



DAGS

Notes: DAGs, Topological Sort, and Shortest Paths

◆ Directed Acyclic Graphs (DAGs)

- A **DAG** is a directed graph with **no directed cycles**lecture08_dags_toposort.
 - Generalization of a tree:
 - Trees = special case (1 root, 1 parent per node).
 - DAGs allow multiple roots, multiple parents, and more edges.
 - Useful for modeling **dependencies** (e.g., build systems, course prerequisites).
 - Key concepts:
 - **Sources**: nodes with no incoming edges.
 - **Sinks**: nodes with no outgoing edges.
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◆ Topological Sort

Definition: An ordering of vertices where if $(u, v) \in E$, then u appears before v lecture08_dags_toposort.

- Represents a valid order to process tasks with dependencies.
- A DAG can have **many valid topo orders**.

Algorithms

1. **Kahn's Algorithm**lecture08_dags_toposort:

- Count indegrees.
- Put all indegree=0 nodes into a queue.
- Repeatedly pop, add to order, and decrease indegrees of children.
- Complexity: $O(V+E)$.

2. DFS-based Toposort

- Run DFS, record vertices in **postorder** (finish times).
- Reverse the postorder → topological order.
- Complexity: $O(V+E)$.

◆ Shortest Path in a DAG

Key insight: Toposort gives the perfect order to relax edges.


- In Dijkstra/Bellman-Ford, the challenge is deciding order.
- In DAGs, **toposort ensures parents are processed before children**.

Algorithm (gist)

1. Compute topological order of DAG.
2. Initialize distances:
 - $d(s) = 0$ for source s .
 - $d(v) = \infty$ (or `None`) for others.
3. Process vertices in topo order:
 - For each edge (u, v) : $d(v) = \min(d(v), d(u) + w(u, v))$
 - Since u comes before v , all shortest paths into u are already known.

Complexity

- Toposort = $O(V+E)$.

- Relax edges once each = $O(V+E)$.
-  Total = $O(V+E)$ (faster than Dijkstra or Bellman-Ford on general graphs).lecture08_dags_toposort

Implementation gist

```
def dag_shortest_paths(adjlist, s):
    order = toposort([[v for v, _ in vs] for vs in adjlist]) # topo sort
    dists = [None] * len(adjlist)
    dists[s] = 0
    for u in order:
        if dists[u] is None:
            continue
        for v, w in adjlist[u]: # relax edges
            if dists[v] is None or dists[u] + w < dists[v]:
                dists[v] = dists[u] + w
    return dists
```

◆ Summary (for test)

- **DAGs:** directed graphs without cycles, generalize trees.
- **Toposort:** ordering where parents come before children.
 - Kahn's (indegree queue) or DFS (finish times).
- **Shortest Path in DAGs:**
 - Use topological order to relax edges in one pass.
 - Complexity = $O(V+E)$.
 - Works because *every prefix of a shortest path is itself shortest*, and topo order guarantees prerequisites are ready.

Would you like me to also add a **worked example DAG** (with edge weights, topo order, and step-by-step distance table) so you can quickly reference the shortest

path process in your test?