

Article

Improving Access to Justice with Legal Chatbots

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Abstract: On average, one in three Canadians will be affected by a legal problem over a three-year period. Unfortunately, whether it is legal representation or legal advice, the very high cost of these services excludes disadvantaged and most vulnerable people, forcing them to represent themselves. For these people, accessing legal information is therefore critical. In this work, we attempt to tackle this problem by embedding legal data in a conversational interface. We introduce two dialog systems (chatbots) created to provide legal information. The first one, based on data from the Government of Canada, deals with immigration issues, while the second one informs bank employees about legal issues related to their job tasks. Both chatbots rely on various representations and classification algorithms, from mature techniques to novel advances in the field. The chatbot dedicated to immigration issues is shared with the research community as an open resource project.

Keywords: Chatbot; Information Retrieval; Natural Language Processing; Question Answering System; Dialog System

1. Introduction

The non-representation of a high proportion of litigants is one of the most striking factors contributing to problems of access to justice. Laniel *et al.* [1] addresses this problem and highlights the unintended side of this situation for many litigants, while judges treat "self-representation" as a choice, if not a privilege. To reflect the fact that this situation is often not a choice, the authors prefer to refer to it as "non-representation". Schneider [2] describes the situation in the United States, where the Supreme Court has ruled that requests submitted by a Non-Represented Litigants (NRLs) (*pro se complaints*) should be subject to a lower level of requirement than motions brought by counsel. According to the author, the criteria used by the courts to determine the validity of claims further disadvantages NRLs. The onus is on the plaintiff to show that the complaint is credible, which is difficult for those typically under-resourced. This gap is even greater where preliminary research is required, or where the opposition holds all the key elements of the case. According to Schneider [2], the constraints of building a case and studying pleadings jeopardize the right to represent oneself in court and even the constitutional right of citizens to an opportunity to be heard.

Beyond the high costs of consultation and representation that hinder the representation of litigants, other obstacles make access to justice difficult, such as limited access to legal information, but also geographical constraints, etc. Our contribution in the form of an immigration chatbot could facilitate access to information for litigants in this area. The work presented in this article was carried out as part of the LegalIA project¹. This project brings together researchers from Université du Québec à

¹ <https://legalia.uqam.ca/>

32 **Montréal (UQAM)**, Concordia University and Université de Montréal around the issue of the ethical
 33 and responsible development of the law. To present the project, we produced a video² illustrating the
 34 need for such initiatives. The first part of the proposal is to create a chatbot to assist the actors in the
 35 legal field: lawyers, judges and litigants. This tool will then constitute a case study for the sociological
 36 and ethical analyses in the second phase of the project. In practice, the contribution presented here
 37 approaches the part intended for individuals, as opposed to lawyers and judges, as described in the
 38 video. There are many other initiatives that address different facets of the access to justice problem.
 39 Some associations offer free legal aid to the most disadvantaged. In Montreal, for example, clinic *Droits*
 40 *Devant* accompanies homeless people, and helps them protect their rights, particularly during criminal
 41 proceedings. In several universities, students have access to free legal advice (e.g., at Université de
 42 Montréal and **UQAM**), provided by law school students under professional supervision. Since March
 43 2018, the website *La boussole juridique*³ lists organizations which offer legal services for free or at a
 44 lower cost.

45 In Quebec, *Éducaloï*⁴ brings together experts from many legal fields and produces concise guides
 46 to inform citizens about their rights. These guides facilitate access to legal information by popularizing
 47 it and organizing it into more user-friendly elements which better correspond to what people are
 48 looking for than would a simple popularization of each piece of legislation. It is in this context, and
 49 particularly considering the problems of access to legal information, that our work fits in. The global
 50 context of our research is that of access to justice and how to improve its current state using AI-powered
 51 technology, but in this work, we focus on access to information. In practice, **we develop Information**
52 Retrieval (IR)-based chatbots in two different settings. The first is targeted at the general public in
 53 need of immigration information. The second is an internal resource for the employees of **National**
 54 **Bank of Canada (NBC)** who have questions regarding the legality of different aspects of their jobs.

55 First, we introduce in Section 2 recent developments in chatbot technology in the areas we are
 56 interested in. Next, we explain in Section 3 the methodology we followed in this work. We describe
 57 in Section 3.2 the data used, as well as the problems we encountered, especially in collecting them.
 58 Section 4 reports on the experiments as well as their analysis. Finally, the last Section summarizes the
 59 work carried out and presents future steps.

60 2. State of the Art

61 In this Section, we introduce important work and recent best approaches in the areas we are
 62 interested in. To properly understand the approaches used by the proposed systems and their
 63 limitations, it is necessary to know the metrics used to evaluate them. We therefore begin by defining
 64 them. Next, we introduce predictive justice approaches, and we end with dialogue systems. For more
 65 details on the presented techniques, we recommend these two reference manuals: [3] for **Natural**
 66 **Language Processing (NLP)** and [4] for **IR**.

67 2.1. Evaluation Metrics

68 In **IR** and classification, the following metrics are often used for binary classification. For each
 69 metric, one can calculate the results by class and aggregate them afterwards if the problem has more
 70 than two classes. Instances of the positive class, correctly classified, are called True Positives (TP). True
 71 Negatives (TN), False Positives (FP) and False Negatives (FN) are defined in the same way.
 72 The **precision** is the proportion of truly positive instances among those identified as positive by the
 73 system: precision = $\frac{TP}{TP+FP}$.

2 <https://legalia.uqam.ca/legalia/>

3 <http://boussolejuridique.ca/>

4 <https://www.educaloi.qc.ca/>

Table 1. Confusion matrix for a three-class classification problem

		predicted		
		A	B	C
true	A	3	1	1
	B	4	5	1
	C	0	1	6

74 The **recall** is the proportion of truly positive instances that have been correctly classified by the system:
 75 $\text{recall} = \frac{\text{TP}}{\text{TP} + \text{FN}}$.

76 Figure 1⁵ illustrates which part of the dataset precision and recall refer to.

77 The **accuracy** is the proportion of instances, both positive and negative, that were classified correctly:
 78 $\text{accuracy} = \frac{\text{TP} + \text{TN}}{\text{TP} + \text{FN}}$.

79 Accuracy can be used if the classes are well balanced, but will give biased results towards the majority
 80 class otherwise. For example, with a 90/10 distribution of instances between the positive class and the
 81 negative class, the rule "always assigns to the positive class" would get 90% accuracy.

82 The **F-measure F₁** is the harmonic mean of precision and recall: $F_1 = 2 \frac{\text{precision} \times \text{recall}}{\text{precision} + \text{recall}}$.

83 In general, this metric is the best choice if the classes are not well balanced.

84 Each of the aforementioned metrics is defined in the case of a binary classification, and must be
 85 aggregated to evaluate a multi-class classification system. Then, three different averages are used: the
 86 *micro*, *macro* and *weighted* averages, which are defined and illustrated hereafter.

87 For example, consider a classification task with 3 classes A, B and C where there can be only one class
 88 for each example, the results provided by the classification system being reported in the confusion
 89 matrix from Table 1.

90 In the case of the **micro-average**, one evaluates all the classes together. For the **micro-precision**
 91 (**microP**), one counts the total of TP and FP using the confusion matrix:

92 $\text{TP} = \text{TP}_A + \text{TP}_B + \text{TP}_C = 3 + 5 + 6 = 14$, $\text{FP} = \text{FP}_A + \text{FP}_B + \text{FP}_C = 4 + 2 + 2 = 8$, then one calculates
 93 the micro-precision = $\frac{\text{TP}}{\text{TP} + \text{FP}} = \frac{14}{14+8} \approx 0.64$.

94 For the **macro-precision (macroP)**, the precision for each class is calculated (which is noted p_A to p_C),
 95 then the average is calculated. Using the same example, one has $p_A = \frac{\text{TP}_A}{\text{TP}_A + \text{FP}_A} = \frac{3}{7}$, same for p_B and
 96 p_C . Macro-precision is therefore: $(p_A + p_B + p_C)/3 = (\frac{3}{7} + \frac{5}{7} + \frac{3}{4})/3 \approx 0.63$

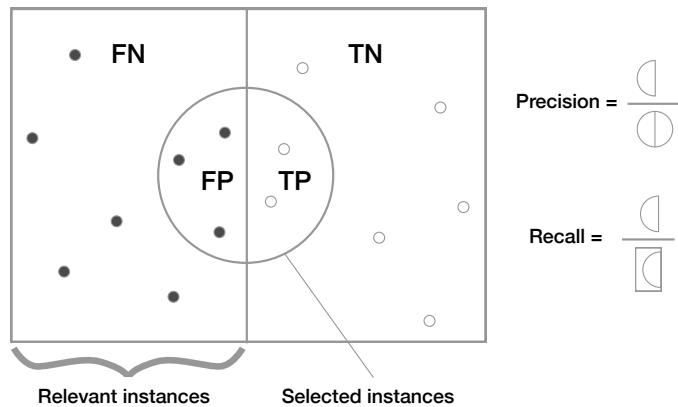
97 The weighted average assigns a weight to each class equal to the number of instances associated with
 98 it. In our case of 22 instances, they are respectively 5 instances of A, 10 of B and 7 of C. The **weighted**
 99 **precision (wP)** is therefore $(p_A \times 5 + p_B \times 10 + p_C \times 7)/3 = (\frac{3 \times 5}{7} + \frac{5 \times 10}{7} + \frac{3 \times 7}{4})/22 \approx 0.66$.

100 Notation: In all this document, a variable in bold, for instance \mathbf{v} , denotes a vector.

The **cosine similarity** between two vectors allows to compare these two vectors with each other, being equal to their scalar product divided by the product of their Euclidean norms. With two vectors \mathbf{v}_1 , \mathbf{v}_2 and θ the angle between \mathbf{v}_1 and \mathbf{v}_2 :

$$\text{sim}(\mathbf{v}_1, \mathbf{v}_2) = \cos(\theta) = \frac{\mathbf{v}_1 \cdot \mathbf{v}_2}{|\mathbf{v}_1| \times |\mathbf{v}_2|} \quad (1)$$

5 Contribution by a Wikipedia author https://en.wikipedia.org/wiki/Precision_and_recall#/media/File:Precisionrecall.svg, visited January 2, 2020, adjusted for landscape format.

**Figure 1.** Graphical interpretation of accuracy and recall**Table 2.** Example of BoW representations with a small corpus

	a	all	am	apply	can	for	foreign	get	how	I	on	online	student	to	visa	while	work
A	1	1	0	1	1	1	1	0	0	0	0	1	1	0	1	0	
B	1	0	0	0	0	0	0	1	1	0	1	0	1	1	1	0	
C	1	0	1	0	1	0	0	0	1	1	0	0	1	0	0	1	

101 2.2. Representation Learning and Text Classification

102 One of the main sources of performance improvement in [NLP](#) is the way the text is represented
 103 so that it can be processed by the different classification algorithms. To understand the value of current
 104 techniques, it is important to put them in context. This Section describes the main methods that have
 105 been used over time. We will see later that some of them, although developed several decades ago,
 106 still make it possible to design competitive models in various contexts.

107 2.2.1. Bag-of-Words and Variants

108 One of the most naive ways to represent a textual document is to use the unordered set of words
 109 that make it up. This technique is called [Bag-of-Words \(BoW\)](#). The representation of a particular
 110 document depends on a dictionary of terms, which is usually built on the whole corpus of available
 111 documents. For each document, a vector is built, with coordinate values of 0 or 1 depending on the
 112 presence or absence of each word in the dictionary. The binary variables can also be replaced by the
 113 number of occurrences of each word. In both cases, this leads to the production of sparse vectors,
 114 because their coordinates consist mainly of zeros. A toy example is given using the following very
 115 short documents:

- 116 A: "All foreign students can apply for a visa online.",
- 117 B: "How to get on a student visa?",
- 118 C: "How can I work while I am a student?".

119 Table 2 shows the [BoW](#) for these sentences, representing the only three documents used to build the
 120 dictionary. In this example, the sentences have been normalized by keeping only the lowercased
 121 lemmas, so that for instance, apply and applicant are grouped under the same term "appl*". With a
 122 reasonable number of documents not dealing with exactly the same topics, the number of terms in
 123 the dictionary grows rapidly, while the number of ones in each vector hardly changes. For example,
 124 if the dictionary has 10 000 words, there are only 15-20 non-zero values in each vector of size 10 000,

for documents the size of an average sentence. The large dimensionality of these representations implies a high computational cost for many algorithms, but the fact that the vectors are sparse allows for the development of specific techniques to reduce this cost. These techniques will be presented in Section 2.2.2. These representations are useful for any task in NLP, as input to classification algorithms as described later, or to directly compare documents with each other, using for example the cosine similarity defined in Section 2.1.

A major disadvantage of these representations is that they give equal weight to all words. They do not take into account either the length of the document or the fact that certain words are present in the vast majority of documents. Indeed, a very long document has a high probability of containing any word, but this word has a lower impact on the subject of the document than in a shorter document. Similarly, very frequent words (pronouns, for example) provide little information about the subject of a document that uses them. The statistic called **Term Frequency-Inverse Document Frequency (TF-IDF)** calculates a score for each word that takes into account the two points we have just described (document length and word frequency). The frequency of the term in the document (TF) weights the number of occurrences of this term by the length of the document. This component is defined in Equation 2, where $f_{t,d}$ is the number of occurrences of the term t in the document d .

$$TF(t, d) = \frac{f_{t,d}}{\sum_{t' \in d} f_{t',d}} \quad (2)$$

The IDF component is a heuristic introduced by Karen Spärck Jones [5] on the intuition that a term (a word) appearing in many documents does not allow to properly discriminate between them. This score for a term t_i , which appears in n_i documents among N documents, is calculated as defined in Equation 3.

$$IDF(t_i) = \log \frac{N}{n_i} \quad (3)$$

Each of the three sentences:

I: "I received my work visa.",

J: "I need a student visa",

K: "I received a letter.",

would have BoW representations equally different from the other two. Indeed, the word *visa* is common to I and J, the word *a* is common to J and K, the word *received* is common to I and K and the word *I* is shared by all of them. Since *a* and *received* are very common words compared to *visa*, the score associated with the latter would be higher than for the other two words with the TF-IDF representation, so I and J would be the closest pair among the three possible. Many authors have sought to give a strong theoretical justification for the intuition of Spärck Jones [5], often based on the information theory of Shannon and Weaver [6]. According to Robertson [7], one can find many limitations to these a posteriori interpretations. Nevertheless, Robertson [7] acknowledges the impact of this statistic on the field of NLP, being the key resource of almost every search engine, among other applications.

2.2.2. Word Embeddings

Vector representations produced by BoW have the advantage of being simple to understand and quite efficient. However, they also have limitations. Here, we reuse the example sentences A, B and C from Section 2.2.1. If we replace the word *visa* in document B by its synonym *permit*, the resulting document B' : "How to get on a student permit?" has no more words in common with sentence A (with the exception of *a*, which is shared among all documents).

Using cosine similarity on their BoW or TF-IDF representations, these documents would be considered entirely different, while the similarity between A and C, and between B and C, is non-zero. However, for most classification tasks, obtaining similar representations for semantically close words is important. *Word embeddings* are among the approaches where vector representations of words are

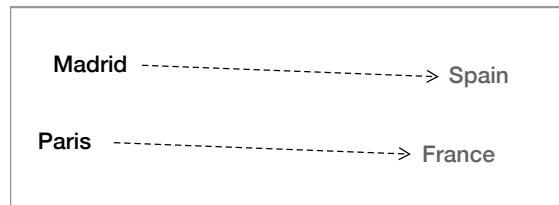


Figure 2. Word embeddings of city and country names

learned from their context, rather than explicitly defined as previously described. The distributional hypothesis introduced by Harris [8] suggests that words that are semantically close tend to be used in the same context. While latent semantic analysis represents the text by identifying it with the topics to which it relates [9], word embeddings use words as context. Mikolov *et al.* [10] introduces two techniques for learning their representations from their surroundings.

Even though these two techniques are not the first to allow the learning of distributed representations of words, the light structure of their model allows for the first time for training on very large datasets with limited resources. According to Mikolov *et al.* [11], representations for 100 billion of words can be learned in one day calculation on a single machine. Mikolov *et al.* [11] also show that these representations contain not only semantic information about words, but also syntactic features. What is surprising is that it is possible, in this representation space, to perform linear translations (displacements) that correspond to these characteristics. Figure 2 illustrates that the embeddings of the cities are close to each other, and those of the countries are too, but more importantly, the relative position of “France” compared to “Paris” is similar to that of “Spain” compared to “Madrid”.

Since the words *visa* and *permit* are semantically close and should often appear in the same context, their embeddings are very similar. In our example, the following relationship holds true: $\text{sim}_{emb}(A, B') \sim \text{sim}_{emb}(A, B)$. If we used word embeddings and simply averaged or summed all vectors to create a sentence vector, the similarity between any two sentences among A, B, C would be similar since they all have exactly two words in common with the others. Using a weighting system [12] or an embedding technique designed for sentences [13,14] would allow the similarity between A and B to be the largest, which makes the most sense since they are both about student visas.

2.3. Language Models and Recurrent Networks

While word embeddings are trained with the explicit goal of retaining semantic information in their representations, *language models* learn it implicitly. Indeed, the objective of language models is to capture the probability distributions of word sequences. Since the nature of language is not well understood and the universe of possible word sequences is extremely large, language models use certain simplifications to approximate the probability of appearance of a sentence. For example, n -gram models maintain a count of occurrences of word sequences of n length or less. To calculate the probability of appearance of a sequence of length $m > n$, one simply multiplies the probability of each of the n word sequences it contains. Once trained, these models can be used in concrete applications to represent words as one would do using word embeddings.

The first language patterns were learned using non-recurrent neural networks [15,16]. To handle contexts of variable size, one now uses recurrent *encoder-decoder* architectures instead [17]. The first of the two networks, the *encoder*, is a [Recurrent Neural Network \(RNN\)](#) which reads the words of the sentence to be translated one-by-one, and predicts the next word at each step. Once the sentence is complete, the hidden state contains a summary of the sentence. That summary, also called the *context* is then fed to the second network, the *decoder*. This model then generates an output sequence based on that context, but also the previous outputs as it goes on.

These two steps of the recurrent encoder-decoder are illustrated by Figure 3. For each symbol being read, the encoder updates its hidden state using the previous state as well as the current symbol.

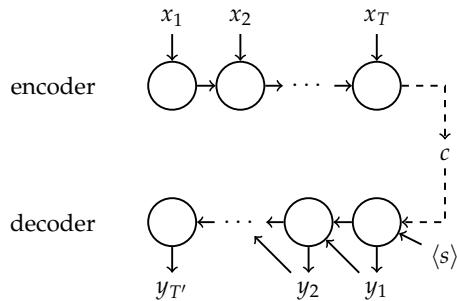


Figure 3. Encoder-decoder sequence to sequence model

Once the last symbol has been read, the network has the context in its memory. Each symbol is predicted by the decoder using the context, the previously predicted symbol and the current hidden state. The latter is itself derived from the hidden state and the symbol of the previous time step. In our example, machine translation is the task used to jointly train the encoder and decoder models. While this model can be used as-is, the pre-trained encoder can then be used independently in other tasks with smaller corpora to represent documents.

The recurrent encoder-decoder is based on a variant of [RNN](#), which uses the recurrence mechanism to model the order of words (or symbols) in the text, while *Transformers* are a new type of neural networks which use the attention mechanism instead of recurrence. This mechanism introduced by Bahdanau *et al.* [18], originally for automatic text translation, has become the source of performance improvements for many reference tasks in [NLP](#). The general idea is to predict, at each timestep (token) in a sequence, the importance of each of the elements passed as input to the network. This is referred to as the *attention* that the network attaches to particular elements of the input sequence. In the case of translation, one part of the network learns the translation part *per se*, and the other part learns to align the words or groups of words. Transformers [19] use [Convolutional Neural Networks \(CNNs\)](#), combined with the attention mechanism. This technique completely eliminates the sequential dependency of recurrent networks, and thus allows to fully parallelize training. Although their training has a much higher overall computational cost than their equivalent in recurrent networks for example, this advantage makes them faster to execute, provided one has access to large parallel computing resources. As with word embeddings (see Section 2.2.2), what allowed the popularization of transformers is the public availability of pre-trained networks, which can be used as-is to represent sequences of text, or fine-tuned to specific tasks in a reasonable amount of time to achieve even better performance. Devlin *et al.* [19] introduced a transformer-based architecture called [Bidirectional Encoder Representations from Transformers \(BERT\)](#), whose pre-trained models are now very popular.

2.4. Chatbots

Chatbots could support the improvement of access to legal information. In this Section, we describe some important contributions in this area. Chatbot systems can be divided into three different categories, [Question Answering Systems \(QASs\)](#), "social" chatbots and focused dialog systems. The main characteristic of a [QAS](#) is the use of data of various types, such as web pages or knowledge graphs, to provide direct answers to user questions. Social chatbots are rather generalist systems, while focused dialog systems are usually dedicated to a specific tasks.

2.4.1. Question-Answering Systems

Search engines or other search systems return documents in response to user requests. These queries can consist of a combination of keywords, but can also be in natural language (without any particular constraints, notably in terms of vocabulary). As an example, a user seeking information on work authorizations could formulate the following queries:

- Student visa, work authorization.

Table 3. Database table of a knowledge-based QAS

nationality	type	requirements
american	work	You need a job offer.
american	study	You only need a document mentioning the equivalent degree.
american	PVT	This visa is not offered to American citizens.
french	work	You need a job offer and a report from a competitiveness analysis.
french	study	You need to show an acceptance letter and have \$10 000.
french	PVT	You need to register to the random drawing.

232 - I'm on a student visa. Can I work?

233 While a search engine would return essentially the same documents to both queries, a QAS could
 234 use the information from the natural language query to answer it precisely. Rather than having to
 235 read the complete documents describing student visa rules, the user of the QAS could receive an
 236 answer such as "As a general rule, students can work 20 hours per week during the semester, [...]" .
 237 According to Jurafsky and Martin [20], QASs are of two types. The first type associates queries with
 238 logical representations to query structured knowledge bases. In the second, relevant documents are
 239 first searched for using IR techniques, and then text understanding algorithms are used to extract
 240 relevant Sections.

241 In the case of a QAS whose role is to provide information to immigrants, a simple knowledge base
 242 could be a table associating nationality of origin and visa type to a list of pre-requisites. We have the
 243 sets (incomplete but for the purposes of the example) $type = \{work, study, PVT\}$ and $nationality =$
 244 $\{american, french\}$. The corresponding database table is shown in Table 3. Figure 4 presents a flowchart
 245 of the interactions with this QAS to answer the question "What are the pre-requisites to get a visa?".
 246 The interactions with the user must inform the two strangers (nationality and type of visa) before they
 247 can be given an answer using the database Table 3. Since the system follows very simple rules, it is
 248 entirely predictable and, assuming the information is correct and complete, the correct answer will be
 249 provided to the user in all cases.

250 It would be possible to apply this paradigm in a second step to systems such as the ones we are
 251 developing, to further facilitate access to information. However, this paradigm is not flawless since it
 252 forces interactions to remain within a very rigid framework. The effort required to build the knowledge
 253 base is also much greater than that required to bring together an unstructured corpus of data. Work
 254 exists to extract structured information from relatively homogeneous textual data, notably Auer *et al.*
 255 [21] created an ontology from the set of Wikipedia pages and the relationships between them (the
 256 hypertext links). These approaches allow access to a large relational knowledge base, at the cost of
 257 a decrease in data quality compared to manual work. Despite this limitation, this type of tool is an
 258 interesting source of improvement for further work. In particular, we have begun its integration into
 259 the NLP tools of the NBC to increase their coverage thanks to the automatic extraction of synonyms
 260 from this database.

261 A IR-based QAS could be designed using a corpus that includes the documents below:

- 262 - d_a : "If you are an American citizen, you need a job offer to apply to a work visa. To get a student
 263 visa, you only need to prove your student status. There is no *working holiday* visa option."
- 264 - d_f : "If you are French, you will need [...]"

265 To answer the following queries r_1 and r_2 , the first step consists of identifying the right document.

- 266 - r_1 : "What are the prerequisites for a work permit for U.S. citizens?"
- 267 - r_2 : "What are the prerequisites for Americans to get a work permit?"

268 This step can be performed using one of the methods presented in Section 2.1. A simple cosine
 269 similarity on BoW vectors would work with the r_1 query, which has vocabulary in common with d_a ,
 270 but not with the r_2 query, which uses slightly different words. Trained embeddings would match these
 271 both queries with d_a .

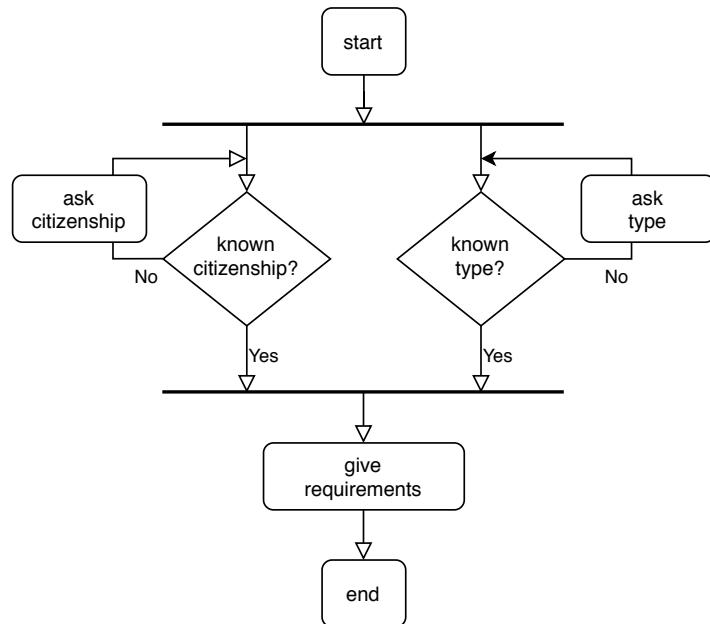


Figure 4. Flowchart of the “knowing visa requirements” part of a immigration chatbot relying on a structured knowledge base

272 Various techniques can then be used to extract the relevant part of the document to answer the
 273 question. One usually begins by applying a grammatical analysis of the query to determine the type
 274 of question (“Who”, “What” “When”, etc.). It is then possible to use morpho-syntactic labeling tools
 275 to filter the results and make a cosine similarity comparison for example to select the most relevant
 276 sentence(s).

277 2.4.2. General Chatbots

278 The design of chatbot systems not restricted to a specific task is difficult, and the evaluation of
 279 such systems is complex. The characterization of what constitutes a good conversation has inspired
 280 many authors but still remains an open research question [22]. The first generalist chatbot, ELIZA
 281 [23], was created to mimic a conversation with a psychotherapist. The algorithm simply consisted
 282 of associating certain keywords with predefined phrases. Thanks to Weizenbaum *et al.*’s choice of
 283 “persona”, the system received very positive feedback from users, without taking great risks since it
 284 answered mainly with new questions.

285 The ALICE [24] system was the first to handle natural language entries. The Artificial Intelligence
 286 Markup Language was developed within this framework, to design a system of conversational rules.
 287 Many chatbots created using this language are listed in Satu *et al.* [25].

288 As with other areas of NLP, learning-based dialogue systems are currently the most common
 289 approach to conversational systems. Vinyals and Le [26] use a sequence-to-sequence neural network
 290 architecture (*seq2seq*, introduced by Sutskever *et al.* [27]) to train a chatbot from end-to-end without any
 291 prior knowledge. The model simply learns how to predict the most probable answer (character
 292 by character) to a question from the training corpus. The simplicity of this model has several
 293 advantages. The only data needed are discussions: no special annotation is required, so many
 294 corpora are usable. Moreover, since this method does not require any domain-specific knowledge, it is
 295 very easily applicable in a variety of contexts.

296 However, this approach has limitations, which the authors acknowledge. First, the objective of
 297 predicting the most likely next step in a conversation is not a very good indicator of the purpose of
 298 a conversation. Indeed, the goal of a conversation is often a longer-term objective such as sharing a
 299 certain piece of information or completing a specific task. Second, the model tends to favour low-risk

300 responses, which often amount to very short and uninteresting answers. Finally, the model does
 301 not contain any mechanism ensuring the answers are consistent with each other. This last point is,
 302 according to the authors, one of the points that prevent their model from passing the Turing test.

303 Qiu *et al.* [28] explain that IR-based methods often fail to deal with long, precise questions. They
 304 also point out that text generation-based models may generate inconsistent or meaningless answers.
 305 Motivated by the limitations of both of these approaches, they developed a hybrid chatbot, which
 306 combines IR and text generation in a commercial setting, to provide customer service and shopping
 307 recommendation. This approach leads to three models: a IR model, a text generation model, and a
 308 third one selects a answer to provide a user with according to the confidence threshold of the first
 309 algorithm. When evaluated manually, the hybrid model outperforms the simple model with 60% of
 310 text accuracy versus 40%.

311 The Turing test, introduced by Turing [29] under the name of "Imitation Game", involves a
 312 machine trying to impersonate a human through a written conversation with an examiner. This test
 313 was Turing's precise way of answering the question "Can machines think?" through observation.
 314 According to Radziwill and Benton [30], this objective has guided the development of chatbots since
 315 ELIZA [23]. Ramos [31] as well as Radziwill and Benton [30] suggest that this ability to mimic human
 316 behaviour is not necessarily a desirable quality however, and argue that even human empathy towards
 317 these systems would not suffer from a lack of it.

318 Deriu *et al.* [32] list other competitions and metrics, which attempt to evaluate the quality of a
 319 chatbot system, but no evaluation method stands out as a de-facto standard. Metrics such as BLUE [33]
 320 and RED [34] measure the overlap between the chatbot dialogue and pre-set phrases. Some approaches,
 321 such as Lowe *et al.* [35], use a RNN to try to predict how judges would rate sentences or the entire
 322 conversation. This approach requires extensive manual annotation, but its results correlate quite
 323 closely with user judgments. Despite many promising leads, the problem is still open since it seems
 324 difficult to identify the quality factors of a chatbot in general.

325 2.4.3. Task-specific Chatbots

326 For task-specific chatbots, whether informational or transactional, the application domain is
 327 known in advance. In the later case, the role of the chatbot is to automate the exchanges in order
 328 to carry out a transaction: the cancellation of a subscription, or the sending of a bank transfer for
 329 example. This has allowed the development of finite state systems [36] and rules-based systems to
 330 govern transitions between these states. The state of a system is composed of variables and their
 331 values, which describe all the elements of the environment and chatbot configuration needed to guide
 332 the chatbot decisions. In our very simple example, illustrated in Figure 4, a state of the system could
 333 be described as follows:

334 started: TRUE; citizenship: UNKNOWN, visa_type: STUDENT; requirements_given: FALSE
 335 When users provide their citizenship, the property citizenship is now set (to FRENCH for instance)
 336 and the updated properties and their values now constitutes the new state.

337 These successful techniques, coupled with statistical approaches [37,38], are still in use today
 338 because they are capable of supporting the design of simple and robust systems. The system developed
 339 by Bobrow *et al.* [36] is still the basis of many flight reservation systems today [39].

340 However, these techniques have the disadvantage of not being flexible. Indeed, transitions
 341 between states are normally questions (or patterns of questions, as with ALICE). If several questions
 342 should lead to the same action, the rule must be duplicated. Other information may also be taken into
 343 account when choosing a state transition (e.g. the geographical position of the user or the number of
 344 days before the next visa lottery, where applicable). In general, with n binary variables, the size of the
 345 tree of possible states will be 2^n .

346 For this reason, it is often difficult keep track of states and their transitions. The concept
 347 of "intent" [40] was developed to help to remove the coupling from a specific user utterance
 348 with a state transition. The intent designates the desired outcome of the interaction. The two

349 sentences "I want to know how to get a student visa." and "Requirements for foreigners
 350 to study in Canada" both convey a similar information need, which could be an intent called
 351 `get_information_student_visa`. The Rasa framework⁶ uses intents and handles the state transitions
 352 in the following way. An intent classification model is responsible for assigning the correct intent to
 353 each user interaction, and then a second model uses the context of the conversation and that intent to
 354 identify the best response to that interaction. Assuming that there is no history with relevant additional
 355 information, a chatbot could answer with an action such as `give_generic_student_visa_info`.
 356 If additional information is known, the action could be personalized, for example, by returning
 357 information specific to French immigrants.

358 As we will explain in Sections 4.1 and 4.2, the systems we developed do not need to track any
 359 state in their initial versions, but could benefit from state tracking in future versions. While the intent
 360 classification task could be approached with many techniques, the StarSpace [13] algorithm is one of
 361 the most efficient supporting this task. StarSpace is an algorithm for learning embeddings for entities
 362 of different types in the same space, in a supervised manner. For intention classification, the entities
 363 are therefore the documents (user-generated text and [Frequently Asked Questions \(FAQ\)](#)), as well as
 364 the intent labels. The algorithm consists of matching positive document-intent pairs (those where the
 365 intent matches the document) and limiting the proximity of negative pairs. In practice, entities are
 366 represented by their features, and the representation of these features that is updated by minimizing
 367 the loss function by stochastic gradient descent. To optimize the training time, the authors use negative
 368 instance sampling [10] and a margin parameter in the loss function to avoid focusing on near-perfect
 369 instances.

370 The next Section will present the methodology we followed to develop two chatbots by building
 371 on these techniques.

372 3. Methodology

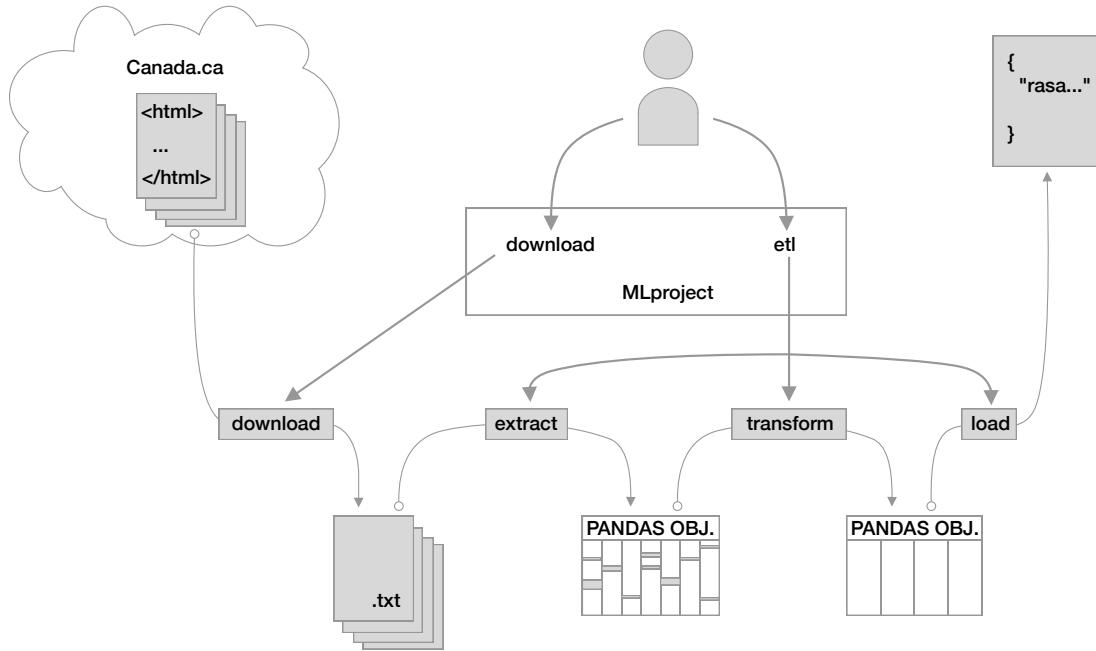
373 3.1. Experiment tracking and reproducibility

374 In recent years, the phenomenon of the "reproducibility crisis" in science has been much discussed.
 375 Baker [41] reports the results of a survey in which more than 1500 researchers are questioned about
 376 their experience in reproducing research work. More than 70% of the participants have already
 377 failed to replicate other researchers' experiments, and more than 50% have failed to replicate their
 378 own experiments. This study covers various fields of science but computer science is not spared.
 379 Gundersen and Kjensmo [42] report on a similar observation: they review 400 papers from top [Machine](#)
 380 [Learning \(ML\)](#) conferences⁷, and find that most of these experiments are non-reproducible due to lack
 381 of documentation. Gundersen and Kjensmo [42] suggest that the format of scientific papers does not
 382 lend itself to the transmission of all the precise information needed to reproduce the experiments, as
 383 opposed to code. Sharing the code and model parameters would therefore allow an additional level of
 384 reproducibility when compared to simply describing the experiment in a scientific paper. Code version
 385 management is enabled by tools such as subversion or git. These tools intervene in several steps
 386 before publishing models and articles to describe experiments. The design of a learning-based system
 387 contains many interacting elements. Earlier, we discussed this topic to support the recommendation to
 388 share the source code of experiments, but before that, it often takes dozens of model training attempts.
 389 Managing these experiments is a complex but necessary task, for which there is no widely accepted
 390 solution such as code versioning systems.

391 We use the MLflow framework [43] for two elements of the model development process. First, for
 392 experience tracking, we keep track of each execution of the scripts for data collection, data preparation,

⁶ <https://rasa.com>

⁷ IJCAI and AAAI, ERA ratings through <http://www.conferenceranks.com/>.

Figure 5. Data collection and cleaning for the immigration chatbot, and developer interaction

393 and model training and evaluation. This tool allows us to go back later on to an experimental result,
 394 to find exactly its context in order to analyze and describe it, and to reproduce it, or to make new
 395 experiments from the same experimental set-up. We have also added a level of abstraction on top of
 396 each of the scripts we use (a *MLflow project*) to be able to call them simply with default values. These
 397 scripts allow a better repeatability of our experiments since only a few commands are needed to train
 398 the models we describe.

399 For the immigration chatbot for example, Figure 5 describes the interaction of a user with the
 400 data collection and preparation project. As can be seen, the user make use of only the two entry points
 401 exposed in the *MLproject* file. The first entry point triggers the download of the document collection,
 402 and the second one starts its processing. This data processing is decomposed according to the design
 403 pattern “extract, transform and load”. The three steps are respectively data recovery from the source,
 404 data cleaning and formatting, and then export to the final format usable by the RASA framework.

405 3.2. Data

406 3.2.1. Immigration Canada FAQ

407 In an attempt to use chatbots to provide an easy way to access legal information, we set out to
 408 look for a suitable dataset. The ideal corpus for such a task would contain a large number of diverse
 409 conversations about a fair number of different topics. Conversations datasets are already hard to find to
 410 develop general-purpose chatbots though, and this problem is even more pronounced for law-related
 411 corpora. Indeed, many conversations would contain potentially sensitive information, which would
 412 make those datasets impossible to release. In cases were lawyers are involved, the attorney-client
 413 privilege protects the conversations even more strictly, so accessing this kind of data is not an option.

414 One source of legal information that is not typically considered as a conversational dataset is
 415 the explanations given by the government on administrative procedures. We have collected 1088

⁴¹⁶ webpages in English from the Government of Canada's Immigration and Citizenship Help Desk⁸. This
⁴¹⁷ dataset presents the advantage of being public and exempt of any privacy concerns.

⁴¹⁸ Together these pages constitute an immigration [FAQ](#). Each page begins with a question associated
⁴¹⁹ with a category (e.g. "Studying") and is followed by an answer consisting of one or more paragraphs
⁴²⁰ of text. The page also contains a list of questions that other users have found useful. Finally, two lists
⁴²¹ of keywords are also present in the page but invisible to the user. After verification, we have chosen
⁴²² not to extract these lists since it does not change from one page to another.

⁴²³ Once the documents are retrieved, we use the HTML structure to extract the information from
⁴²⁴ each page. The data collection and preparation code is made available⁹ to facilitate the reproduction of
⁴²⁵ the results.

⁴²⁶ Our dataset consists of 1088 classes with only one (1) example per class. For learning-based
⁴²⁷ models, these examples will constitute our training dataset. In order to guide the optimization phase
⁴²⁸ of our system and perform a preliminary evaluation, we have created paraphrases of 88 examples
⁴²⁹ of the training dataset. With this set of validation data, we can validate our hypotheses and quickly
⁴³⁰ iterate on the system design. This dataset would benefit from a larger volume by increasing the
⁴³¹ number of annotated examples to evaluate the system performance more precisely. However, for the
⁴³² proof-of-concept we present here, this small corpus is sufficient.

⁴³³ 3.2.2. Internal Legal QAS

⁴³⁴ Our second chatbot is developed within the [NBC](#) to answer employees' legal questions. As for the
⁴³⁵ immigration chatbot, this chatbot is based on a [FAQ](#), and the conversation turns are fairly independent
⁴³⁶ from each other. So the main difficulty is again in classifying the user's intent based on the intents
⁴³⁷ our model was exposed to at its conception. In this case as well, little data is initially available for the
⁴³⁸ design of the chatbot.

⁴³⁹ This dataset initially contained 2 formulations for each of the 275 questions. A first chatbot was
⁴⁴⁰ trained on this corpus. It is described as the reference experiment with classic StarSpace in Section [4.2.2](#).
⁴⁴¹ The chatbot was then exposed to about 30 of its users - the members of the legal services - at the
⁴⁴² [NBC](#), in this preliminary version, to collect real interactions. The new formulations for existing intents
⁴⁴³ made it possible to generate a test set that was representative of the users' actual questions. After
⁴⁴⁴ filtering questions outside the [FAQ](#) framework and removing duplicates, we annotated 292 interactions
⁴⁴⁵ covering 126 intentions to create the test dataset.

⁴⁴⁶ In this Section, we have presented two legal [FAQs](#) that will be the source of content for our
⁴⁴⁷ chatbots. In the next Section, we will describe the design of these chatbots based on these small
⁴⁴⁸ datasets. The first is intended to provide information on topics related to immigration to Canada. The
⁴⁴⁹ second is integrated into a corporate framework to inform its users about the legal rules related to
⁴⁵⁰ their work.

⁴⁵¹ 4. Experiments and results

⁴⁵² 4.1. Immigration chatbot

⁴⁵³ This Section presents our experiments to build an immigration chatbot. We start with the de-facto
⁴⁵⁴ standard model in Rasa: the StarSpace intent classifier described in Section [2.4.3](#). Since our chatbot
⁴⁵⁵ is based on [FAQs](#), it is very similar to an [IR](#) task, so we compared this baseline with an [IR](#)-inspired
⁴⁵⁶ model.

⁸ <https://www.cic.gc.ca/english/helpcentre/index-featured-can.asp>

⁹ https://gitlab.ikb.info.uqam.ca/marc/immigration_faq_scrapper

Table 4. Results of intent classification for the immigration chatbot

	microP	microR	microF ₁	macroP	macroR	macroF ₁	wP	wR	wF ₁
softmax	0,92	0,52	0,67	0,51	0,52	0,52	0,51	0,52	0,52
marge	1	0,60	0,75	0,60	0,60	0,60	0,60	0,60	0,60
IR	1	0,60	0,75	0,60	0,60	0,60	0,60	0,60	0,60

457 4.1.1. Baseline using StarSpace

458 We trained a classifier on the immigration Q&A dataset, described in Section 3.2.1, using the
 459 StarSpace algorithm described in Section 2.4.3. We therefore created a common representation of user
 460 sentences and intents (one for example from the training set). The implementation of RASA¹⁰ also
 461 returns a ranking of the instances with the highest similarity value to the input value.

462 We train two models for 40 epochs, meaning that the algorithm will see the entire dataset 40 times
 463 in total. The first model uses the standard loss described in Wu *et al.* [13], with the *mu* parameter, which
 464 controls the margin, at 0.8. For the second model, the loss is controlled by a function *softmax*, so there
 465 is no margin at which the training stops for a particular pair of instances. The function *softmax* takes as
 466 input a vector of *K* real numbers and produces a vector of *K* strictly positive real numbers whose sum
 467 is 1. Because of this feature, the output can be interpreted as a probability distribution. In the case of a
 468 multi-label classification, these probabilities are the chances that a given instance corresponds to each
 469 of the possible classes.

470 4.1.2. Approach Based on Information Retrieval

471 We also use a modified version of the StarSpace algorithm, which abandons the concept of intent
 472 to directly associate a user's sentence with an answer from the knowledge base. Rather than learning
 473 how to associate a text document to a class (which does not carry information), we bring two text
 474 documents together. We described in Section 2.4.3 how learning the position of entities is indirect. It is
 475 indeed the position of features (BoW) which is learned. The representation of the known words thus
 476 informs the learning of embeddings of other documents that use them, as in the original StarSpace
 477 algorithm. This approach, however, has two differences. First, adding the responses increases the
 478 amount of data available for learning the representations. Second, when predicting the correct response
 479 to a user interaction, the information contained in the response can be leveraged.

480 The first representation of documents uses *n*-grams with $n \in \{1, 4\}$, and then we train the
 481 embeddings for 40 epochs with the same parameters as the classic StarSpace model described in
 482 Section 4.1.1.

483 4.1.3. Results

484 The results of the experiments are reported in Table 4. Between the two versions of classic
 485 StarSpace, the model using loss with a margin outperforms the version using softmax. Note that in
 486 this case, using the StarSpace IR variant brings no improvement over the version which uses intents.
 487 There are several reasons for this. For example, the easy instances of the test corpus have already
 488 been classified correctly and the difficult instances cannot be classified by simple vocabulary similarity.
 489 Also, since the test covers only 88 of the 1088 classes, it may not be sufficiently representative of the
 490 entire domain for the model to be successfully applied. Variants using pre-trained models [19] might
 491 be more efficient but have the disadvantage of having more classes for fewer instances. The relative
 492 size of the questions and answers could also influence the results.

¹⁰ <https://github.com/RasaHQ/rasa>

493 4.2. Legal information chatbot in a corporate environment

494 The following Section presents three systems providing **NBC** employees with answers to legal
495 questions. We use StarSpace, and the **IR** variant previously described, and we compare these
496 approaches with a system based on **BERT** [19], a transformer model.

497 4.2.1. Baseline using StarSpace

498 For the development of this chatbot, we also use the standard model provided by Rasa as a
499 baseline, the StarSpace algorithm that we described in Section 2.4.3. This baseline model uses an initial
500 representation of documents by n -grams with $n \in \{1, 2\}$. The model is run on 20 epochs with the
501 default margin loss of StarSpace. The margin for positive instances (when to stop moving positive
502 couples closer together) is $\mu_{\text{pos}} = -0.8$ and the negative margin (when to stop moving negative
503 couples further apart) is $\mu_{\text{neg}} = -0.4$.

504 To understand why the value of μ_{neg} is negative, we have to go back to the definition of cosine
505 similarity. If the word vectors being compared are **BoW** (vectors of binary values), the minimum value
506 $\text{sim}_{\text{cosine}}$ can take is 0. However, for some characteristics such as the feeling associated with a term,
507 negative values can make sense. Word embeddings, and those learned by StarSpace in particular, can
508 learn such characteristics implicitly. In these cases, the lowest similarity that can be obtained is -1,
509 which corresponds to a cos angle of π , or 180 degrees. This explains the negative value of μ_{neg} , since
510 the range of possible values is actually [-1;1].

511 4.2.2. Enhanced Baseline

512 Another reference experiment to which we will compare our approach uses **BERT** [19] to represent
513 conversations. **BERT** is a *transformer* (as described in 2.3) for which a pre-trained model is available.
514 There is an English version, but no French version, so we use a trained model for 104 languages
515 (including French). The pre-trained model is M-BERT_{BASE}¹¹, *i.e.* the basic version of **BERT** with
516 110M parameters, as opposed to the 345M parameters of **BERT_{LARGE}** (which was not available in
517 multilingual version). The model was then fine-tuned to the training dataset for 100 epochs, on a
518 machine with a Nvidia GTX1070 graphics card. Using a model this large comes with additional
519 constraints of compute power and inference time. Training this model from scratch is not realistic in
520 most contexts, but fine-tuning a pre-trained one as we did is possible with relatively modest hardware.

521 4.2.3. Approach Based on Information Retrieval

522 Similar to the model described in Section 4.1.2, we use a classic StarSpace variant that uses the
523 answers (to the questions in **FAQ**) to answer the questions.

524 Figure 6 illustrates the pipeline from questions in text form to their embedding representations
525 using StarSpace. The text of the questions is pre-processed, and each word is then represented as an
526 embedding. The representation of the question is the combination of the words that compose it. The
527 representation of the intent ID is initialized at random, but it is then updated to be closer in the vector
528 space to the words of the corresponding sentences.

529 In the **IR**-inspired version of StarSpace, questions are matched directly with answers, rather than
530 having the intermediate steps of intent recognition (and optionally next action prediction). Figure 7
531 represents how the representation learning pipeline differs from the classic version of StarSpace. At the
532 initialization, questions and answers are matched together, then pre-processed in the same way. All
533 text documents, whether they are questions or answers, share the word embeddings. The embedding
534 positions are updated for each question-answer pair, to be closer to that of words present in their

¹¹ https://storage.googleapis.com/bert_models/2018_11_23/multi_cased_L-12_H-768_A-12.zip

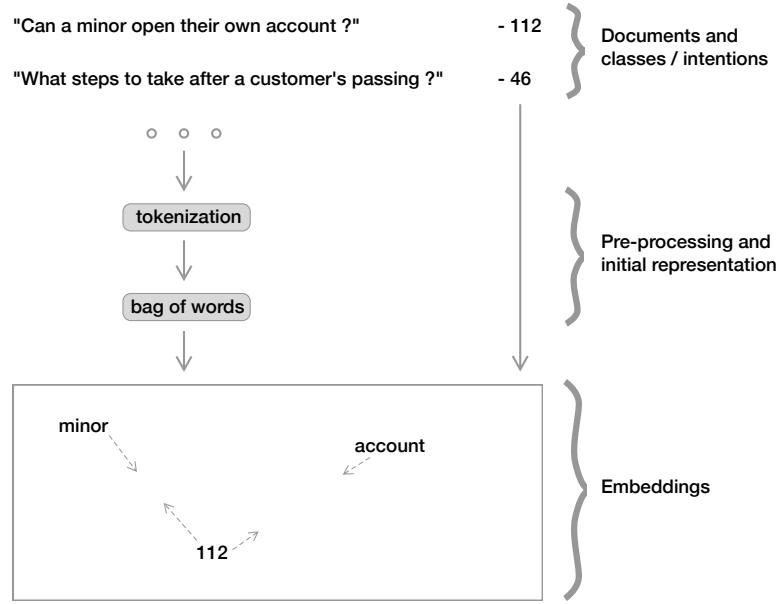


Figure 6. Embeddings learning pipeline for both questions and intents

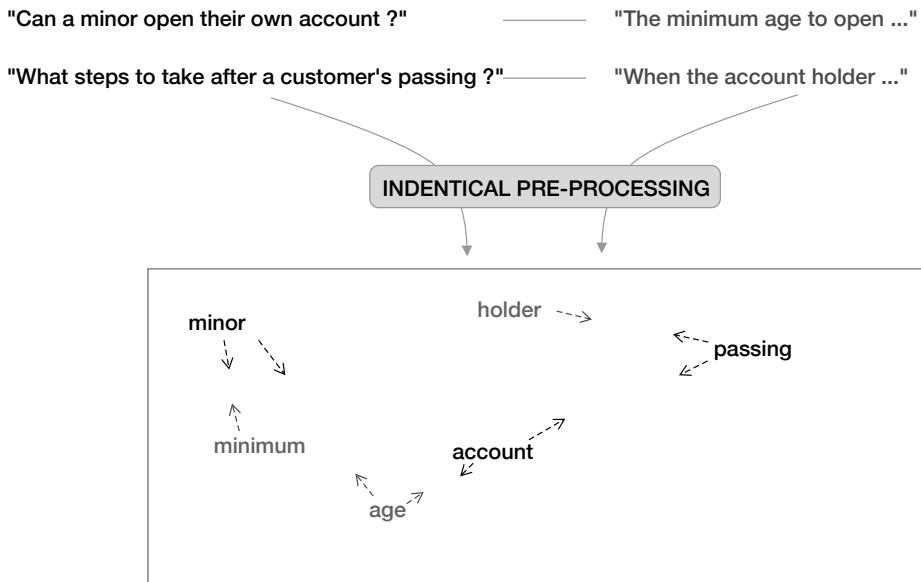


Figure 7. Embeddings learning pipeline for both questions and answers

535 match. For instance, the representations of “minimum” and “minor” are updated to be closer to each
 536 other because they are used in the first question-answer pair of our example.

537 4.2.4. Results

538 Results of the legal data experiments are reported in Table 5. The standard version of StarSpace
 539 is outperformed by the other two approaches. Performance using an average of predictions at the
 540 instance level (microP and microF₁) gives our model the advantage, while for the other two types of
 541 averaging (macro and weighted), the BERT model is better. If we consider the differences between the
 542 original StarSpace model and the IR modification, we observe differences of more than 10% of F₁ in
 543 favor of the second one. It appears that the IR-based model uses the additional information contained

Table 5. Intention classification results on NBC legal chatbot

	microP	microR	microF ₁	macroP	macroR	macroF ₁	wP	wR	wF ₁
StarSpace	0,61	0,61	0,61	0,52	0,48	0,48	0,73	0,61	0,63
BERT	0,70	0,67	0,66	0,75	0,75	0,75	0,85	0,75	0,76
IR	0,78	0,64	0,70	0,64	0,62	0,60	0,72	0,64	0,65

in the responses to better rank user interactions. However, this difference is not as large if we use a weighted average by the number of instances in each class, which could be similar to the questions presented in 4.1.2. The performance level of the IR-based model is also not sufficient to exceed the performance level of a language model like BERT, which takes advantage of information learned from the entire content of Wikipedia. While training the model from scratch is extremely cost-prohibitive, using a pre-trained model in a low-resource context is beneficial. Considering the weight of the model and especially the inference time, however, a simple IR-based model like the one we presented offers a significant improvement over a simple StarSpace model.

5. Conclusion

Access to legal information is a major obstacle to access to justice. In this article, we have designed two chatbots in order to inform their users about legal issues. One answers immigration-related questions, and the other, relying on a knowledge base of the NBC, answers legal questions from its employees. Both are based on FAQs, with the number of questions not exceeding, or barely exceeding, the number of answers. The underlying classification task therefore has a very low number of examples per class (less than 5) for a very high number of classes (275 and 1088 respectively). We have hence experimented with an algorithm to learn embeddings in a supervised way.

We noticed that, in the least extreme case of the NBC dataset, the use of a StarSpace variant, which represents the answers in the same space and uses them to make predictions, brings a very significant improvement. On the same dataset, using a language model pre-trained on a very large corpus and fine-tuned to ours further increases performance. The extra training cost is unrealistic for all but the biggest system providers in the field, but the existence of pre-trained networks on some languages limits the impact of this drawback. On the immigration dataset, the variant does not bring any performance improvement. These results should be put into perspective with the small size of the test dataset compared to the training dataset (only 10% of the classes are covered by the test dataset).

Both chatbots we described consisted mainly in an intent recognition module. The NBC chatbot also uses keyword-based query disambiguation [44] techniques to increase its overall score. We plan to supplement our immigration chatbot with documents from case law, collected and annotated in a previous work [45]. While the information these documents contain would not be as useful to the average reader as the content specifically targeted at them, the added context would help where no clear-cut answer is provided. This would also serve as an additional step in a proof-of-concept for an information system that would eventually support lawyers. More information about these use cases can be found in the LegalIA presentation video¹².

https://gitlab.ikb.info.uqam.ca/marc/immigration_bot https://gitlab.ikb.info.uqam.ca/marc/immigration_faq_scrapper

Supplementary Materials: The source code related to the immigration chatbot is available under MIT licence to ensure reproducibility. It can be found in these two repositories: https://gitlab.ikb.info.uqam.ca/marc/immigration_bot(chatbot) and https://gitlab.ikb.info.uqam.ca/legalia/immigration_faq_scrapper (data collection). The repositories are not accessible freely, because one need to sing in first.

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Faible qté de données et probablement déséquilibré entre les classes
I suggest for further work to check dataless and few-shot text classification litterature

cross-validation or better one held-out

¹² <https://legalia.uqam.ca/video/LegalIA.mp4> this link doesn't work

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589 **Abbreviations**

590 **BERT** Bidirectionnal Encoder Representations from Transformers. [7](#), [15](#), [16](#), [17](#)

591 **BoW** Bag-of-Words. [4](#), [5](#), [8](#), [14](#), [15](#)

592 **CNN** Convolutional Neural Network. [7](#)

593 **FAQ** Frequently Asked Questions. [11](#), [13](#), [15](#), [17](#)

594 **IR** Information Retrieval. [2](#), [8](#), [10](#), [13](#), [14](#), [15](#), [16](#), [17](#)

595 **ML** Machine Learning. [11](#)

596 **NBC** National Bank of Canada. [2](#), [8](#), [13](#), [15](#), [17](#), [18](#)

597 **NLP** Natural Language Processing. [2](#), [4](#), [5](#), [7](#), [8](#), [9](#)

598 **NRLs** Non-Represented Litigants. [1](#)

599 **QAS** Question Answering System. [7](#), [8](#)

600 **RNN** Recurrent Neural Network. [6](#), [7](#), [10](#)

601 **TF-IDF** Term Frequency-Inverse Document Frequency. [5](#)

602 **UQAM** Université du Québec à Montréal. [1](#), [2](#)

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