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1 Section 7.1

1.1 7.1.1

Transform the given differential equation into an equivalent system of first-order differential equations.

$$x'' + 4x' - 3x = 6t$$

Let $x_1 = x$ and $x_2 = x'$. Complete the system below.

$$\begin{aligned} x_1' &= x_2 \\ x_2' &= -4x' + 3x + 6t = -4x_2 + 3x_1 + 6t \end{aligned}$$

1.2 7.1.2

Transform the given differential equation into an equivalent system of first-order differential equations.

$$x^{(4)} + 5x'' + 2x = 5t^3 \sin(2t)$$

Let $x_1 = x$, $x_2 = x'$, $x_3 = x''$, and $x_4 = x^{(3)}$. Complete the system below.

$$\begin{aligned} x_1' &= x_2 \\ x_2' &= x_3 \\ x_3' &= x_4 \\ x_4' &= -5x'' - 2x + 5t^3 \sin(2t) = -5x_3 - 2x_1 + 5t^3 \sin(2t) \end{aligned}$$

1.3 7.1.5

Transform the given differential equation into an equivalent system of first-order differential equations.

$$x^{(3)} = (x'')^2 - 2 \cos(x')$$

Let $x_1 = x$, $x_2 = x'$, and $x_3 = x''$. Complete the system below.

$$\begin{aligned}x'_1 &= x_2 \\x'_2 &= x_3 \\x'_3 &= (x_3)^2 - 2\cos(x_2)\end{aligned}$$

1.4 7.1.8

Transform the given differential equation into an equivalent system of first-order differential equations.

$$\begin{aligned}x'' + 6x' - 6x - 5y &= 0 \\y'' - 4y' + 3x - 5y &= \sin(t)\end{aligned}$$

Let $x_1 = x$, $x_2 = x'$, $y_1 = y$, and $y_2 = y'$. Complete the system below.

$$\begin{aligned}x'_1 &= x_2 \\x'_2 &= -6x' + 6x + 5y = -6x_2 + 6x_1 + 5y_1 \\y'_1 &= y_2 \\y'_2 &= 4y' - 3x + 5y + \sin(t) = 4y_2 - 3x_1 + 5y_1 + \sin(t)\end{aligned}$$

1.5 7.1.9

Transform the given differential equation into an equivalent system of first-order differential equations.

$$\begin{cases} x'' = 9x - y + 3z \\ y'' = x + y - 3z \\ z'' = 6x - y - z \end{cases}$$

$$\begin{aligned}x'_1 &= x_2 \\y'_1 &= y_2 \\z'_1 &= z_2\end{aligned}$$

$$\begin{aligned}x'_2 &= 9x_1 - y_1 + 3z_1 \\y'_2 &= x_1 + y_1 - 3z_1 \\z'_2 &= 6x_1 - y_1 - z_1\end{aligned}$$

1.6 7.1.22

- (a) Beginning with the general solution of the system $x' = -2y$, $y' = 2x$, calculate $x^2 + y^2$ to show that the trajectories are circles.
- (b) Show similarly that the trajectories of the system $x' = \frac{1}{2}y$, $y' = -8x$ are ellipses with equation of the form $16x^2 + y^2 = C^2$.

- (a) Find the solution of the system $x' = -2y$, $y' = 2x$ below. Start with $x(t)$.

$$\begin{aligned}x' &= -2y \\x'' &= -2y' \\x'' &= -2(2x) \\x'' + 4x &= 0\end{aligned}$$

$$\begin{aligned}r^2 + 4 &= 0 \\r &= \pm 2i\end{aligned}$$

$$x(t) = C_1 \cos(2t) + C_2 \sin(2t)$$

Now find $y(t)$ so that $y(t)$ and the solution for $x(t)$ found in the previous step are a general solution to the system of differential equations.

$$\begin{aligned}y' &= 2x \\y' &= 2(C_1 \cos(2t) + C_2 \sin(2t)) \\\int y' dt &= 2 \int (C_1 \cos(2t) + C_2 \sin(2t)) dt \\y(t) &= C_1 \sin(2t) - C_2 \cos(2t)\end{aligned}$$

Now calculate and simplify $x^2 + y^2$.

$$\begin{aligned}x^2 + y^2 &= (C_1 \cos(2t) + C_2 \sin(2t))^2 + (C_1 \sin(2t) - C_2 \cos(2t))^2 \\x^2 + y^2 &= C_1^2 + C_2^2\end{aligned}$$