Taeyoon Kim

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in Taeyoon Kim │ 🞧 taeraemon │

Seoul, Republic of Korea

EXPERIENCE

Perigee Aerospace []

Feb 2023 - Jan 2024

Engineer, Flight Control Team (Dynamics & Control)

Daejeon, South Korea

- Developed avionics firmware for the suborbital launch vehicle BW0.4
- Developed inspection software for BW0.4
- Developed an IRIG 313-01 compliant flight termination system (FTS) for BW0.4
- Performed HILS, WDR, and static fire tests for BW0.4

• **S.O.X** [�]

May 2021 - Aug 2022

Freelancer

Seoul, South Korea

- Participated in the development of indoor localization using GPR
- Developed a mobile app for collecting WiFi, BLE, and LTE signals
- Developed an LTE-based signal collecting tag

EDUCATION

Seoul National University

Mar 2024 - Present

M.S. in Intelligent Aerospace Systems (Interdisciplinary Program)

Seoul, South Korea

o GPA: 3.89/4.3

Kwangwoon University

Mar 2019 - Feb 2023

B.S. in Electronic and Communications Engineering

Seoul, South Korea

∘ GPA: 3.61/4.5

PROJECTS

• Integrated Navigation Systems for Precision Landing of Reusable Launch Vehicles

Jan 2025 - Present

Tools: MATLAB, Python, C/C++, ROS2, Gazebo

Hanwha Aerospace

- Developing integrated navigation algorithms to achieve high altitude accuracy during the landing phase of reusable launch vehicles
- Artificial Intelligence Research Laboratory for Flight Control

Feb 2024 - Present

Tools: MATLAB, Python

Agency for Defense Development

- Conducted research on methodologies for selecting and detecting valid targets in infrared imagery, focusing on reliable extraction of meaningful target data
- Developed AI-based tracking algorithms to enable robust and accurate tracking of detected targets in infrared video

PATENTS AND PUBLICATIONS

C=CONFERENCE, J=JOURNAL, P=PATENT, S=IN SUBMISSION, T=THESIS

- [C.3] T. Y. Kim, C. G. Park (2025). **Performance Evaluation of Infrared Target Tracking Method in Virtual Environment**. In *Proceedings of the KSAS 2025 Spring Conference*, Korean Society for Aeronautical and Space Sciences (KSAS), Paper No. 1075–1076. 2025.
- [C.2] T. Y. Kim, C. G. Park (2024). Performance Analysis of Siamese Tracker Through Preprocessing of Infrared Images. In 2025 17th International Conference on Knowledge and Smart Technology (KST), Bangkok, Thailand, 2025, pp. 1-4, doi: 10.1109/KST65016.2025.11003338.
- [C.1] T. Y. Kim, I. H. Lee, C. G. Park (2024). Infrared Target Tracking Method Based on Siamese Network with Template Update. In *Proceedings of the KSAS 2024 Fall Conference*, Korean Society for Aeronautical and Space Sciences (KSAS), Paper No. 1292–1293. 2024.

SKILLS

- Programming Languages: C, C++, Python, MATLAB, Simulink, Verilog, Assembly
- Libraries: ROS1, ROS2, PyTorch, PyQt
- Embedded Systems: STM32, Altera, Arduino
- Hardware design: EasyEDA, KiCad, Altium, Orcad(Virtuoso, Hspice, Capture, PSpice), Inventor
- Simulation: Gazebo, Unity

HONORS AND AWARDS

• Grand Prize - 22nd Korea Robot Aircraft Competition (AAM Tech Challenge)

Oct 2024

Ministry of Trade, Industry and Energy (MOTIE), Republic of Korea

• Awarded the **grand prize** as a member of the SNU team "Bulnabi" for outstanding performance in UAV development and innovation.

CERTIFICATIONS

• Class 3 Amateur Radio Operator (Morse Code)

Jun 2020

REFERENCES

1. Chan Gook Park

Professor, Department of Aerospace Engineering

Seoul National University Email: chanpark@snu.ac.kr Phone: +82-2-880-7308

Relationship: Advisor during M.S. program