

## **Mastering Embedded system online diploma**

<https://www.learn-in-depth.com/>

Student(s)

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Profile learn-in-depth: <https://www.learn-in-depth.com/online-diploma/boulmane818%40gmail.com>

### **First term final project 1**

Date of Submission

Saturday, August 7, 2021

Lecturer/Tutor

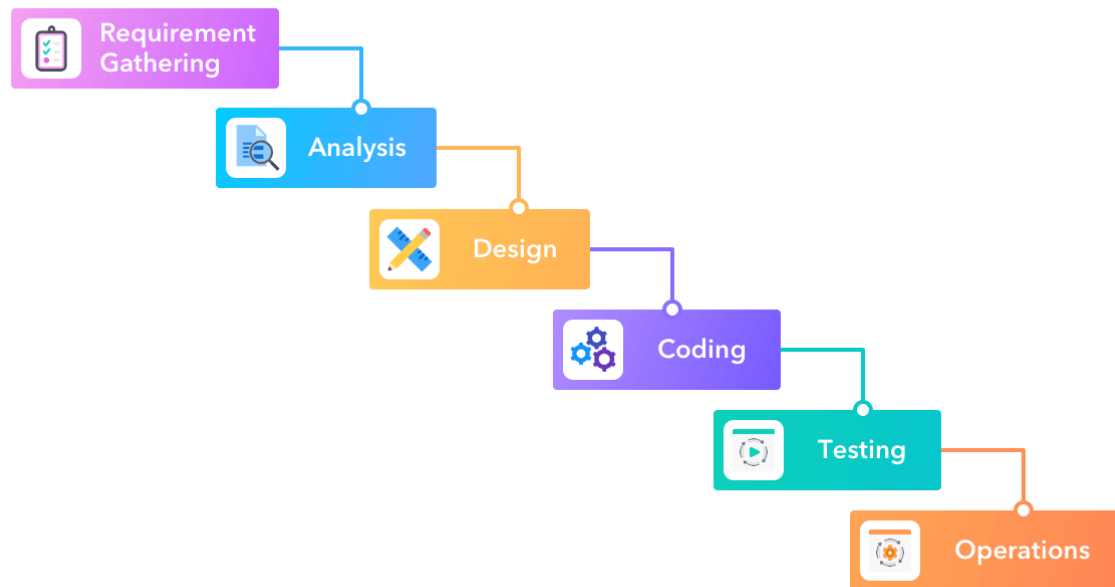
Keroles Shenoda

## ABSTRACT

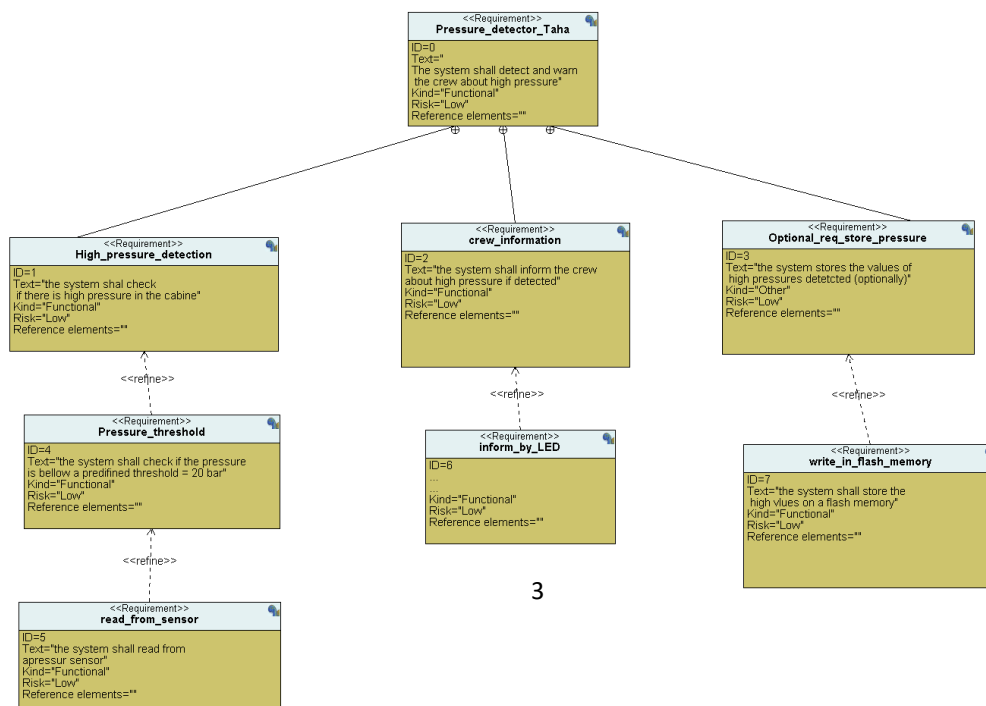
In this report we try to evaluate our competencies on the term of embedded C and system design using tools and knowledge we learned in depth in the first term of the learn-in-depth diploma. In this first project it's required that we design a system that inform pilots about high pressure if detected by lightning an LED for a delay.

## INTRODUCTION

The first step in the system design is to choose in which way (methodology) you will proceed, in our case the system is simple enough that the waterfall method as explained in the figure below



In the phase of requirement gathering we made a meeting with the customer (Eng Keroles) and we get arranged about the following requirements

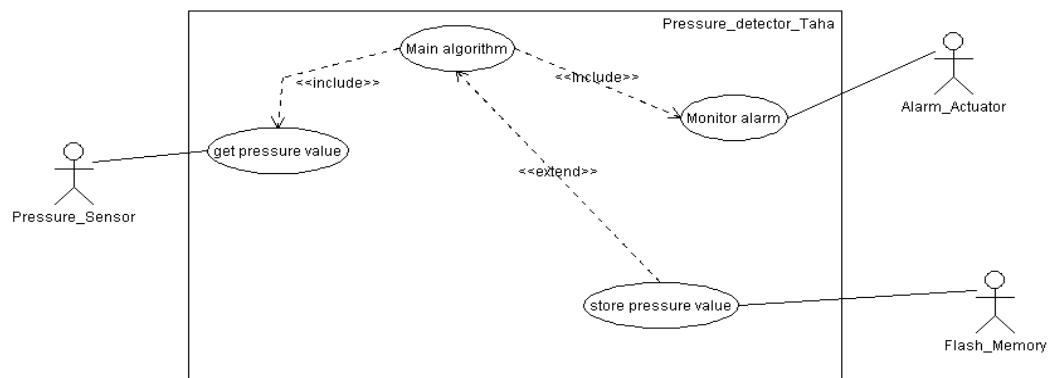


after that we analyzed the requirements the results of our analyzes lead to the diagrams described in the next section

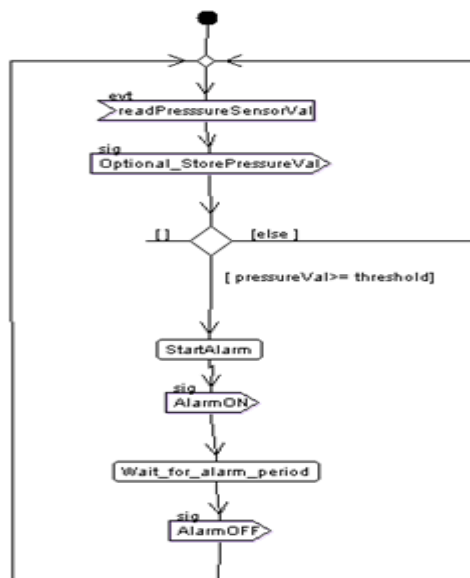
## SYSTEM ANALYSIS

### USE CASE DIAGRAM

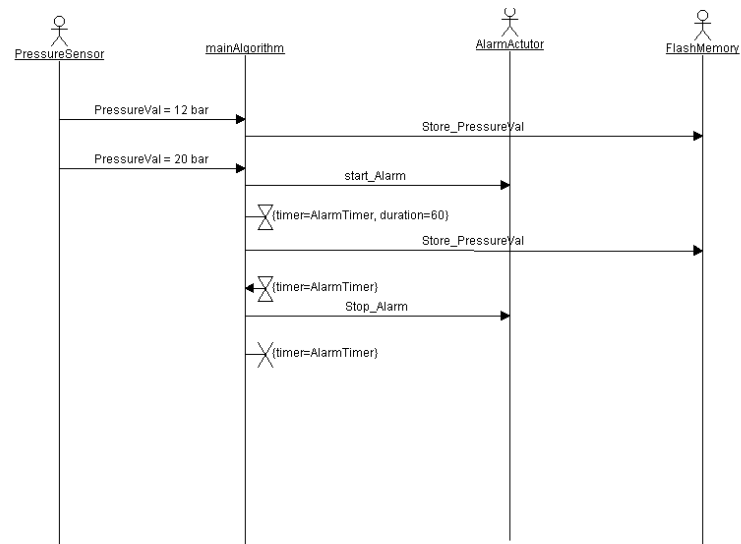
the figure below shows the use case diagram. The system communicate with three actors from the external environment ( the third is optional)



.Activity diagram

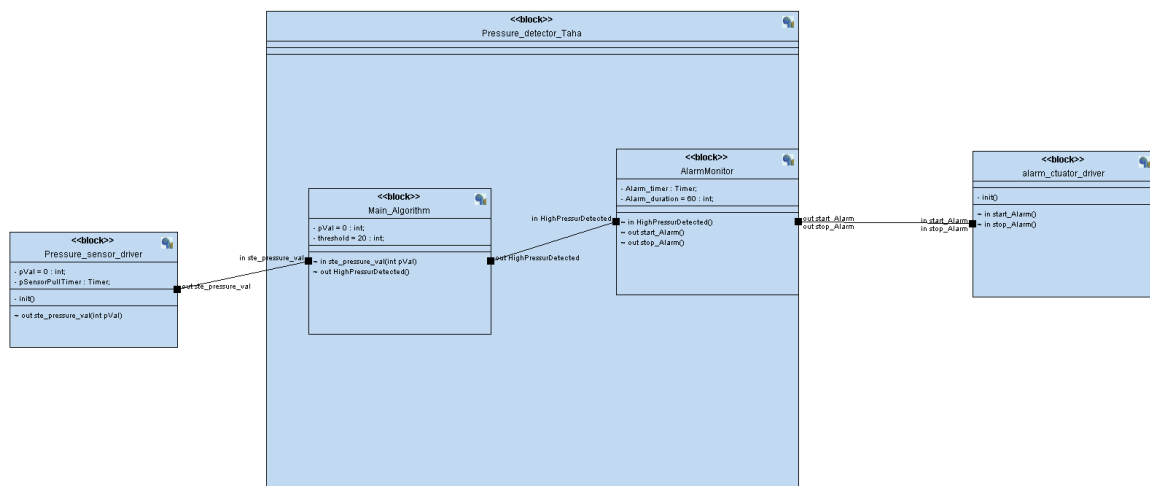


## SEQUENCE DIAGRAM



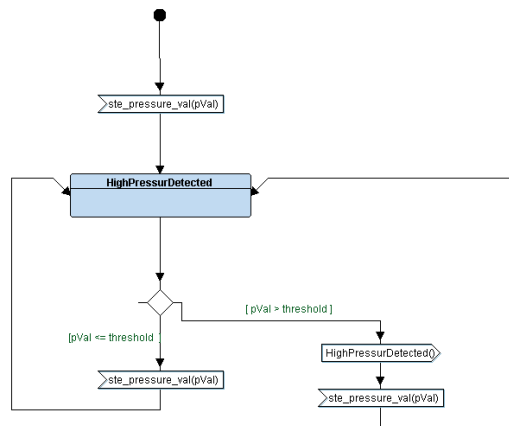
## DESIGN :

our system will consist of three blocks as shown in the figure below

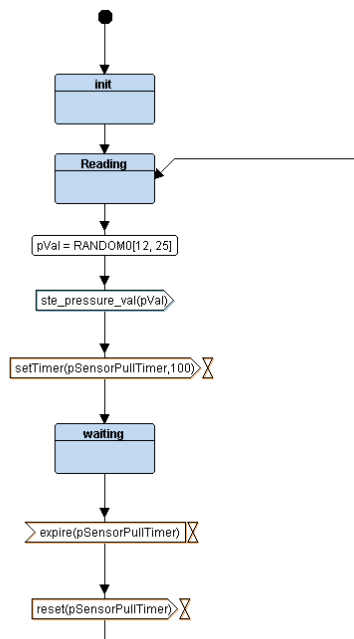


## STATE MACHINES:

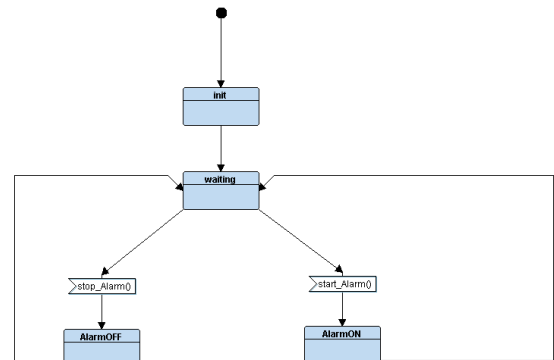
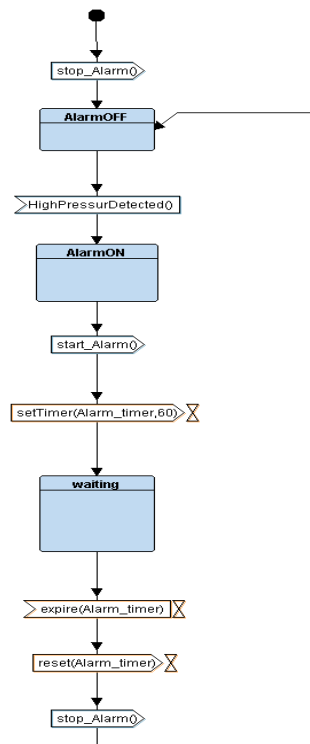
main algorithms:



## PRESSURE SENSOR DRIVER



## ALARM MONITOR AND ACTUATOR



## CODING

to implement the system hereafter, we present some shots obj files also we can see our own Startup.c the linker script and the makefile to automate the building. First, we created headers (look on GitHub repository)

### STARTUP.C

```
#include<stdint.h>
```

```
extern uint32_t _E_text;
extern uint32_t _S_data;
extern uint32_t _E_data;
extern uint32_t _S_bss;
extern uint32_t _E_bss;
```

```
extern void main();
```

```
void reset_handler()
```

```
{
    uint32_t data_size = (unsigned char*)&_E_data - (unsigned char*)&_S_data;
    unsigned char * p_scr= (unsigned char*)&_E_text;
    unsigned char * p_dst= (unsigned char*)&_S_data;
    int i;
    for(i=0;i<data_size;i++)
    {
        *(unsigned char*) p_dst++ = * (unsigned char*) p_scr++;
    }
}
```

```

uint32_t bss_size = (unsigned char*)&_E_bss - (unsigned char*)&_S_bss;
p_dst= (unsigned char*)&_S_bss;

for(i=0;i<bss_size;i++)
{
    *(unsigned char*) p_dst++ = (unsigned char) 0;
}

    main();
}

void default_handler()
{
    reset_handler();
}
void nmi_handler() __attribute__((weak,alias("default_handler")));
void h_fault_handler() __attribute__((weak,alias("default_handler")));
void bus_fault() __attribute__((weak,alias("default_handler")));

static unsigned long stack_top [256];
void (* const g_vector [] )() __attribute__((section(".vectors"))) =
{
    (void(*)()) (unsigned long) &stack_top [256],
    &reset_handler,
    &nmi_handler,
    &h_fault_handler,
    &bus_fault
};

```

## LINKER SCRIPT

```

MEMORY
{
    flash(rx) : o = 0X00000000, l = 512M
    sram(rwx):  o = 0X20000000, l = 512M
}

SECTIONS
{
    .text : {
        *(.vectors*)
        *(.text*)
        _E_text = .;
    }>flash

    .data :{
        _S_data = .;
        *(.data*)
        _E_data = .;
    }>sram AT> flash

    .bss :{
        _S_bss = . ;
        *(.bss*)
        _E_bss = .;
        _stack_top = . +0x1000;
    }>sram
}

```



## MAKEFILE

#First term project makefile by Eng: Taha Omar Boulmane

CC=arm-none-eabi-

CFLAGS= -g -gdwarf-2 -mcpu=cortex-m3

INCS=-I

LIBS=

SCR=\$(wildcard \*.c)

OBJ=\$(SCR:.c=.o)

AS=\$(wildcard \*.s)

ASOBJ=\$(AS:.s=.o)

Project\_name=pressureDetectionSystem

all:\$(Project\_name).bin

@echo "====Build is done===="

%.o:%.s

\$(CC)as.exe \$(CFLAGS) \$< -o \$@

%.o:%.c

\$(CC)gcc.exe -c \$(INCS) \$(CFLAGS) \$< -o \$@

\$(Project\_name).elf: \$(OBJ) \$(ASOBJ)

\$(CC)ld.exe -T linker.ld \$(LIBS) \$(OBJ) \$(ASOBJ) -o \$@ -Map=map\_file.map

cp \$(Project\_name).elf \$(Project\_name).axf

\$(Project\_name).bin: \$(Project\_name).elf

\$(CC)objcopy.exe -O binary \$< \$@

symbol:\$(Project\_name).elf

\$(CC)nm.exe \$<

header:\$(Project\_name).elf

\$(CC)objdump.exe -h \$<

asm:\$(Project\_name).elf

\$(CC)objdump.exe -d \$<

clean:

rm \*.elf \*.bin

clean\_all:

rm \*.elf \*.bin \*.o

## MAKE RESULTS

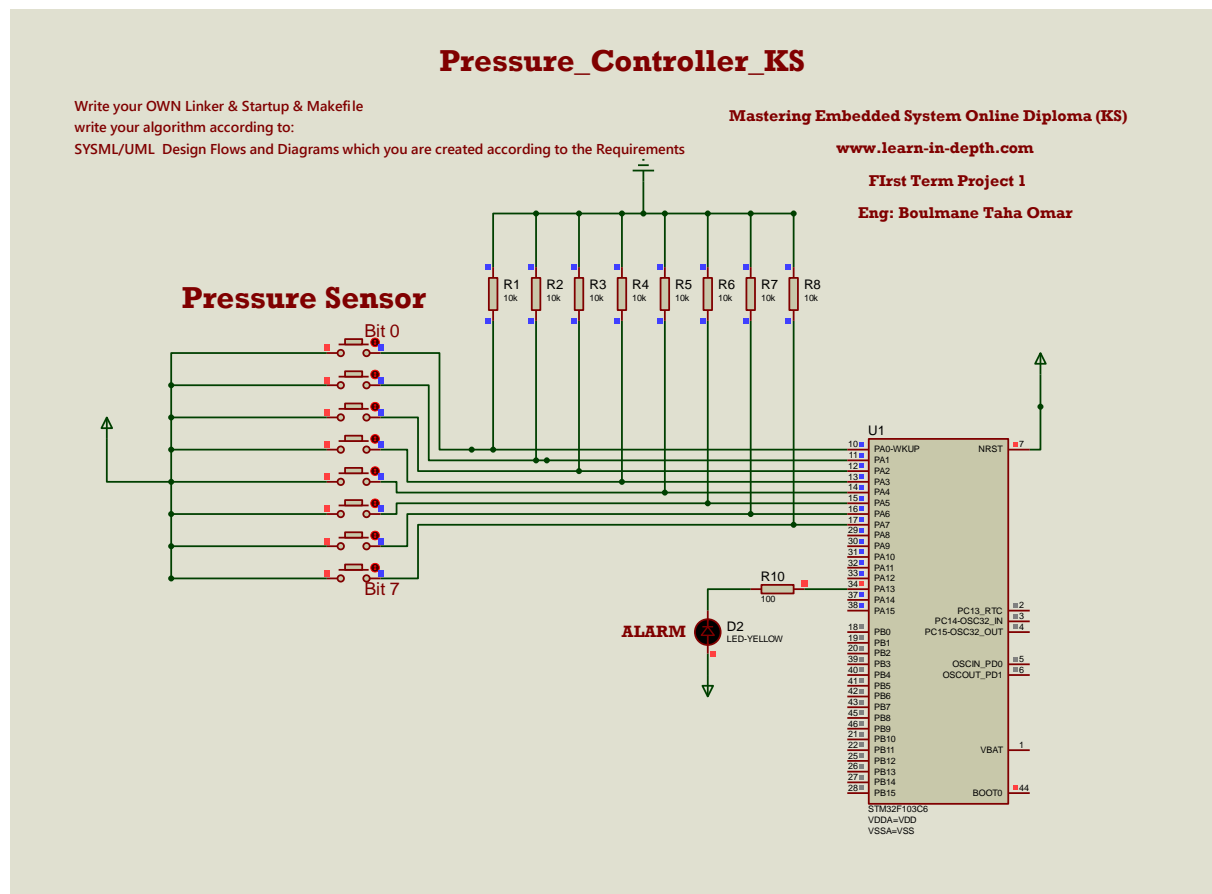
```

Name
  .project
  driver.c
  driver.h
  driver.o
  linker.ld
  main.c
  main.o
  Makefile
  map_file.map
  p_alarm.c
  p_alarm.h
  p_alarm.o
  p_sensor.c
  p_sensor.h
  p_sensor.o
  pressureDetectionSystem
  pressureDetectionSystem
  pressureDetectionSystem
  startup.c
  startup.o

$ make
arm-none-eabi-gcc.exe -c -I -g -gdwarf-2 -mcpu=cortex-m3 startup.c
arm-none-eabi-gcc.exe -c -I -g -gdwarf-2 -mcpu=cortex-m3 main.c -o
arm-none-eabi-gcc.exe -c -I -g -gdwarf-2 -mcpu=cortex-m3 p_sensor.c
o
arm-none-eabi-gcc.exe -c -I -g -gdwarf-2 -mcpu=cortex-m3 p_alarm.c
arm-none-eabi-gcc.exe -c -I -g -gdwarf-2 -mcpu=cortex-m3 driver.c
arm-none-eabi-ld.exe -T linker.ld startup.o main.o p_sensor.o p_al
-o pressureDetectionSystem.elf -Map=map_file.map
cp pressureDetectionSystem.elf pressureDetectionSystem.axf
arm-none-eabi-objcopy.exe -O binary pressureDetectionSystem.elf pres
System.bin
=====Build is done=====

TahaOmar@DESKTOP-2T05IIC MINGW32 ~/Desktop/learn_in_depth/learn_in_
erolles/unit5/Pressure_detection_project/ImplementationCodeForPressu
$
  
```

## TEST AND SIMULATION



## Pressure\_Controller\_KS

Write your OWN Linker & Startup & Makefile  
write your algorithm according to:

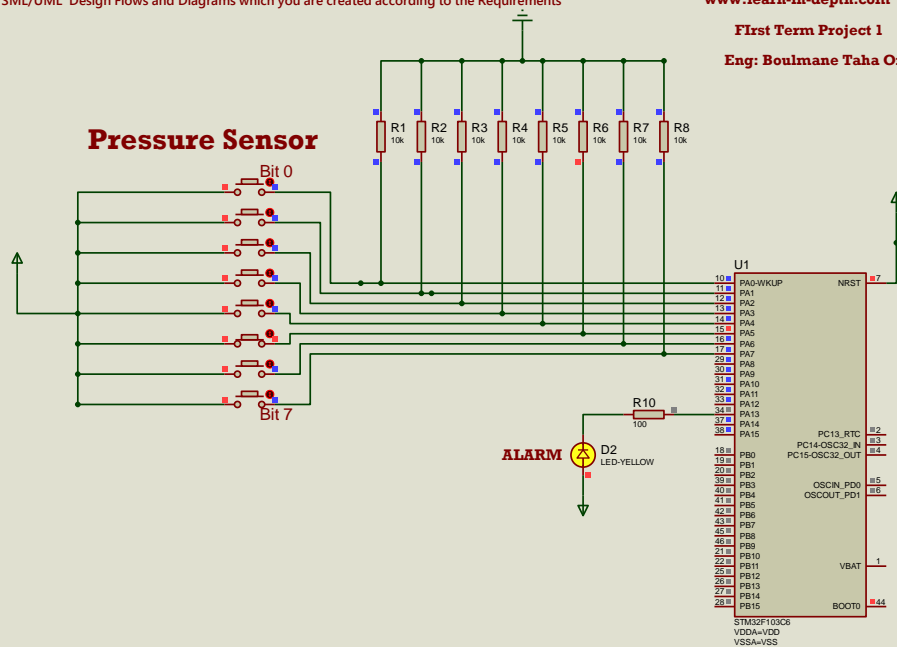
**SYSML/UML Design Flows and Diagrams which you are created according to the Requirements**

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## First Term Project 1

**Eng: Boulmane Taha Omar**



(In this report I used data from other engineers repositories for that I thank them all )