

② 角速度のベクトル  $\vec{v} = (r\omega e, r\sin\theta \vec{e})$ ,  $\vec{r} = (-r\sin\theta \cdot \vec{e}, r\cos\theta \cdot \vec{e})$   
 $\downarrow$   
 点  $r$  の位置で回転した

$$dK_e = \frac{1}{2} dm (\vec{v})^2 = \frac{1}{2} \underbrace{dm}_{\frac{m}{L} dr} \cdot \underbrace{\|\vec{v}\|^2}_{r^2 \dot{\theta}^2} = \frac{1}{2} \frac{m}{L} (r \dot{\theta})^2 dr$$

質量要素の長さ

$$K_e = \int_V dK_e = \int_0^L dr \frac{1}{2} \frac{m}{L} r^2 \dot{\theta}^2 = \frac{m}{6} L^2 \dot{\theta}^2$$

$$\frac{d}{dt} \left( R \frac{d\theta}{dt} \right) - \frac{1}{2} a^2 \omega(t) B_1 \sin \omega_1 t = 0 \quad \therefore \frac{d}{dt} \left( \frac{1}{2} a^2 \omega(t) \right) B_1 \sin \omega_1 t = 0$$

$$0 = \frac{1}{2} C a^2 \omega B_1 \sin \omega_1 t$$

$$\left( \frac{1}{2} \lambda a^3 \right) \ddot{\omega} = - \frac{1}{4} C a^2 \cdot \left( \ddot{\omega} B_1 \sin \omega_1 t + \omega \cdot \omega_1 \cdot B_1 \cos \omega_1 t \right) B_1 \sin \omega_1 t a^2$$

$$\downarrow$$

$$\frac{\ddot{\omega}}{\omega} = - \frac{\left( \frac{1}{2} \lambda a^3 + \frac{1}{4} B_1 C a^4 \sin^2 \omega_1 t \right)}{\frac{1}{2} \lambda a^3} = - \frac{\omega B_1^2 C a^2 \sin \omega_1 t \cos \omega_1 t}{\frac{1}{2} \lambda a^3}$$

$$Q(\omega)' = - \frac{1}{2} (L_H A)'$$

$$0 = \left( Q_H \omega + \frac{1}{2} Q_H A \right)' = \left\{ Q_H (\omega \cdot \sqrt{F})' \right\},$$

$$\omega \sqrt{F}|_{t=0} = \omega_0 \int \frac{1}{2} \lambda a^3$$

$$\omega = \omega_0 \cdot \frac{\sqrt{\frac{1}{2} \lambda a^3}}{\sqrt{F}} = \omega_0 \int \frac{1}{1 + \frac{3 B_1^2 C a^2 \sin^2 \omega_1 t}{2 \lambda}}$$

