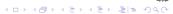
Deterministic Integration of Hard and Soft Real-Time Communication over Shared-Ethernet

Paul Regnier George Lima

Distributed Systems Laboratory (LaSiD) - Computer Science Department (DCC) - Pos-Graduation Program on Mechatronics

8th Brazilian Workshop of Real-Time Systems - WTR 2006





Outline

Motivation

Problem Formulation Ethernet protocols and Real Time

2 DoRiS Protocol Hybrid systems DoRiS





Outline

1 Motivation
Problem Formulation
Ethernet protocols and Real Time

2 DoRiS Protocol Hybrid systems DoRiS





Elements

Assumed Distributed System

A set of nodes but only one communication bus (Ethernet)

Goals

Timeliness and Reliability of communication services

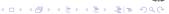
Local Resources

Carrier Sense ability, Clocks and Processing capacities

Constraints

No shared-memory, no centralized mechanism.





The solution: Protocols

Set of rules

Organizes the MAC utilization

Shared knowledge

- ► MAC layer state ∈ {idle, busy, jam}
- Message information (piggybacked)
- ► Timing information (synchronization)





The solution: Protocols

Set of rules

Organizes the MAC utilization

Shared knowledge

- ► MAC layer state ∈ {idle, busy, jam}
- Message information (piggybacked)
- ▶ Timing information (synchronization)





Outline

1 Motivation
Problem Formulation
Ethernet protocols and Real Time

2 DoRiS Protocol Hybrid systems DoRiS





CSMA/CD

Carrier Sense Multiple Access with Collision Detection

Mechanisms

- Carrier Sense ⇒ State Detection
- Jam ⇒ Collision Detection
- ⇒ Shared Knowledge ≜ MAC state ∈ {idle, busy, jam}





CSMA/CD

Carrier Sense Multiple Access with Collision Detection

Mechanisms

- Carrier Sense ⇒ State Detection
- Jam ⇒ Collision Detection

 \Rightarrow Shared Knowledge \triangleq MAC state \in {idle, busy, jam}

Protocol Outline

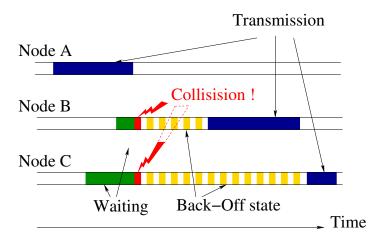
Node:

IF MAC = idle THEN transmit immediately
IF MAC = busy THEN wait next EOF interrupt
and transmit immediately
IF MAC = jam THEN enter in Back-Off state
for an aleatory time





Waiting ⇒ Synchronization ⇒ Collision





Hardware modification

 Priority Reservation by Interruption, modification of Jam message...

Switch Ethernet

- Utilization of point-to-point communication channel
- Time delays in the switchs, Possible message loss Broadcast communication less efficient

Master / Slave (FTT)

- The master allocates bandwidth to the slaves using triggering messages
- Centralized solution, message overhead





Hardware modification

 Priority Reservation by Interruption, modification of Jam message...

Switch Ethernet

- Utilization of point-to-point communication channel
- Time delays in the switchs, Possible message loss, Broadcast communication less efficient

Master / Slave (FTT)

- The master allocates bandwidth to the slaves using triggering messages
- Centralized solution, message overhead





Hardware modification

 Priority Reservation by Interruption, modification of Jam message...

Switch Ethernet

- Utilization of point-to-point communication channel
- Time delays in the switchs, Possible message loss, Broadcast communication less efficient

Master / Slave (FTT)

- The master allocates bandwidth to the slaves using triggering messages
- · Centralized solution, message overhead





TDMA Time Division Multiple Access

- For each communication period, each nodes has a slot time to transmit
- Synchronization of local clocks, waste of the bandwidth

Token Ring

- An explicit token rotates between the nodes, allowing the nodes transmission (scheduling possibilities)
- Token overhead, token loss, significant variability between best case and worst case



TDMA Time Division Multiple Access

- For each communication period, each nodes has a slot time to transmit
- Synchronization of local clocks, waste of the bandwidth

Token Ring

- An explicit token rotates between the nodes, allowing the nodes transmission (scheduling possibilities)
- Token overhead, token loss, significant variability between best case and worst case



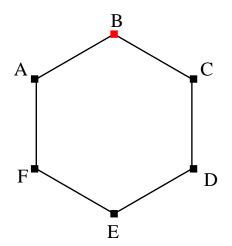


TDMA Approach

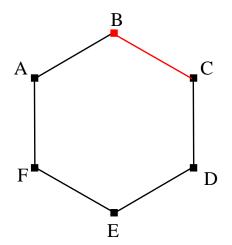
□ : Slot Time A B C D E F Time



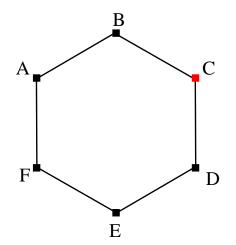
Token Ring Approach



Token Ring Approach



Token Ring Approach



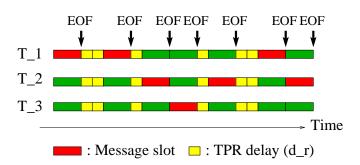
Virtual Token Ring

- An implicit token rotates between the nodes, allowing the nodes transmission according to temporal rules
- No token overhead and token loss, significant variability between best case and worst case





TPR Mechanism





Outline

Motivation
 Problem Formulation
 Ethernet protocols and Real Time

2 DoRiS Protocol Hybrid systems DoRiS



Hard Real Time

Controlled jitter and bounded message transmission time

Soft Real Time

Firm deadline, High throughput, Non-periodic tasks

Specialities

- Integration of Hard and Soft communications
- Deterministic service for real-time applications
- Flexible service for soft communication





Hard Real Time

Controlled jitter and bounded message transmission time

Soft Real Time

Firm deadline, High throughput, Non-periodic tasks

Specialities

- Integration of Hard and Soft communications
- Deterministic service for real-time applications
- Flexible service for soft communication





Hard Real Time

Controlled jitter and bounded message transmission time

Soft Real Time

Firm deadline, High throughput, Non-periodic tasks

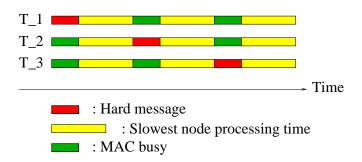
Specialities

- Integration of Hard and Soft communications
- Deterministic service for real-time applications
- Flexible service for soft communication





The Processing Time Delay







Constraints

- Isolation of Hard and Soft communication
- Hard message processing delays (slow nodes)
- High throughput for soft communication

Elements of Solutions

- TDMA
- Interleaving of Hard and Soft messages
- Virtual Token Scheme for Soft communication





Constraints

- Isolation of Hard and Soft communication
- Hard message processing delays (slow nodes)
- High throughput for soft communication

Elements of Solutions

- TDMA
- Interleaving of Hard and Soft messages
- Virtual Token Scheme for Soft communication





Outline

Motivation
 Problem Formulation
 Ethernet protocols and Real Time

2 DoRiS Protocol Hybrid systems DoRiS



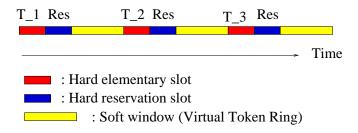
Computation Model

- Ring of tasks: $R^H = \{T_1, T_2, ..., T_{N_H}\}$
- Ring of processes: $R^S = \{P_1, P_2, \dots, P_{N_S}\}$
- Size of hard message = 64B
- π : maximum processing time of hard messages
- Publish-Subscribe communication model





DoRiS: The Double Ring Structure

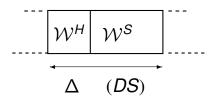






The Hard Real-Time Ring R^H

- DoRiS Segments (DS_k for $k \in \mathbb{N}^*$) of size Δ
- Hard Window \mathcal{W}_k^H
- Soft Window \mathcal{W}_k^S

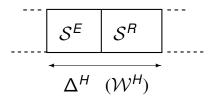






The Hard Real-Time Ring R^H

- Each Hard Window W_k^H is divided in two slots
- Elementary Slot S_k^E
- Reservation Slot S_k^R
- The slot size is δ (transmission time of 64B)







Fundamental property

 Elementary Messages are mandatory: Each task sent one elementary message per DoRiS rotating sequence (RS)





Fundamental property

 Elementary Messages are mandatory: Each task sent one elementary message per DoRiS rotating sequence (RS)

Consequences

- Pulse Decentralization
- Periodicity ⇒ Determinism
- Local clocks synchronization ⇒ Reliability

Other properties

Reservation mechanism ⇒ Flexibility



Fundamental property

• Elementary Messages are mandatory: Each task sent one elementary message per *DoRiS* rotating sequence (*RS*)

Consequences

- Pulse Decentralization
- Periodicity ⇒ Determinism
- Local clocks synchronization ⇒ Reliability

Other properties

Reservation mechanism ⇒ Flexibility





- A Soft Window \mathcal{W}_k^S implements temporal rules using local timers
- A virtual token rotates between processes according to temporal rules
- Elementary messages serve as pulses
- Time Packet Release Mechanism of parameter d_r
- STOP mechanism ⇒ Fairness
- The maximum soft message size is 1518B





- A Soft Window \mathcal{W}_k^S implements temporal rules using local timers
- A virtual token rotates between processes according to temporal rules
- Elementary messages serve as pulses
- Time Packet Release Mechanism of parameter d_r
- STOP mechanism ⇒ Fairness
- The maximum soft message size is 1518B





- A Soft Window \mathcal{W}_k^S implements temporal rules using local timers
- A virtual token rotates between processes according to temporal rules
- Elementary messages serve as pulses
- Time Packet Release Mechanism of parameter d_r
- STOP mechanism ⇒ Fairness
- The maximum soft message size is 1518B





- A Soft Window \mathcal{W}_k^S implements temporal rules using local timers
- A virtual token rotates between processes according to temporal rules
- Elementary messages serve as pulses
- Time Packet Release Mechanism of parameter d_r
- STOP mechanism ⇒ Fairness
- The maximum soft message size is 1518B





- A Soft Window \mathcal{W}_k^S implements temporal rules using local timers
- A virtual token rotates between processes according to temporal rules
- Elementary messages serve as pulses
- Time Packet Release Mechanism of parameter d_r
- STOP mechanism ⇒ Fairness
- The maximum soft message size is 1518B

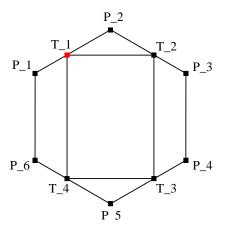




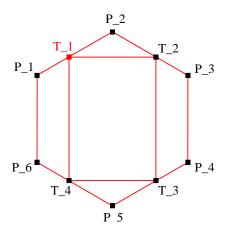
- A Soft Window \mathcal{W}_k^S implements temporal rules using local timers
- A virtual token rotates between processes according to temporal rules
- Elementary messages serve as pulses
- Time Packet Release Mechanism of parameter d_r
- STOP mechanism ⇒ Fairness
- The maximum soft message size is 1518B



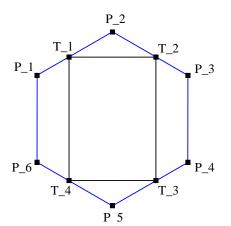




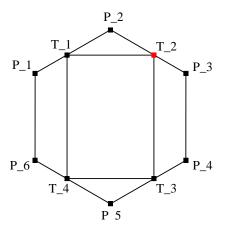






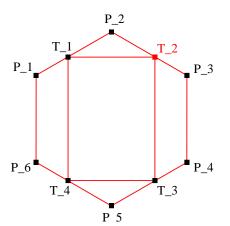




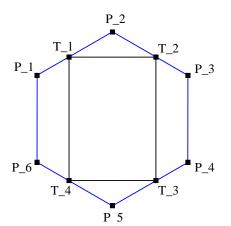




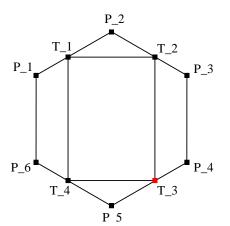














Reservation Mechanism

- An Elementary Message carry a reservation list
- A task can only reserve free slots of the next DoRiS rotating sequence
- · There is always at least one free slot

Fault Tolerance Mechanism

 A task can only reserve if it received all elementary messages sent in the previous DoRiS rotating sequence





Reservation Mechanism

- An Elementary Message carry a reservation list
- A task can only reserve free slots of the next DoRiS rotating sequence
- There is always at least one free slot

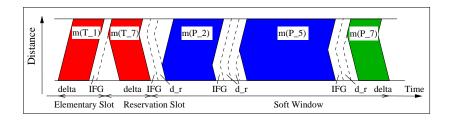
Fault Tolerance Mechanism

 A task can only reserve if it received all elementary messages sent in the previous DoRiS rotating sequence





A DoRiS segment







Summary

- The CSMA/CD protocol over Shared-Ethernet is not deterministic .
- The DoRiS protocol mixed TDMA and Virtual Token approaches to turn Shared-Ethernet Deterministic, providing high throughput for soft task.

- Future works
 - Membership control, dynamic reconfiguration
 - Formal specification with TLA+





For Further Reading I

- J.-D. Decotignie
 Ethernet-based real-time and industrial communications

 Proc. IEEE (Special issue on industrial communication systems), 93(6):1102-1117, 2005
- D. Pritty and J. Malone ans J. Smeed and D. Banerjee and N. Lawrie
 A realtime upgrade for Ethernet based factory networking Int. Conf. Industrial Electronics (IECON), 1995
- F. B. Carreiro, J. A. Fonseca and P. Pedreiras Virtual Token-Passing Ethernet - VTPE Proc. FeT2003 5th IFAC Int. Conf. on Fieldbus Systems and their Applications, 2003



