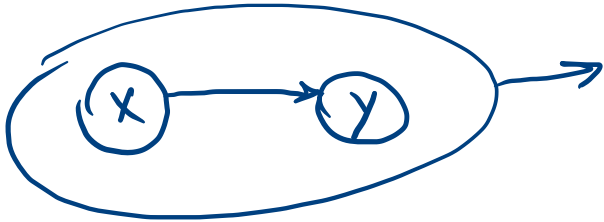


Identifiability



$$x = u_x$$

$$y = f(x, u_y)$$

$$u_y \perp u_x$$

$$y = u_y$$

$$x = g(y, u_x)$$

$$u_x \perp u_y$$

$$D = \{(x_1, y_1), \dots, (x_n, y_n)\}$$

SCM: ANM

$$X = U_x$$

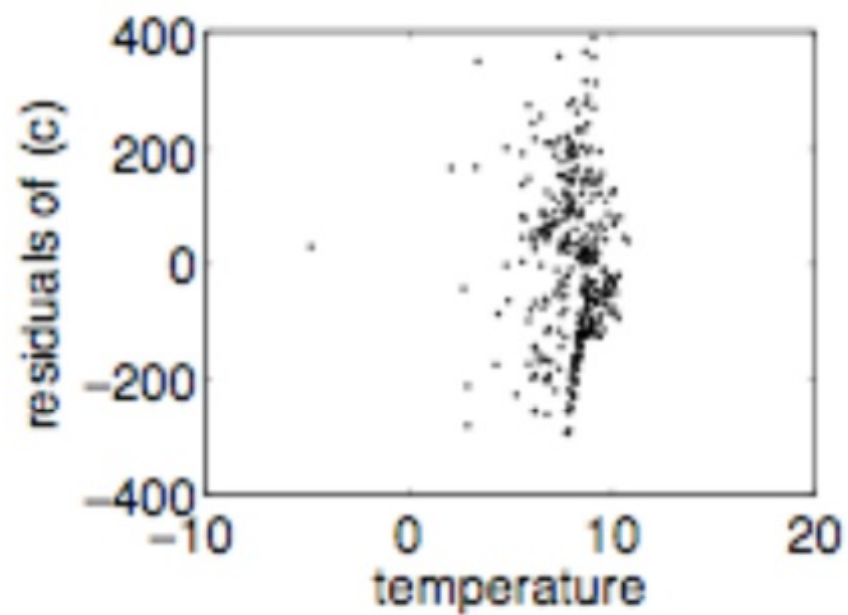
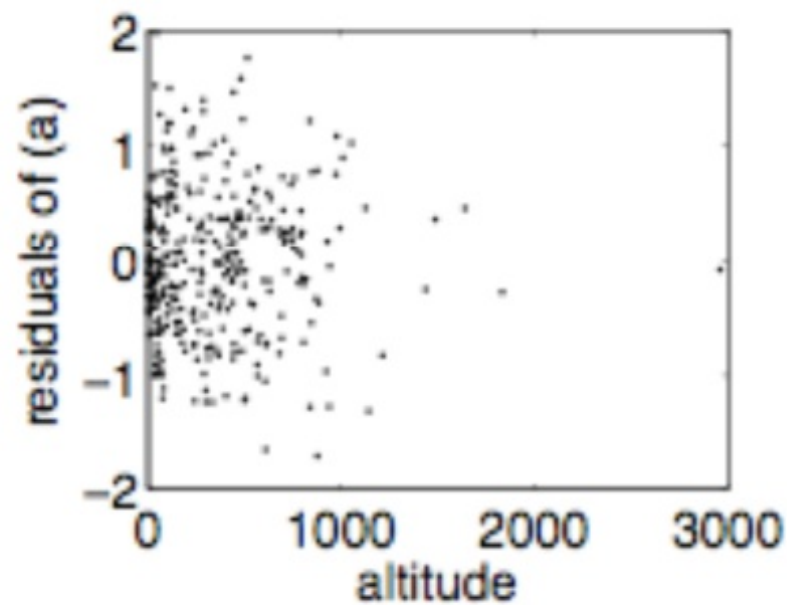
$$Y = f(X) + U_y$$

$$U_x \perp U_y$$

$$Y = U_y$$

$$X = g(Y) + U_x$$

$$U_x \perp U_y$$

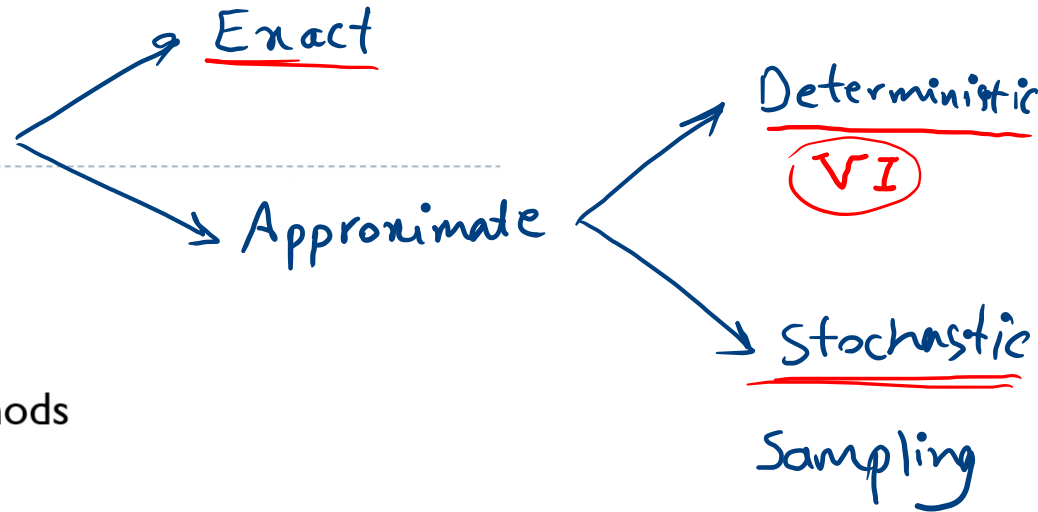


Our independence tests detect strong dependence.
Hence the method prefers the correct direction

altitude \rightarrow temperature

Approximate inference

- ▶ Approximate inference techniques
 - ▶ Deterministic approximation
 - ▶ Variational algorithms
 - ▶ Stochastic simulation / sampling methods



$$P(y|x) = ?$$

Sampling-Based Estimation

$$x \sim \underline{p(x)}$$

$$\{x_1, \dots, x_n\}$$

$$E[x] = ?$$

$$E[x] \approx \frac{1}{n} \sum_i x_i$$

$$E[f(x)] \approx \frac{1}{n} \sum_{i=1}^n f(x_i)$$

$$\rightarrow P(x = x_0)$$

MC MC

Monte Carlo methods

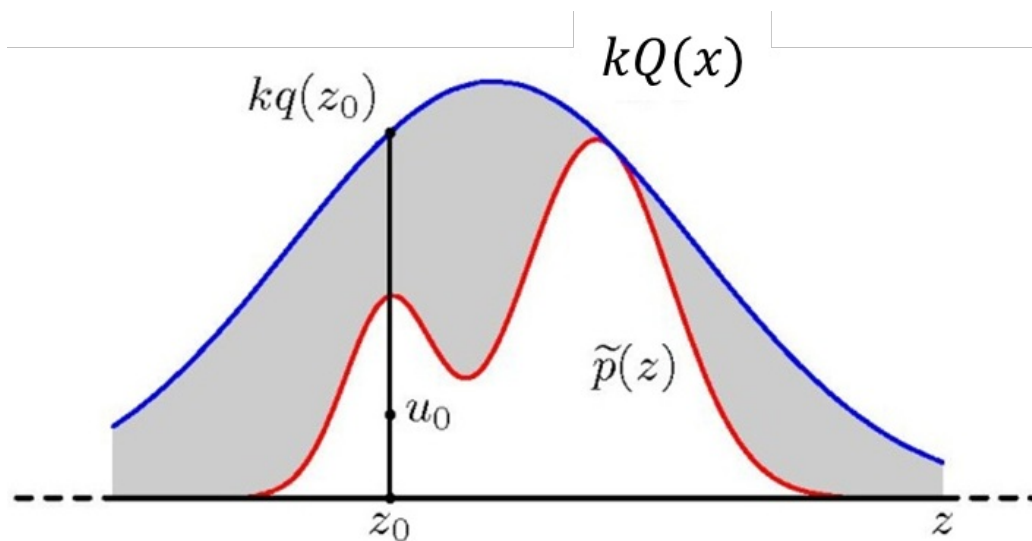
- ▶ Using a set of samples to find the answer of an inference query
 - ▶ expectations can be approximated using sample-based averages

Rejection Sampling

$p(x)$ $Q(x)$

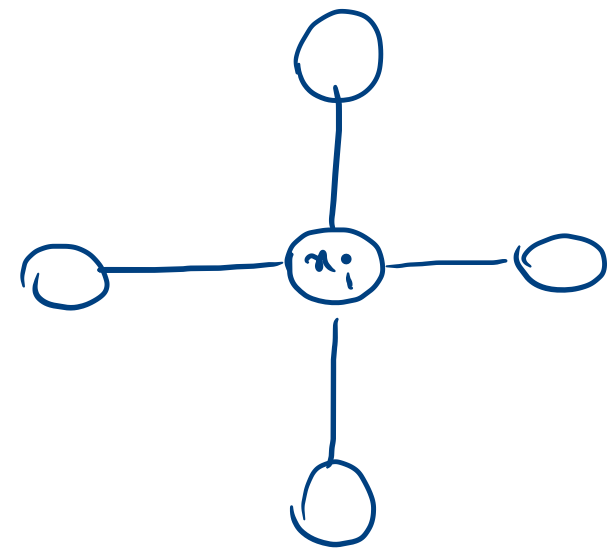
proposal distribution

$$p(x) = \frac{\tilde{p}(x)}{Z}$$



$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{100} \end{bmatrix}$$

$\tilde{p}(x)$



$$\Phi(x_i, x_j) = e^{+\alpha x_i x_j}$$



$$p(x) = \frac{\tilde{p}(x)}{Z}$$

$Z = ?$

$$K Q(x) \geq \tilde{p}(x)$$

$$D = \{x_1, x_2, \dots, x_n\}$$

$$x \sim Q(x)$$

$$p(\text{Accept}) = \frac{\tilde{p}(x)}{K Q(x)} \leq 1$$

$$q(x) = \frac{\cancel{Q(x)} \frac{\tilde{p}(x)}{\cancel{K Q(x)}}}{\int \cancel{Q(x)} \frac{\tilde{p}(x)}{\cancel{K Q(x)}} dx} = \frac{\tilde{p}(x)}{\int \tilde{p}(x) dx} = \frac{\tilde{p}(x)}{Z} = p(x)$$

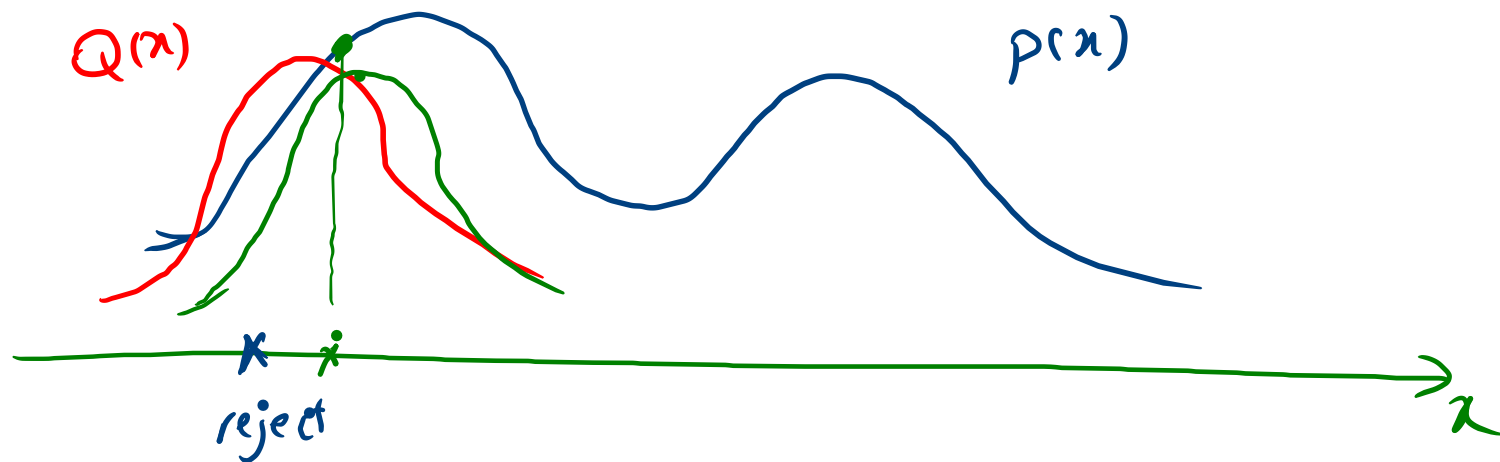
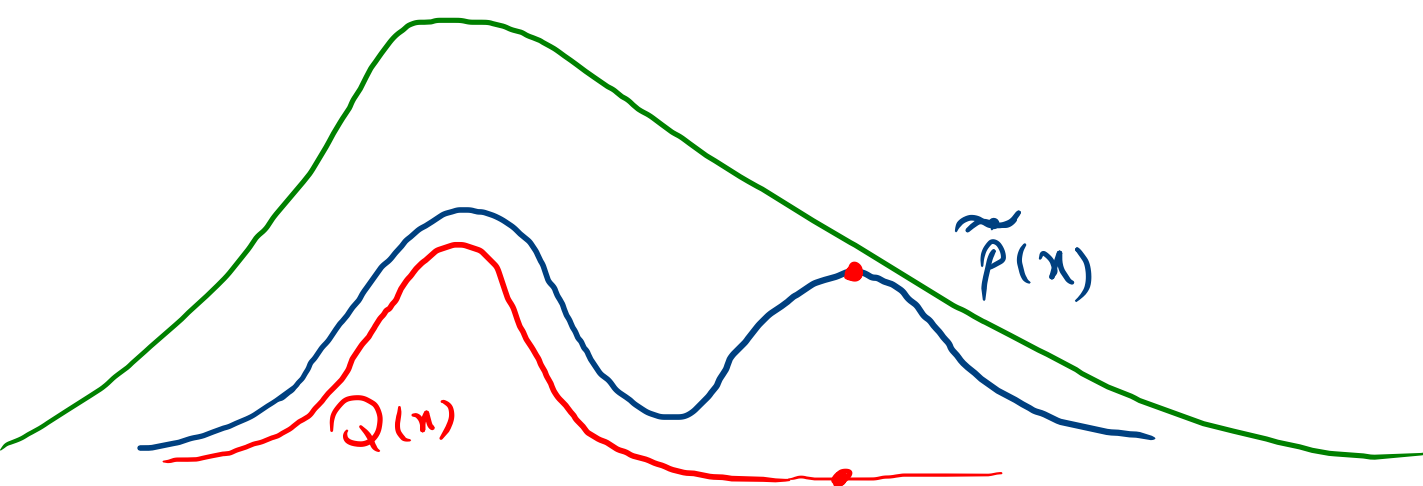
$q(x) = p(x)$

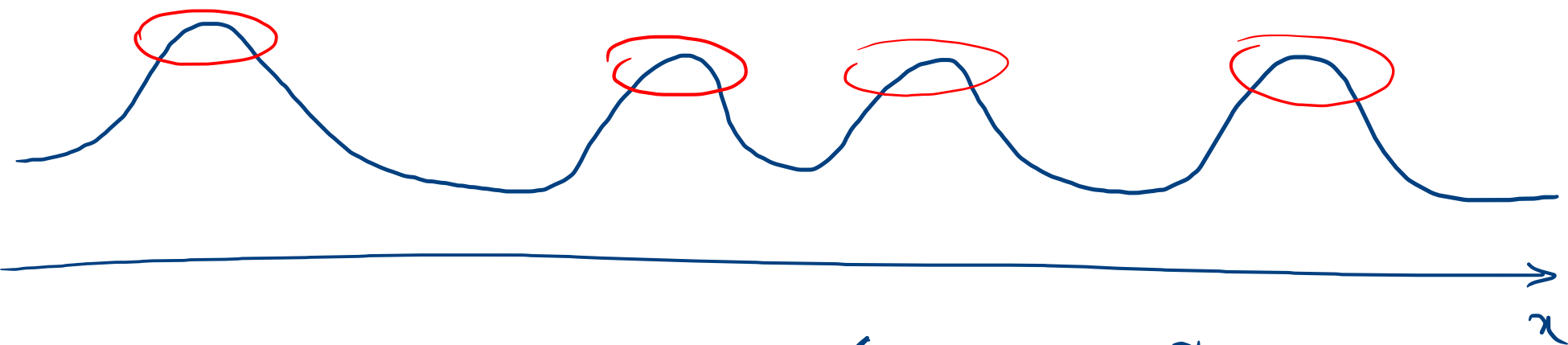
$$\textcircled{K} Q(x) \geq \tilde{p}(x)$$

$$\frac{\textcircled{\tilde{p}(x)}}{\textcircled{K} \underline{Q(x)}}$$

10000

MCMC





$f(x)$
↑

z'

$\tilde{p}(x)$

$$\underline{Q(x)} = \frac{\tilde{p}(x)}{\textcircled{z'}}$$

$$Q(x) = \frac{\tilde{p}(x)}{\textcircled{z}} = p(x)$$

MCMC

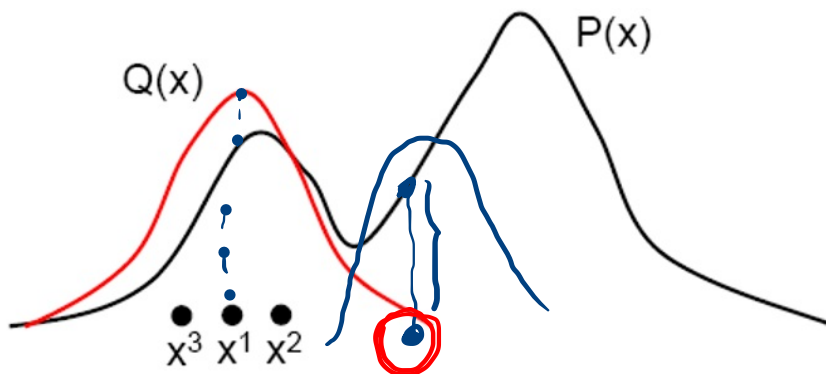
Markov chain Monte Carlo

► MCMC algorithms feature adaptive proposals

- Instead of $Q(x')$, they use $Q(x'|x)$ where x' is the new state being sampled, and x is the previous sample

Gibbs
sampling

Importance sampling with
a (bad) proposal $Q(x)$



MCMC with adaptive
proposal $Q(x'|x)$

