National Textile University, Faisalabad



Department of Computer Science

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Registration No:	23-NTU-CS-1074
Lab Report:	iot
Course Code:	
Course Name:	iot
Submitted To:	Sir Nasir
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CODE:

```
// 23 ntu cs 1074
// Muhammad talal shariq
// Embedded iot systems
// esp32 dual led toggle
#include <Arduino.h>
#define LED1_PIN 19
#define LED2_PIN 2
#define BTN1_PIN 32
#define BTN2_PIN 26
#define DEBOUNCE MS 50
#define DEBOUNCE_US (DEBOUNCE_MS * 1000UL)
hw_timer_t* timer1 = nullptr;
hw_timer_t* timer2 = nullptr;
volatile bool debounce1Active = false;
volatile bool debounce2Active = false;
void ARDUINO_ISR_ATTR onDebounce1() {
if (digitalRead(BTN1_PIN) == LOW) {
  digitalWrite(LED1_PIN, !digitalRead(LED1_PIN));
```

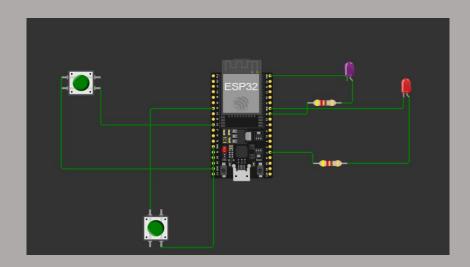
```
debounce1Active = false;
void ARDUINO_ISR_ATTR onDebounce2() {
 if (digitalRead(BTN2_PIN) == LOW) {
  digitalWrite(LED2_PIN, !digitalRead(LED2_PIN));
 debounce2Active = false;
void ARDUINO_ISR_ATTR onButton1() {
if (!debounce1Active) {
  debounce1Active = true;
  timerAlarm(timer1, DEBOUNCE_US, false, 0);
void ARDUINO_ISR_ATTR onButton2() {
 if (!debounce2Active) {
  debounce2Active = true;
  timerAlarm(timer2, DEBOUNCE_US, false, 0);
void setup() {
```

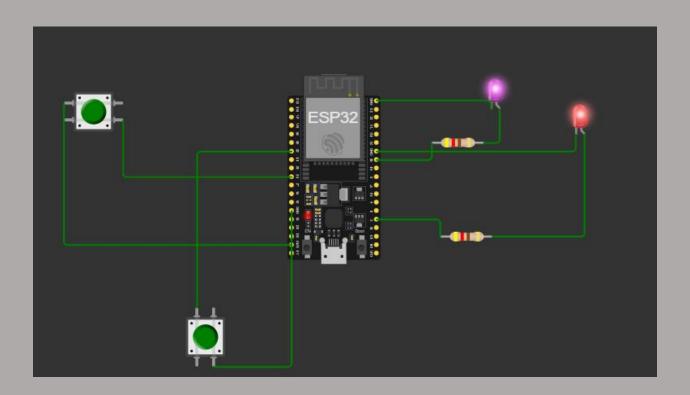
```
Serial.begin(115200);
 Serial.println("ESP32 Dual LED with Interrupt + Timer Debounce");
 pinMode(LED1 PIN, OUTPUT);
 pinMode(LED2_PIN, OUTPUT);
 pinMode(BTN1_PIN, INPUT_PULLUP);
 pinMode(BTN2_PIN, INPUT_PULLUP);
 digitalWrite(LED1_PIN, LOW);
 digitalWrite(LED2_PIN, LOW);
 timer1 = timerBegin(1000000);
 timerAttachInterrupt(timer1, &onDebounce1);
 timer2 = timerBegin(1000000);
 timerAttachInterrupt(timer2, &onDebounce2);
 attachInterrupt(BTN1_PIN, onButton1, FALLING);
 attachInterrupt(BTN2_PIN, onButton2, FALLING);
void loop() {
```

SCREEN SHOTS:

```
// Muhammad talal shariq
    #include <Arduino.h>
    #define LED1 PIN
                         19
10 #define LED2 PIN
    #define BTN1 PIN
                          32
    #define BTN2_PIN
                         26
    #define DEBOUNCE MS 50
    #define DEBOUNCE_US (DEBOUNCE_MS * 1000UL)
    hw timer t* timer1 = nullptr;
    hw_timer_t* timer2 = nullptr;
    volatile bool debounce1Active = false;
    volatile bool debounce2Active = false;
    void ARDUINO_ISR_ATTR onDebounce1() {
       if (digitalRead(BTN1_PIN) == LOW) {
         digitalWrite(LED1_PIN, !digitalRead(LED1_PIN));
       debounce1Active = false;
     void ARDUINO ISR ATTR onDebounce2() {
       if (digitalRead(BTN2_PIN) == LOW) {
        digitalWrite(LED2_PIN, !digitalRead(LED2_PIN));
       debounce2Active = false;
     void ARDUINO_ISR_ATTR onButton1() {
     if (!debounce1Active) {
         debounce1Active = true;
         timerAlarm(timer1, DEBOUNCE_US, false, 0);
```

```
void ARDUINO ISR ATTR onButton2() {
       if (!debounce2Active) {
         debounce2Active = true;
         timerAlarm(timer2, DEBOUNCE_US, false, 0);
     void setup() {
       Serial.begin(115200);
       Serial.println("ESP32 Dual LED with Interrupt + Timer Debounce");
54
       pinMode(LED1_PIN, OUTPUT);
       pinMode(LED2_PIN, OUTPUT);
       pinMode(BTN1_PIN, INPUT_PULLUP);
       pinMode(BTN2_PIN, INPUT_PULLUP);
       digitalWrite(LED1_PIN, LOW);
       digitalWrite(LED2_PIN, LOW);
       timer1 = timerBegin(1000000);
64
       timerAttachInterrupt(timer1, &onDebounce1);
       timer2 = timerBegin(1000000);
       timerAttachInterrupt(timer2, &onDebounce2);
       attachInterrupt(BTN1_PIN, onButton1, FALLING);
70
       attachInterrupt(BTN2_PIN, onButton2, FALLING);
73
     void loop() {
76
```





<u>LINK :</u>
EHAK :
https://wokwi.com/projects/444074584480646145