

[1.]

[1.1]. 机械能守恒的力. $mgR = mgR \cos \theta + \frac{1}{2}mv^2 \quad \therefore v = \sqrt{2gR(1 - \cos \theta)}$

[1.2]. 圆周运动. $\Sigma F = 0$.

$$\begin{aligned} m \frac{v^2}{R} + N &= mg \cos \theta \quad \therefore N = mg \cos \theta - m \frac{v^2}{R} \\ &= mg \cos \theta - m \frac{1}{R} (2gR(1 - \cos \theta)) \\ &= 3mg \cos \theta - 2mg = 0 \quad \text{at } \theta = \frac{2}{3}\pi \end{aligned}$$

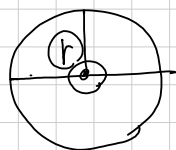
$$\therefore \cos \theta_{cr} = \frac{2}{3}$$

$$\boxed{\cos \theta = \frac{2}{3}}$$

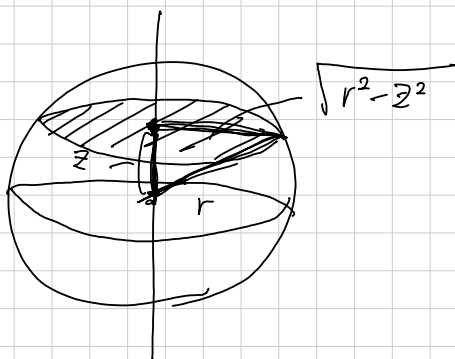
$$v_{cr} = \sqrt{2gR(1 - \frac{2}{3})} = \sqrt{\frac{2}{3}gR}$$

[2.]

[2.1]



$$Z = \int dm x^2 = \int_{-r}^r \left(\frac{m}{\frac{4}{3}\pi r^3} \times dV \right) \int_{-r}^r (r^2 - z^2) dV$$



$$\int_0^\pi \sin \theta d\theta = [-\cos \theta]_0^\pi = -(-1) - (-1) = 2$$

$$\begin{aligned} &\frac{3m}{4\pi r^3} \times 2\pi \times 2 \times \frac{1}{4} \int_0^r (r^4 - 2r^2 z^2 + z^4) dz \\ &= \frac{3m}{4\pi r^3} \times \frac{1}{4} \times \left[r^5 - \frac{2}{3} r^5 + \frac{1}{5} r^5 \right] \\ &= \frac{15 - 10 + 3}{15} \\ &= \frac{8}{15} \end{aligned}$$

$$\frac{8m}{r^3} \times \frac{1}{4} \times \frac{2}{15} =$$

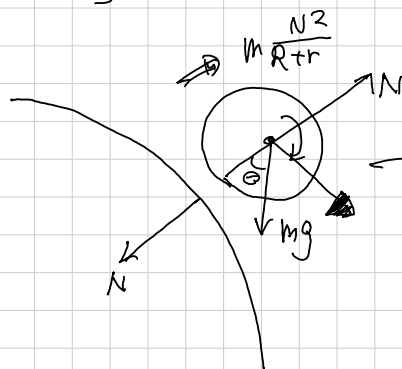
[2.2]

→ 12 (12" 係) 則

$$mg(R+r) = mg(R+r)\cos\theta + \underbrace{\frac{1}{2}m\omega^2}_{\text{軸の回転}} + \underbrace{\frac{1}{2}mV^2}_r$$

[2.3]

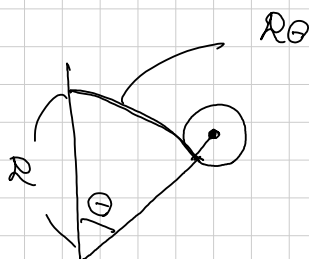
④



→ 20 N 回転に 20 N が必要なの??

→ 20 N 回転に 20 N が必要なの??

$mg < N$ 2. 回転に 20 N が必要なの??



S. S. 3500

$$\frac{L}{(1000g)}$$

相乗条件の復習

N 個の質点の系が P 個の相乗条件: $f^\mu(x_1, x_2, \dots, x_N, t) = 0$ かつ

↓

($\mu = 1, 2, \dots, P$)

拘束力: $T^\mu = \lambda_\mu \nabla f^\mu(x, t)$ で表わす

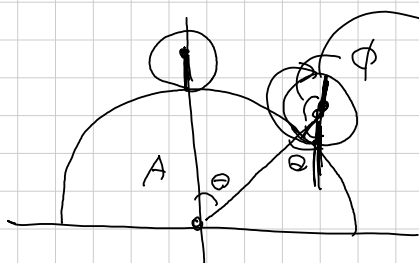
↓
Lagrangian eq: $\frac{d}{dt}\left(\frac{\partial T}{\partial \dot{x}^\alpha}\right) + \frac{\partial U}{\partial x^\alpha} - \lambda_\mu \frac{\partial f^\mu}{\partial x^\alpha} = 0$ ($\alpha = 1, 2, \dots, N$)

↓ かつ、本質的に Lagrangian

$$\Sigma = L - U = L(x, \dot{x}) + \lambda_\mu f^\mu(x, t)$$

→ 可変 f 及び P, 1. 1. $r = A + a \alpha$ とき $f(r) = r - (A + a) = 0$

→ 接点から少しずらしたときの条件:



基準点と (3.11) の関係?

$$A\theta = a(\phi - \theta) \quad \therefore (A+a)\dot{\theta} = a\dot{\phi}$$

$$L^0 = \underbrace{\frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2)}_{\text{重心の運動eq}} + \underbrace{\frac{1}{2} \cdot I \omega^2}_{\substack{\text{回転の運動eq} \\ \downarrow \\ \frac{1}{2} \cdot \frac{1}{2} m a^2 \cdot \dot{\phi}^2}} \Rightarrow \boxed{\frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2) + \frac{1}{4} m a^2 \dot{\phi}^2}$$

$$-m g r \sin \theta$$

$$\mathcal{E}[L^0] = \lambda_1 \frac{\partial L}{\partial r}$$

$$\mathcal{Q}[L^0] = \lambda_2 \frac{\partial L}{\partial \theta}$$

$$= \lambda_2 (A+a)$$

$$\therefore \frac{d}{dt} (m r^2 \dot{\theta}) - m g r \sin \theta = (A+a) \lambda_2$$

$$\mathcal{Q}[L^0] = \lambda_2 (-a) \quad \therefore \frac{m}{2} a^2 \ddot{\phi} = -a \lambda_2$$

$$f(r) = r - (A+a) = 0$$

$$df_1 = dr = 0, \quad df_2 = (A+a) d\theta - a d\phi = 0$$

Li 法を書く

$$\dot{r} = 0, \dot{\theta} = 0, \quad a \ddot{\phi} = (a+A) \ddot{\theta}$$

$$2m \cancel{r} \dot{\theta} + m r^2 \ddot{\theta} - m g r \sin \theta = (A+a) \lambda_2$$

$$\frac{m}{2} a^2 \left(\frac{a+A}{a} \right) \ddot{\theta} = -a \lambda_2$$

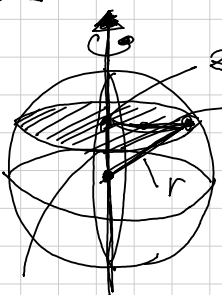
$$\lambda_2 = -\frac{m}{2} (a+A) \ddot{\theta}$$

$$\ddot{\theta} m r^2 + (A+a) \cdot \frac{m}{2} (a+A) \ddot{\theta} - m g r \sin \theta = 0$$

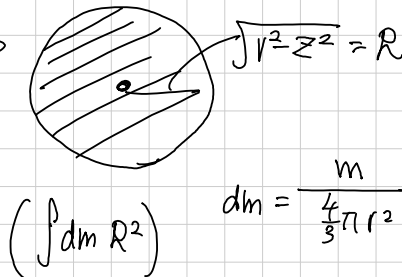
$$\boxed{\frac{3}{2} m (A+a) \ddot{\theta} - m g \sin \theta = 0}$$

$$\Rightarrow T_r = \lambda_1 \frac{\partial L}{\partial r} \text{ 等 } \ddot{\theta} \neq 0$$

[2]



$$\sqrt{r^2 - z^2}$$



$$dm = \frac{m}{\frac{4}{3}\pi r^2} dV$$

$$I = \left(\int \cancel{r^2} (dV) \right) \cdot \frac{3m}{4\pi r^2}$$

$$0 \leq r' \leq \sqrt{r^2 - z^2}$$

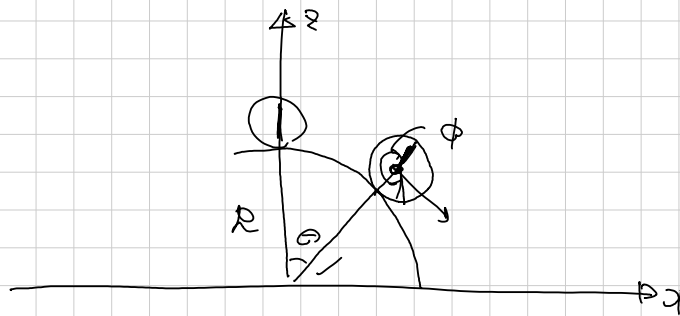
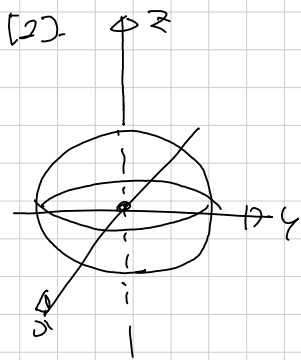
$$\frac{1}{2} \cdot \frac{3m}{2r^2} \int_0^r (r^4 - 2r^2 z^2 + z^4) dz$$

$$\left(r^4 - \frac{2}{3} r^4 + \frac{1}{5} r^4 \right)$$

$$\frac{15-2+1}{15} = \frac{14}{15} r^4 \times \frac{3m}{2r^2}$$

$$= \left(\int_0^{\sqrt{r^2 - z^2}} r'^3 dr' \right) \cdot 2\pi \cdot \frac{3m}{4\pi r^2}$$

$$= 2 \int_0^r \frac{1}{4} \cdot (r^2 - z^2)^2 dz = \frac{3m}{2r^2}$$



$$\therefore R\theta = r(\phi - \theta)$$

$$R\dot{\theta} = r(\dot{\phi} - \dot{\theta})$$

$$\omega = \dot{\phi}, (R+r)v = \dot{\theta}$$

$$(R+r)\dot{\theta} = r\omega \quad \therefore \boxed{(R+r)^2 v = r\omega}$$

[2.3], 有约束条件

$$f(r') = r' - (r+R) = 0, \quad f_{\theta, \phi}(\theta, \phi) = (R+r)\theta - r\phi = 0$$

$$L_0 = \frac{1}{2}m \left(\dot{r}'^2 \sin^2 \theta + \dot{r}'^2 \cos^2 \theta \right)$$

$$+ \left(\dot{r}' \sin \theta + r' \cos \theta \cdot \dot{\theta}, \dot{r}' \cos \theta - r' \sin \theta \cdot \dot{\theta} \right)^2$$

$$\boxed{\frac{1}{2}m(\dot{r}'^2 + r'^2 \dot{\theta}^2) + \frac{1}{2} \left(\frac{2}{5}mr^2 \right) \cdot \dot{\phi}^2 - mgr' \cos \theta}$$

$$\mathcal{E}[L_0]_r = \underbrace{m\ddot{r}'}_0 - (mr'\dot{\theta}^2 - mgr' \cos \theta) = \lambda_1$$

$$\mathcal{E}[L_0]_{\theta} = mr'^2 \cdot \ddot{\theta} - mgr' \sin \theta = \lambda_2 (R+r)$$

$$\mathcal{E}[L_0]_{\phi} = \frac{2}{5}mr^2 \dot{\phi} = \lambda_2 (-r)$$

$$\therefore \lambda_2 = -\frac{mr}{5} \dot{\phi} = -\frac{m}{5} \cdot (R+r) \dot{\theta}$$

$$(R+r)\dot{\theta} = r\dot{\phi}$$

$$mr'^2 \ddot{\theta} - mgr' \sin \theta = -\frac{m}{5} (R+r)^2 \dot{\theta}$$

$$\downarrow \text{约束条件 } R+r = r'$$

$$\frac{6}{5}mr'\ddot{\theta} - mgr' \sin \theta = 0$$

$$\downarrow$$

$$\frac{6}{5}mr' \ddot{\theta} - \dot{\theta} mgr' \sin \theta = 0 \Rightarrow$$

$$\frac{3}{5}mr'\ddot{\theta}^2 + mgr' \cos \theta = 0$$

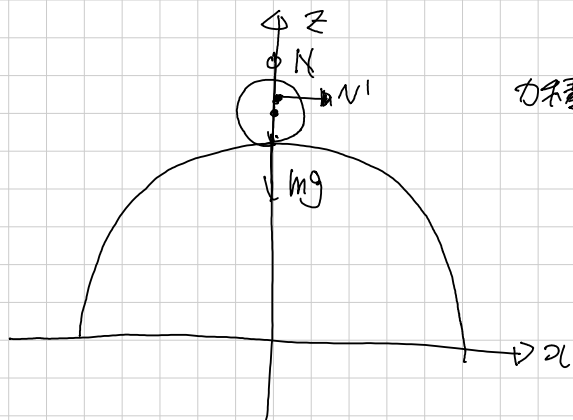
$$\therefore -mr' \cdot \frac{5}{3r'} g(1 - \cos \theta) + mgr' \cos \theta = \lambda_1$$

$$= \frac{5}{3}mg(\cos \theta) - \frac{2}{3}mg$$

$$\therefore \cos \theta = \frac{5}{5} - \frac{2}{3} = \frac{3}{5}$$

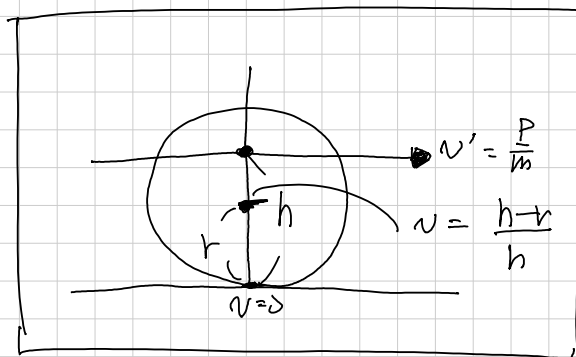
$$\therefore \dot{\theta}^2 = \frac{5}{3r'} g(1 - \cos \theta)$$

$$= \frac{5}{3}g \cdot \frac{2}{3} = \frac{10}{9}g$$

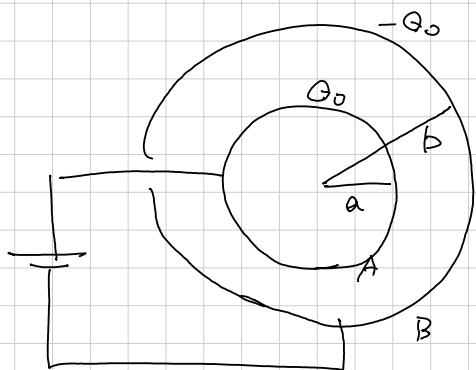


力平衡: $0 + P = mv'$

[3]??



[装2問]



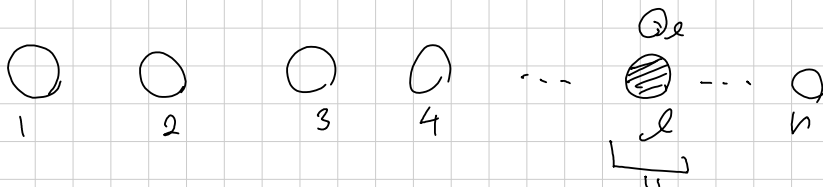
[1.1]

ϵ_0

PAE: Greenの相互定理

<復習>

n個の帯電体が存在する。

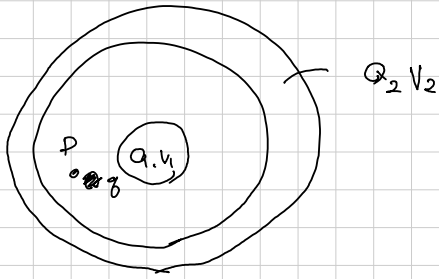


各帯電体の電位は、

$$\begin{aligned} V_1 &= p_{11}Q_1 + p_{12}Q_2 + \dots + p_{1n}Q_n \\ V_2 &= p_{21}Q_1 + p_{22}Q_2 + \dots + p_{2n}Q_n \\ &\vdots \\ V_n &= p_{n1}Q_1 + p_{n2}Q_2 + \dots + p_{nn}Q_n \end{aligned}$$

$$\begin{bmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_n \end{bmatrix} = \underbrace{\begin{bmatrix} p_{11} & p_{12} & \dots & p_{1n} \\ p_{21} & p_{22} & \dots & p_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ p_{n1} & p_{n2} & \dots & p_{nn} \end{bmatrix}}_{\text{係数行列}} \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_n \end{bmatrix}$$

[4]



両導体の電位を V_1, V_2 にした時の電荷を Q_1, Q_2 ,
それらの電位を g_{11}, g_{12} とする

$$V_1 \cdot g_{11} + V_2 \cdot g_{12} + V' \cdot g = 0 \cdot Q_1 + 0 \cdot Q_2 + V' \cdot Q = 0$$

相互定理より, $\sum V_k^{(1)} Q_k^{(2)} = \sum V_k^{(2)} Q_k^{(1)}$

仮に電荷がゼロに等しいとすると, $g_{11} + g_{12} + g = 0$

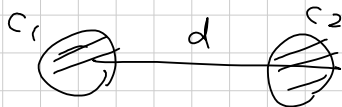
$$\begin{pmatrix} V_1 = p_{11} Q_1 + p_{12} Q_2, & V_2 = p_{21} Q_1 + p_{22} Q_2, & Q_1 + Q_2 = Q \end{pmatrix}$$

またこの時の静電容量が C_1, C_2 であるとする。 $g_{11} = C_1, g_{22} = C_2$

[8.1]

$$Q_1 = C_1 V_1 + \beta V_2, Q_2 = \beta V_1 + C_2 V_2 \quad Q_1 = (C_1 + \beta) V, Q_2 = (\beta + C_2) V$$

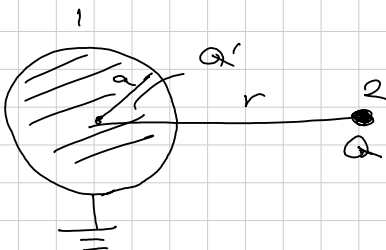
$$Q = Q_1 + Q_2 \therefore C = \frac{Q}{V} = C_1 + C_2 + 2\beta$$



$$g_{11} = C_1, g_{22} = C_2 \text{ の間 } C_1 \rightarrow Q$$

$$V_2 = \frac{Q}{4\pi\epsilon_0 d}$$

$$V_1 = \frac{Q}{C_1}, V_2 = \frac{Q}{4\pi\epsilon_0 d} \therefore Q_2 = g_{21} V_1 + g_{22} V_2$$



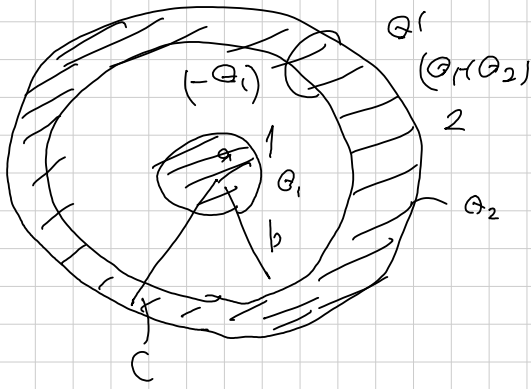
→ 相互定理を用いて、2 点。

$$\begin{pmatrix} 1 \text{ は } 1, 2 \text{ は } 0 \text{ の間} \\ V_1 = \frac{1}{4\pi\epsilon_0 a}, V_2 = \frac{1}{4\pi\epsilon_0 r} \end{pmatrix} \rightarrow \text{結局}$$

$$1 \text{ は } Q_1, 2 \text{ は } Q_2$$

$$V_1 = 0, V_2 = \frac{Q}{4\pi\epsilon_0 r}$$

$$\frac{Q_1}{4\pi\epsilon_0 a} + \frac{Q_2}{4\pi\epsilon_0 r} = 0$$

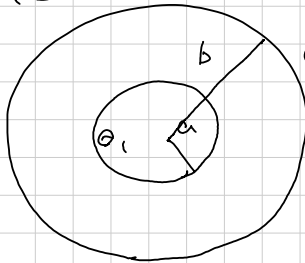


$$0 = Q_1 + Q' \in \text{Gauss}$$

(17)

$$\therefore V_1 = \frac{Q_1}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{b} + \frac{1}{c} \right) + \frac{Q_2}{4\pi\epsilon_0 c}, \quad V_2 = \frac{Q_1}{4\pi\epsilon_0 c} + \frac{Q_2}{4\pi\epsilon_0 c}$$

[16,2]



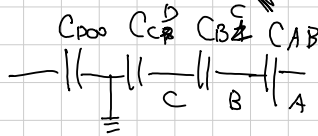
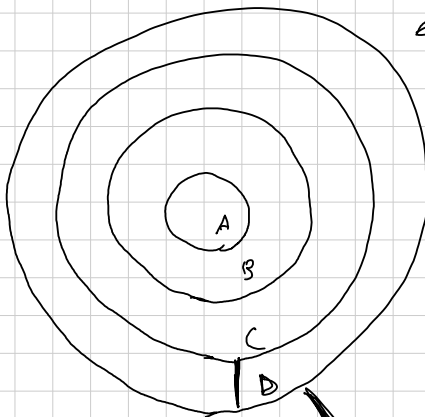
Q_2 → 1030000 450 520 300 600

$$V_1 = \frac{1}{4\pi\epsilon_0} \left(\frac{Q_1}{a} + \frac{Q_2}{b} \right) \quad V_2 = \frac{1}{4\pi\epsilon_0} \left(\frac{Q_1}{b} + \frac{Q_2}{b} \right)$$

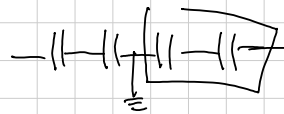
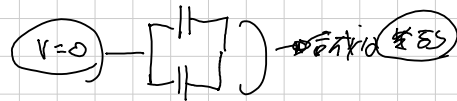
「高電圧量と低電圧」

[33]

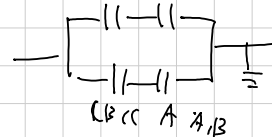
← 静電容量



↓

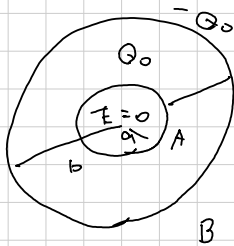


$1, C_{AB}, C_{BC}, C_{CA}$



1問2問

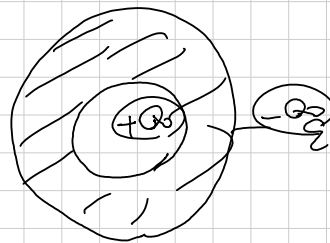
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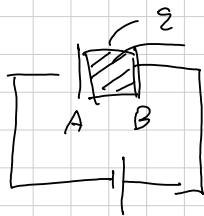
0問3

$$V = \frac{Q_0}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{b} \right) \therefore Q = 4\pi\epsilon_0 V \cdot \frac{ab}{b-a}$$

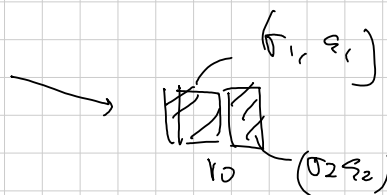
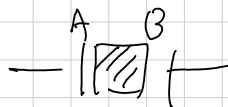
?? $r > b$? $r < a$?



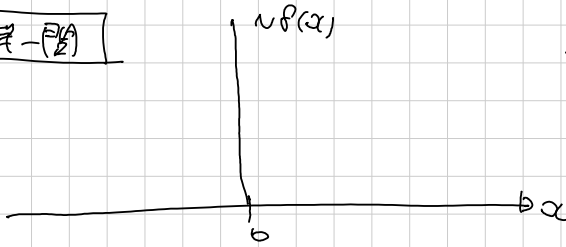
$\rightarrow \epsilon_0 \sim \epsilon(r)$ のこと



\Rightarrow 0.5. 電荷が2つある場合



1問-2問



$$\square \quad -\frac{\hbar^2}{2m} \phi'' = E \phi(x)$$

$$\phi'' = -\frac{2mE}{\hbar^2} \phi(x)$$

$$\phi(x) = A \exp\left(\sqrt{-\frac{2mE}{\hbar^2}} x\right) + B \exp\left(-\sqrt{\frac{2mE}{\hbar^2}} x\right)$$

$x > 0$ のとき

$$\phi(x) = B \exp\left(-\sqrt{\frac{2mE}{\hbar^2}} x\right)$$

$$\therefore \boxed{\xi = \sqrt{\frac{2mE}{\hbar^2}}}$$

$$\int \phi^* \phi dx = |B|^2 \int_0^\infty \exp\left(-2\sqrt{\frac{2mE}{\hbar^2}} x\right) dx$$

$$= 2|B|^2 \cdot \left(+\frac{1}{2} \sqrt{\frac{\hbar^2}{2mE}}\right) = 1$$

$$\therefore \boxed{|B|^2 = \sqrt{\frac{2mE}{\hbar^2}}}$$

電場の強さを求める

$$-\frac{\hbar^2}{2m} (\phi'(x>0) - \phi'(x<0)) = V \phi(0) \quad , \quad \boxed{A=B}$$

\rightarrow 連続性条件

→ 2nd 1st Schrödinger



$$(a+b) \hat{F} (a' + ib') \rightarrow \underbrace{a \hat{F} a'}_{\textcircled{A}} + a \hat{F} b' + \underbrace{b \hat{F} a'}_{\textcircled{B}} + \underbrace{b \hat{F} b'}_{\text{" "}}$$

$|c_1|^2$ $c_1^* c_2$ $c_1^* c_2$ $??$

