

AM 147: Computational Methods and Applications: Winter 2021

Homework #7

Instructor: Abhishek Halder

Due: February 23, 2021

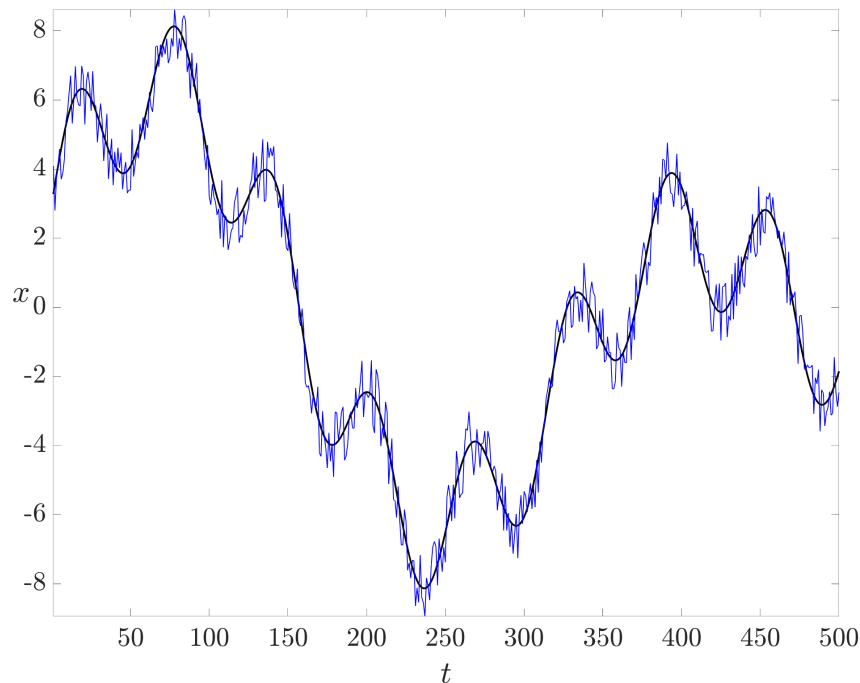
NOTE: Please submit your Homework as a single zip file named `YourlastnameYourfirstnameHW7.zip` via CANVAS. For example, `HalderAbhishekHW7.zip`. Please strictly follow the capital and small letters in the filename of the zip file you submit. You may not receive full credit if you do not follow the file-naming conventions. Your zip file should contain all .m files (MATLAB scripts) for the questions below.

Your zip file must be uploaded to CANVAS by 11:59 PM Pacific Time on the due date. The uploads in CANVAS are time-stamped, so please don't wait till last moment. Late homework will not be accepted.

Problem 1

Estimate the true signal from the measured noisy signal

(50 points)



Download the starter code `HW7p1.m` from CANVAS Files section folder “HW Problems” to your computer, and rename it as `YourlastnameYourfirstnameHW7p1.m`. The starter code plots a

true signal $x(t)$ (in solid black) that is NOT known. Only the noise corrupted signal $x_{\text{noisy}}(t)$ (in solid blue), as shown in the plot above, is available. As a data scientist, your job is to recover an estimate $\hat{x}(t)$ of the true signal from the noisy measured signal $x_{\text{noisy}}(t)$. We think of t as time; the noisy signal was measured at 500 different time instances.

To solve this problem, you need to formulate it as

$$\hat{x} = \arg \min_x \|x - x_{\text{noisy}}\|_2^2 + \beta \sum_{k=1}^{499} (x_{k+1} - x_k)^2, \quad \beta > 0.$$

We can interpret the above optimization problem as follows. Since we want the recovered signal to be close to the measured signal x_{noisy} , it makes sense to minimize $\|x - x_{\text{noisy}}\|_2^2$. This justifies the first summand in the objective. We also want the estimated signal to be “smooth” in the sense it should not change too rapidly between consecutive times. To mathematically capture this, the second summand penalizes rapid changes in the signal between consecutive times. The parameter $\beta > 0$ is fixed. Therefore, the first summand in the objective represents data fidelity; the second summand in the objective promotes regularization/smoothness. Large β implies smoother but more distant from the measured signal. Similarly, smaller β implies closer to the measured but more “spiky” signal. You need to reformulate this problem as a standard least square problem $\arg \min_x \|Ax - b\|_2^2$ for some appropriately defined matrix A and vector b .

Your job is to complete the starter code by typing in some lines between lines 26 and 28. Then uncomment lines 32–41 and complete line 35 within the for loop. The completed code should make a plot of the estimated signals for $\beta = 1, 10, 100$ together with the blue and black curves shown above, all in the same figure.

In the zip file containing your completed code, please also include a file named `YourlastnameYourfirstnameHW7p1.pdf` that clearly shows your hand calculations in deriving the matrix A and vector b appearing in the standard least square form.