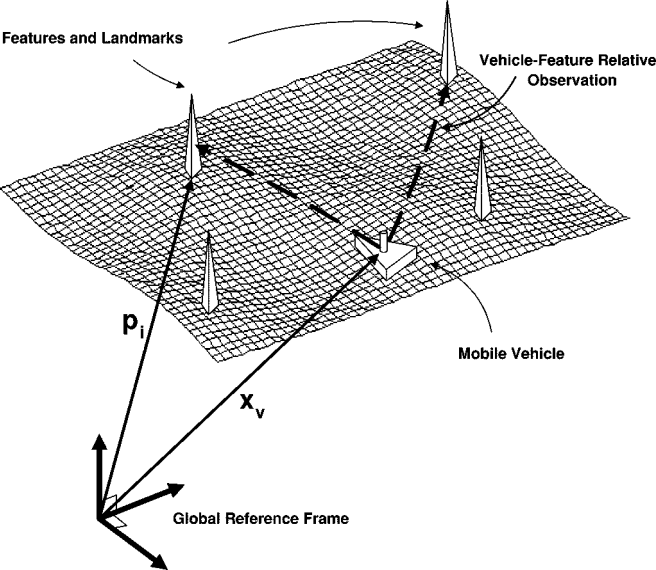


Features and Landmarks



Vehicle-Feature Relative Observation

Mobile Vehicle

p_i

x_v

Global Reference Frame