Sensor

Pinhole
$$\mathbf{r}_{o} + \delta \mathbf{r}_{o}$$

$$\mathbf{v}_{i} \cdot \delta t$$

Perspective projection:
$$\frac{\mathbf{r}_{i}}{f} = \frac{\mathbf{r}_{o}}{\mathbf{r}_{o} \cdot \mathbf{z}}$$

Image Point Velocity:
$$\mathbf{v}_{i} = \frac{d\mathbf{r}_{i}}{dt} = f \frac{(\mathbf{r}_{o} \cdot \mathbf{z})\mathbf{v}_{o} - (\mathbf{v}_{o} \cdot \mathbf{z})\mathbf{r}_{o}}{(\mathbf{r}_{o} \cdot \mathbf{z})^{2}}$$

$$\mathbf{v}_{i} = f \frac{(\mathbf{r}_{o} \times \mathbf{v}_{o}) \times \mathbf{z}}{(\mathbf{r}_{o} \cdot \mathbf{z})^{2}}$$