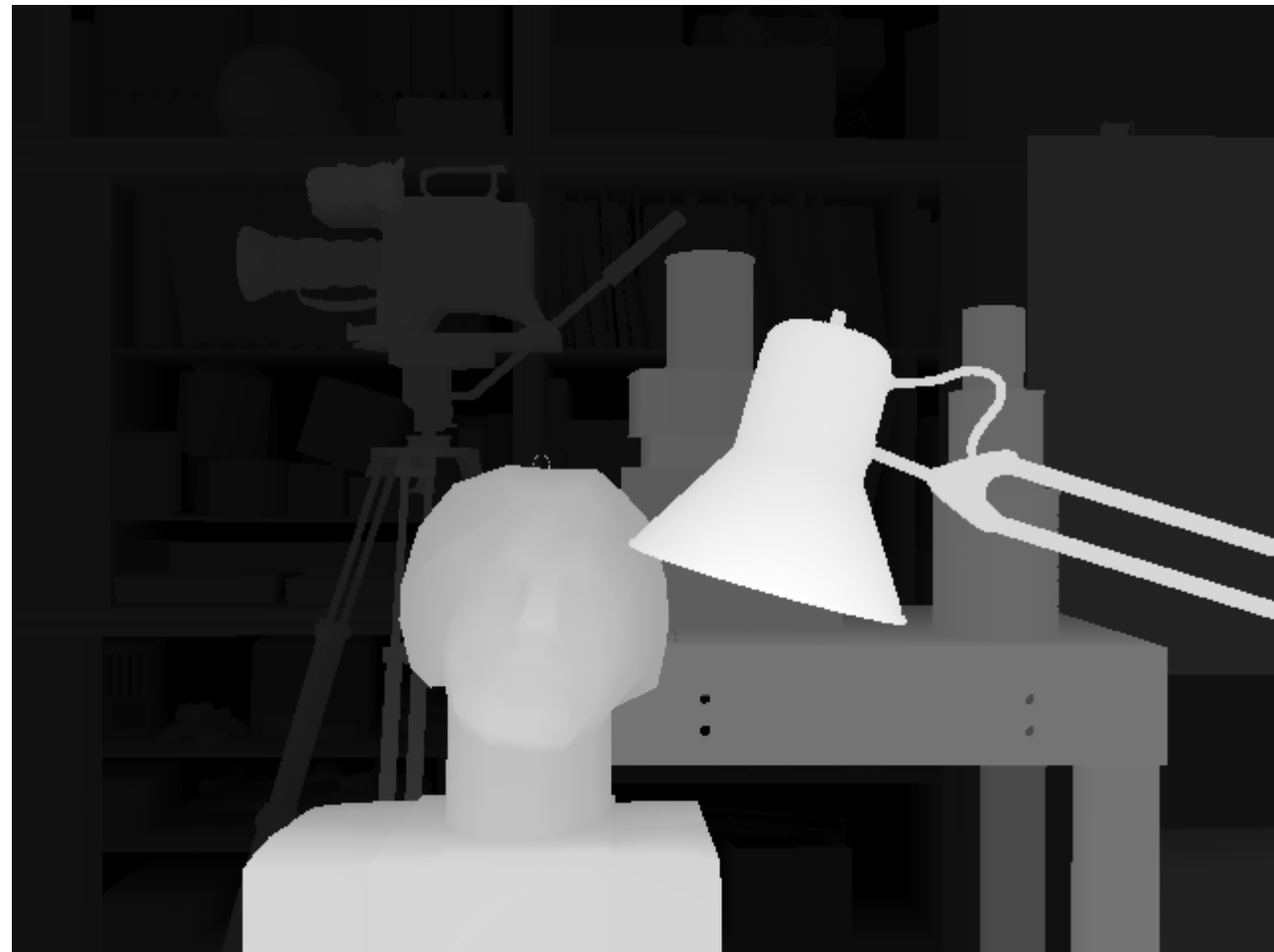




Left/Right Camera Images



Disparity Map (Ground-truth)