

Started on

苗 Thursday, 8 May 2025, 11:00 AM

State

→ Finished

Completed on

Thursday, 8 May 2025, 11:08 AM

Time taken

© 8 mins 41 secs

Grade

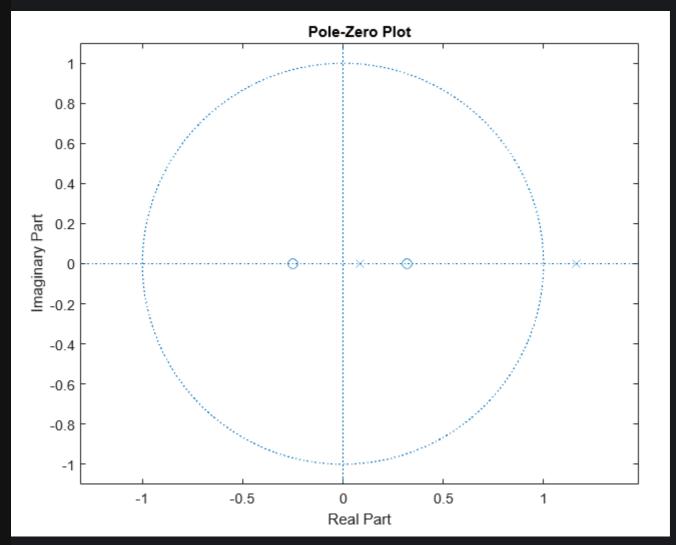
2 8.00 out of 10.00 (80%)

Complete

Mark 2.00 out of 2.00

ЕСТЕ203_Q3 (сору)

This system is NOT stable.



Select one:

True

False

Complete

Mark 0.00 out of 2.00

ECTE203_Q3

Which option best describes the general format of impulse response?

$$A = [1, 0.2, -.0.5]$$

$$B = [1 2.2]$$

$$n = 0.10$$

$$x = (n==1);$$

a. $y = impz(B,A,x);$

$$y = impz(B,A,100);$$

$$x = (n>=1);$$

d. $y = filter(B,A,x);$

Qι	estion	3

Flag question

Complete

Mark 2.00 out of 2.00

ECTE203_Q3 (copy)

Which of the following gives the correct formula to compute the length N of the output signal y when two discrete-time signals x and h are convolved using MATLAB's conv(x, h)?

- a. length(x)+length(h)-1
- b. length(x)*length(y)
- length(x)*length(h)
- d. length(x)-length(h)-1

Question 4

Flag question

Complete

Mark 2.00 out of 2.00

ECTE203_Q3

Given the length of x_in [A,B] and h[C,D], the range of convolution of x and h (y = x * h) will be _____.

- [B,D]
- b. [A, D]
- [A+C, B+D] c.
- [A+B, C+D] d.

Question 5		
Complete Mark 2.00 out of 2.00		
CTE203_Q3 system is stable when		
a. all zeros are in the unit circle		
b. at least 1 pole is inside the unit circle		
c. Magnitude of all poles are less than 1		
d. Magnitude of zeros are above 1		
	Finish review	

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