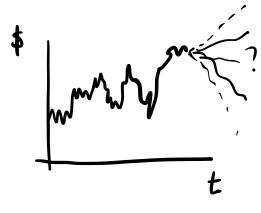
#### rod luger@gmail.com





PREDICTION

## GAUSSIAN DISTRIBUTION (ID)

$$\rho(x|\mu,\sigma^2) = \sqrt{\frac{1}{2\pi\sigma^2}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

$$\chi \sim \mathcal{N}(\mu, \sigma^2)$$

# GAUSSIAN DISTRIBUTION (Many D)

to to the to

$$\underline{y} \sim \mathcal{N}(\underline{\mu}, \underline{\Sigma})$$
 $\underline{z} = \begin{bmatrix} \sigma_0 & \sigma_1 \\ \sigma_1 & \sigma_2 \\ \sigma_3 \end{bmatrix}$ 

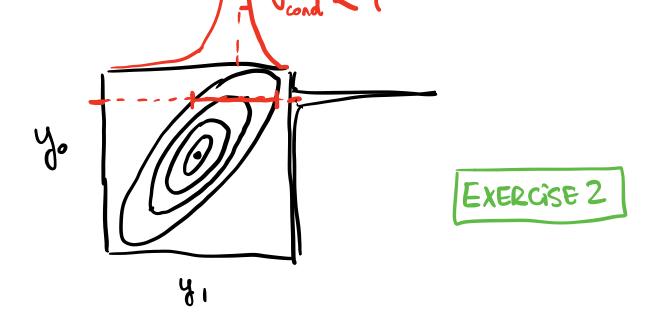
Sometimes
$$\sum_{i=1}^{n} \int_{-\frac{1}{2}}^{2} \left(\frac{y_{0} - \mu_{0}}{V_{0}}\right)^{2} \\
\times \frac{1}{\sqrt{2\pi V_{1}^{2}}} e^{-\frac{1}{2}\left(\frac{y_{0} - \mu_{0}}{V_{0}}\right)^{2}} \\
\times \frac{1}{\sqrt{2\pi V_{1}^{2}}} e^{-\frac{1}{2}\left(\frac{y_{0} - \mu_{0}}{V_{0}}\right)^{2}}$$

$$= \prod_{n=0}^{N-1} \sqrt{2\pi \sigma_n^2} e^{-\frac{1}{2} \sum_{n=0}^{N-1} \left( \frac{y_n - \mu_n}{\sigma_n} \right)}$$

$$= \int_{-\frac{1}{2}}^{N-1} \left( \frac{y_n - \mu_n}{\sigma_n} \right)$$

GENERAL

# marginal COVARIANCE $\Sigma = \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix}$ y. conditional P(g. | yo) y, joint joint 41



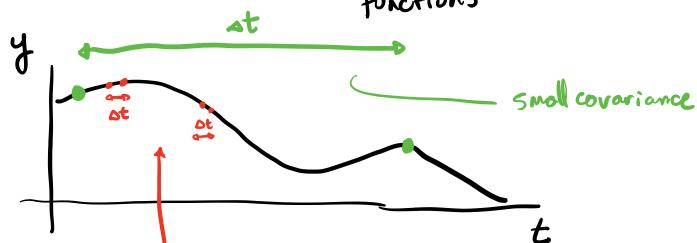
## BACK TO GPS



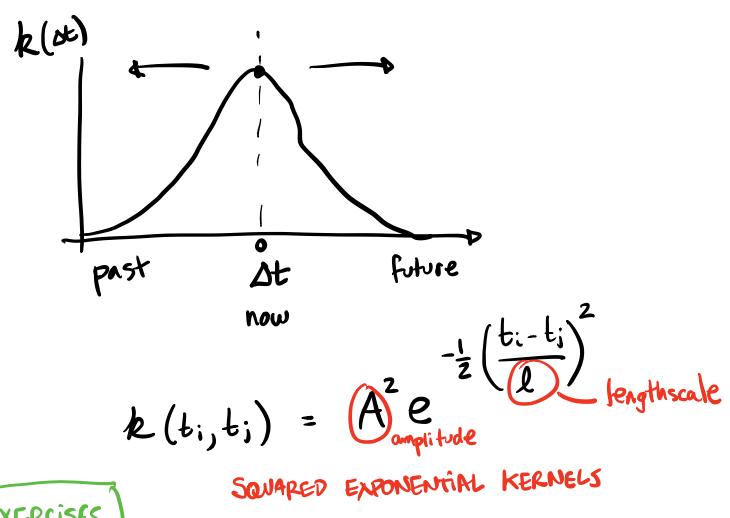
GP = GAUSS DISTR OVER FUNCTIONS

$$y \sim GP(m, k(\cdot,\cdot))$$

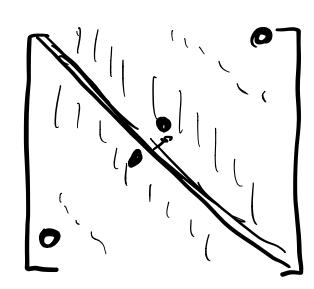
functions



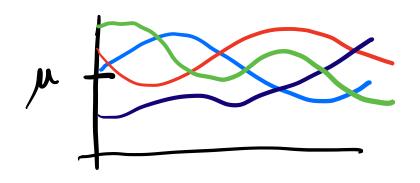
#### large covariance



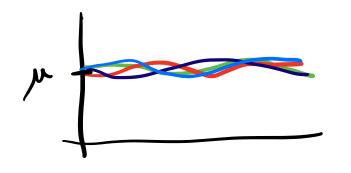
Exercises



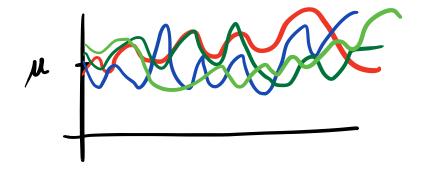
$$y \sim \mathcal{N}(\mu, \sum_{i} (A, \ell))$$



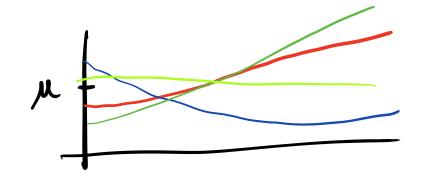
Ao, lo



 $A \ll A_0$   $l = l_0$ 

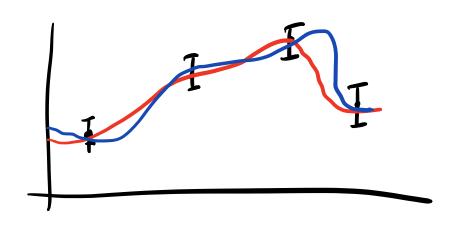


A=A0 L << lo



A=A0 L>>lo

## EXERCISE 5



REJECTION SAMPLING

$$\frac{1}{2}$$
 $\frac{1}{2}$ 
 $\frac{1}{2}$ 

Exercises 6,7,8

$$y_* \sim \mathcal{N}(\mu', \Sigma')$$

$$\mu' = \sum_{t,t} (t,t) \sum_{t} (t,t)^{-1} y$$

$$\Sigma' = \Sigma(t_*,t_*) - \Sigma(t_*,t) \Sigma(t_*,t) \Sigma(t_*,t_*)$$

## TUNING THE GP

# EXERCISE 9

$$P(y|\mu, \Sigma) = \sqrt{(2\pi)^{N} |\Sigma|} P(y|\mu, \lambda, \lambda, \ell)$$

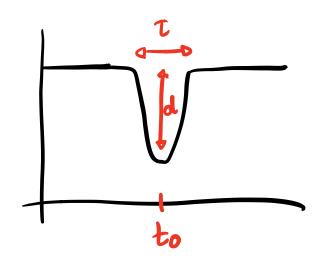
$$P(y|\mu, \lambda, \lambda, \ell)$$

$$P(y|\mu, \lambda, \lambda, \ell)$$

$$P(y|\mu, \lambda, \lambda, \ell)$$

## INFERENCE

#### EXERCISE 10



$$P(y \mid d, T, to, A, l)$$
model
parameters
parameters
$$= \frac{1}{2\pi^{N}|\Sigma|} e$$

$$\Sigma = \Sigma(A,l) + k$$
 $M = \mu(d,t,t_0)$ 

[MCMC]

[emcee]

 $P(d|y)$ 
 $P(t|y)$ 
 $P(t|y)$ 
 $P(t|y)$ 
 $P(t|y)$