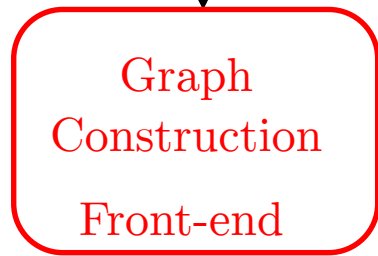
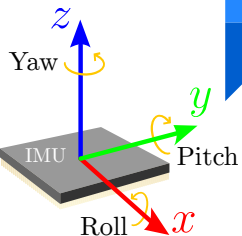
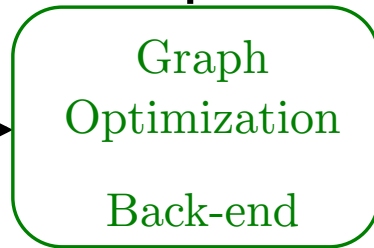


Sensor
data

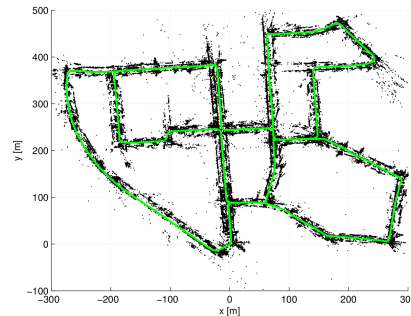


node positions

graph
(nodes & edges)



SLAM
estimate



En esta clase