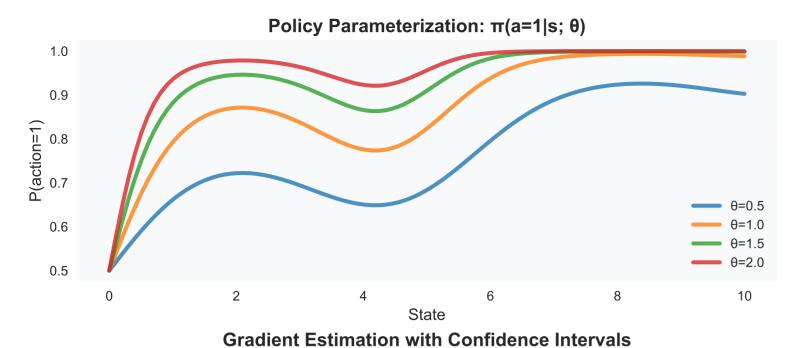
# **Comprehensive Policy Gradient Intuition**





100

Training Iteration

125

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175

200

#### **Mathematical Foundation**

75

## **Policy Gradient Theorem Derivation:**

$$J(\theta) = E[\sum \Box_{\theta} \log \pi_{\theta}(a_t|s_t) \cdot G_t]$$

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- Where:

  J(θ): Expected return

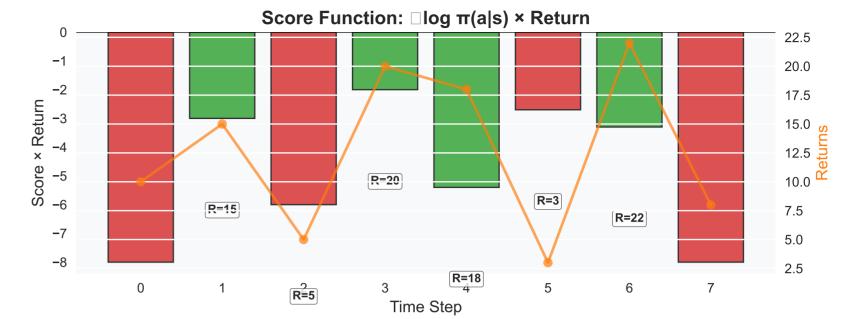
  □ θ log π\_θ: Score function
  G t: Return from time t
  F⊡: Expectation over trajectories

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$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\pi_{\theta}} \left[ \sum_{t=0}^{T-1} \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) \cdot G_t \right]$$

## **Policy Gradient Algorithms Comparison**

Algorithm	Variance	Bias	Sample Eff.	Stability
REINFORCE	High	Low	Low	Low
Actor-Critic	Medium	Medium	Medium	Medium
PPO	Low	Low	High	High
TRPO	Low	Low	High	Very High





Step 0

Step 25

Step 50

Step 100

Step 200 Step 500

