プッシュダウンオートマトン

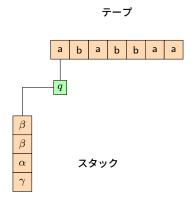
離散数学・オートマトン 2024 年後期 佐賀大学理工学部 只木進一

- ① プッシュダウンオートマトン: Pushdown automata
- ② 決定性プッシュダウンオートマトン: Deterministic PDA
- ③ PDA と受理言語: PDA and Their Accepted Languages
- 4 非決定性プッシュダウンオートマトン: Nondeterministic PDA

プッシュダウンオートマトン: Pushdown automata

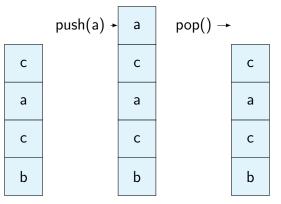
- テープとともに、スタックの文字を読む: Reading stack symbols along with tape symbols
- 状態遷移するとともに、スタックへ文字列を書き込む: Writing strings to the stack along with state transitions
- スタックという特殊な無限に大きなメモリを持つ機械: A machine with a special infinite memory called a stack

プッシュダウンオートマトンのイメージ Image of a pushdown automaton



スタック: stacks

- リストのような1次元のデータ列: A one-dimensional data sequence like a list
- 先頭に書く (push) ことと、先頭から読む (pop) ことだけが許される: Only writing (push) and reading (pop) from the top are allowed
 - 先頭以外のデータは触れない: Other data except at the top cannot be touched
 - FILO (First-In Last-Out)
 - pop: 先頭を取り出して読む、つまり、先頭の要素はスタックから無くなることに注意: Pick up and read the top element, i.e., the top element is removed from the stack



Stack: Python での実装例

- deque を利用: Use deque
- append(): 最後に要素を追加: Add an element at the end
- pop(): 最後の要素を取り出し、削除: Pick up and remove the last element

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Stack クラス定義

```
from collections import deque
     from typing import TypeVar, Generic
     T = TypeVar('T')
     class Stack(Generic[T]):
4
         スタックのクラス
6
         def __init__(self):#コンストラクタ
8
             self.elements:deque[T] = deque()
         def is_empty(self) -> bool: #要素が無いとき True
10
             return len(self.elements) == 0
11
         def push(self,e:T) -> None:#要素を追加
12
13
             self.elements.append(e)
         def pop(self) -> T:#末尾の要素を取り出す。要素は削除される
14
             return self.elements.pop()
15
         def peek(self) -> T:#末尾の要素を調べる
16
             return self.elements[-1]
17
         def size(self) -> int:#要素数を返す
18
             return len(self.elements)
19
         def __str__(self) -> str:#文字列化
20
21
22
             for x in self.elements:
                s += str(x)+','
23
             s = s.removesuffix(',')
24
             s += ']'
25
26
             return s
```

Stack クラス利用例

```
myStack = Stack[str]()
myStack.push('a')
myStack.push('b')
myStack.push('b')
print(myStack)

myStack.pop()
myStack.pop()
print(myStack)
```

https://github.com/discrete-math-saga/PDA

決定性プッシュダウンオートマトン

Deterministic Pushdown Automata

$$M = \langle Q, \Sigma, \Gamma, \delta, q_0, Z_0, F \rangle \tag{2.1}$$

- Q: 内部状態の集合: Set of internal states
- Σ: テープのアルファベット: Alphabet of the tape
- Γ: スタックのアルファベット: Alphabet of the stack
- $\delta: Q \times \Sigma \times \Gamma \to Q \times \Gamma^*$: **遷移関数**: Transition function
 - 注意: スタックから1文字読み、文字列を書き込む
- $q_0 \in Q$: 開始状態: Initial state
- $Z_0 \in \Gamma$: スタックの底の記号: Symbol at the bottom of the stack
- F⊆Q: 終状態の集合: Set of final states

 $Q = \{q_0, q_1, q_2\},\$

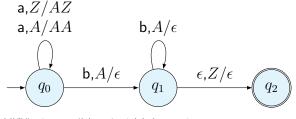
例 2.1:

$$\Sigma = \left\{ \mathsf{a}, \mathsf{b} \right\}, \qquad \qquad \Gamma = \left\{ A, Z \right\}.$$

$$\delta \left(q_0, \mathsf{a}, Z \right) = \left(q_0, AZ \right), \quad \delta \left(q_0, \mathsf{a}, A \right) = \left(q_0, A \right), \quad \delta \left(q_0, \mathsf{b}, A \right) = \left(q_0, \epsilon \right),$$

 $F = \{q_2\},$

$$\begin{array}{ll} \delta \left(q_{0}, \mathsf{a}, Z \right) = \left(q_{0}, AZ \right), & \delta \left(q_{0}, \mathsf{a}, A \right) = \left(q_{0}, A \right), & \delta \left(q_{0}, \mathsf{b}, A \right) = \left(q_{0}, \epsilon \right), \\ \delta \left(q_{1}, \mathsf{b}, A \right) = \left(q_{1}, \epsilon \right), & \delta \left(q_{1}, \epsilon, Z \right) = \left(q_{2}, \epsilon \right). \end{array}$$

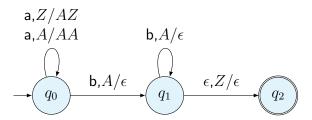


注意: $\delta\left(q_1,\epsilon,Z
ight)$ は決定的動作であることに注意。スタック文字が Z のときのみ。

動作: (Q, Σ^*, Γ^*) の変化

$$(q_0, \mathsf{aaabbb}, Z) \vdash (q_0, \mathsf{aabbb}, AZ)$$
 aを読んでいる間は q_0 に留まる $\vdash (q_0, \mathsf{abbb}, AAZ)$ $\vdash (q_0, \mathsf{bbb}, AAAZ)$ bを読むと q_1 へ遷移 $\vdash (q_1, \mathsf{bb}, AAZ)$ $\vdash (q_1, \mathsf{b}, AZ)$ $\vdash (q_1, \epsilon, Z)$ 空スタックで q_2 へ遷移 $\vdash (q_2, \epsilon, \epsilon)$

aabb に対する動作



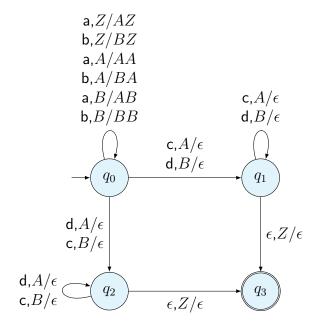
動作失敗: aとbの数が異なる

$$\begin{aligned} (q_0, \mathsf{aaabb}, X) &\vdash (q_0, \mathsf{aabb}, AZ) \\ &\vdash (q_0, \mathsf{abb}, AAZ) \\ &\vdash (q_0, \mathsf{bb}, AAAZ) \\ &\vdash (q_1, \mathsf{b}, AAZ) \\ &\vdash (q_1, \epsilon, AZ) \end{aligned}$$

例 2.2:

$$\begin{split} Q &= \{q_0, q_1, q_2, q_3\} \,, \\ \Sigma &= \{\mathsf{a}, \mathsf{b}, \mathsf{c}, \mathsf{d}\} \,, \\ \delta &\left(q_0, \mathsf{a}, Z\right) = \left(q_0, AZ\right) \,, \\ \delta &\left(q_0, \mathsf{a}, A\right) = \left(q_0, AA\right) \,, \\ \delta &\left(q_0, \mathsf{a}, A\right) = \left(q_0, AA\right) \,, \\ \delta &\left(q_0, \mathsf{a}, A\right) = \left(q_0, AB\right) \,, \\ \delta &\left(q_0, \mathsf{c}, A\right) = \left(q_1, \epsilon\right) \,, \\ \delta &\left(q_0, \mathsf{c}, A\right) = \left(q_1, \epsilon\right) \,, \\ \delta &\left(q_0, \mathsf{d}, A\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_1, \mathsf{c}, A\right) = \left(q_1, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{d}, A\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{d}, A\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,, \\ \delta &\left(q_2, \mathsf{c}, B\right) = \left(q_2, \epsilon\right) \,$$

注意: $\delta\left(q_1,\epsilon,Z
ight)$ は決定的動作であることに注意。スタック文字が Z のときのみ。



動作例:abaaccdc

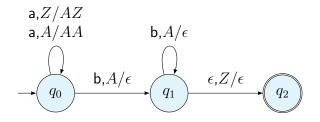
$$\begin{split} (q_0, \mathsf{abaaddcd}, Z) &\vdash (q_0, \mathsf{baaddcd}, AZ) \\ &\vdash (q_0, \mathsf{aaddcd}, BAZ) \\ &\vdash (q_0, \mathsf{addcd}, ABAZ) \\ &\vdash (q_0, \mathsf{ddcd}, AABAZ) \\ &\vdash (q_2, \mathsf{dcd}, ABAZ) \\ &\vdash (q_2, \mathsf{cd}, BAZ) \\ &\vdash (q_2, \mathsf{cd}, AZ) \\ &\vdash (q_2, \mathsf{cd}, AZ) \\ &\vdash (q_2, \mathsf{cd}, AZ) \\ &\vdash (q_3, \epsilon, \mathcal{E}) \\ &\vdash (q_3, \epsilon, \epsilon) \end{split}$$

動作例:ababdcdc

$$\begin{aligned} (q_0, \mathsf{ababdcdc}, Z) &\vdash (q_0, \mathsf{babdcdc}, AZ) \\ &\vdash (q_0, \mathsf{abdcdc}, BAZ) \\ &\vdash (q_0, \mathsf{bdcdc}, ABAZ) \\ &\vdash (q_0, \mathsf{dcdc}, BABAZ) \\ &\vdash (q_1, \mathsf{cdc}, ABAZ) \\ &\vdash (q_1, \mathsf{cdc}, ABAZ) \\ &\vdash (q_1, \mathsf{cc}, AZ) \\ &\vdash (q_1, \mathsf{c}, AZ) \\ &\vdash (q_1, \epsilon, Z) \\ &\vdash (q_3, \epsilon, \epsilon) \end{aligned}$$

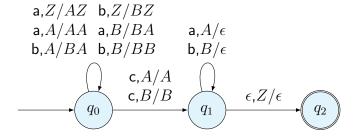
受理言語: Accepted Languages

例 2.1



- 入力とスタックが空になった時に、終状態に居るか?: Stop automata the final state when the input and stack are empty?
- 例 2.1: $L = \{ \mathsf{a}^i \mathsf{b}^i | i \in N \}$
 - a の数をスタック文字 A で記録: Record the number of a's with stack symbols A
 - テープ上の b とスタック上の A を照合: Match b's on the tape with A's on the stack
 - FA では受理できない言語: 任意の数の a の「数」を記録: FA cannot accept languages that record the number of a's
- 例 2.2 の受理言語は?: The accepted language of Example 2.2?
- 例 3.1: $L = \left\{ w c w^R | w \in (\mathsf{a} + \mathsf{b})^* \right\}$

例 3.1:



$$Q = \{q_0, q_1, q_2\},$$
 $F = \{q_2\},$ $\Sigma = \{a, b, c\},$ $\Gamma = \{A, B, Z\}.$

$$\begin{split} \delta\left(q_{0},\mathsf{a},Z\right) &= \left(q_{0},AZ\right), & \delta\left(q_{0},\mathsf{a},A\right) = \left(q_{0},AA\right), & \delta\left(q_{0},\mathsf{a},B\right) = \left(q_{0},AB\right), \\ \delta\left(q_{0},\mathsf{b},Z\right) &= \left(q_{0},BZ\right), & \delta\left(q_{0},\mathsf{b},A\right) = \left(q_{0},BA\right), & \delta\left(q_{0},\mathsf{b},B\right) = \left(q_{0},BB\right), \\ \delta\left(q_{0},\mathsf{c},A\right) &= \left(q_{1},A\right), & \delta\left(q_{0},\mathsf{c},B\right) = \left(q_{1},B\right), \\ \delta\left(q_{1},\mathsf{a},A\right) &= \left(q_{1},\epsilon\right), & \delta\left(q_{1},\mathsf{b},B\right) = \left(q_{1},\epsilon\right), & \delta\left(q_{1},\epsilon,Z\right) = \left(q_{2},\epsilon\right). \end{split}$$

動作例

$$(q_0,\mathsf{abaacaaba},Z) \vdash (q_0,\mathsf{baacaaba},AZ) \\ \vdash (q_0,\mathsf{aacaaba},BAZ) \\ \vdash (q_0,\mathsf{acaaba},ABAZ) \\ \vdash (q_0,\mathsf{caaba},AABAZ) \\ \vdash (q_1,\mathsf{aaba},AABAZ) \\ \vdash (q_1,\mathsf{aba},ABAZ) \\ \vdash (q_1,\mathsf{aba},ABAZ) \\ \vdash (q_1,\mathsf{ba},BAZ) \\ \vdash (q_1,\mathsf{c},Z) \\ \vdash (q_2,\epsilon,\epsilon)$$

動作失敗例

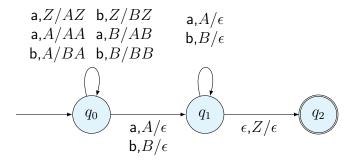
```
(q_0, \mathsf{abaaaaba}, Z) \vdash (q_0, \mathsf{baaaaba}, AZ) 
\vdash (q_0, \mathsf{aaaaba}, BAZ) 
\vdash (q_0, \mathsf{aaaba}, ABAZ) 
\vdash (q_0, \mathsf{aaba}, AABAZ) 
\vdash (q_0, \mathsf{aaba}, AAABAZ) 
\vdash (q_0, \mathsf{aba}, AAABAZ) 
\vdash (q_0, \mathsf{ba}, AAAABAZ) 
\vdash (q_0, \mathsf{a}, BAAAABAZ) 
\vdash (q_0, \mathsf{c}, ABAAAABAZ)
```

非決定性プッシュダウンオートマトン Non-deterministic PDA

$$M = \langle Q, \Sigma, \Gamma, \delta, q_0, Z_0, F \rangle \tag{4.1}$$

- Q: 内部状態の集合: Set of internal states
- Σ: テープのアルファベット: Alphabet of the tape
- Γ: スタックのアルファベット: Alphabet of the stack
- $\delta: Q \times \Sigma \times \Gamma \to 2^{Q \times \Gamma^*}$: **遷移関数**: Transition function
- $q_0 \in Q$: 開始状態: Initial state
- $Z_0 \in \Gamma$: スタックの底の記号: Symbol at the bottom of the stack
- $F \subseteq Q$: 終状態の集合: Set of final states

例 4.1:



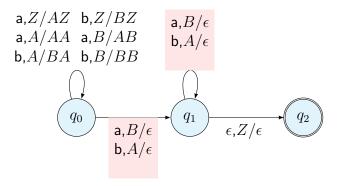
$$\begin{split} Q &= \left\{q_0, q_1, q_2\right\}, & F &= \left\{q_2\right\}, \\ \Sigma &= \left\{\mathsf{a}, \mathsf{b}, \mathsf{c}\right\}, & \Gamma &= \left\{A, B, Z\right\}. \end{split}$$

$$\delta\left(q_0, \mathsf{a}, Z\right) &= \left\{(q_0, AZ)\right\} & \delta\left(q_0, \mathsf{a}, A\right) &= \left\{(q_0, AA), (q_1, \epsilon)\right\} \\ \delta\left(q_0, \mathsf{a}, B\right) &= \left\{(q_0, AB)\right\} & \delta\left(q_0, \mathsf{b}, Z\right) &= \left\{(q_0, BZ)\right\} \\ \delta\left(q_0, \mathsf{b}, A\right) &= \left\{(q_0, BA)\right\} & \delta\left(q_0, \mathsf{b}, B\right) &= \left\{(q_0, BB), (q_1, \epsilon)\right\} \\ \delta\left(q_1, \mathsf{a}, A\right) &= \left\{(q_1, \epsilon)\right\} & \delta\left(q_1, \mathsf{b}, B\right) &= \left\{(q_1, \epsilon)\right\} \\ \delta\left(q_1, \epsilon, Z\right) &= \left\{(q_2, \epsilon)\right\} \end{split}$$

動作 (受理した例)

$$\begin{array}{c} (q_0,\mathsf{abaaaaba},Z) \vdash (q_0,\mathsf{baaaaba},AZ) \\ \qquad \vdash (q_0,\mathsf{aaaaba},BAZ) \\ \qquad \vdash (q_0,\mathsf{aaaba},ABAZ) \\ \qquad \vdash (q_0,\mathsf{aaba},AABAZ) \\ \qquad \vdash (q_1,\mathsf{aba},ABAZ) \\ \qquad \vdash (q_1,\mathsf{ba},BAZ) \\ \qquad \vdash (q_1,\mathsf{a},AZ) \\ \qquad \vdash (q_1,\epsilon,Z) \\ \qquad \vdash (q_1,\epsilon,\epsilon) \end{array}$$

例 4.2:



$$\begin{split} Q &= \{q_0, q_1\}\,, & F &= \{q_1\}\,, \\ \Sigma &= \{\mathsf{a}, \mathsf{b}, \mathsf{c}\}\,, & \Gamma &= \{A, B, Z\}\,. \end{split}$$

$$\delta\left(q_0, \mathsf{a}, Z\right) &= \{(q_0, AZ)\} & \delta\left(q_0, \mathsf{a}, A\right) &= \{(q_0, AA)\} \\ \delta\left(q_0, \mathsf{a}, B\right) &= \{(q_0, AB)\,, (q_1, \epsilon)\} & \delta\left(q_0, \mathsf{b}, Z\right) &= \{(q_0, BZ)\} \\ \delta\left(q_0, \mathsf{b}, A\right) &= \{(q_0, BA)\,, (q_1, \epsilon)\} & \delta\left(q_0, \mathsf{b}, B\right) &= \{(q_0, BB)\} \\ \delta\left(q_1, \mathsf{a}, B\right) &= \{(q_1, \epsilon)\} & \delta\left(q_1, \mathsf{b}, A\right) &= \{(q_1, \epsilon)\} \end{split}$$

動作 (受理した例)

$$(q_0,\mathsf{abaabbab},Z) \vdash (q_0,\mathsf{baabbab},AZ) \\ \vdash (q_0,\mathsf{aabbab},BAZ) \\ \vdash (q_0,\mathsf{abbab},ABAZ) \\ \vdash (q_0,\mathsf{bbab},AABAZ) \\ \vdash (q_1,\mathsf{bab},ABAZ) \\ \vdash (q_1,\mathsf{ab},BAZ) \\ \vdash (q_1,\mathsf{ab},BAZ) \\ \vdash (q_1,\mathsf{c},Z) \\ \vdash (q_1,\epsilon,\epsilon)$$

- 例 4.1: $L = \{ww^R | w \in (a+b)^*\}$
 - 注意: 折り返しの文字 c は不要: The folding character c is not necessary
- 例 4.2: w^R において a と b を入れ替えた文字列を受理: Accept strings with a and b swapped in w^R

PDA の受理言語: Accepted Languages of PDA

- PDA の受理言語は、正規表現では表せない: PDA's accepted languages cannot be expressed by regular expressions
 - 前半と後半の文字数が同じ、前後を反転などは正規表現では表せない: The number of characters in the first and second halves are the same, the second half is the reversed string of the first, etc. cannot be expressed by regular expressions
 - $L_{01}=\{0^n1^n|n\in N\}$ は正規表現で表せない: 反復補題: L_{01} cannot be expressed by regular expressions: Pumping lemma
- スタックを使うことで、前半の文字列を覚えることができる:
 Using a stack, you can remember the first half of the string
 - 長さに制限なし: No limit on length
- 再帰関数の実装にはスタックが必要: A stack is required for implementing recursive functions

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回文の集合は正規言語ではない:

A set of palindromes is not a regular language

- 0と1からなる回文全体 *L* が正規言語であると仮定: Assume that the entire set of palindromes *L* consisting of 0's and 1's is a regular language
- 反復補題に現れるn に対して、 $w=xyz=0^n1^n1^n0^n$ を考える: Consider $w=xyz=0^n1^n1^n0^n$ for n appearing in the pumping lemma
- $|xy| \le n \, \text{J} \, \text{J} \, , \ y = 0^k (1 \le k \le n)$

$$xy^0z = xz = 0^{n-k}1^n1^n0^n \notin L$$

• L は正規言語ではない: L is not a regular language

回文(palindrome) 受理する Python コード: 再帰

```
def palindrome(inputStr:str) -> bool:
    if len(inputStr) <= 1:
        return True
    if inputStr[0] != inputStr[-1]:
        return False
    return palindrome(inputStr[1:-1])</pre>
```

回文 (palindrome) 受理する Python コード: 非 再帰

```
def palindrome2(inputStr:str) -> bool:
1
         myStack:Stack[str] = Stack()
2
         n = len(inputStr)
3
         m = n//2
4
         for i in range(m):#前半をスタックに積む
5
6
             myStack.push(inputStr[i])
         if n % 2 !=0:#入力の長さが奇数の場合
             m += 1
         for j in range(m,n):#後半と照合
             c = myStack.pop()
10
             if c != inputStr[j]:
11
                return False
12
13
         return True
```