



Laplace Transform and its Applications (Chapter 15 & 16)

Laplace Transform



Definition of Laplace Transform

- The Laplace Transform is an integral transformation of a function f(t) from the time domain to the complex frequency domain, giving F(s).
- The two-sided Laplace transform of a signal *f*(*t*) is defined as:

$$F(s) = \int_{-\infty}^{\infty} f(t)e^{-st}dt$$

• The single-sided (unilateral) Laplace transform of a signal f(t) is defined as:

$$F(s) = \int_0^\infty f(t)e^{-st}dt$$



Example Laplace Transforms

2. Find LT of exponential function e-at

$$LT(e^{-at}) = \int_0^\infty e^{-at} e^{-st} dt = \left[\frac{e^{-(s+a)t}}{-(s+a)} \right]_0^\infty = \frac{1}{s+a}$$

3. Find LT of the delta function δ (t):

$$LT[\delta(t)] = \int_{0^{-}}^{\infty} \delta(t)e^{-st}dt = e^{-0} = 1$$

Since $\delta(t)$ is 1 at t = 0, and zero everywhere else.



Simple RL Circuit Example

■ A simple differential equation can be derived to describe the system

$$L \frac{di(t)}{dt} + Ri(t) = v(t)$$

$$= Vu(t), \qquad t > 0$$

- Input: voltage, v(t) (in this case, a unit step)
- \blacksquare Output: current, i(t)
- One method: Solve the DE for different input voltages



Alternative solution

• Take Laplace transforms of both sides and then solve

$$L(sI(s)-i(0))+RI(s)=V(s)=\frac{V}{s}$$

- A linear equation
- Assuming i(0)=0, simplification yields:

$$I(s) = \frac{V/L}{s(s+R/L)}$$

• To find i(t), take the inverse transform

Hence: Laplace transforms convert differential equations to algebraic equations, which are simpler to solve.

Laplace Transform Tables

- Describe transforms of different functions
- Also describe various properties
- Much of this is covered in MATH283

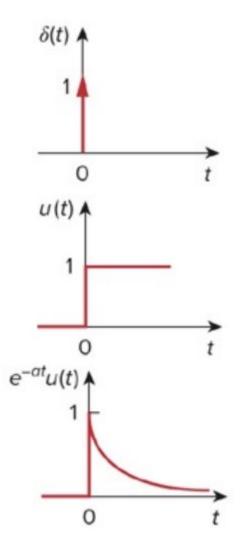


Example LT pairs

(ii)
$$\delta(t) \leftrightarrow 1$$

$$u(t) \leftrightarrow \frac{1}{s}$$

$$u(t)e^{-at} \leftrightarrow \frac{1}{s+a}$$
(iii) $u(t)\sin \omega t \leftrightarrow \frac{\omega}{s^2 + \omega^2}$
(iii) $u(t)\cos \omega t \leftrightarrow \frac{s}{s^2 + \omega^2}$
(iv) $u(t)t^n \leftrightarrow \frac{n!}{s^{n+1}}$





LT pairs

Laplace transform pairs.*

f(t)	F(s)
$\delta(t)$	1
u(t)	$\frac{1}{s}$
e^{-at}	$\frac{1}{s+a}$
r	$\frac{1}{s^2}$
T"	$\frac{n!}{s^{n+1}}$
te^{-at}	$\frac{1}{(s+a)^2}$
$t^n e^{-at}$	$\frac{n!}{(s+a)^{n+1}}$
$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
$\sin(\omega t + \theta)$	$\frac{s\sin\theta + \omega\cos\theta}{s^2 + \omega^2}$
$\cos(\omega t + \theta)$	$\frac{s\cos\theta - \omega\sin\theta}{s^2 + \omega^2}$
$e^{-at}\sin \omega t$	$\frac{\omega}{(s+a)^2+\omega^2}$
$e^{-at}\cos\omega t$	$\frac{s+a}{(s+a)^2+\omega^2}$

^{*}Defined for $t \ge 0$; f(t) = 0, for t < 0.



LT properties

Properties of the Laplace transform.

Property	f(t)	F(s)
Linearity	$a_1f_1(t) + a_2f_2(t)$	$a_1F_1(s) + a_2F_2(s)$
Scaling	f(at)	$\frac{1}{a}F\left(\frac{s}{a}\right)$
Time shift	f(t-a)u(t-a)	$e^{-as} F(s)$
Frequency shift	$e^{-at}f(t)$	F(s+a)
Time differentiation	$\frac{df}{dt}$	$sF(s) - f(0^-)$
	$\frac{d^2f}{dt^2}$	$s^2F(s) - sf(0^-) - f'(0^-)$
	$\frac{d^3f}{dt^3}$	$s^3F(s) - s^2f(0^-) - sf'(0^-) - f''(0^-)$
	$\frac{d^n f}{dt^n}$	$s^{n}F(s) - s^{n-1}f(0^{-}) - s^{n-2}f'(0^{-})$ - $\cdots - f^{(n-1)}(0^{-})$
Time integration	$\int_0^t f(x)dx$	$\frac{1}{s}F(s)$
Frequency differentiation	tf(t)	$-\frac{d}{ds}F(s)$
Frequency integration	$\frac{f(t)}{t}$	$\int_{s}^{\infty} F(s)ds$
Time periodicity	f(t) = f(t + nT)	$\frac{F_1(s)}{1 - e^{-sT}}$



Examples

Use the LT tables and properties to find the find the Laplace Transform of the following functions

1.
$$Cos(2t+30^{\circ})$$

2.
$$\delta(t) + t$$

3.
$$te^{-2t}$$
 u(t)

4.
$$t^2e^{-2t}$$
 u(t)

5.
$$cos(5t)u(t)$$

6.
$$e^{-4t} \sin(t) u(t)$$

7.
$$\delta(t)+2 u(t)-3 e^{-5t} u(t)$$

8.
$$\cos(10t - 10)u(t - 1)$$

9.
$$t^2 \sin 2t \, u(t)$$

$$10.e^{-3t}u(t-2)$$



Inverse Laplace Transform

Let $F(s) = \frac{N(s)}{D(s)}$ where N & D are polynomials in s of order m and n respectively.

The roots of N(s) & D(s) are called zeros & poles respectively. F(s) can always be reduced to a ratio with m < n by polynomial division.

Example

Find the ILT of
$$F(s) = \frac{s^2 + s + 1}{(s+1)(s+2)}$$

$$= \frac{s^2 + s + 1}{(s^2 + 3s + 2)} = 1 - \frac{2s + 1}{(s^2 + 3s + 2)}$$



Inverse Laplace Transform

$$F(s) = \frac{2s+1}{(s+1)(s+2)} = \frac{A}{(s+1)} + \frac{B}{(s+2)}$$

Method 1: Multiply by denominator & equate powers of s

$$2s + 1 = A(s + 2) + B(s + 1)$$

$$2s + 1 = (A + B)s + (2A + B)$$

equate like coefficients of s

$$2 = A + B & & 1 = 2A + B$$
giving $A = -1 & B = 3$

$$hence F(s) = 1 - \frac{-1}{(s+1)} + \frac{3}{(s+2)} :$$

$$f(t) = \delta(t) + e^{-t} - 3e^{-2t}$$



General solution for simple poles

$$F(s) = \sum_{j=1}^{n} \frac{k_{j}}{(s+p_{j})}$$

$$k_{j} = (s+p_{j})F(s)\Big|_{s=-p_{j}}, \quad j=1,2,+n$$



Example, repeated poles

We need a term for each power of the repeated root

$$F(s) = \frac{S+1}{(s+2)^2} = \frac{A}{(s+2)} + \frac{B}{(s+2)^2}$$

Soln: Multiply both sides by the denominator, D(s)

$$s+1 = As + (2A + B)$$

equating terms
$$A = 1$$
, $B = -1$

& thus
$$F(s) = \frac{1}{(s+2)} - \frac{1}{(s+2)^2}$$

$$f(t) = e^{-2t} - te^{-2t} = (1-t)e^{-2t}$$

Example, repeated poles

Reactive circuit example:

$$e^{-t} = x + \frac{dx}{dt} \quad \text{and} \quad x(0^-) = 0$$

Ans.
$$LT \to \frac{1}{s+1} = X(s) + sX(s) - x(0^-) = (s+1)X(s) \to X(s) = \frac{1}{(s+1)^2}$$

using ILT pairs
$$\rightarrow x(t) = te^{-t}$$



Complex poles

Leads to a partial fraction term with a quadratic denominator. These can be found by *completing the square* in denominator re-expressed in frequencyshift form.

$$F(s) = \frac{A_1 s + A_2}{s^2 + as + b} + F_1(s)$$
 Remaining portion of $F(s)$ not containing quadratic forms

$$s^{2} + as + b \rightarrow s^{2} + 2\alpha s + \alpha^{2} + \beta^{2} \rightarrow (s + \alpha)^{2} + \beta^{2}$$

$$F(s) = \frac{A_1(s+\alpha)}{(s+\alpha)^2 + \beta^2} + \frac{B_1\beta}{(s+\alpha)^2 + \beta^2} + F_1(s)$$

$$cos \omega t \leftrightarrow \frac{s}{s^2 + \omega^2}$$

$$e^{-\alpha t} f(t)u(t) \leftrightarrow F(s+\alpha)$$

 $A_1S + A_2 \rightarrow A_1(S + \alpha) + B_1\beta$

$$\frac{\sin \omega t}{s^2 + \omega^2}$$

$$\cos \omega t \leftrightarrow \frac{s}{s^2 + \omega^2}$$

$$e^{-\alpha t} f(t) u(t) \leftrightarrow F(s + \alpha)$$

$$f(t) = (A_1 e^{-\alpha t} \cos \beta t + B_1 e^{-\alpha t} \sin \beta t) u(t) + f_1(t)$$



Example, complex poles

$$F(s) = \frac{s+1}{s^2 + 6s + 10} \qquad \rightarrow = \frac{(s+3)}{(s+3)^2 + 1} - \frac{2}{(s+3)^2 + 1}$$

$$f(t) = e^{-3t} (\cos t - 2\sin t)$$

$$F(s) = \frac{10}{(s+2)(s^2+6s+10)} \rightarrow \frac{A}{(s+2)} + \frac{Bs+C}{(s^2+6s+10)}$$

$$\therefore 10 = (A+B)s^2 + (6A+2B+C)s + (10A+2C)$$

$$0 = (A+B)$$

$$0 = (6A+2B+C)$$

$$0 = (6A+2B+C)$$

$$10 = (10A+2C)$$

$$F(s) = \frac{5}{(s+2)} - \frac{5s+20}{(s^2+6s+10)} = \frac{5}{(s+2)} - \frac{5(s+3)+5}{(s+3)^2+1}$$

$$\rightarrow f(t) = e^{-2t} - 5e^{-3t}(\cos t + \sin t)$$



equating coefficients

Initial & final value theorems

The initial- & final-value properties allow us to determine the initial value f(0) and the final value $f(\infty)$ of f(t) directly from the Laplace Transform. If one only wants the initial or final value behaviour there is no need to find the ILT.

$$\mathcal{L}[f'(t)] = sF(s) - f(0^{-})$$

$$sF(s) - f(0) = \mathcal{L}\left[\frac{df}{dt}\right] = \int_{0^{-}}^{\infty} \frac{df}{dt} e^{-st} dt$$

$$\lim_{s \to \infty} [sF(s) - f(0)] = 0$$

$$f(0) = \lim_{s \to \infty} sF(s)$$



Example, initial value

Find the initial value of: $F(s) = \frac{s}{s^2 + \omega^2}$ (LT of cos ωt)

Ans.
$$f(0) = \lim_{s \to \infty} \frac{s^2}{s^2 + \omega^2} = \lim_{s \to \infty} \frac{1}{1 + \frac{\omega^2}{s^2}} = 1$$

Find the initial value of: $F(s) = \frac{\omega}{s^2 + \omega^2}$ (LT of sin ωt)

Ans.
$$f(0) = \lim_{s \to \infty} \frac{s\omega}{s^2 + \omega^2} = \lim_{s \to \infty} \frac{\frac{\omega}{s}}{1 + \frac{\omega^2}{s^2}} = 0$$



Final value theorem

$$\mathcal{L}[f'(t)] = sF(s) - f(0^-)$$

$$sF(s) - f(0) = \mathcal{L}\left[\frac{df}{dt}\right] = \int_{0^{-}}^{\infty} \frac{df}{dt} e^{-st} dt$$

$$\lim_{s \to 0} [sF(s) - f(0^{-})] = \int_{0^{-}}^{\infty} \frac{df}{dt} e^{0t} dt = \int_{0^{-}}^{\infty} df = f(\infty) - f(0^{-})$$

$$f(\infty) = \lim_{s \to 0} sF(s)$$



Example, Final value

Obtain the initial and final values of

$$G(s) = \frac{s^3 + 2s + 6}{s(s+1)^2(s+3)}$$

$$g(0) = \lim_{s \to \infty} sF(s) = \lim_{s \to \infty} \frac{s^3 + 2s + 6}{(s^2 + 2s + 1)(s + 3)}$$

$$g(0) = \lim_{s \to \infty} \frac{1 + \frac{2}{s^2} + \frac{6}{s^3}}{\left(1 + \frac{2}{s} + \frac{1}{s^2}\right)\left(1 + \frac{3}{s}\right)} = \underline{\mathbf{1}}$$

Since all poles s = 0, -1, -1, -3 the left-hand s-plane, we can apply the final-value theorem.

$$g(\infty) = \lim_{s \to 0} sF(s) = \lim_{s \to 0} \frac{s^3 + 2s + 6}{(s+1)^2 (s+3)} \qquad g(\infty) = \lim_{s \to 0} \frac{6}{(1)^2 (3)} = \underline{2}$$



Convolution

Convolution is used to find the response y(t) of a system to an excitation x(t), when the impulse response h(t) of the system is known.

$$y(t) = \int_{-\infty}^{\infty} x(\lambda)h(t-\lambda)d\lambda$$
 or $y(t) = x(t)*h(t)$

$$h(t)$$

$$h(t)$$

$$F_{1}(s)F_{2}(s) = L\left[f_{1}(t)*f_{2}(t)\right]$$

$$L\left[x(t)*h(t)\right] = X(s)H(s)$$

Convolution in the t-domain \equiv Multiplication in the s-domain



Example

A system has the following response to an impulse:

$$h(t) = 4e^{-t}$$

Find the output y(t), when the input is

$$x(t) = 5e^{-2t}$$

solution

$$y(t) = x(t) * h(t)$$

$$H(s) = \frac{4}{s+1}, \qquad X(s) = \frac{5}{s+2}$$

$$Y(s) = X(s).H(s) = \frac{4}{s+1} \frac{5}{s+2} = \frac{20}{(s+1)(s+2)}$$

$$y(t) = 20(e^{-t} - e^{-2t})$$



Differential Equations

$$\frac{d^2v}{dt^2} + 4v = 1 \quad were \ v(0^-) = 10V \& dv/dt(0^-) = 100V/s$$

Soln. LT of the equation above gives

$$s^{2}V(s) - 10s - 100 + 4V(s) = \frac{1}{s} \rightarrow (s^{2} + 4)V(s) = \frac{1}{s} + 10s + 100 = \frac{10s^{2} + 100s + 1}{s}$$

$$\therefore V(s) = \frac{10s^2 + 100s + 1}{s(s^2 + 4)} \qquad expand by P.F. \quad V(s) = \frac{A}{s} + \frac{Bs + C}{(s^2 + 4)}$$

$$\times by D(s)$$
, $\rightarrow 10s^2 + 100s + 1 = (A + B)s^2 + Cs + 4A$

whereby equating coefficients we find : A = 0.25, B = 9.75, C = 100

Hence
$$V(s) = \frac{0.25}{s} + \frac{9.75s + 100}{(s^2 + 4)}$$
 $ILT \Rightarrow v(t) = 0.25 + 9.75\cos(2t) + 50\sin(2t)$

Check i.c: subs.into de?

$$v'(t) = -19.5\sin(2t) + 100\cos(2t)$$

$$v''(t) = -39\cos(2t) - 200\sin(2t)$$

$$v'' + 4v = -39\cos(2t) - 200\sin(2t) + 39\cos(2t) + 200\sin(2t) + 1=1$$



Applying the Laplace Transform to Circuit Problems

- **1. Transform the circuit:** from the time domain to the s-domain
- 2. Solve the circuit: using nodal analysis, mesh analysis, source transformation, superposition, or any circuit analysis technique with which we are familiar.
- 3. Take the inverse transform:

 of

 the solution and thus obtain the solution in the time domain.

Impedance of an element in the s-domain.*

Element	Z(s) = V(s)/I(s)
Resistor	R
Inductor	sL
Capacitor	1/sC

^{*} Assuming zero initial conditions



Difference between Phasor domain and Laplace Transform

- A similar procedure was followed when analysing circuits in the phasor domain
- Key assumptions for phasors was **sinusoidal inputs** and **steady-state** (i.e. zero initial conditions)
- Laplace domain can be applied to a wider range of inputs
 - E.g. exponentials, unit steps etc.
- Laplace transforms can include effects caused by nonzero initial conditions



Definition: Zero-State & Zero-Input Response

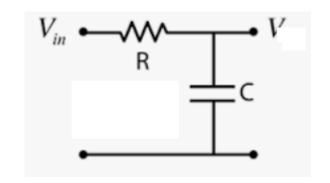
- 1. ZERO-State: ZSR with zero initial conditions
- 2. Zero Input: ZIR with no input



Example Zero-State & Zero-Input Response

For the RC circuit, Find the ZSR and ZIR for the voltage across the capacitor?

$$v_i = RC\frac{dv}{dt} + v$$



$$LT V_i(s) = RCsV(s) - RCv(0) + V(s)$$

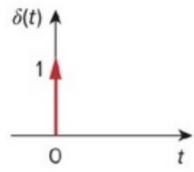
$$\therefore V(s) = \frac{V_i(s) + RCv(0)}{RCs + 1} = ZSR + ZIR$$



Impulse response and step response

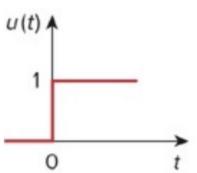
Impulse response: is the **zero-state response** for an impulsive input $\delta(t)$

With an impulsive input, Vi(s) = 1



Step response: is the **system response** when a unit step is the input $\mathbf{u}(t)$

With unit step input, Vi(s) = 1/s





Example: Impulse response and step response

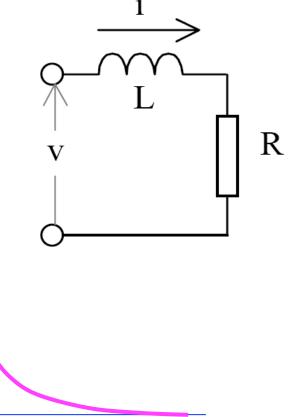
What is the impulse & step response of the system shown where **v** is the *input* & **i** is the *output* ?

Impulse response

$$H(s) = \frac{I(s)}{V(s)} = \frac{1}{(Ls+R)} = \frac{1/L}{(s+R/L)}$$

$$h(t) = \frac{1}{L}e^{-\frac{R}{L}t}$$

Input



Impulse response

Example: Impulse response and step response

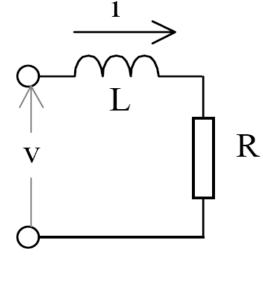
What is the impulse & step response of the system shown where **v** is the *input* & **i** is the *output* ?

Step response

$$H(s) = \frac{I(s)}{V(s)} = \frac{1}{s(Ls+R)} = \frac{1/L}{s(s+R/L)}$$

$$H(s) = \frac{1}{Rs} - \frac{1}{R(s+R/L)}$$

$$h(t) = \frac{1}{R}(1 - e^{-\frac{R}{L}t})$$

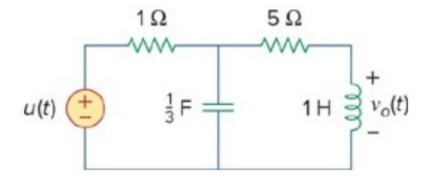


Input

Step response

Example:

Find Vo in the circuit of the figure assuming Zero initial conditions





Example 1:

Find f(t) if Fs is shown below

a)
$$F(s) = \frac{6s^2 + 26s + 26}{(s+1)(s+2)(s+3)}$$

b)
$$F(s) = \frac{7s^2 + 63s + 134}{(s+3)(s+4)(s+5)}$$

Example 2:

Find f(t) if Fs is shown below

$$F(s) = \frac{100(s+3)}{(s+1)(s^2+6s+25)}$$

Example 3:

Find f(t) if Fs is shown below

$$F(s) = \frac{10(s^2 + 119)}{(s+5)(s^2 + 10s + 169)}$$

Example 4:

Find the Laplace transform of each of the following functions:

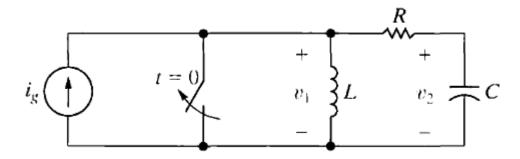
- a) $f(t) = te^{-at}$;
- b) $f(t) = \sin \omega t$;
- c) $f(t) = \sin(\omega t + \theta)$:
- d) f(t) = t;
- e) $f(t) = \cosh(t + \theta)$.

Example 5:

There is no energy stored in the circuit shown in the below circuit at the time the switch is opened.

- a) Derive the integrodifferential equations that govern the behavior of the node voltages v1, and v2.
- b) Show that

$$V_2(s) = \frac{sI_g(s)}{C[s^2 + (R/L)s + (1/LC)]}.$$

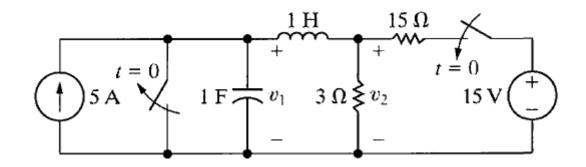




Example 6:

The dc current and voltage sources are applied simultaneously to the circuit shown. No energy is stored in the circuit at the instant of application.

- a) Derive the s-domain expressions for V1 and V2.
- b) For t > 0, derive the time-domain expressions for V1 and V2.
- c) Calculate V1(0+) and V2(0+).
- d) Compute the steady-state values of V1 and V2





Laplace Transform End

