Remauto Meeting Minutes

Date: October 9, 2022 Attendees: Darton, Taim

Software

Codebase Setup

Client has

UX/UI

GUI will have gear shifting menu (activated by Options button on PS4)

Documentation

Use Doxygen, either comment code now or later after working prototype (revising and cleaning code up)

Git Merge Time?

- Finish PS4 functions stub, then merge into master
- Organize code into /src, /build, /test, /doc, etc

Research

Darton

- https://github.com/waveform80/pistreaming/blob/9b1a8719fa34f8737e6292d52c1cb0f 1d86a1d1a/server.py#L88
- Multiprocessing
- https://tutorials-raspberrypi.com/raspberry-pi-servo-motor-control/
- Cython

Taim

- PyQt5
- Function stubs to fill in later
 - \circ L2 \rightarrow brake
 - \circ R2 \rightarrow gas pedal
 - \circ L1 \rightarrow left signal
 - \circ R1 \rightarrow right signal
 - \circ Option \rightarrow gear shift menu
 - \circ Left joystick \rightarrow steering wheel

Hardware

A4988:

Large Stepper Motor Control A4988: 5 Steps - Instructables

MOSFET choice

Rotary encoders

Timelining

Darton:

- Camera
- Git Merge
- Document lifecycle of the comms module in a readme file:
- Code cleanup
- See if controllers work?

Taim:

- Git Merge
- Preliminary investigation into PyQT5?

Mechanical