

DMA 12g

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January 16, 2017

Part 1

(a)

We need to show that given a path e_n with $0 \leq n < k$, we can rewrite $-\log(\prod_{0 \leq n < k} w(e_n)) = \sum_{0 \leq n < k} -\log(w(e_n))$.

We will do this by induction on k .

When $k = 0$, we have:

$$\begin{aligned} -\log(\prod_{n \in \emptyset} w(e_n)) &= -\log(1) \\ &= 0 \\ &= \sum_{n \in \emptyset} -\log(w(e_n)) \end{aligned}$$

When $k = j + 1$, we have:

$$\begin{aligned} -\log(\prod_{0 \leq n < j+1} w(e_n)) &= -\log(w(e_j) \cdot \prod_{0 \leq n < j} w(e_n)) \\ &= -\log(w(e_j)) - \log(\prod_{0 \leq n < j} w(e_n)) \\ &= -\log(w(e_j)) + \sum_{0 \leq n < j} -\log(w(e_n)) \\ &= \sum_{0 \leq n < k} -\log(w(e_n)) \end{aligned}$$

(b)

To find the most probable path, we wish to maximize $\prod_{0 \leq n < k} w(e_n)$. This is equivalent to minimizing $-\log \prod_{0 \leq n < k} w(e_n)$, which we have just shown is the same as $\sum_{0 \leq n < k} -\log(w(e_n))$. This is equivalent to finding the shortest path with a weight function $w'(e) = -\log(w(e))$. We use Dijkstra's algorithm for this:

pathfind.fsx

1 | type Graph = {

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2      size : int;
3      edges : Set<int * int>;
4      weight : (int * int -> float)
5  }
6
7  type Search = float * int
8
9  let setToMap n s =
10    [0 .. n] |> List.map (fun k ->
11      (k, s |> Set.filter (fun (a, _) -> a = k) |> Set.map snd)
12    ) |> Map.ofList
13
14  let pathfind (g : Graph) (a : int) (b : int) =
15    let neighbours = setToMap g.size g.edges
16    let mutable queue = Set.ofList[(0.0, a)]
17    let dists = Array.init g.size (fun _ -> infinity)
18    while not queue.IsEmpty do
19      let (dist, node) = queue.MinimumElement
20      queue <- queue.Remove (dist, node)
21      if dists.[node] > dist then
22        dists.[node] <- dist
23        for neighbour in Set.toSeq neighbours.[node] do
24          let cost = - log(g.weight(node, neighbour))
25          queue <- queue.Add (dist + cost, neighbour)
26    if dists.[b] = infinity then
27      None
28    else
29      let reversed =
30        g.edges |> Set.map (fun (x, y) -> (y, x)) |> setToMap g.size
31      let mutable path = [b]
32      while path.Head <> a do
33        let neighs = reversed.[path.Head] |> Set.toList
34        let prev = neighs |> List.minBy (fun node -> dists.[node])
35        path <- prev :: path
36      Some path

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Part 2

(a)

$\delta_{BFS}(s, v)$ represents the length of the shortest path from s to v , whereas $\delta_{SP}(s, v)$ represents the cost of the lowest-cost path from s to v . However, when $w(e) = 1$, the cost of a path and its length coincides, and as such δ_{BFS} and δ_{SP} will be equal.

(b)

A node is black during BFS if it has been visited. This means that the processing for that node is done.

The set S represents the nodes for which the shortest distance has been determined. Similarly to a node in BFS being black, a node being in S means that the processing for that node is done.

(c)

The loop invariant states that at the start of each iteration of the while loop, $v.d = \delta(s, v)$ for each vertex v . When Dijkstra's algorithm visits a node u , it has already visited all nodes w with a distance $\delta(s, w)$ less than $\delta(s, u)$. This means that any node in V with distance less than $\delta(s, u)$ is already in S , and so the nodes v in $V \setminus S$ must have a distance greater than or equal to that of u from s .