

1 LSH

1.1 Min Hashing

$h_\pi(C) = \min_i \pi(i)$ first row in randomly shuffled column that contains a one.

$P(h(C_1) = h(C_2)) = \text{sim}_J(C_1, C_2)$ Jaccard similarity

Shuffling implemented with hash function $\pi(i) = ai + b \bmod n$

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for each column c do
  for each row r do
    if c has 1 in row r then
      for each hash function  $h_i$  do
         $M(i, c) \leftarrow \min\{h_i(r), M(i, c)\}$ 

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1.2 Hashing Signature Matrix

M partitioned into b bands of r rows. Probability C1,C2 collide on at least one band: $1 - (1 - s^r)^b$

Family of hash functions F is $(d_1, 1, d_2, p_1, p_2)$ sensitive if

$$\forall x, y \in S : d(x, y) \leq d_1 \implies P[h(x) = h(y)] \geq p_1$$

$$\forall x, y \in S : d(x, y) \geq d_2 \implies P[h(x) = h(y)] \leq p_2$$

r-way and: For $h = [h_1, \cdot, h_r]$ $h(x) = h(y) \leftrightarrow h_i(x) = h_i(y)$ F' is (d_1, d_2, p_1^r, p_2^r) sensitive

b-way or: For $h = [h_1, \cdot, h_b]$ $h(x) = h(y) \leftrightarrow h_i(x) = h_i(y)$ for some i F' is $(d_1, d_2, 1 - (1 - p_1)^b, 1 - (1 - p_2)^b)$ sensitive

1.3 Other Distance Functions

Cosine distance: Family of hash functions for uniformly random vector u

$$h_u(x) = \text{sign}(u^T x) \quad P(h_u(x) = h_u(y)) = 1 - \frac{\theta_{x,y}}{\pi}$$

Euclidean distance: Family functions for random line divided into a buckets. If distance $d = \|x - y\|_2 \gg a$, $h(x) = h(y)$ with low probability. F forms a $(\frac{a}{2}, 2a, \frac{1}{2}, \frac{1}{3})$ sensitive family.

2 Supervised Learning

2.1 Canonical hyperplanes

$$x' = \bar{x} + \frac{w}{\|w\|} \gamma$$

$$w^T x' + b = w^T \bar{x} + b + \frac{w^T w}{\|w\|} \gamma = 1$$

$$\gamma = 1/\|w\|$$

2.2 Formulations

$$\begin{aligned} \min_{w,b} w^T w \quad & \text{s.t. } y_i(w^T x_i + b) \geq 1 \\ \min_{w,b} w^T w + C \sum_i \xi_i \quad & \text{s.t. } y_i(w^T x_i + b) \geq 1 - \xi_i \\ \min_{w,b} w^T w + C \sum_i \max\{0, 1 - y_i(w^T x_i + b)\} \\ \min_{w,b} \lambda w^T w + \sum_i \max\{0, 1 - y_i(w^T x_i + b)\} \\ \min_{w,b} \sum_i \max\{0, 1 - y_i(w^T x_i + b)\} \quad & \text{s.t. } \|w\| < 1/\lambda \end{aligned}$$

2.3 Online Convex Programming

$$\text{Regret: } R_T = \sum_{t=1}^T l_t - \min_w \sum_{t=1}^T f_t(w)$$

$$\text{OCP Regret: } R_T \leq \frac{\|S\|^2 \sqrt{T}}{2} + (\sqrt{T} - 1/2) \|\nabla f\|^2 \text{ for } \eta_t = 1/\sqrt{t}$$

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If new point violates margin  $y_t(w_t x_t + b) < 1$ 
Update  $w_{t+1} = w_t - \eta_t \nabla f_t(w_t)$ 
Project  $\min\{w, \frac{w}{\|w\|\lambda}\}$ 

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2.4 Modifications

- **SGD:** training samples picked at random.

- **PEGASOS:** uses minibatch of random samples, loss function with $\lambda/T w^T w$ term. Strongly convex loss function for better convergence.

- **PSGD:** randomly partition data to k machines which run SGD independently. After T iterations take weighted sum of obtained weights.

$$w_T = \frac{1}{k} \sum_{i=1}^k w_i. \text{ Parallelization helps if } k = O(1/\lambda) \text{ for some } i$$

- **L1-ball projection:** $\text{Proj}_S(w) = \arg \min_{\|w'\|_1 \leq c} \|w' - w\|_2$ using $w_i = \text{sign}(w_i) \max\{w_i - \beta, 0\}$

- **multi-class:** $l(W, (x, y)) = \max_{r \in k \setminus y} [1 - (Wx)_y + (Wx)_r]_+$

2.5 Feature selection

L1 regularization: replace $\|w\|_2$ with $\|w\|_1$ for sparse solutions.

modified projection: $\bar{w}_i = \text{sign}(w_i) \max\{|w_i| - \beta, 0\}$ where β is computed in linear time.

3 Active Learning

Pick most uncertain points for labeling $x^* = \arg \min_{x_i \in U} |w^T x_i|$

3.1 Hashing a Hyperplane

$$h_{u,v} = [h_u(a), h_v(b)] = [\text{sign}(u^T a), \text{sign}(v^T b)] \quad u, v \sim \mathcal{N}(0, 1)$$

Hash family: $h_{u,v}(z) = \begin{cases} h_{u,v}(z, z) & \text{if } z \text{ is a database point} \\ h_{u,v}(z, -z) & \text{if } z \text{ is a query hyperplane} \end{cases}$

$$\begin{aligned} P(h(w) = h(x)) &= P(h_u(w) = h_u(x)) P(h_v(-w) = h_v(x)) \\ &= \frac{1}{4} - \frac{1}{\pi^2} (\theta - \frac{\pi}{2})^2 \end{aligned}$$

3.2 Generalised binary search (GBS)

$$D = \{(x_1, y_1) \cdots (x_n, y_n)\} \quad \mathcal{V}(D) = \{w : \forall (x, y) \in D \text{ sign}(w^T x) = y\}$$

unlabeled pool: $U = \{x'_1, \dots, x'_n\}$

relevant version space: $\hat{\mathcal{V}}(D, U) = \{h : U \rightarrow \{+1, -1\} : \exists w \in \mathcal{V}(D) \forall x \in U \text{ sign}(w^T x) = h(y)\}$

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start with  $D = \{\}$ 
while  $|\hat{\mathcal{V}}(D, U)| > 1$  do
  for each unlabeled example x in a compute do
     $|\hat{\mathcal{V}}(D \cup \{x^+\}, U)| = w_+$ 
     $|\hat{\mathcal{V}}(D \cup \{x^-\}, U)| = w_-$ 
  pick example where  $|w_- - w_+|$  is smallest
  request label and add to D

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3.3 Version space reduction

max-min margin: $\max |w_- - w_+|$ **ratio margin:** $\max\{\frac{w_-}{w_+}, \frac{w_+}{w_-}\}$

3.4 Tricks

- only pick from a random subsample of points
- only use ‘fancy’ criteria for first 10 examples then switch to uncertainty sampling
- occasionally pick points uniformly at random

4 Unsupervised Learning

4.1 Online K-means

$$L(\mu) = \sum_{i=1}^N \min_j \|u_j - x_i\|_2^2$$

$$\frac{\partial f_i(\mu)}{\partial \mu_j} = \begin{cases} 0 & \text{if } j \notin \arg \min \| \mu_j - x_i \|^2 \\ 2(\mu_j - x_i) & \text{otherwise} \end{cases}$$

initialize centers randomly

for $t = 1 : N$ **do**

$$c \leftarrow \arg \min_j \|\mu_j - x_t\|^2$$

$$\mu_c \leftarrow \mu_c + \eta_t (x_t - \mu_c)$$

Converges to local optimum given $\sum_t \eta_t = \infty$ and $\sum_t \eta_t^2 < \infty$

4.2 Constructing Coresets

C is called a (k, ϵ) coreset for data D if

$$(1 - \epsilon)L_k(\mu, D) \leq L_k(\mu, C) \leq (1 + \epsilon)L_k(\mu, D)$$

$$C = \{(x_{R1}, \frac{1}{nq(R1)}), \dots, (x_{Rn}, \frac{1}{nq(Rn)})\}$$

$$L(\mu, C) = \sum_{i=1}^n \frac{1}{nq(R_i)} \min_j \|x_{Ri} - \mu_j\|^2$$

$$E[L(\mu, C)] = \sum_{l=1}^N \sum_{i=1}^n \frac{q(l)}{nq(l)} \min_j \|x_{Rl} - \mu_j\|^2 = L(\mu, D)$$

$B \leftarrow \emptyset, D \leftarrow D'$

while $D' \neq \emptyset$ **do**

$S \leftarrow$ uniformly sample $10dk \log(\frac{1}{\epsilon_{\text{psilon}}})$ points from D

Remove $\frac{|D'|}{2}$ points nearest to S from D'

$B \leftarrow B \cup S$

Partition D into Voronoi cells D_b centered at $b \in B$

$$q(x) \propto \frac{5}{|D_b|} + \frac{\text{dist}(x, B)^2}{\sum_{x'} \text{dist}(x', B)^2} \quad \gamma(x) = \frac{1}{|C|q(x)}$$

$C \leftarrow$ sample $10dk \log^2 n \log(\frac{1}{\delta})/\epsilon^2$ from D via q

Can find a coreset in $\mathcal{O}(k^3/\epsilon^{d+1})$ and weak coreset in $\mathcal{O}(\text{poly}(k, d/\epsilon))$

merge: union of two (k, ϵ) coresets is a (k, ϵ) coreset

compress: (k, δ) coreset of a (k, ϵ) coreset is a $(k, \epsilon + \delta + \epsilon\delta)$

5 Recommender Systems

regret: $\mu^* n - \mu_j \sum_{j=1}^K E[n_j(n)]$ after n steps where μ^* is expectation of optimal machine payoff and μ_j expectation of machine j.

5.1 Epsilon Greedy

set ϵ_t $1/t$ and explore with $P = \epsilon_t$, exploit otherwise

$$R_T = \mathcal{O}(k \log T)$$

5.2 Confidence Bounds

Let X_1, X_m be iid RV taking values in $[0, 1]$

$$\mu = E[X] \quad \hat{\mu}_m = \frac{1}{m} \sum_{l=1}^m X_l$$

then $P(|\mu - \hat{\mu}_m| \geq b) \leq 2 \exp(-2b^2 m)$ with $b = \sqrt{\frac{1}{2m} \log \frac{2}{\delta}}$

5.3 UCB1

Optimum in face of uncertainty

set $\hat{\mu}_1, \dots, \hat{\mu}_k = 0, n_1, \dots, n_k = 0$

for $t = 1 : T$ **do**

$$\text{UCB}(i) = \hat{\mu}_i + \sqrt{\frac{2 \log t}{n_i}}$$

pick $j = \arg \max_i \text{UCB}(i)$ and observe y_t

$$n_j \leftarrow n_j + 1 \quad \hat{\mu}_j \leftarrow \hat{\mu}_j + \frac{y_t - \hat{\mu}_j}{n_j}$$

6 LinUCB

$$y_t = w_i^T z_t + \epsilon_t \quad \arg \min_w \sum_{t=1}^n (y_t - w_i^T z_i) + \|w\|_2^2$$

closed form solution: $\hat{w}_i = (D_i^T D_i + I)^{-1} D_i^T y_i$ (Ridge Regression)

$$D_i \begin{bmatrix} - & z_1 & - \\ & \vdots & \\ - & z_n & - \end{bmatrix} \quad y_i = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

$$|\hat{w}_i^T z_t - w_i^T z^T| \leq \alpha \sqrt{z_t^T (D_i^T D_i + I)^{-1} z_t}$$

with probability at least $1 - \delta$ as long as $\alpha = 1 + \sqrt{\log(2/\delta)/2}$
 $R_T/T = \mathcal{O}(dd' \text{poly}(\log(T/\sqrt{T})))$

6.1 Hybrid

$$y_t = w_i^T z_t + \beta^T \phi(x_i, z_t) + \epsilon_t$$

6.2 Rejection Sampling

for $t = 1 : T$ **do**

Get next event from $\log(\{x_t^{1:k}\}, z_t, a_t, y_t)$

Use bandit algorithm to select a'_t

if $a'_t = a_t$ **then**

feed back reward y_t to the algorithm

else

ignore log line

7 Appendix

7.1 Distance Functions

$d(s, t)$ is a distance function if

a) $d(s, t) \geq 0$ **b)** $d(s, s) = 0$ **c)** $d(t, s) = d(s, t)$ **d)**

$$d(s, r) \leq d(s, t) + d(t, r)$$

$$l_p \text{ distance: } d_p(x, x') = (\sum_{i=1}^D |x - x'|^p)^{1/p}$$

$$l_\infty \text{ distance: } d_\infty(x, x') = \max_i |x - x'|$$

$$\text{cosine distance: } d(x, x') = \frac{\arccos(x^T x')}{\|x\|_2 \|x'\|_2}$$

edit distance: how many inserts/deletes to transform one string into another

$$\text{Jaccard distance: } d(x, x') = 1 - \frac{x \cap x'}{x \cup x'}$$

7.2 Convex Programming

convex set:

S is convex if $\forall x, x' \in S, \lambda \in [0, 1] \lambda x + (1 - \lambda)x' \in S$

convex function:

$f : \mathbb{R}^d \rightarrow \mathbb{R}$ is convex if $\forall x, x' \in S, \lambda \in [0, 1]$

$$f(\lambda x + (1 - \lambda)x') \leq \lambda f(x) + (1 - \lambda)f(x')$$

subgradient:

for $f(x)$ convex, $g(x)$ is a subgradient of f at x_0 iff

$$\forall x \ f(x) \geq f(x_0) + g^T(x - x_0)$$

7.3 Submodularity

Set function F on V is submodular if $\forall A \subseteq B$ and $s \notin B$ and $a_1, a_2 \notin A$

$$F(A \cup \{s\}) - F(A) \geq F(B \cup \{s\}) - F(B) \quad \text{Diminishing}$$

$$F(S) + F(T) \geq F(S \cup T) + F(S \cap T)$$

$$F(A \cup \{a_1\}) + F(A \cup \{a_2\}) \geq F(A \cup \{a_1, a_2\}) + f(A)$$

Closedness under

Non-negative linear combinations: for F_1, \dots, F_m submodular functions and $\lambda_1, \dots, \lambda_m \geq 0$

$$\begin{aligned} F(A \cup \{s\}) - F(A) &= \left(\sum_i \lambda_i F_i(A \cup \{s\}) \right) - \left(\sum_i \lambda_i F_i(A) \right) \\ &= \sum_i \lambda_i (F_i(A \cup \{s\}) - F_i(A)) \geq \sum_i \lambda_i (F_i(B \cup \{s\}) - F_i(B)) \\ &\geq (F(B \cup \{s\}) - F(B)) \end{aligned}$$

Restrictions: for F submodular over V and $S, W \subseteq V$

$$F'(S) = F(S \cap W) \quad \text{submodular}$$

Conditioning: for F submodular over V and $S, W \subseteq V$

$$F'(S) = F(S \cup W) \quad \text{submodular}$$

Reflection: for F submodular over V

$$F'(S) = F(V \setminus S) \quad \text{submodular}$$

For $F_{1,2}(A)$, $\max\{F_1(A), F_2(A)\}$ or $\min\{F_1(A), F_2(A)\}$ **not** submodular in general.

Example:

$$\begin{aligned} \max_{j \in A \cup \{s\}} M_{ij} - \max_{j \in A} M_{ij} &= \max\{M_{is}, \max_{j \in A} M_{ij}\} - \max_{j \in A} M_{ij} \\ &= \max\{M_{is} - \max_{j \in A} M_{ij}, 0\} \end{aligned}$$

If $A \subseteq B$ then $\max_{j \in A} M_{ij} \leq \max_{j \in B} M_{ij}$

Lazy Greedy Algorithm

start with $A_0 = \{\}$

keep ordered list of marginal benefits Δ_i from prev. it.

for $i=1:k$ **do**

$\Delta_i = F(A_{i-1} \cup \{s^*\})$ where s^* is for top element

if i is still top element **then**

$$A_i = A_{i-1} \cup \{s^*\}$$

else

resort Δ_i and assign greedily