIED TO ANY $f(x)$ — CONVEX OR NOT?

$f^*(y)$ IS CONVEX INDEPENDENTLY OF

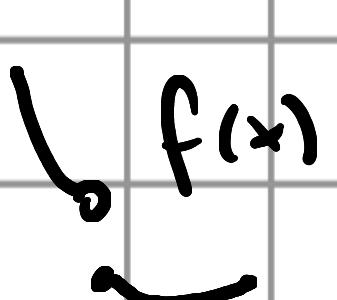
WHETHER f IS CONVEX OR NOT

Fenchel - Young

$x, y \in \mathbb{R}^n$

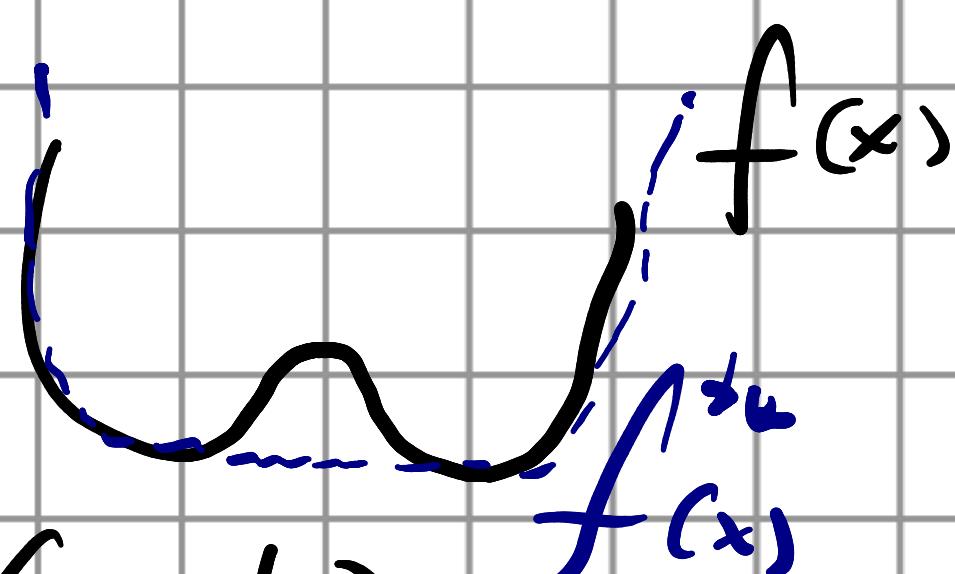
$$x^T y \leq f(x) + f^*(y)$$

Properties of Convex Conjugate: $f: \mathbb{R}^n \rightarrow]-\infty, \infty]$

1) f^* is Lower Semi Continuous (LSC) 

2) f^* is THE LARGEST LSC CONVEX FUNCTION

SATISFYING $f^*(x) \leq f(x)$
 $\forall x \in \mathbb{R}$



3) $\text{epi } f^* = \text{Conv(epi } f)$

4) If f is convex $f^* = f^{\dagger}$!

5) For $\lambda \neq 0$ $[f(\lambda x)]^* = f^*\left(\frac{x}{|\lambda|}\right)$

6) For $\lambda > 0$, $(\lambda f(x))^* = \lambda f^*\left(\frac{x}{\lambda}\right)$

7) For $z \in \mathbb{R}^n$ $(f(x-z))^* = f^*(y) + z^T y$

Example:

$$\cdot f(x) = \|x\|_p \Rightarrow f(y) = \underbrace{\frac{1}{\|y\|_q}}_{\substack{\leq 1 \\ \text{"DUAL BALL" }}} \quad x \in \mathbb{R}$$

where $1 = \frac{1}{p} + \frac{1}{q}$

P.J $f(x) = \|x\|$

$$\begin{array}{lll} l_2 & p=2 \Rightarrow q=2 & l_2 \\ l_1 & p=1 \Rightarrow q=\infty & l_\infty \end{array}$$

Def. THE SUBDIFFERENTIAL OF A CONVEX
FUNCTION $f: \mathbb{R}^n \rightarrow]-\infty, \infty]$ AT POINT $x \in \mathbb{R}^n$ IS

THE SET $\delta f(x) = \left\{ v \in \mathbb{R}^n : f(y) \geq f(x) + v^\top (y-x) \quad \forall y \in \mathbb{R}^n \right\}$

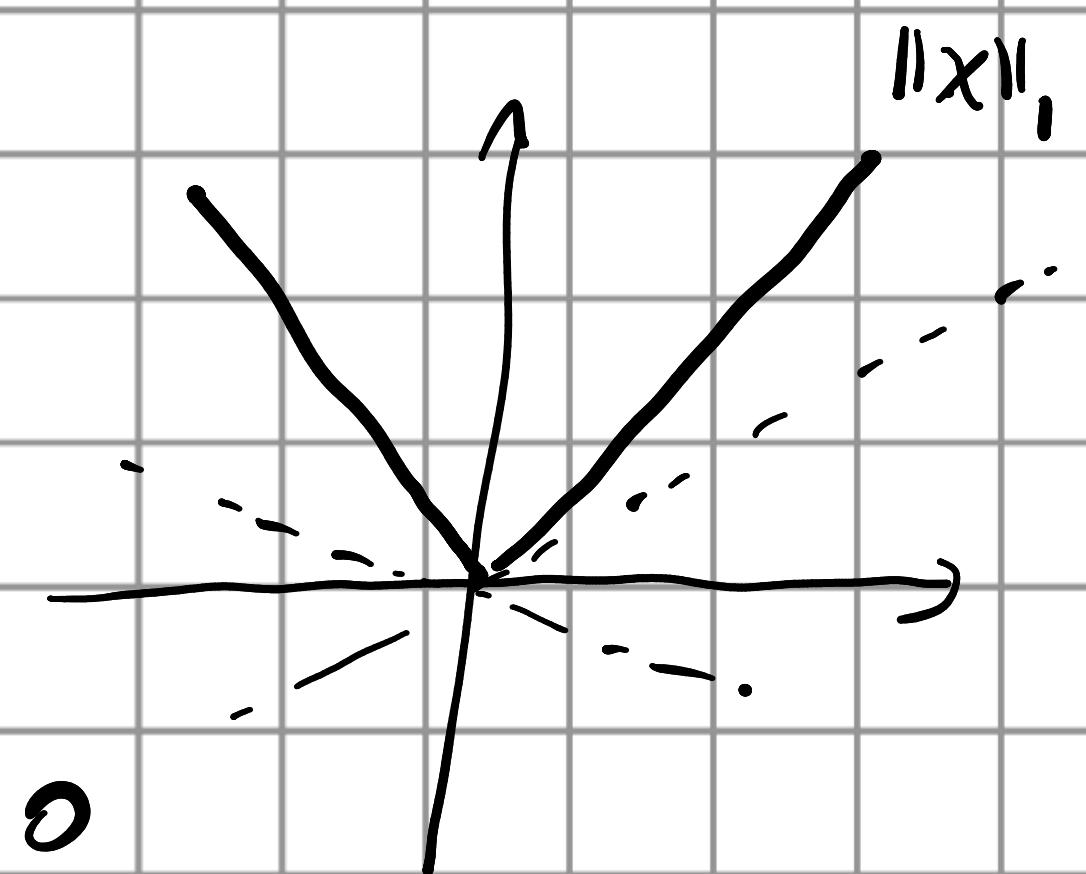
- THE SUBDIFFERENTIAL OF A CONVEX FUNCTION
IS ALWAYS NON-EMPTY

- IF f IS DIFFERENTIABLE AT x
 $\Rightarrow \delta f(x) = \{ \nabla f(x) \}$ SINGLE
POINT.

Example:

$$f(x) = \|x\|_1$$

$$\delta f(x) = \begin{cases} \text{sign}(x) & \text{if } x \neq 0 \\ [-1, 1] & \text{if } x = 0 \end{cases}$$



Theorem: $x \in \mathbb{R}^n$ is a minimum of convex f

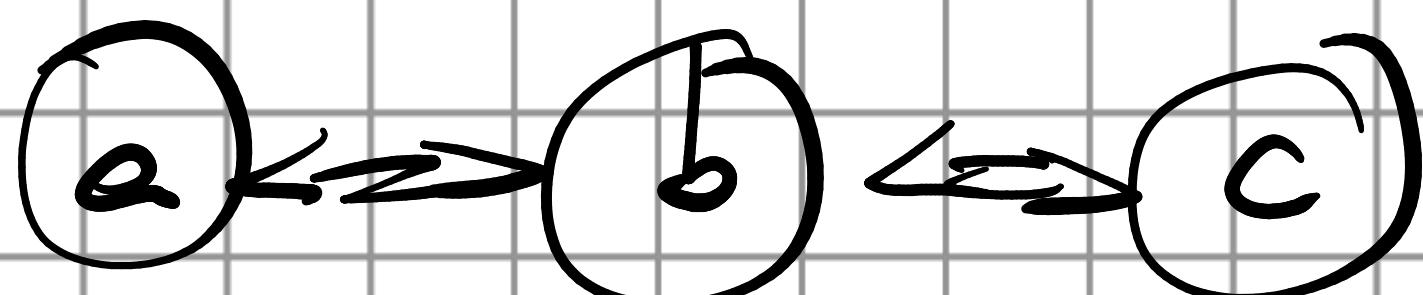
if $0 \in \delta f(x)$

Theorem $f: \mathbb{R}^n \rightarrow]-\infty, +\infty]$ convex, $x, y \in \mathbb{R}^n$
l.s.c.

a $y \in \delta f(x)$

b $x \in \delta f^*(y)$

c $y^T x = f(x) + f^*(y)$
↑ EQUALITY!



e.g. $y=0$

$$0 \in \delta f(x)$$

$$x \in \delta f^*(0)$$

DUAL WAY TO OPTIMIZE $f(x)$

Proximal Mapping: $f: \mathbb{R}^m \rightarrow]-\infty, \infty]$
CONVEX

$$\text{prox}_f(x) = \underset{z \in \mathbb{R}^m}{\arg \min} f(z) + \frac{1}{2} \|x - z\|^2$$

↳ it has a unique minimizer since $f + \frac{1}{2} \| \cdot - z \|^2$ is strongly convex!

EXAMPLES:

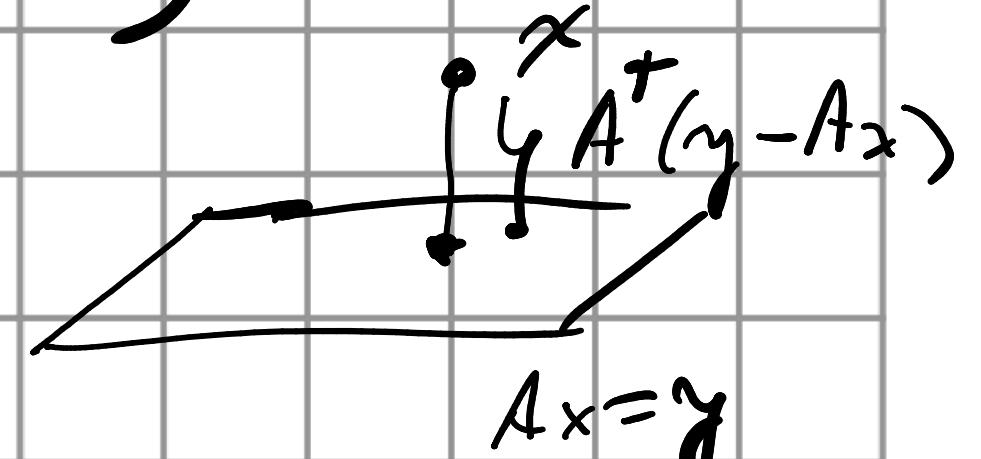
$$① \quad f(x) = \underset{x \in K}{\arg \min} \quad K \text{ convex}$$

→ $\text{prox}_f(x)$ is the orthogonal projection onto K .

$$K = \{x \in \mathbb{R}^n \mid Ax = y\}$$

$$\text{prox}_f(x) = x + A^+(y - Ax)$$

$$② \quad f(x) = \frac{\lambda}{2} \|y - Ax\|^2$$



$$\underset{x}{\operatorname{arg \min}} \frac{1}{2} \|x - z\|^2 + \frac{\lambda}{2} \|y - Ax\|^2$$

$$\frac{d}{dx} \rightarrow (x - z) + \lambda A^T(Ax - y) = 0$$

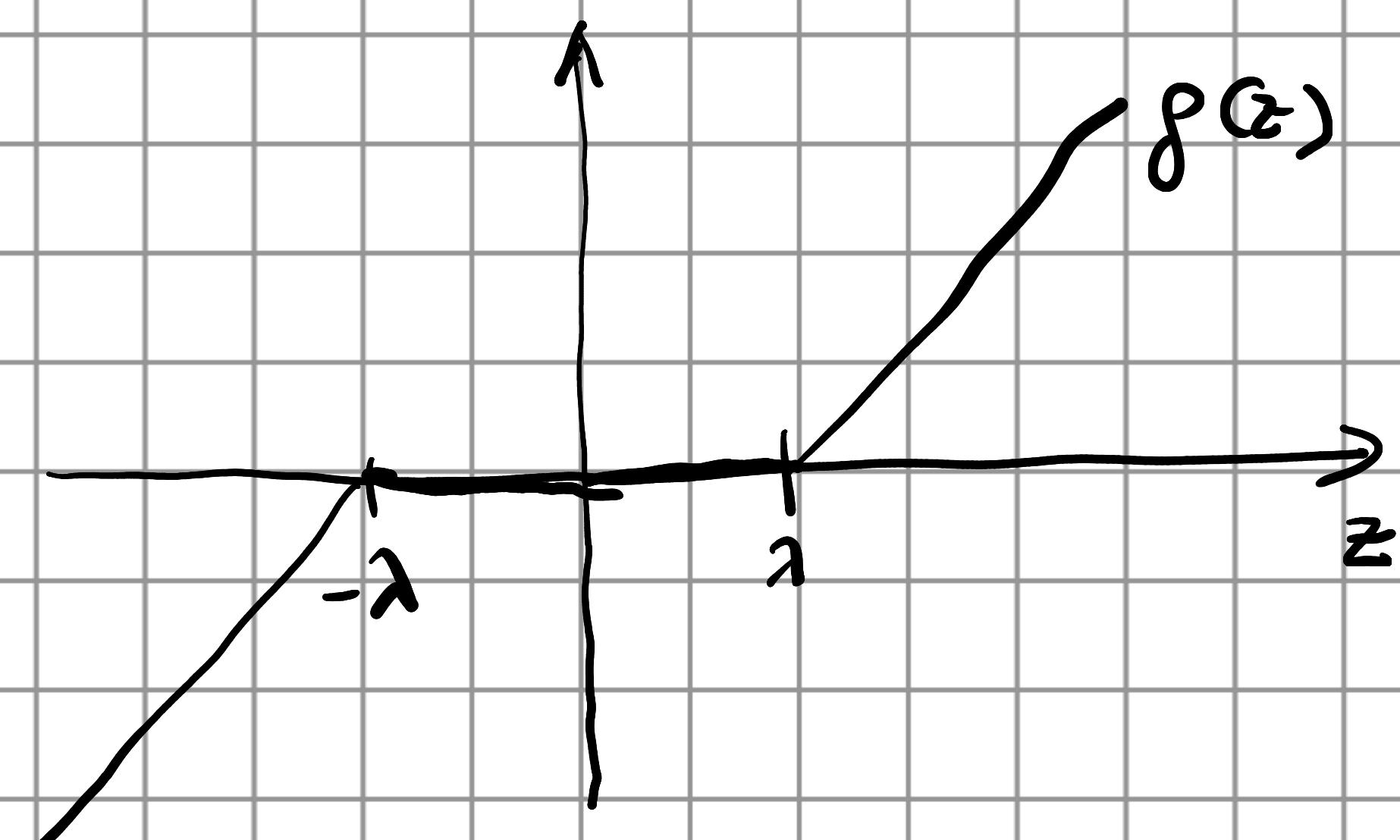
$$x = (I + \lambda A^T A)^{-1}(z + \lambda y)$$

$$③ f(x) = \lambda \|x\|_1$$

$$g(z) \stackrel{\text{def}}{=} \underset{x}{\operatorname{arg\,min}} \lambda \|x\|_1 + \frac{1}{2} \|x - z\|^2$$

$$g_i(z) = \begin{cases} z_i - \lambda & \text{if } z_i \geq \lambda \\ z_i + \lambda & \text{if } z_i \leq -\lambda \\ 0 & \text{if } |z_i| \leq \lambda \end{cases}$$

SOFT
THRESHOLDING



Separable Function:

$$\begin{aligned} \lambda \|x\|_1 + \frac{1}{2} \|x - z\|^2 &= \sum_{i=1}^n \lambda |x_i| - \frac{1}{2} (x_i - z_i)^2 \\ &= \sum_{i=1}^n f_i(x_i) \end{aligned}$$

Proposition $f: \mathbb{R}^n \rightarrow]-\infty, \infty]$ convex

$$x = \text{prox}_f(z) \iff z \in x + \partial f(x)$$

↓ ALSO WRITTEN AS

$$x = (\delta f + I)^{-1} z$$

Theorem: Moreau's identity

$f: \mathbb{R}^n \rightarrow]-\infty, \infty]$ convex L.S.C.

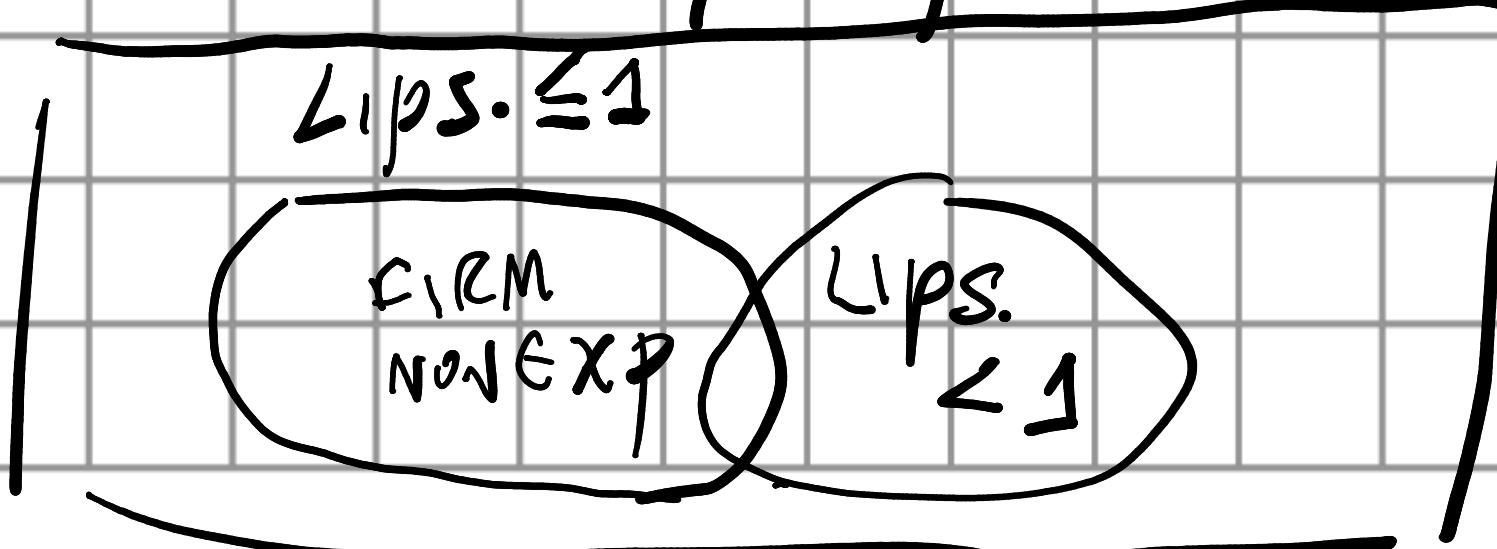
then $\forall z \in \mathbb{R}^n$

$$\boxed{\text{prox}_f(z) + \text{prox}_{f^*}(z) = z}$$

Theorem $\forall z, z' \in \mathbb{R}^n$

$$\|\text{prox}_f(z) - \text{prox}_f(z')\|^2 \leq (z - z')^\top (\text{prox}_f(z) - \text{prox}_f(z'))$$

that is $\text{prox}_f(\cdot)$ is FIRMLY NON-EXPANSIVE



(LIPS. CONS. ≤ 1)
but maybe
 1

Convex Optimisation problems :

objective

$$\min_{x \in \mathbb{R}^n} f(x) \quad \text{subject}$$

to $g_i(x) = 0$

$h_j(x) \leq 0$

constraints

$x \in K$

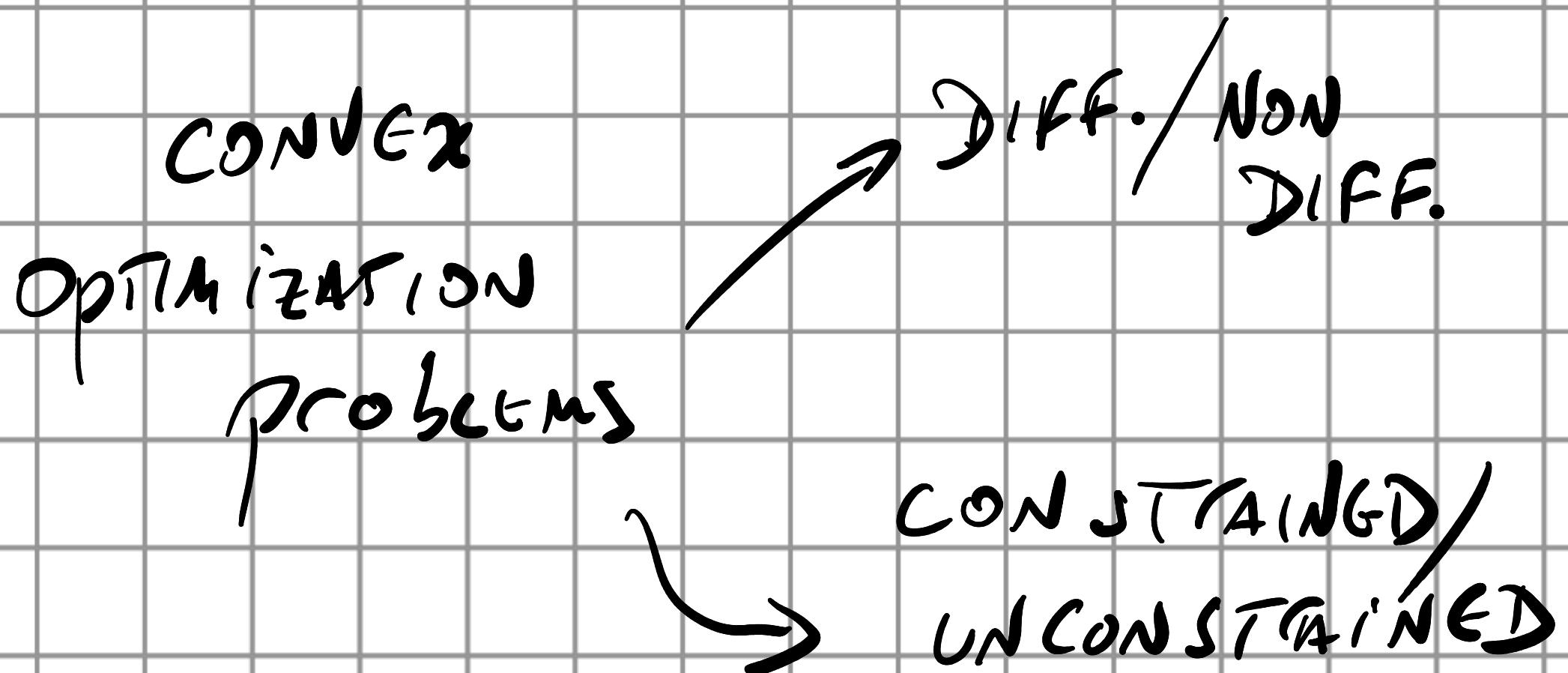
f, g_i, h convex

equivalent

to $\min_{x \in K} f_0(x)$

or

$$\min_{x \in \mathbb{R}^n} f_0(x) + \frac{1}{2} \|x\|_K^2$$



UNCONSTRAINED MINIMIZATION

$$\underset{x}{\operatorname{arg\,min}} f(x)$$

① GRADIENT DESCENT.

- ASSUMES THAT f IS DIFFERENTIABLE

$$x^{k+1} = x^k - \gamma \nabla f(x^k)$$

γ : STEP SIZE

IF f IS LIPSCHITZ

$$\|f(x) - f(\gamma)\| \leq L \|x - \gamma\|$$

THEN $\gamma < \frac{2}{L}$ GUARANTEED CONVERGENCE
TO A GLOBAL MINIMUM.

WHAT HAPPENS IF $f(x)$ IS
NOT DIFFERENTIABLE?

PROXIMAL GRADIENT DESCENT

$$x^{k+1} = \text{prox}(x^k)$$

if

proposition: If f is convex, this algorithm converges to a minimum $\forall \gamma > 0$.

Example: ① $f(x) = \lambda \|x\|_1$

$$x^{k+1} = \text{soft-threshold}(x^k, \lambda \gamma)$$

converges in $\frac{\|x^0\|_\infty}{\lambda \gamma}$ iterations

② $f(x) = \frac{1}{2} \|Ax - b\|^2$

GD

PGD

$$x^{k+1} = (\gamma A^T A + I)^{-1} x^k + c$$

where $c = (\gamma A^T A + I)^{-1} \frac{x^k}{\gamma}$

Converges $\forall \gamma > 0$?

$$x^{k+1} = (I - \gamma A^T A)^{-1} x^k + c$$

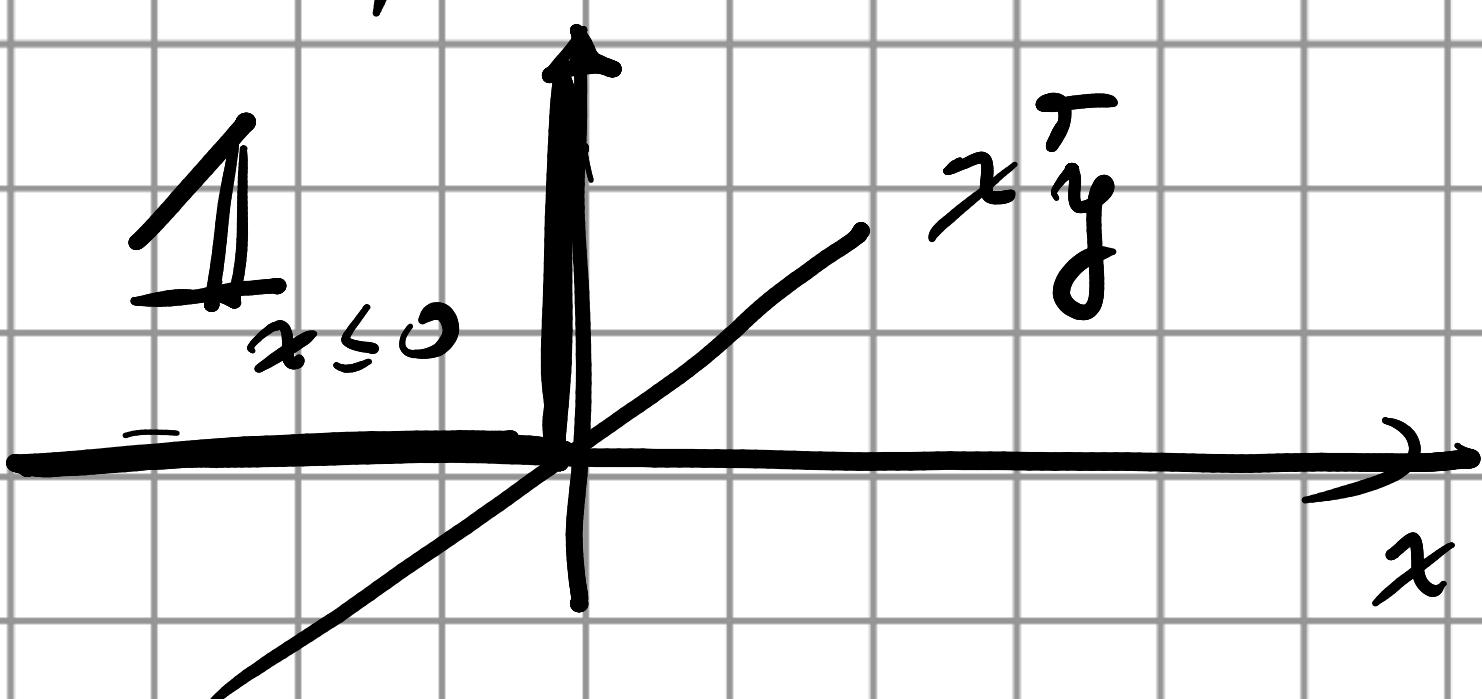
where $c = \gamma A^T b$

Converges for $\gamma < \frac{2}{\lambda_{\max}(A^T A)}$

CONstrained MINIMIZATION WITH LINEAR CONSTRAINTS

$$\underset{x}{\operatorname{argmin}} \quad f_0(x) + \underbrace{\mathbb{1}_{Ax-b \leq 0}}_{f(x)}$$

IDGA RELAX INDICATOR FUNCTIONS
BY LINEAR FUNCTIONS



$$y^T x \leq \mathbb{1}_{x \leq 0} \quad \text{for all } x \quad \text{if } y \leq 0$$

LAGRANGIAN

$$L(x, y) = f_0(x) + y^T(Ax - b) \leq f(x)$$

1) LOWER BOUND

HOLDS
 $\forall x \in \mathbb{R}^n$

$$H(y) = \inf_x f_0(x) + y^T(Ax - b)$$

$$= - \sup_x y^T(b - Ax) - f_0(x)$$

$$= -f(A^T y) - y^T b$$

CONVEX CONJUGATE

WE HAVE

$$H(y) \leq f(x) \quad \forall x \in \mathbb{R}^m \\ y \geq 0$$

⇒ pick BEST LOWER BOUND

$$P^* = \sup_y H(y)$$

WEAK DUALITY: $P^* \leq \min_x f(x)$

STRONG DUALITY: $P^* = \min_x f(x)$
if There
exist feasible point x

DUAL optimisation problem

$$\hat{y} = \arg \max_{y \in \mathbb{R}^m} -f(A^\top y) - b^\top y$$

$$\text{THEN } \hat{x} = \arg \min_x L(x, \hat{y})$$

In particular we consider:

$$\text{or } \min_{x \in \mathbb{R}^n} f(x) + g(x)^T$$

NON-DIFFERENTIABLE
CONVEX

DIFFERENTIABLE
CONVEX
LIPSCHITZ CONSTANT L

(2) proximal GRADIENT /
FORWARD BACKWARD

$$x^{k+1} = \underset{\gamma g}{\text{prox}}(x^k - \gamma \nabla f(x^k))$$

- FIRST we REDUCE f with GRADIENT DESCENT

$$u^k = x^k - \gamma \nabla f(x^k)$$

- THEN we REDUCE $g(x)$ with proximal
GRAD. DESC.

$$x^{k+1} = \underset{\gamma g}{\text{prox}}(u^k)$$

IF $\gamma < \frac{2}{L}$, THE ALGORITHM CONVERGES
TO A GLOBAL MINIMIZER
of $f(x) + g(x)$

③ DOUGLAS - RACHFORD SPLITTING
 (ALTERNATING DIRECTIONS METHOD OF MULTIPLIERS)
ADMM

$$\underset{x, s}{\operatorname{arg \min}} f(x) + g(s)$$

$$f(x) + g(s)$$

$$\text{s.t. } x = s$$

AUGMENTED LAGRANGIAN

(CONSTRAINED
MINIMIZATION)

$$L_p(x, s, y) = f(x) + g(s) + \underbrace{y^T(x-s)}_{\text{DUAL}} + \underbrace{\frac{\rho}{2} \|x-s\|^2}_{\text{AUGMENTATION}}$$

$$x^{k+1} = \underset{x}{\operatorname{arg \min}} f(x) + y^T(x-s) + \frac{\rho}{2} \|x-s\|^2$$

$$s^{k+1} = \underset{s}{\operatorname{arg \min}} g(s) + y^T(x-s) + \frac{\rho}{2} \|x-s\|^2$$

$$y^{k+1} = y^k + \rho (x^{k+1} - s^{k+1}) \rightarrow \text{DUAL ASCENT}$$

USING THE FACT THAT

$$y^T(x \pm s) + \frac{\rho}{2} \|x - s\|^2 = x^T y \pm s^T y + \frac{\rho}{2} x^T x + \frac{\rho}{2} s^T s - \rho x^T s$$

$$x^T \frac{\rho}{2} \|x - (s - y)\|^2$$

$$s^T \frac{\rho}{2} \|s - (x + y)\|^2$$

$\left. \begin{array}{l} x^{k+1} = \text{prox}_f^{-1}(s^k - \frac{y^k}{\rho}) \\ s^{k+1} = \text{prox}_g^{-1}(x^{k+1} + \frac{y^k}{\rho}) \\ y^{k+1} = y^k + \rho(x^{k+1} - s^{k+1}) \end{array} \right\}$

EQUIVALENT ALGORITHMS

$\left. \begin{array}{l} x^{k+1} = \text{prox}_f^{-1}(z^k) \\ z^{k+1} = \text{prox}_g^{-1}(2x^{k+1} - z^k) + (z^k - x^k) \end{array} \right\}$

Inverse problems

$$y = Ax + \varepsilon$$

$$x \in \mathbb{R}^n \quad y \in \mathbb{R}^m$$

$$A \in \mathbb{R}^{m \times n}$$

OBSERVED

→ MEASUREMENTS

$$x \rightarrow \boxed{A} \xrightarrow{+ \text{ noise}} y$$

$$\begin{aligned} & \text{CAMERA /} \\ & \text{ACQUISITION} \\ & \text{PHYSICS} \end{aligned} \quad \varepsilon \sim N(0, I\sigma^2)$$

- THERE ARE INFINITELY MANY SOLUTIONS

if A is LOW RANK, $\text{RANK } A < m$ (EVEN IF $\varepsilon = 0$)

↳ WE REQUIRE REGULARIZATION

$$\underset{x}{\text{argmin}} \quad \underbrace{\|Ax - y\|^2}_{\text{DATA FIDELITY}} + \lambda \|x\|_1 \quad \text{REGULARIZATION}$$

Convex
but not
strictly
convex.

Promotes
sparse
solutions