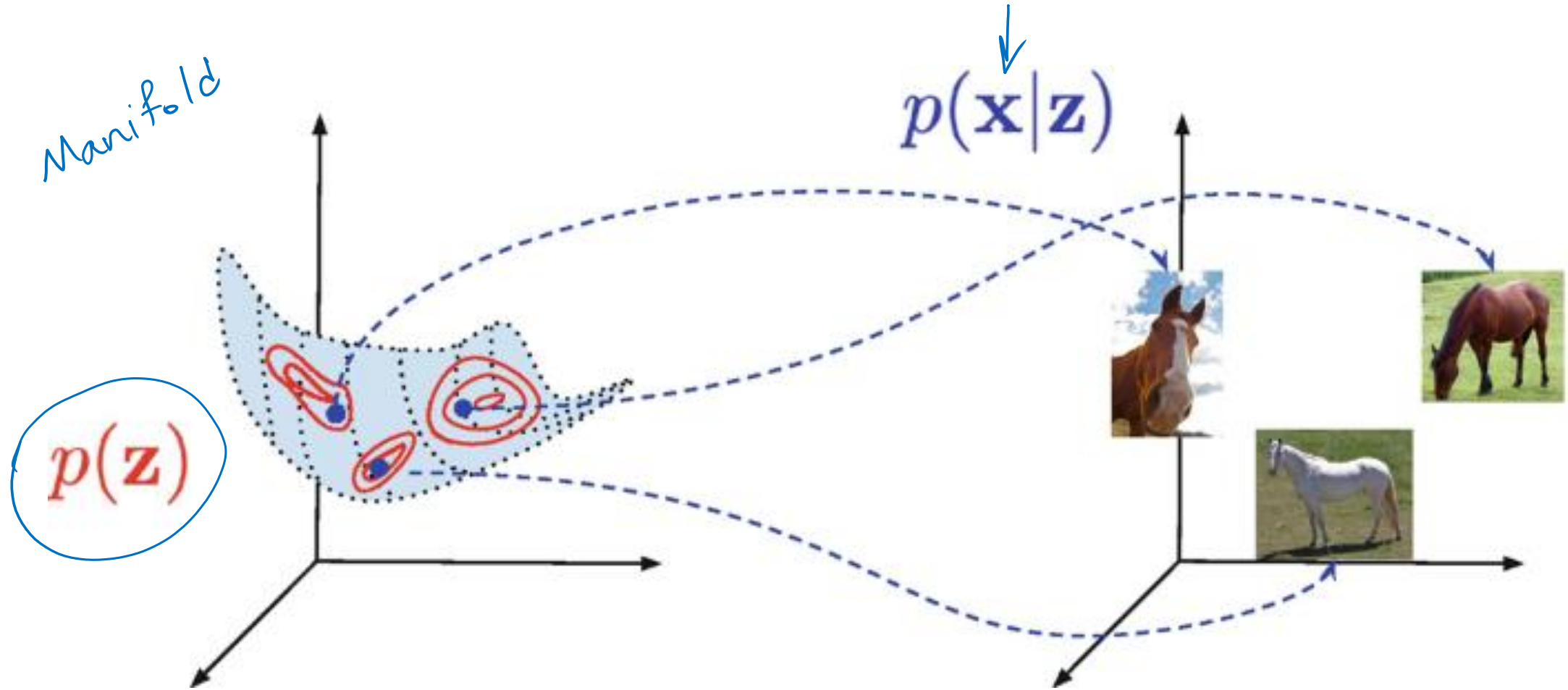


Normalizing Flows

Mostafa Tavassolipour

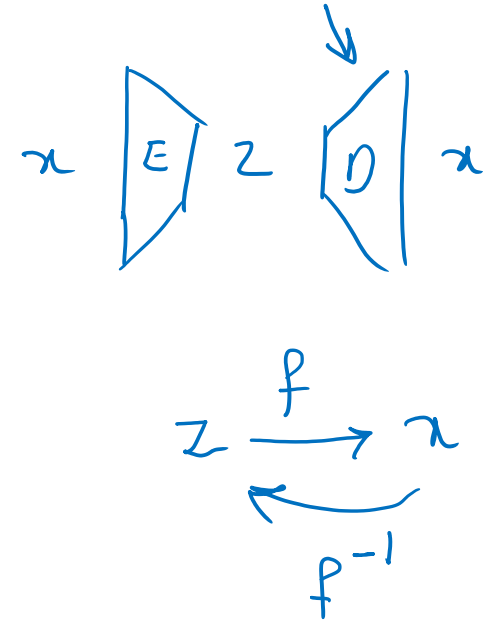
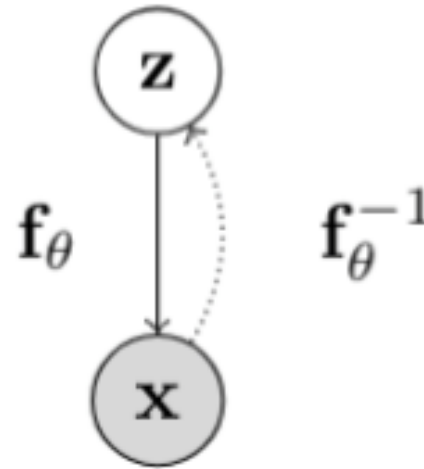
Fall 2024

Latent Variable Models



Normalizing Flow

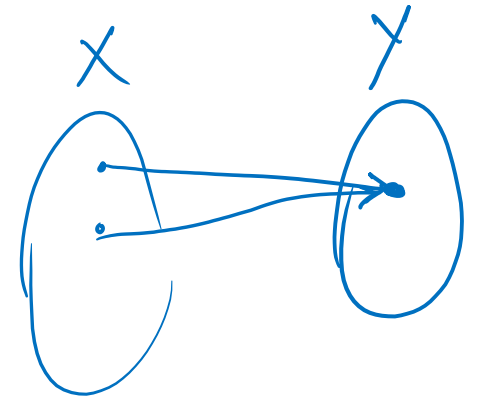
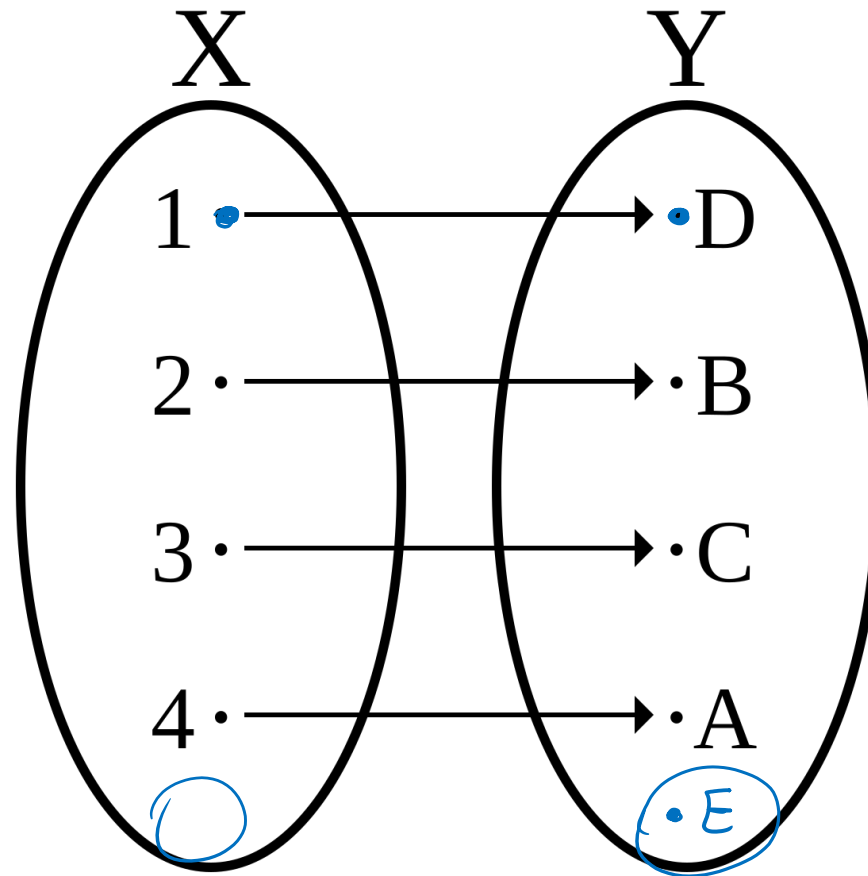
- In a **normalizing flow** model, the mapping between Z and X , given by $f_\theta: \mathbb{R}^n \rightarrow \mathbb{R}^n$, is deterministic and invertible such that $X = f_\theta(Z)$ and $Z = f_\theta^{-1}(X)$



- Note: x, z need to be continuous and have the same dimension.

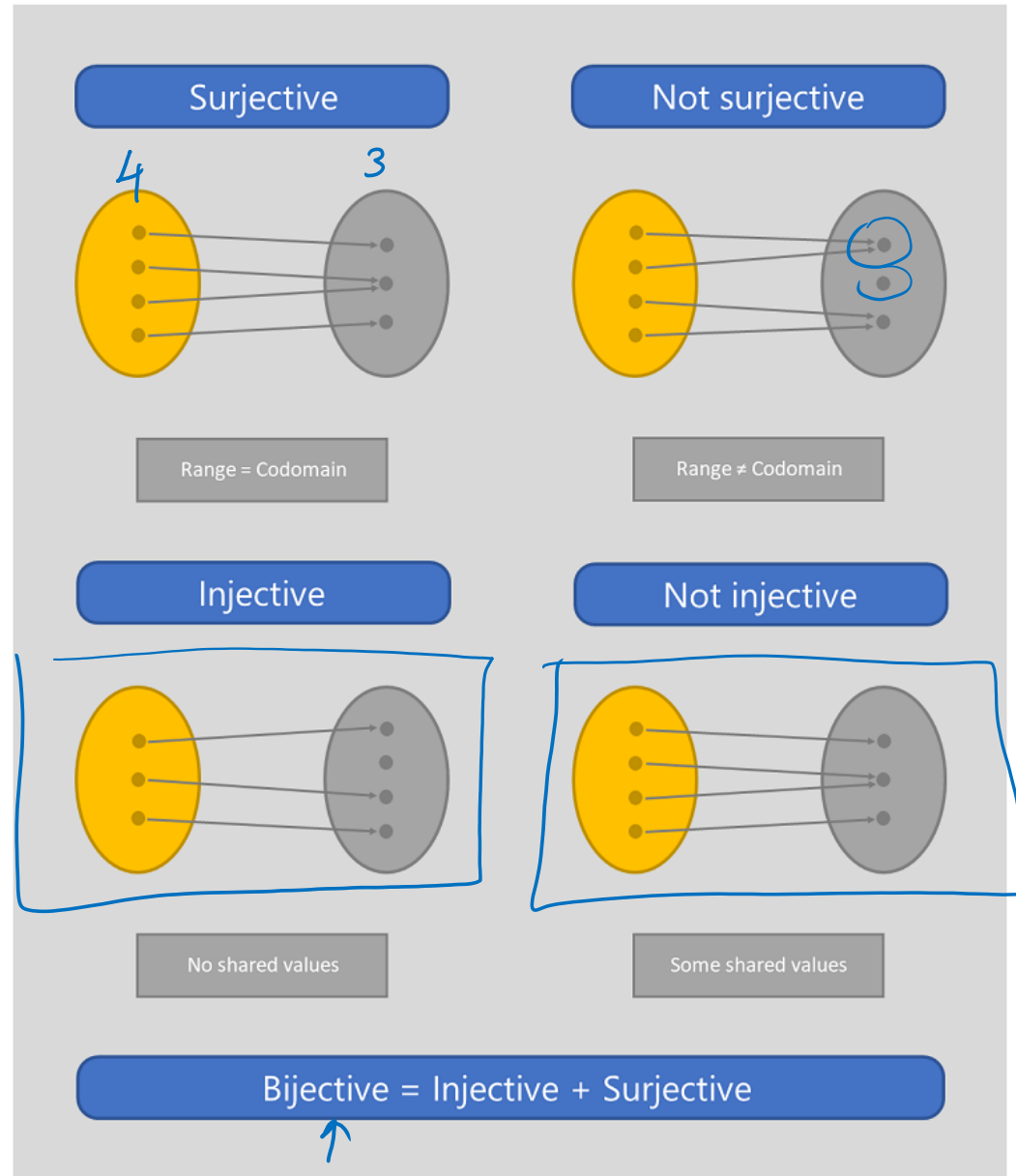
Bijjective Transformation

$$z \xrightarrow{f} x$$



Non-bijective Transformation

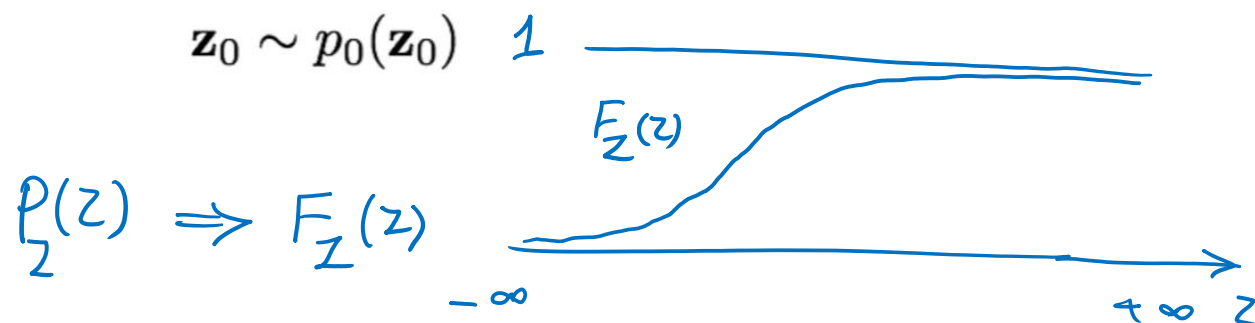
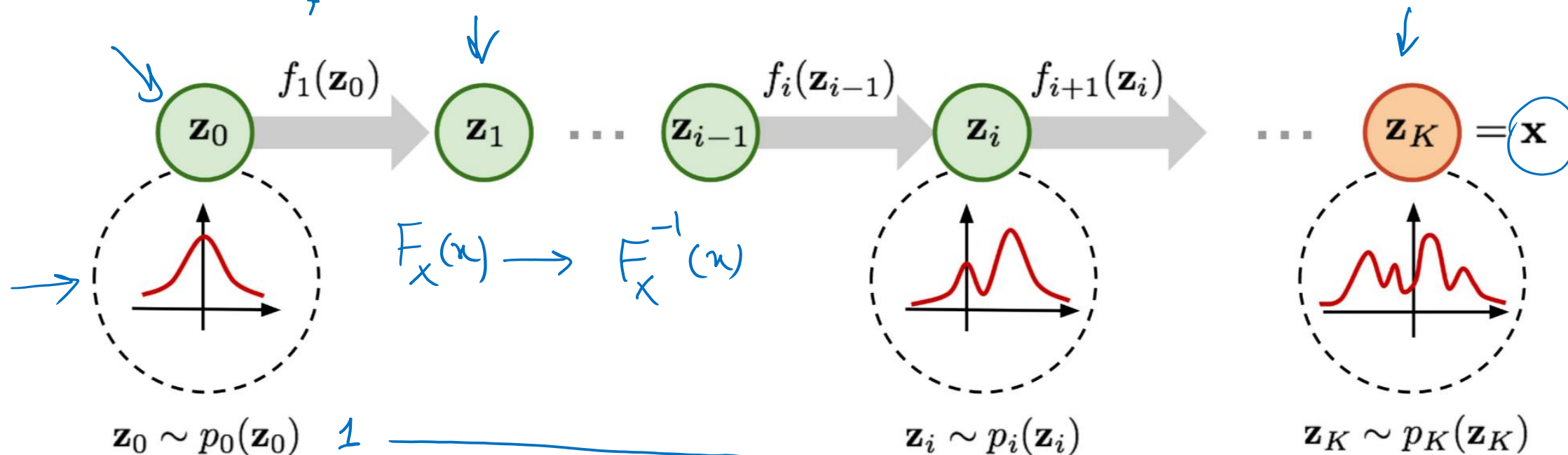
$$z \in \mathbb{R}^5$$
$$x \in \mathbb{R}^{10}$$



Normalizing Flows

$$x = \underbrace{f_k \circ f_{k-1} \circ \dots \circ f_1}_{f}(z_0)$$

$$\Rightarrow \boxed{x = f(z)} \rightarrow \boxed{z = f^{-1}(x)}$$



$$p_Z(z) \Rightarrow F_Z(z)$$

$$y = F_Z(z)$$

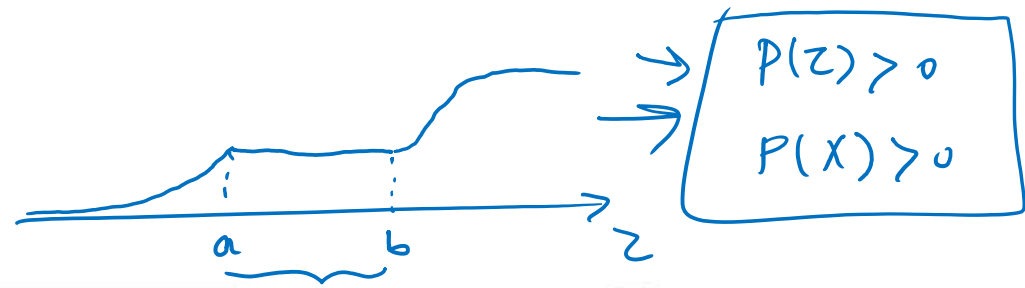
$$w = F_X^{-1}(y)$$

$$y \sim \mathcal{U}(0,1)$$

$$\boxed{x = F_X^{-1}(F_Z(z))}$$

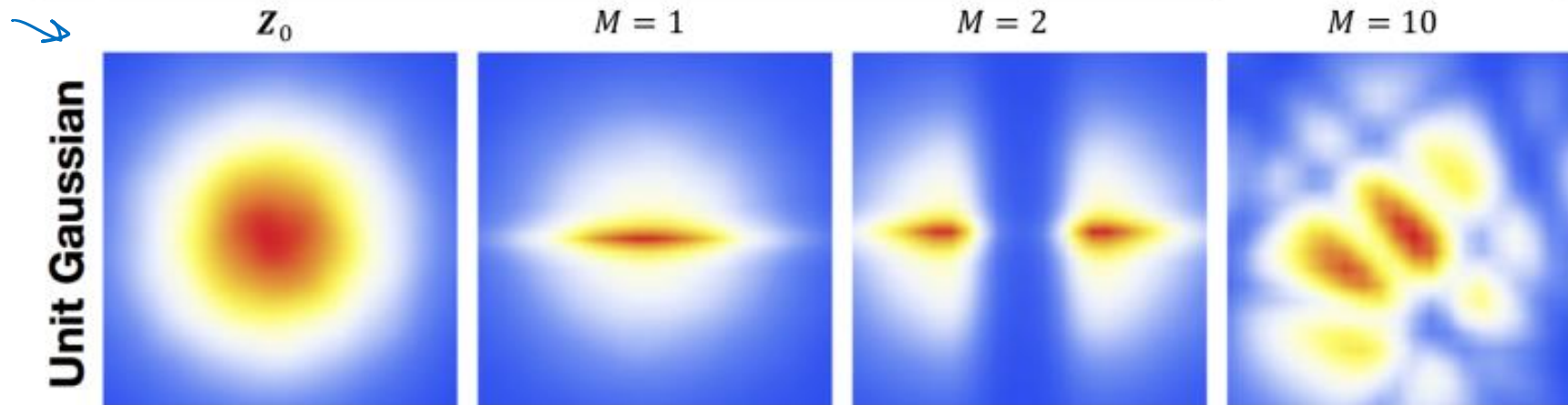
Example

$$\Pr\{a \leq Z \leq b\} = 0$$



- Base distribution: Gaussian

$$p(z) > 0$$

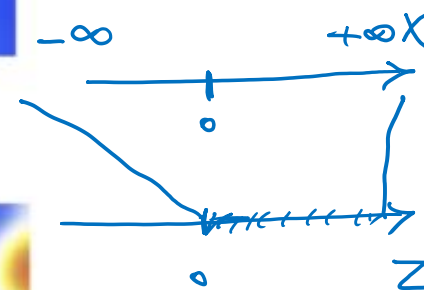
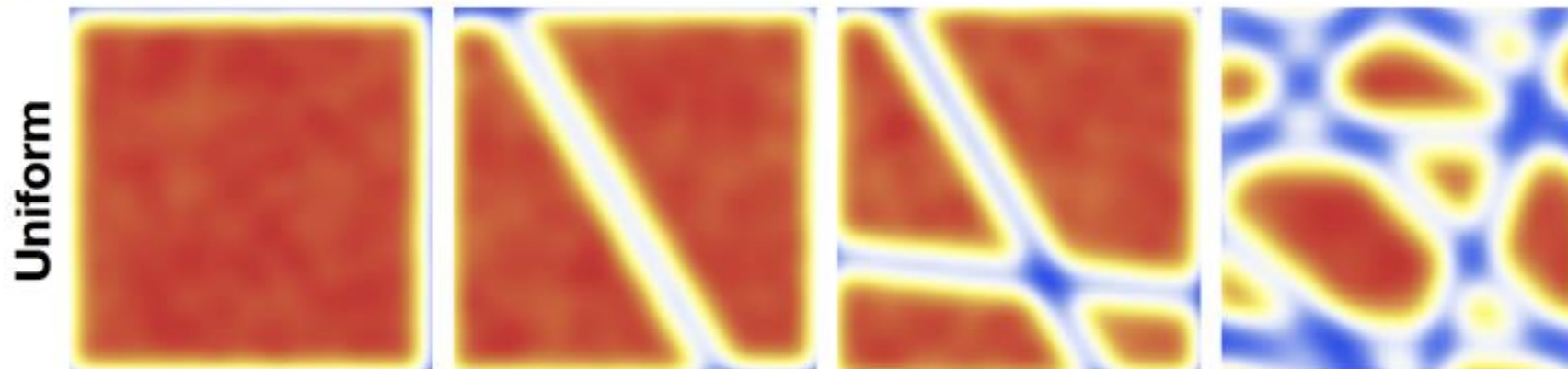


$$X \sim \mathcal{N}(0, I)$$

$$Z = X^2$$

- Base distribution: Uniform

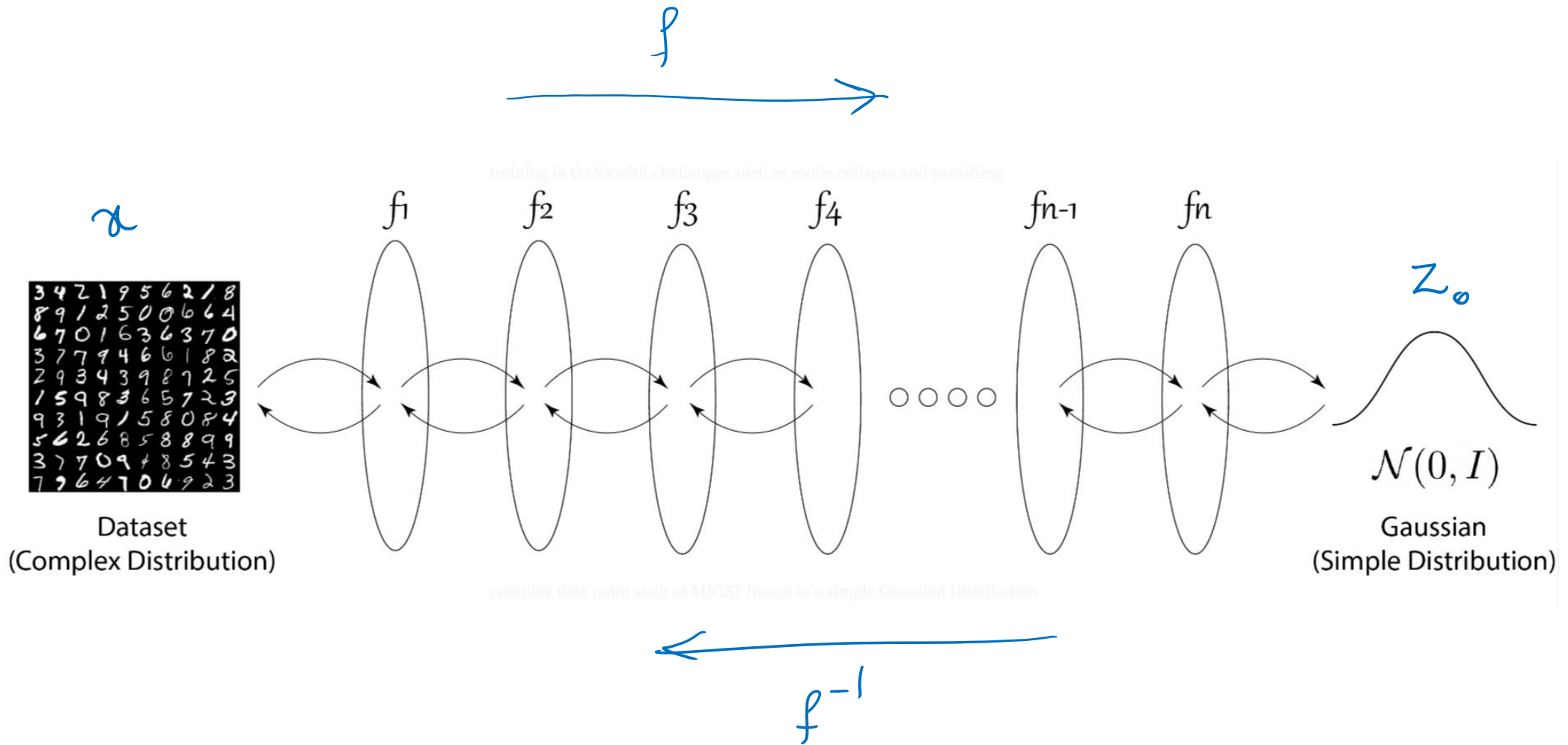
$$Z \rightarrow X$$



$$U \rightarrow X$$

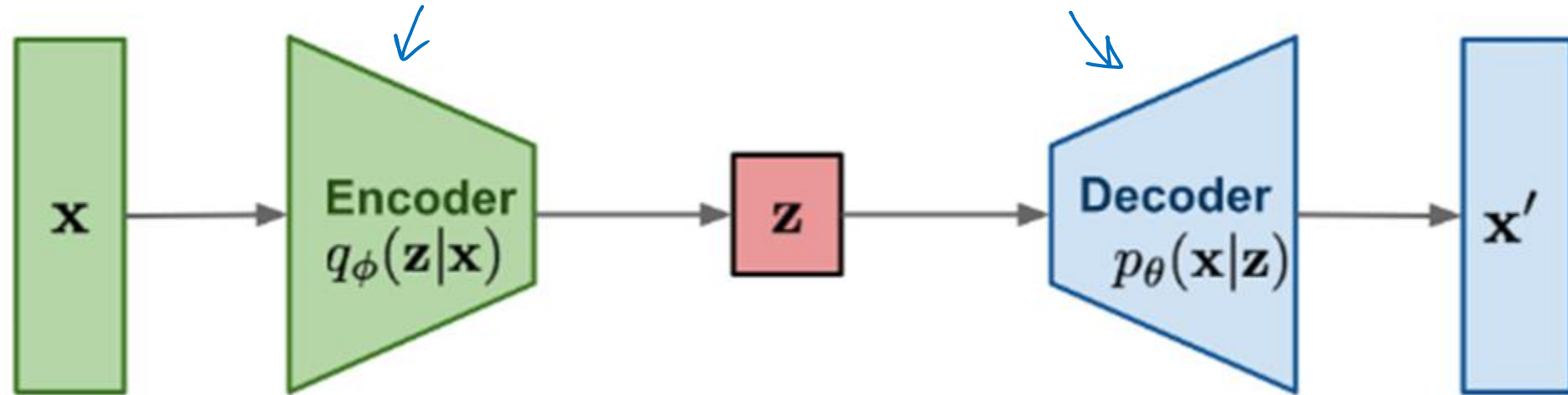
$$P(X) > 0$$

Example: MNIST Dataset

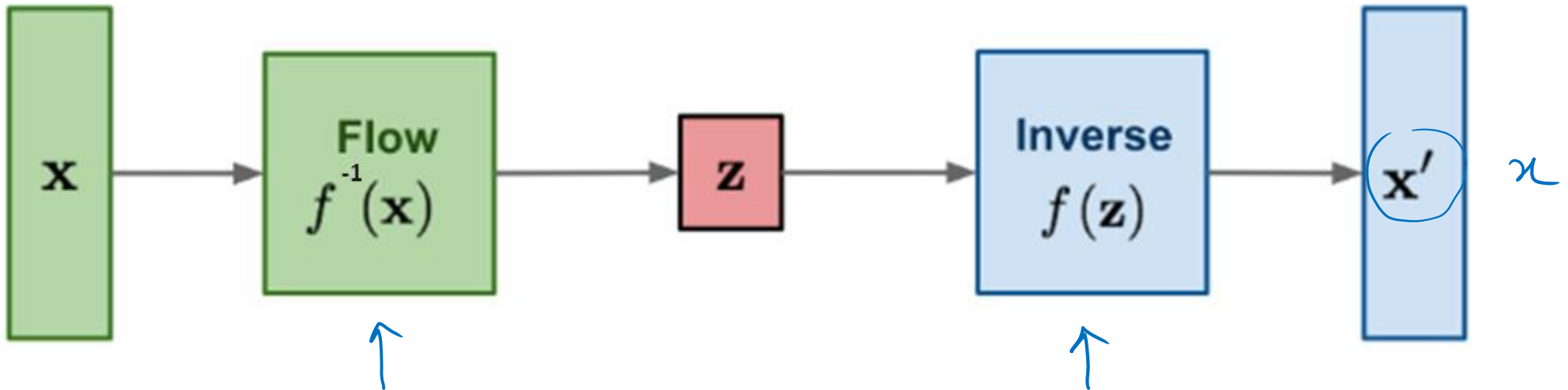


Normalizing Flows vs. VAE

VAE

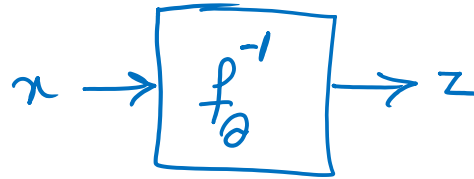
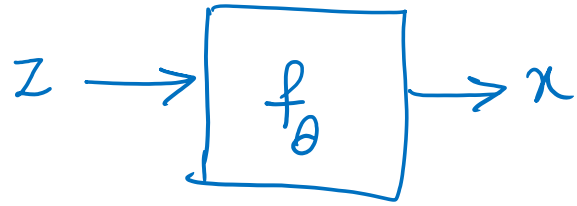


NF:



Marginal Likelihood: VAE vs NF

Decoder



$$D = \{x_1, x_2, \dots, x_n\}$$

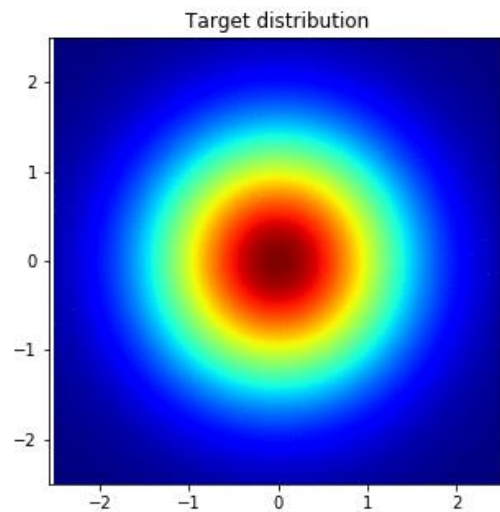
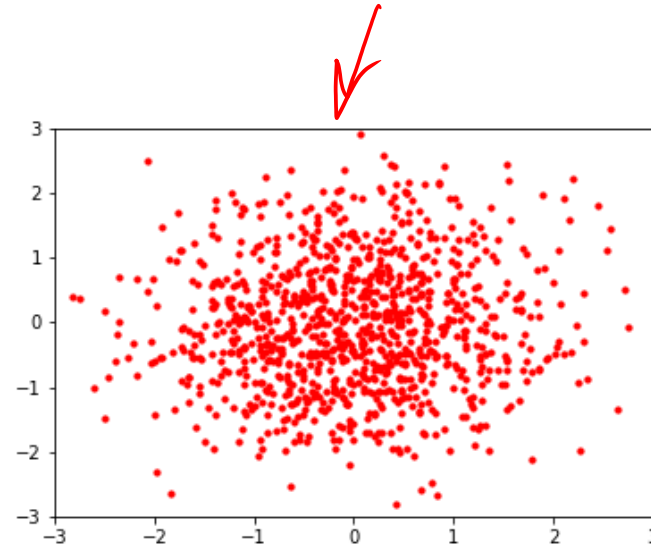
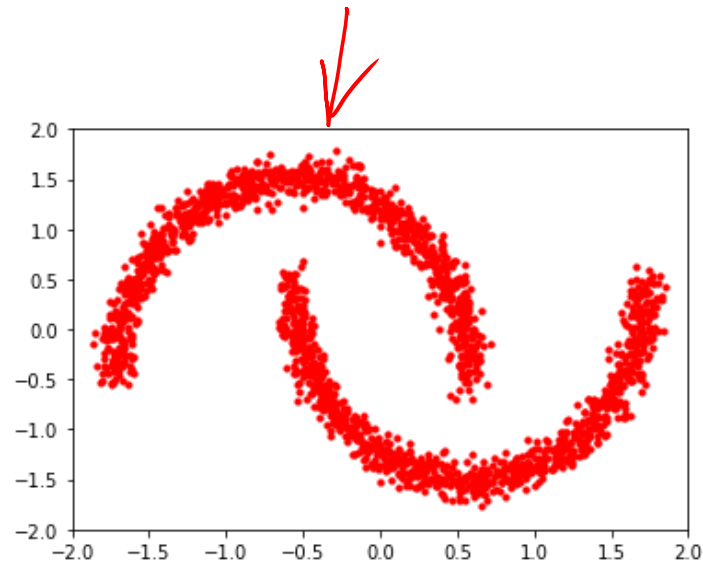
$$\hat{\theta}_{ML} = \arg \max_{\theta} \log P(D) = \arg \max_{\theta} \log P(x_1, \dots, x_n)$$

$$= \arg \max_{\theta} \sum_{i=1}^n \log P(x_i)$$

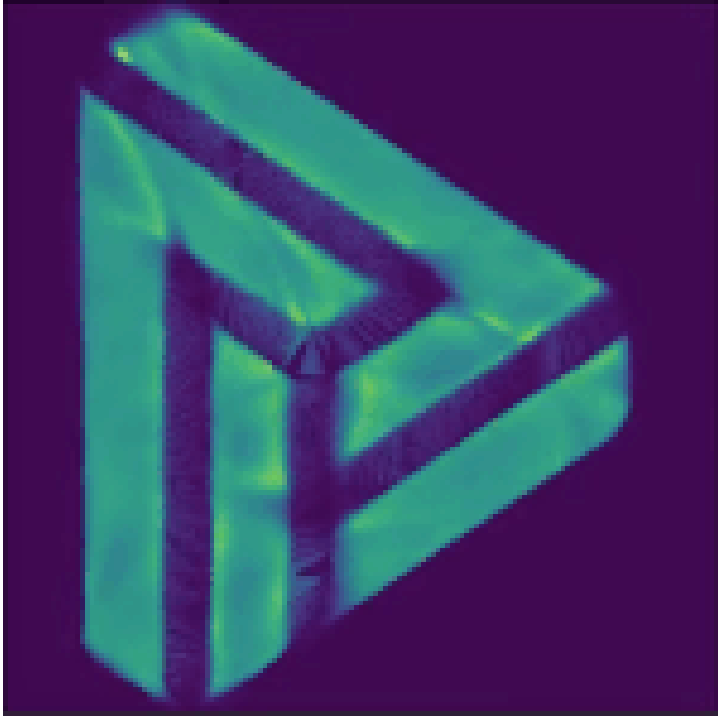
A red box is drawn around the summation term, with a red checkmark below it.

$$\log P(x) \geq ELBO$$

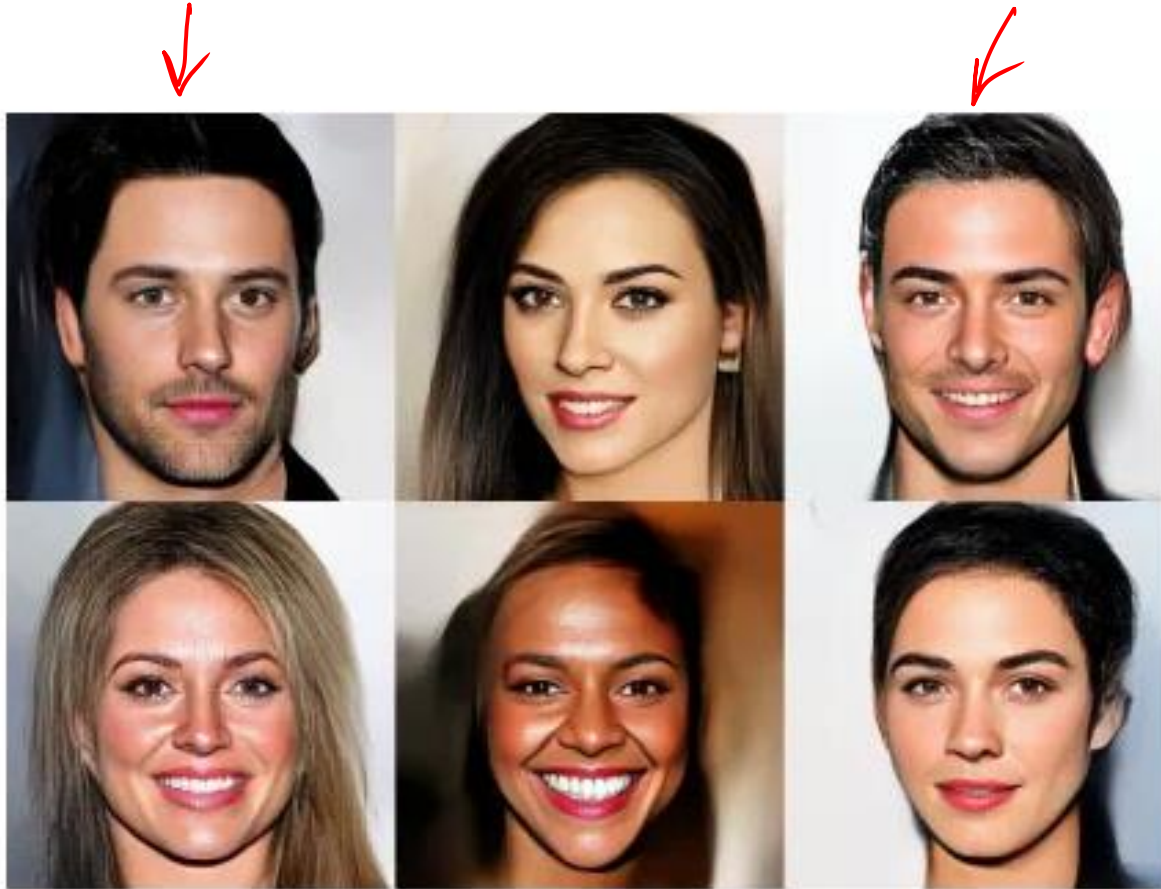
From Normal to Complex Distribution



Normalizing Flow: another Example



Samples from Normalizing Flow

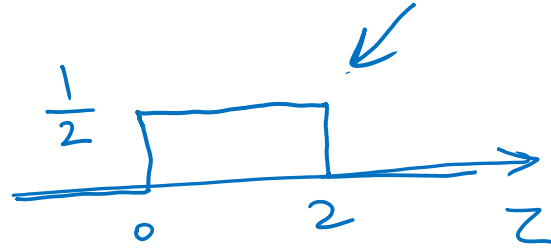


Samples from the Glow model (Source)

① ڪنڀيت X
② سرعت ✓
③ تنوع X

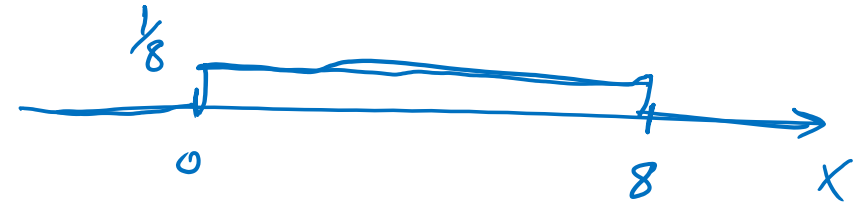
Change of Variable Formula

- Let $Z \sim \mathcal{U}[0,2]$



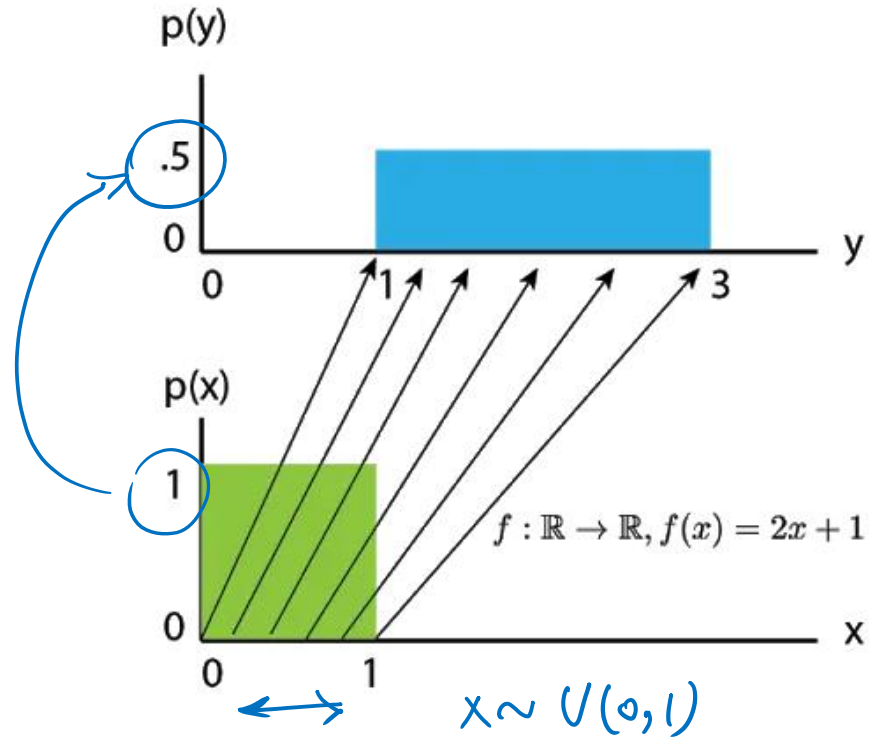
- $P_Z(z) = \frac{1}{2}$

- Let $X = 4Z \Rightarrow 0 \leq X \leq 8$



- $P_X(4) = ?$

Change of Variable Formula



$$Y = 2X + 1$$

$$X = \frac{y - 1}{2}$$

$$P_Y(y) = \frac{1}{2} P_X(x) = \frac{1}{2} P_X\left(\frac{y - 1}{2}\right)$$

Change of variable formula (1-D case)

- If $X = f(Z)$ and $f(\cdot)$ is monotone with inverse $Z = f^{-1}(X) = h(X)$, then:

$$\rightarrow P_X(x) = P_Z(h(x)) |h'(x)|$$

Change of formula: Example

$$Z \sim \mathcal{U}[0,2]$$

$$X = f(Z) = \exp(Z) = e^Z$$

- What is $P_X(x) = ?$

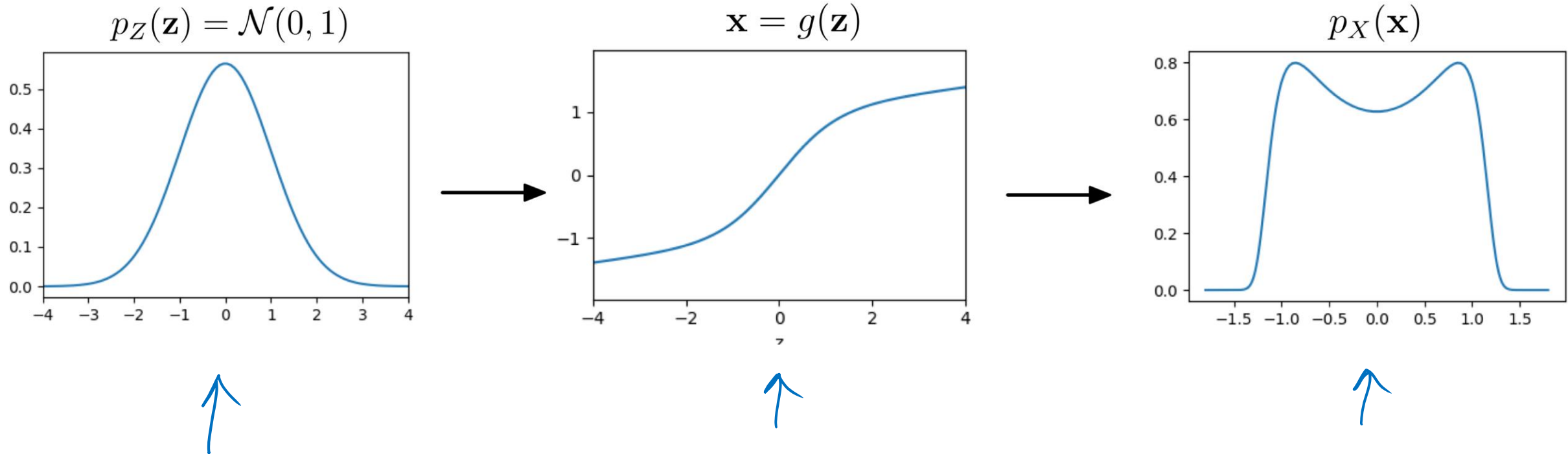
$$P_X(x) = \underbrace{P_Z(f^{-1}(x))}_{\text{}} \left| f^{-1}'(x) \right|$$

$$= \frac{1}{2} x \left| \frac{1}{x} \right| = \frac{1}{2x}$$

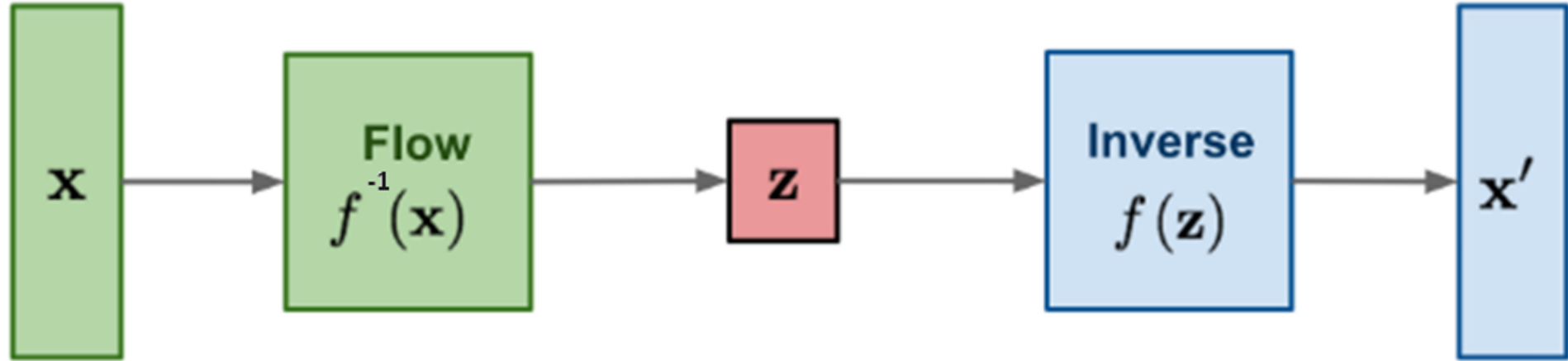
$$Z = f^{-1}(x) = \underbrace{\ln x}$$

$$1 \leq x \leq e^2$$

Change of variable: 1-D case

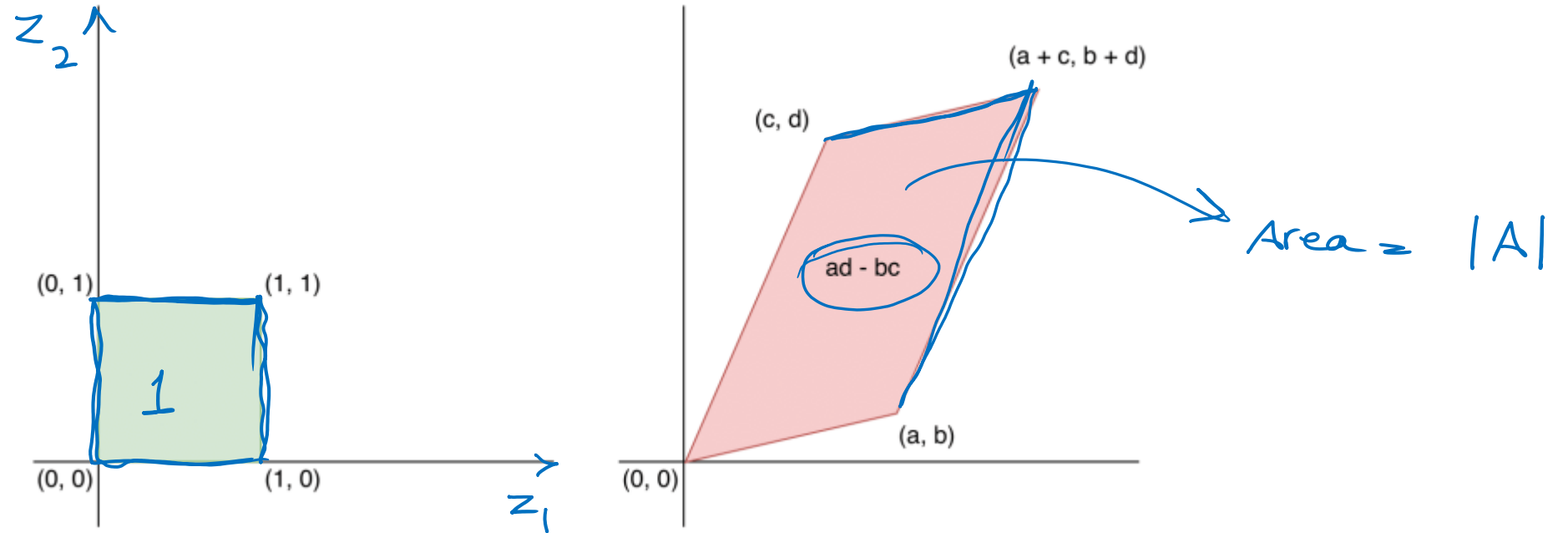


Change of Variable Formula: 1-Dimensional



$$P_X(x) = P_Z(f^{-1}(x)) \left| \frac{\partial f^{-1}(x)}{\partial x} \right|$$

Change of variable: n-Dimensional



تبدیل خطی \rightarrow

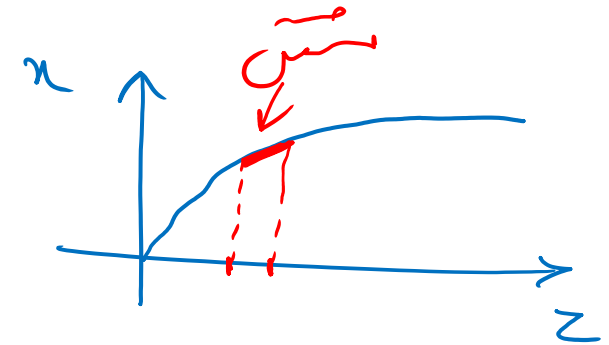
$$\mathbf{x} = A\mathbf{z}$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\mathbf{z} = A^{-1}\mathbf{x}$$

$$\frac{ad - bc}{1}$$

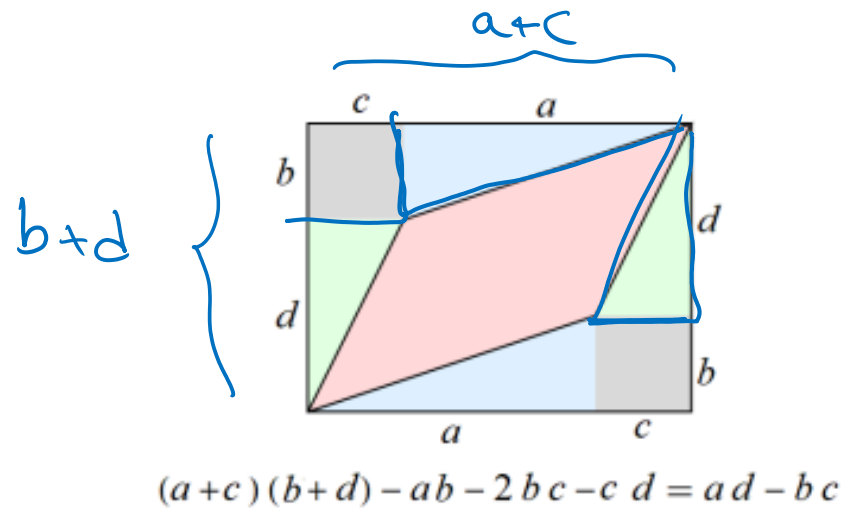
Determinants and Volume



$$\det(A) = \det \begin{pmatrix} a & c \\ b & d \end{pmatrix} = ad - bc$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$J_{n \times n}$$



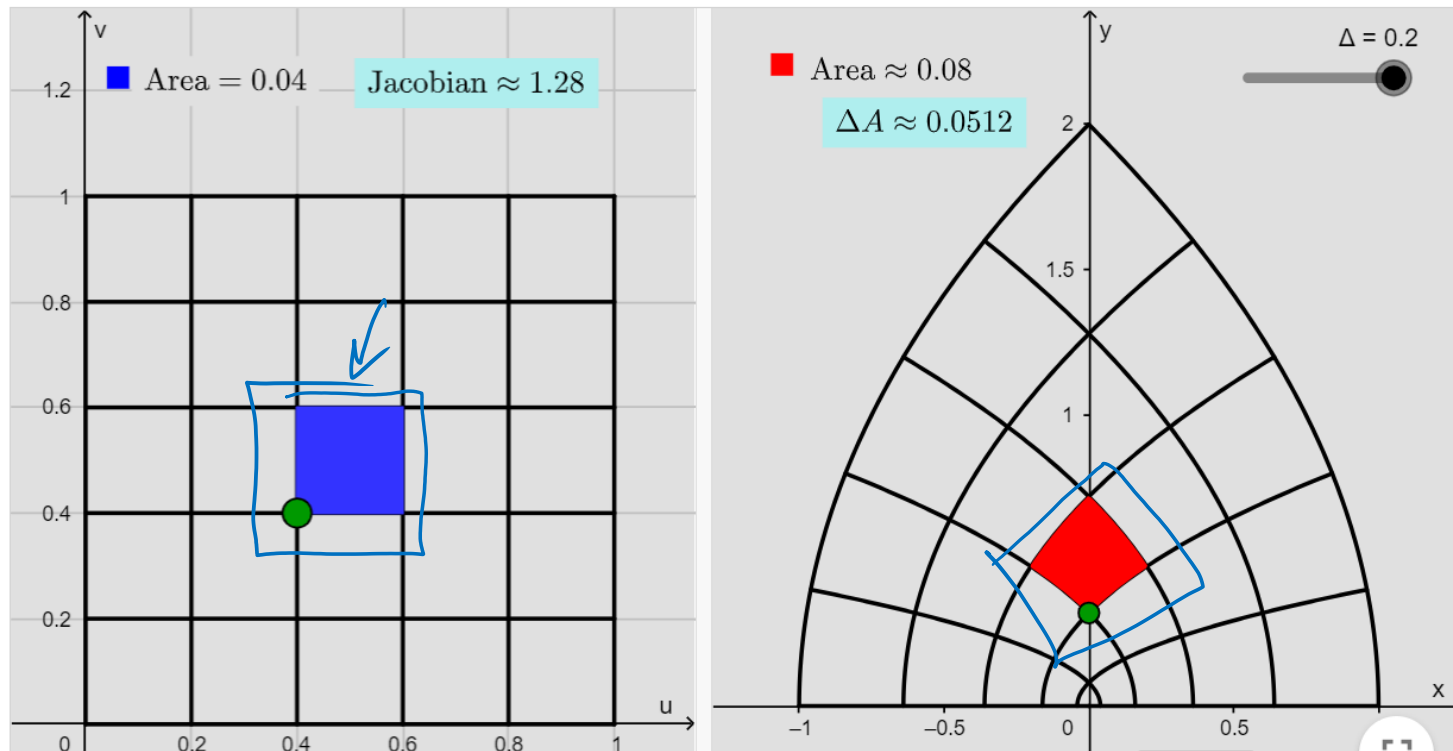
$$x = Az$$

$$P_x(x) = \frac{1}{|\det(A)|} P_z(A^{-1}x)$$

$$x = f(z) \longrightarrow x \simeq \textcircled{A} z$$

Jacobian Determinant

$$\Delta A = |J| \times \text{Area of square}$$



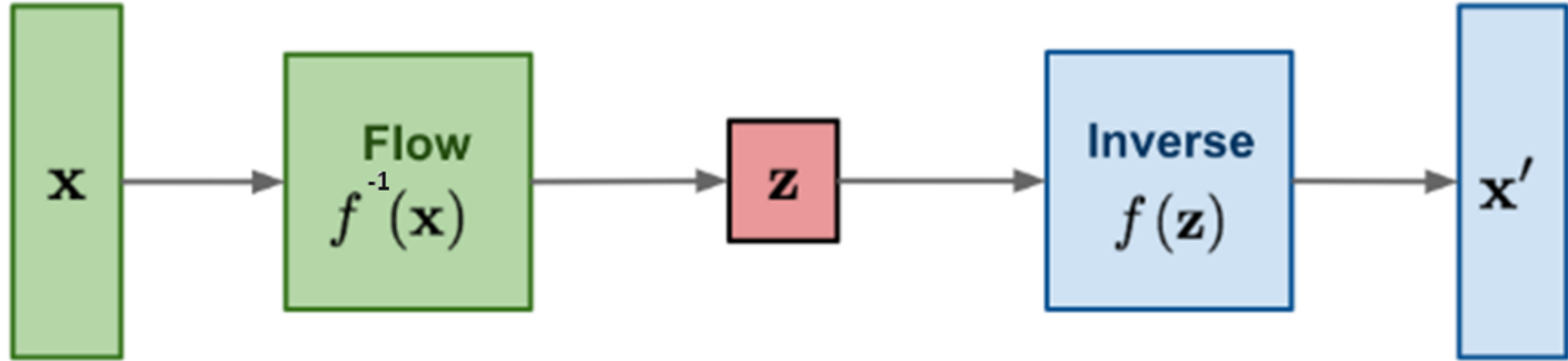
<https://www.geogebra.org/m/qM777NYH>

Jacobian Matrix

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \xrightarrow{f} \mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

$$\frac{\partial(y_1, \dots, y_n)}{\partial(x_1, \dots, x_n)} = \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \dots & \frac{\partial y_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial y_n}{\partial x_1} & \dots & \frac{\partial y_n}{\partial x_n} \end{bmatrix} n \times n$$

Change of Variable Formula: n-Dimensional



$$P_X(x) = P_Z \left(\underbrace{f_{\theta}^{-1}(x)} \right) \left| \det \left(\underbrace{\frac{\partial f_{\theta}^{-1}(x)}{\partial x}} \right) \right|$$

Jacobian

Learning and Inference

$$p_X(x) = p_Z(f_\theta^{-1}(x)) |J|$$

- Learning via **Maximum Likelihood:**

$$\max_{\theta} \log p_X(\mathcal{D}; \theta) = \sum_{x \in \mathcal{D}} \log p_Z(f_\theta^{-1}(x)) + \log \left| \det \left(\frac{\partial f_\theta^{-1}(x)}{\partial x} \right) \right|$$

\downarrow
 $\mathcal{N}(0, I)$

- **Sampling:**

$$z \sim p_Z(z) \quad x = f_\theta(z)$$

- **Latent Representation:**

$$z = f_\theta^{-1}(x)$$

Calculation of the Determinant

- Computing the determinant for an $n \times n$ matrix is $O(n^3)$: prohibitively expensive within a learning loop!

$$n = 10000$$

$$O(10^{12})$$

- Key idea:** Choose transformations so that the resulting Jacobian matrix has **special structure**. For example, the determinant of a **triangular** matrix is the product of the diagonal entries, i.e., an $O(n)$ operation.

$$J = \begin{bmatrix} \circ & \circ & \circ & \circ \\ & \circ & \circ & \circ \\ & & \ddots & \circ \\ & & & \circ \end{bmatrix}$$

$$J = \begin{bmatrix} \circ & \circ & \circ & \circ \\ \circ & \circ & \circ & \circ \\ \circ & \circ & \circ & \circ \\ \circ & \circ & \circ & \circ \end{bmatrix}$$

$$x = Az$$

$$|A|$$