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Introduction

Introduction

• Neural Networks is a machine learning method that is inspired by the human brains (neuron and synapse).



• In the language of statistics, a neural network is just a type of additive single index regression model with a hierarchical structure (layers):

$$Y = f\left(\cdots g\left(\sum_{m=1}^{M} h_m(\mathbf{X}^{\top} \alpha_m) \beta_m\right) \cdots\right) + error$$

Introduction

- As the number of layers increases (= "deep" neural networks), the number of parameters needed to be learned will increase rapidly; computationally extremely burdensome and thought to be intractable in practice, until recently.
- Deep Learning: set of techniques for learning deep neural networks.
- The advance of computational power and the development of deep learning made the use of deep neural networks practically possible.
- Currently, neural networks and deep learning provide the highest performances in many applications, such as image recognition and language processing.

- A single-layer neural network can be viewed as a two-stage regression model.
- Response variable: Y (either continuous or binary).
- Input variables: $\mathbf{X} = (X_1, \dots, X_v)^{\top}$.
- Predicted value of Y given X: $\widetilde{Y}(X; \theta)$, where

$$\widetilde{Y}(\mathbf{X};\theta) = g(T)$$

$$T = \beta_0 + \sum_{m=1}^{M} Z_m \beta_m$$

$$Z_m = \sigma \left(\alpha_{m,0} + \sum_{j=1}^{p} X_j \alpha_{m,j} \right)$$
(1)

$$\theta = (\alpha, \beta), \ \alpha = (\alpha_{1,0}, \alpha_{1,1}, \dots, \alpha_{M,p}) \text{ and } \beta = (\beta_0, \beta_1, \dots, \beta_M).$$

• (1) can be written in a single nonlinear regression model:

$$Y = \underbrace{g\left(\beta_0 + \sum_{m=1}^{M} \sigma\left(\alpha_{m,0} + \sum_{j=1}^{p} X_j \alpha_{m,j}\right) \beta_m\right)}_{=\widetilde{Y}(\mathbf{X};\theta)} + error.$$

- The function $\sigma(\cdot)$ is called the activation function. The choice of activation function significantly influences the performance of neural networks. (This issue will be discussed later.)
- The output function $g(\cdot)$ allows a final transformation of the intermediate output T. For example,
 - Regression: g(T) = T.
 - Binary classification: $g(T) = \exp(T)/[1 + \exp(T)]$.

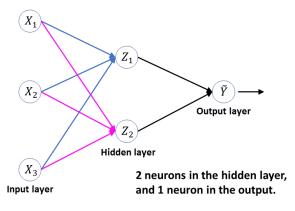
• The units in the middle of the network,

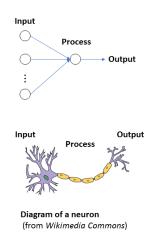
$${Z_m: 1 \leq m \leq M}, \ Z_m = \sigma\left(\alpha_{m,0} + \sum_{j=1}^p X_j \alpha_{m,j}\right)$$

are called hidden units because the values of Z_m 's are not directly observed.

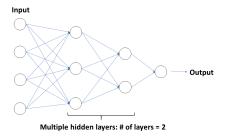
- We can think of Z_m as a "generated" regressor that is constructed from the weighted average (linear combination) of the original input X.
- The above single layer neural network (1) can be represented by the following *network diagram*.

3 inputs, single hidden layer with M = 2, scalar-valued response variable.





 In general, there can be more than one hidden layer: multi-layer neural networks (deep neural networks).



- As the number of hidden layers increases, deeper neural networks are formed, and the capacity of neural networks to learn increasingly more complex information increases.
 - Deep learning is a set of machine learning techniques that can be used to optimize such deep neural networks.

- The purpose of the activation function $\sigma(\cdot)$ is to introduce a "nonlinearity" into the neural network.
- If $\sigma(\cdot)$ and $g(\cdot)$ are linear, the neural network collapses to a linear regression model; in the special case when both functions are identity,

$$Y = g \left(\beta_0 + \sum_{m=1}^{M} \sigma \left(\alpha_{m,0} + \sum_{j=1}^{p} X_j \alpha_{m,j}\right) \beta_m\right) + error$$

$$= \beta_0 + \sum_{m=1}^{M} \left(\alpha_{m,0} + \sum_{j=1}^{p} X_j \alpha_{m,j}\right) \beta_m + error$$

$$= c_0 + \sum_{j=1}^{p} X_j c_j + error$$

where
$$c_0 = \beta_0 + \sum_{m=1}^M \alpha_{m,0} \beta_m$$
, and $c_i = \sum_{m=1}^M \alpha_{m,i} \beta_m$.

Commonly used activation functions are: letting $\mathbf{X}_m^* = \sum_{i=1}^p X_i \alpha_{m,i}$,

• Logistic function:

$$\sigma\left(\alpha_{m,0} + \mathbf{X}_{m}^{*}\right) = \frac{\exp(\alpha_{m,0} + \mathbf{X}_{m}^{*})}{1 + \exp(\alpha_{m,0} + \mathbf{X}_{m}^{*})}.$$

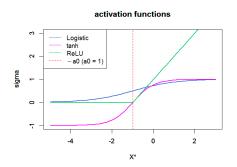
Hyperbolic tangent:

$$\sigma\left(\alpha_{m,0} + \mathbf{X}_{m}^{*}\right) = \tanh(\alpha_{m,0} + \mathbf{X}_{m}^{*}).$$

• ReLU (Rectified Linear Unit):

$$\sigma\left(\alpha_{m,0}+\mathbf{X}_{m}^{*}\right)=\max\{0,\alpha_{m,0}+\mathbf{X}_{m}^{*}\}.$$

Currently, ReLU is the most popularly used for deep neural networks.



Fitting Neural Networks

- Suppose that we have training data of size N: $\{(Y_i, \mathbf{X}_i) : 1 \le i \le N\}$.
- In the neural network

$$\widetilde{Y}(\mathbf{X};\theta) = g\left(\beta_0 + \sum_{m=1}^{M} \sigma\left(\alpha_{m,0} + \sum_{j=1}^{p} X_j \alpha_{m,j}\right) \beta_m\right),$$

there are M(p+2)+1 unknown parameters:

$$\{(\alpha_{m,0},\alpha_{m,1},\ldots,\alpha_{m,p}): 1 \leq m \leq M\}: M(p+1),$$

 $\{\beta_0,\beta_1,\ldots,\beta_M\}: M+1.$

• To learn these parameters from the training dataset, we need to set an objective function (i.e., loss function).

The goal of learning is to obtain

$$\widehat{\theta}_N = \operatorname*{argmin}_{\theta} \ell_N(\theta)$$

for some loss function $\ell_N(\cdot)$.

• Regression: Y = continuous and g(T) = T,

$$\ell_N(heta) = \sum_{i=1}^N s_i(heta)$$
 , where $s_i(heta) = (Y_i - \widetilde{Y}(\mathbf{X}_i; heta))^2$.

• Binary classification: $Y = \text{dummy and } g(T) = \frac{\exp(T)}{1 + \exp(T)}$,

$$\ell_N(heta) = \sum_{i=1}^N s_i(heta)$$
 , where negative log-likelihood

$$s_i(\theta) = -\left[Y_i \ln \widetilde{Y}(\mathbf{X}_i; \theta) + (1 - Y_i) \ln(1 - \widetilde{Y}(\mathbf{X}_i; \theta))\right].$$

- Since $\ell_N(\theta)$ is not convex in general, it is impossible to directly find a "global" minimizer.
- Then, we instead consider to find a "local" minimizer of $\ell_N(\theta)$.
- The generic approach to (locally) minimizing $\ell_N(\theta)$ is by a Gradient Descent Method.
- Here, the gradient means the gradient vector defined by

$$\nabla \ell_N(\theta) = \left[\frac{\partial \ell_N(\theta)}{\partial \alpha_{1,0}}, \dots, \frac{\partial \ell_N(\theta)}{\partial \beta_M}\right]^\top.$$

$$(M(p+2)+1)\times 1$$

(Recall:
$$\theta = (\alpha, \beta) = (\alpha_{1,0}, \dots, \alpha_{M,p}, \beta_0, \dots, \beta_M)$$
)

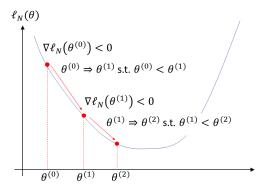
- Set an initial candidate value of θ as $\theta^{(0)}$.
- The gradient descent method generates a new guess $\theta^{(t+1)}$ by moving in the negative gradient direction:

$$\theta^{(t+1)} = \theta^{(t)} - \gamma_t \nabla \ell_N(\theta^{(t)}) \ (t = 0, 1, ...),$$

where γ_t is the parameter that determines the amount of update at the t-th iteration, which is called the learning rate.

• If the learning rate is sufficiently small, it must hold that

$$\ell_N(\theta^{(t)}) \ge \ell_N(\theta^{(t+1)}) \ge \ell_N(\theta^{(t+2)}) \ge \cdots$$



ullet Thus, for sufficiently large t and small γ_t , we will obtain

$$\nabla \ell_N(\theta^{(t)}) \approx 0$$
,

and then the iteration stops, and define $\widehat{\theta}_N = \theta^{(t)}$ for such t.¹

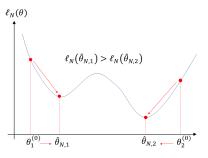
- A practical difficulty in directly implementing the above method: the partial derivatives of $\ell_N(\theta)$ w.r.t. the parameters in a layer closer to the input layer have more complicated form to calculate.
 - This can be a serious problem particularly when using deeper neural networks.
 - Several computationally easy-to-implement algorithms to perform gradient descent have been proposed; e.g., back-propagation.

 $^{^1}$ Obviously, how to choose an optimal learning rate γ_t in practice is a critical problem determining the quality of the learning. There is a huge literature on this issue; however, beyond the scope of this lecture.

Some Issues in Training Neural Networks

Starting Values

One should try several starting values to get the best solution.²



- The starting values $\theta^{(0)}$ are usually chosen to be random values near zero.
- Note that using exact zero weights leads to perfect symmetry among the units in the same layer, and the learning fails.

 $^{^2}$ Another approach is Bagging: take the average of the predictions from several different neural networks.

Scaling of the Inputs

- The scaling of the inputs determines the effective scaling of the weights in the bottom layer, and it can have a large effect on the quality of the solution.
- It is common to standardize the input variables (subtract the mean and divide by the standard deviation) before running the learning algorithm.

Number of Hidden Units and Layers

- Generally speaking it is better to have too many hidden units (M) than too few.
- It is most common to put down a reasonably large number of units and train them with regularization (LASSO, etc).
- Choice of the number of hidden layers is guided by background knowledge and experimentation (this is still a theoretically unsolved problem).

Neural Networks in R

Spam Email Data

- Training data: spam_train.csv, Test data: spam_test.csv
- The data csv files are available from my website or from Course Navi.
- In this exercise, we use the **neuralnet** package.

```
install.packages("neuralnet")
library(neuralnet)
```

Set your working directory appropriately, and import the csv files:

```
setwd("C:/Rdataset")
train <- read.csv("spam_train.csv")
test <- read.csv("spam_test.csv")</pre>
```

```
head(train)
                    mail
                                will.
                                            free
          our
                                                         you
                                                                   your
 -0.13713261
               2.0171787
                           0.3925946
                                      0.49788818
                                                  0.6803231
                                                              0.6081222
  1,61748092
               1.0710834
                          -0.6286443
                                      1.95103913
                                                 -0.4123388
                                                              0.4915342
 -0.01817576 -0.3713240
                         -0.2804946
                                      0.06194289
                                                  0.2579022
                                                              1.8489515
 -0.46426394 -0.1696972
                           0.1372849 -0.30134485 -0.3391192
                                                             -0.1247166
 -0.46426394 -0.3713240 -0.6286443
                                     -0.30134485
                                                  0.4888256 -0.6743457
6 - 0.46426394 - 0.3713240 - 0.6286443 - 0.30134485 - 0.9361406 - 0.6743457
  exclamation
                  dollar capitalAve capitalLong capitalTotal
                                                                   type
                           0.12318162
                                       0.06581726
    0.4780467
              0.1553156
                                                     0.7334251
                                                                   spam
  0.3701602 0.5620147 -0.01769697
                                       0.06068619
                                                    -0.1159224
                                                                   spam
  -0.3298764
                                                     -0.1621005
               0.5498137
                         -0.10862197
                                      -0.21126026
                                                                   spam
  -0.3298764 - 0.3083214 0.01296855
                                       0.02476874
                                                    1.4458874 nonspam
  0.4657869 -0.3083214
                          0.02154103 -0.03167298
                                                     -0.3121794
                                                                   spam
                                                     -0.2528075
  -0.1803064 -0.3083214 -0.09418743
                                      -0.20612919
                                                                nonspam
  dim(train)
    3601
          12
  dim(test)
[1] 1000
           12
```

Definitions of variables

```
Response variable
```

type "spam" or "nonspam"

Input variables

our, ..., your the frequency of the variable name in the email.

exclamation, dollar the frequency of the characters "!" and "\$" in the email.

capitalAve, Long, Total the average, longest and total run-length of capital letters.

* All input variables are standardized.

• We first transform the response variable into a dummy variable.

```
train$type <- train$type == "spam"
test$type <- test$type == "spam"</pre>
```

• Logistic regression (binary logit model):

```
Estimate Std. Error z value Pr(>|z|)
(Intercept)
            0.06514
                      0.06733
                               0.967 0.333310
            0.48660
                      0.05407 9.000 < 2e-16 ***
our
mail
            0.18191
                      0.05221 3.484 0.000493 ***
will
                      0.05647
           -0.18123
                              -3.210 0.001329 **
            0.87583 0.08552
                             10.242 < 2e-16 ***
free
you
            0.04772 9.575 < 2e-16 ***
your
           0.45690
exclamation 0.66066
                      0.08776 7.528 5.13e-14
dollar
           2.39538
                      0.17056 14.044 < 2e-16 ***
capitalAve -0.47163
                      0.56789
                             -0.831 0.406254
capitalLong 2.77667
                      0.37104 7.484 7.23e-14
capitalTotal 0.25398
                      0.07718
                               3.291 0.001000 ***
```

- Fitting neural networks: use the function neuralnet().
- The basic syntax of neuralnet () is as follows:

- hidden: an integer or a vector of integers specifying the number of hidden units in each layer.
- act.fct: activation function: "logistic" or "tanh".
- err.fct: loss function: "sse" (sum of squared errors) or "ce" (cross entropy / negative log-likelihood).
- linear.output: whether the output function is an identity function or not: "TRUE" or "FALSE".

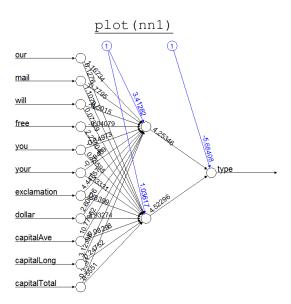
Single-layer 2 hidden units:

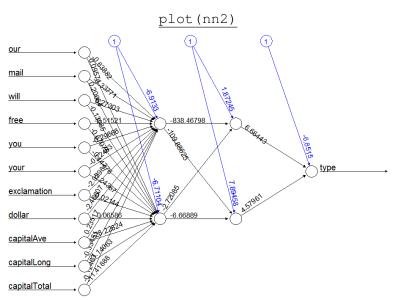
```
nn1 <- neuralnet(type ~ ., data = train, hidden = 2,
act.fct = "logistic", err.fct = "ce", linear.output = FALSE)</pre>
```

• 2-layer 2 hidden units for each (a deep neural network):³

```
nn2 <- neuralnet(type \sim ., data = train, hidden = c(2,2), act.fct = "logistic", err.fct = "ce", linear.output = FALSE)
```

 $^{^3} The optimization of deep neural networks is much more difficult than that of single-layer neural networks. If the following optimization does not return a solution, try typing set.seed(10) before running it.$





• Computation of $\widetilde{Y}(\mathbf{X}^{\text{test}}; \theta)$ (= classification score $s(\mathbf{X}^{\text{test}})$, see Lecture Note # 7):

```
s1 <- predict(nn1, newdata = test)
s2 <- predict(nn2, newdata = test)
s.log <- predict(logit, newdata = test)</pre>
```

Load the ROCR package and create "prediction" object:⁴

```
library(ROCR)
pred1 <- ROCR::prediction(s1, test$type)
auc1 <- performance(pred1, "auc")@y.values[[1]]
roc1 <- performance(pred1, "tpr", "fpr")</pre>
```

⁴Both packages ROCR and neuralnet contain prediction() function with the same name for different purposes. Here, since we would like to use prediction() function from the ROCR, we need to specify using the :: double colons.

pred2 <- ROCR::prediction(s2, test\$type)</pre>

Similarly,

```
auc2 <- performance(pred2, "auc")@y.values[[1]]
  roc2 <- performance(pred2, "tpr", "fpr")

and

pred.log <- ROCR::prediction(s.log, test$type)
auc.log <- performance(pred.log, "auc")@y.values[[1]]
roc.log <- performance(pred.log, "tpr", "fpr")</pre>
```

• Check the AUC scores: c(auc1,auc2,auc.log)

```
> c(auc1,auc2,auc.log)
[1] 0.9391928 0.9474122 0.9202770
```

The deep neural network nn2 performs the best.

Plot the ROC curves:

```
plot(roc1, col = "royalblue")
par(new = T)
plot(roc2, col = "magenta")
par(new = T)
plot(roc.log, col = "black")
```

